Lecture 12: Graphs II: Depth-First Search

Lecture Overview

- Depth-First Search
- Edge Classification
- Cycle Testing
- Topological Sort

Recall:

- graph search: explore a graph e.g., find a path from start vertex s to a desired vertex
- ullet adjacency lists: array Adj of |V| linked lists
 - for each vertex $u \in V$, $\mathrm{Adj}[u]$ stores u's neighbors, i.e., $\{v \in V \mid (u,v) \in E\}$ (just outgoing edges if directed)

For example:

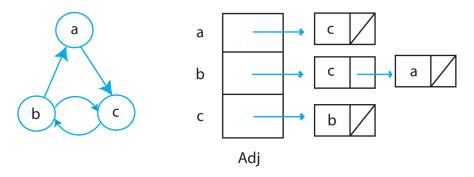


Figure 1: Adjacency Lists

Breadth-first Search (BFS):

Explore level-by-level from s — find shortest paths

Depth-First Search (DFS)

This is like exploring a maze (Charles Pierre Tremaux, Cretan labyrinth). You can use this for finding paths, detecting cycles, checking whether a graph is bipartite (color edges opposite of parent's, then make sure that edges always connect opposite colors).

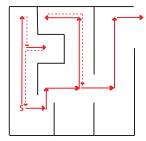


Figure 2: Depth-First Search Frontier

Depth First Search Algorithm

- follow path until you get stuck
- backtrack along breadcrumbs until reach unexplored neighbor
- recursively explore, being careful not to repeat a vertex
- another way to think about it: touch a wall and keep walking!

```
search from
    DFS-visit (Adj, s):
                                                                  start vertex s
start → for v in Adj [s]:
                                                                  (only see
             if v not in parent:
  ٧
                                                                  stuff reachable
                  parent [v] = s
                                                                  from s)
finish
                  DFS-visit (Adj, v)
    DFS (V, Adj)
                                                           explore
        parent = \{ \}
                                                            entire graph
        for s in V:
             if s not in parent:
                                                         (could do same
                  parent [s] = None
                                                         to extend BFS)
                  DFS-visit (Adj, s)
```

Figure 3: Depth-First Search Algorithm

Example

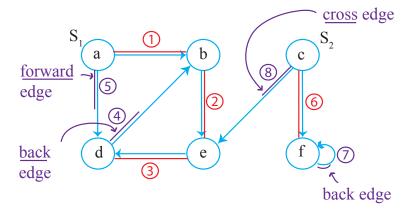


Figure 4: Depth-First Traversal

Edge Classification

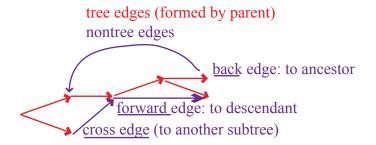


Figure 5: Edge Classification

- to compute this classification (back or not), mark nodes for duration they are "on the stack"
- only tree and back edges in undirected graph

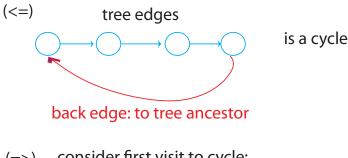
Analysis

- DFS-visit gets called with a vertex s only once (because then parent[s] has been set) \Longrightarrow time in DFS-visit $=\sum_{s\in V}|\mathrm{Adj}[s]|=O(E)$
- DFS outer loop adds just O(V) $\implies O(V + E)$ time (linear time)

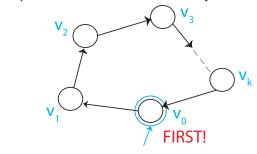
Cycle Detection

Graph G has a cycle \Leftrightarrow DFS has a back edge

Proof



consider first visit to cycle: (=>)



- before visit to v_i finishes, will visit v_{i+1} (& finish): will consider edge (v_i, v_{i+1}) \implies visit v_{i+1} now or already did
- \implies before visit to v_0 finishes, will visit v_k (& didn't before)
- \implies before visit to v_k (or v_0) finishes, will see (v_k, v_0) as back edge

Job scheduling

Given Directed Acylic Graph (DAG), where vertices represent tasks & edges represent dependencies, order tasks without violating dependencies

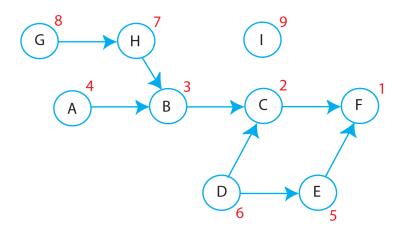


Figure 6: Dependence Graph: DFS Finishing Times

Source:

Source = vertex with no incoming edges = schedulable at beginning (A,G,D,I)

Attempt:

BFS from each source:

- from A finds A, B, C, F (you're already doing C before you do D, if you choose to just take this ordering)
- from D finds D, CE, F
- from G finds G, H (then B, C, F, but depending upon what order this source is BFS-ed vs vertex A, this could be wrong)
- from I finds I

Topological Sort

Reverse of DFS finishing times (time at which DFS-Visit(v) finishes) $\begin{array}{c}
\text{DFS-Visit}(v) \\
\dots \\
\text{order.append}(v)
\end{array}$ order.reverse()

Correctness

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For any edge (u,v) — u ordered before v, i.e., v finished before u



- if u visited before v:
 - before visit to u finishes, will visit v (via (u, v) or otherwise)
 - $\implies v$ finishes before u
- if v visited before u:
 - graph is acyclic
 - $\implies u$ cannot be reached from v
 - $-\implies$ visit to v finishes before visiting u