

Strongly Connected Components and Minimum Spanning Trees

CSCI 700 - Algorithms I

Andrew Rosenberg

- Depth-First Search
- Breadth-First Search

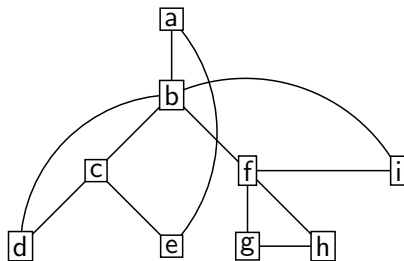
- Strongly Connected Components
- Minimum Spanning Trees: Prim's Algorithm

Ordering Of Nodes using DFS

We can track the **discovery time** $d[v]$ and **finish time** $f[v]$ of each node.

- Sorting by discovery time gives a **preorder traversal**
- Sorting by finish time gives a **postorder traversal**
- Is a node u is a DFS ancestor of a node v ?
 - $d[u] < d[v] < f[v] < f[u]$
- Is a node u to the left is a node v ?
 - $d[u] < f[u] < d[v] < f[v]$

Ordering Of Nodes using DFS



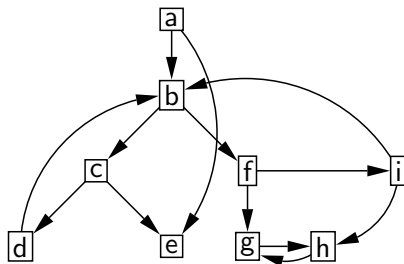
Strongly Connected Components

A Graph G is **strongly connected** if for all $u, v \in V$, u and v are mutually reachable.

We can decompose any Graph into a set of **Strongly Connected Components** – SCCs.

Every node in a cycle appears in the same SCC.

How can we identify SCCs?



Identifying SCCs

Test reachability from every node to every other node.

Runtime?

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$$O(n(n + e)) = O(n^2 + ne)$$

Identifying SCCs

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How can we do better?

- Run a DFS – keep track of $f[v]$.
- Reverse the Graph.
- Run a DFS on the reversed Graph – traversing in order of **decreasing** $f[v]$.
- The DFS Tree contains only the strongly connected components with internal edges included.

Runtime?

Identifying SCCs

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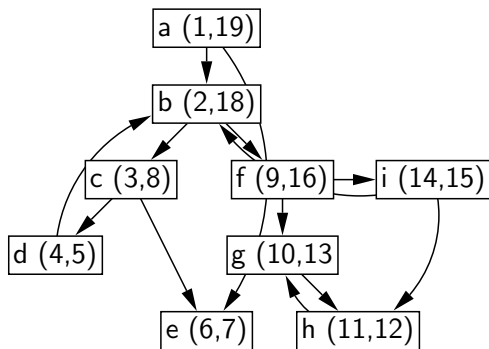
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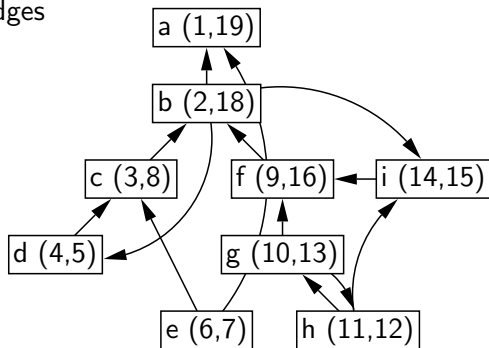
$$O(3(n + e)) = O(n + e)$$

