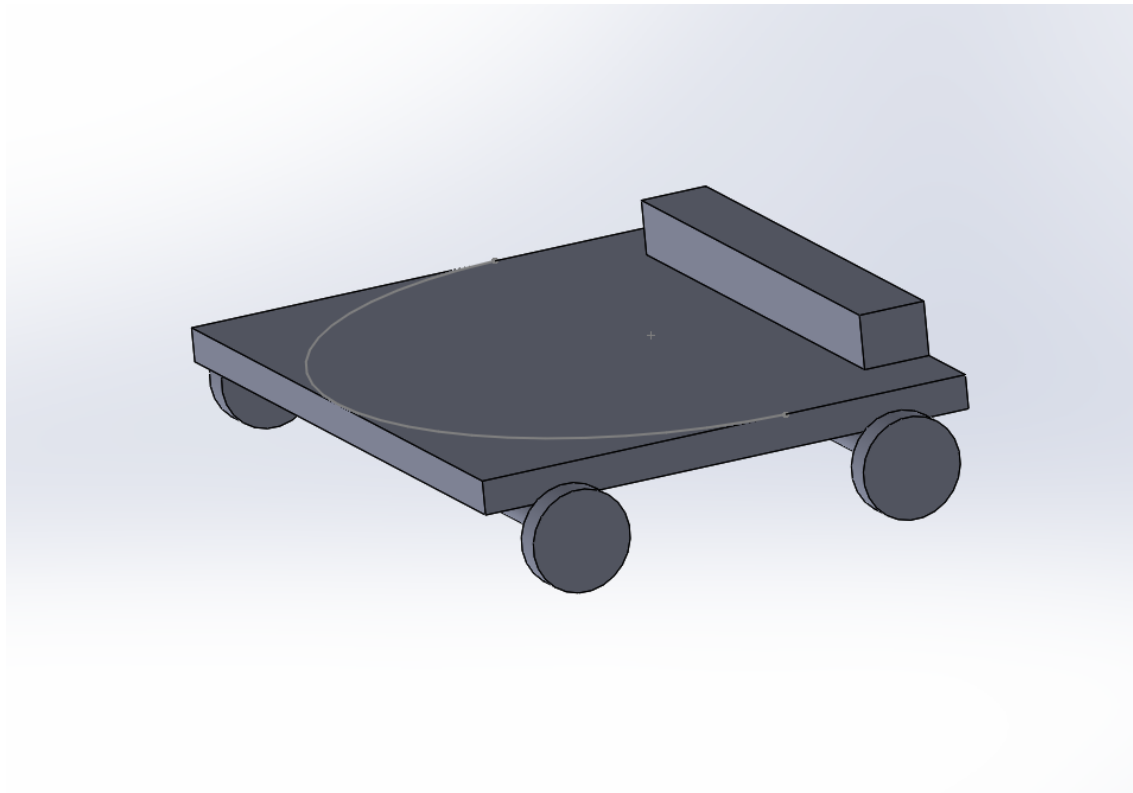
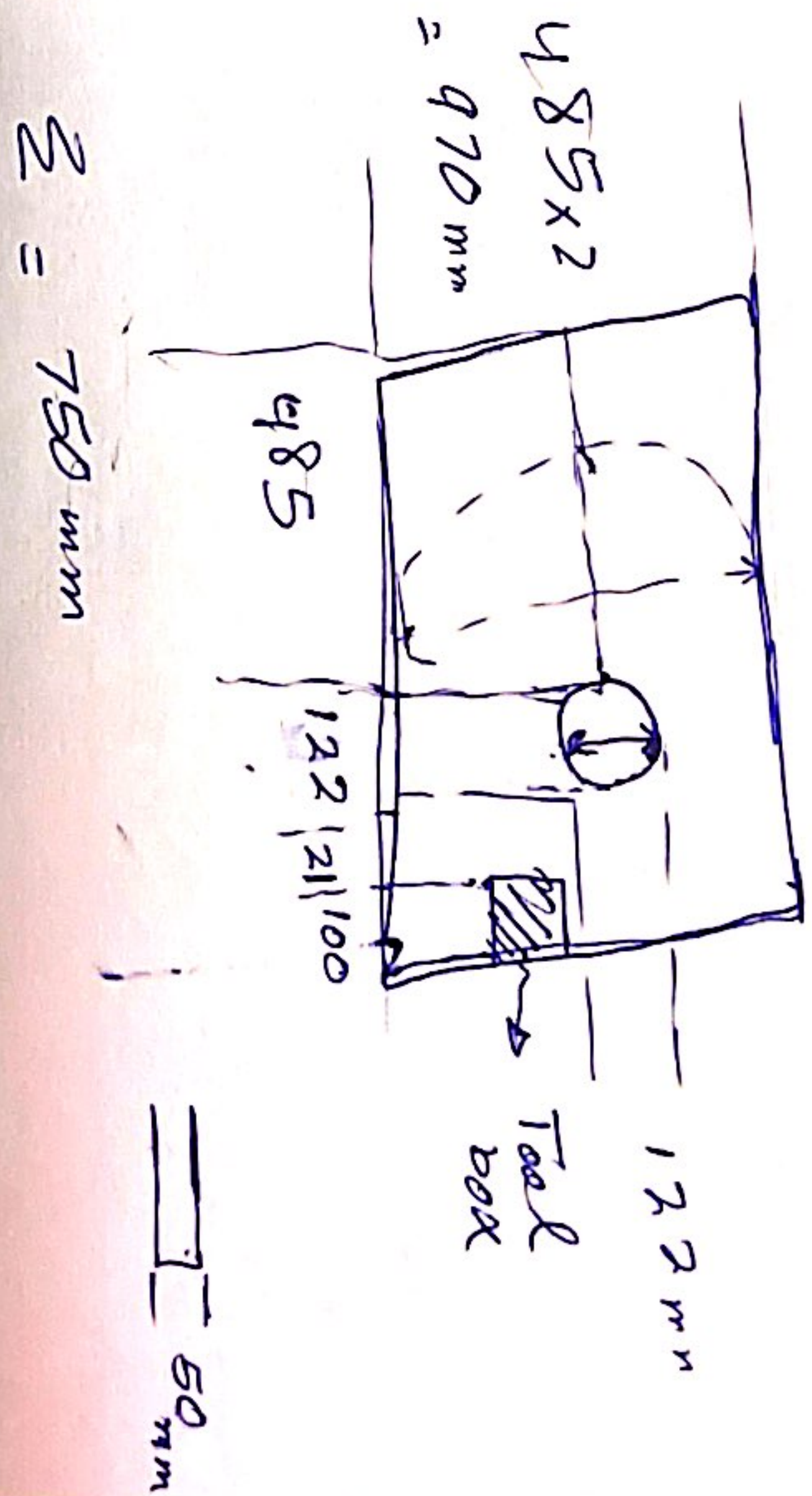


Regarding task 2 for the robot body I upload all the requirement on github the base for arm I designed it using the sheet in the next page and here a photo of it using Solid Works



$$18 + 165 + 180 - 18 + 142$$

$$= 485 \text{ mm} \times 2 = 970$$



$$Z = 750 \text{ mm}$$

with 4 wheel
because it is
The most reliable
and most efficient
way to move