Identifying SCCs

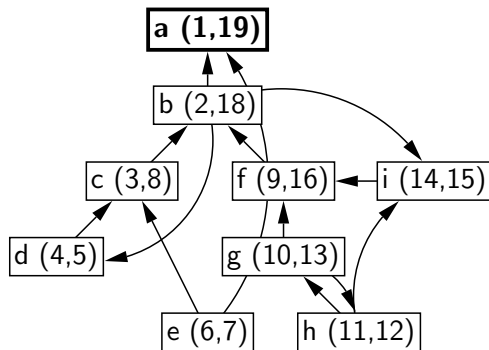


Identifying SCCs

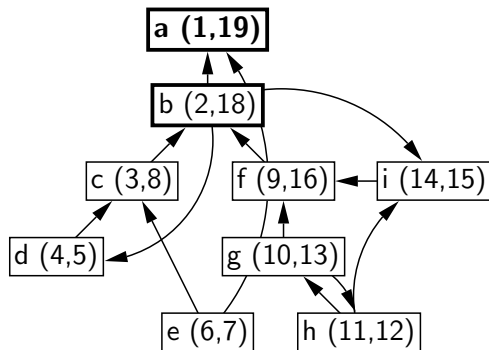
Reverse the edges



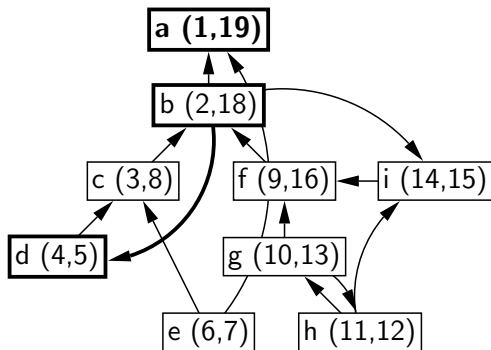
Identifying SCCs



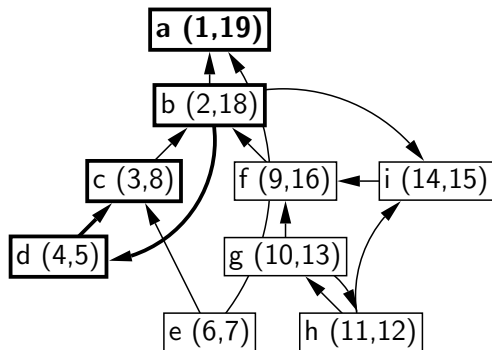
Identifying SCCs



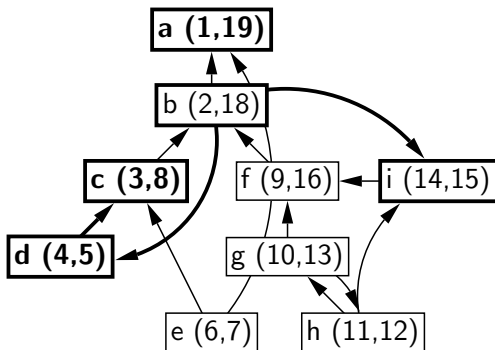
Identifying SCCs



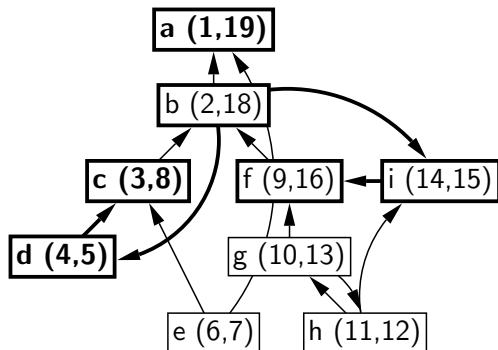
Identifying SCCs



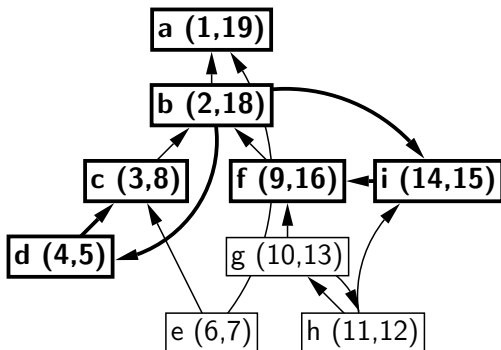
Identifying SCCs



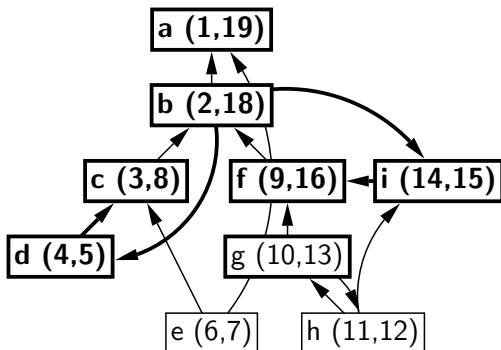
Identifying SCCs



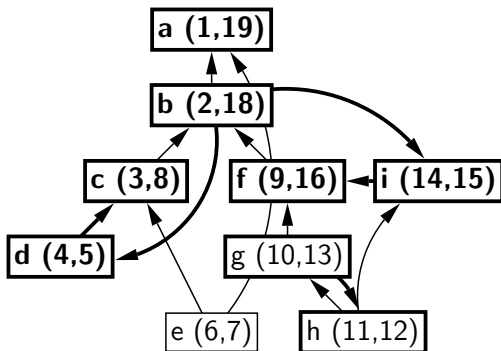
Identifying SCCs



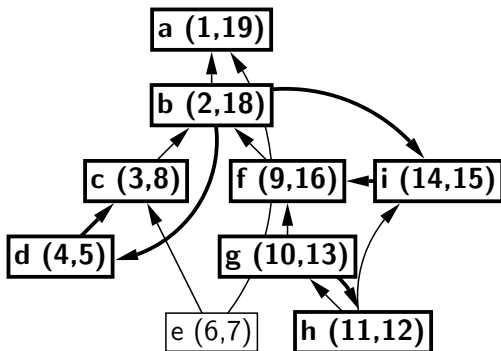
Identifying SCCs



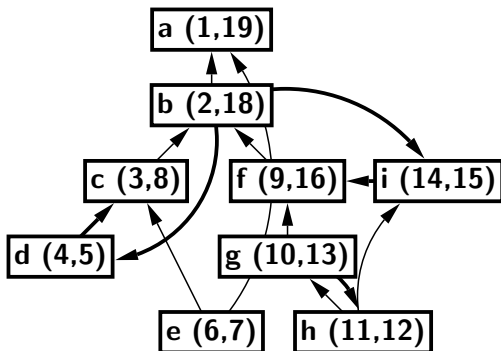
Identifying SCCs



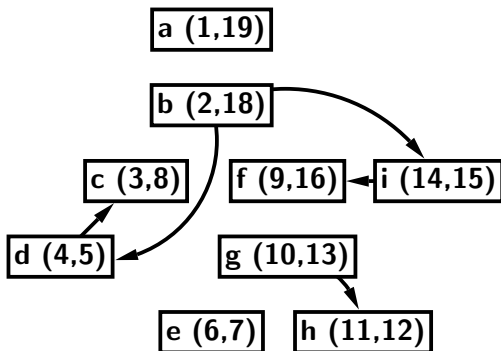
Identifying SCCs



Identifying SCCs



Identifying SCCs



Prove that the SCC procedure identifies all strongly connected components
Must show

- If u and v are mutually reachable then they are in the same DFS tree generated by the second DFS.
- If u and v are in the same DFS tree, then they are mutually reachable.

1. If u and v are mutually reachable in G , then they are mutually reachable in G_R .

If they are mutually reachable in G_R then they will appear in the same SCC.

Case 1) The DFS finds u first. Since u is reachable from v in G , then v is reachable from u in G_R . If v is reachable from u in G_R , the DFS subtree from u will include v .

Case 2) The reverse. The DFS finds v first. Since v is reachable from u in G , then u is reachable from v in G_R . If u is reachable from v in G_R , the DFS subtree from v will include u .

2. If u and v are in the same DFS tree in G_R , then they are mutually reachable.

- Let x be the root of the DFS tree containing u and v .
- Want to show: x and u are mutually reachable, and x and v are mutually reachable. (Only one is necessary)
- $f[v] < f[x]$, otherwise we would have started the DFS with v .
- Since x can reach v in the reverse graph G_R , v can reach x in the original graph G .
- Partition the **first** DFS into four regions when the active node is x .
 - Black nodes – completed.
 - Grey nodes – ancestors of x .
 - White nodes reachable from x .
 - White nodes not reachable from x .

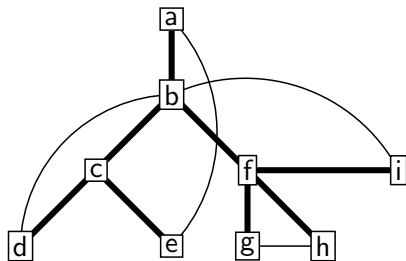
- $f[\text{greynodes}] > f[x]$
- $f[\text{nodesnotreachablefrom}x] > f[x]$.
- Recall $f[v] < f[x]$, thus, v is either black or in reachable from x .
- v cannot be black, because v can reach x in G .
- Thus, v must be below x , therefore reachable from x in G .
- Since x and v are mutually reachable in G , they are mutually reachable in G_R .
- The same logic holds for u .
- Thus, u and v are mutually reachable in G_R if they are in the same DFS Tree.

Definition of a Spanning Tree

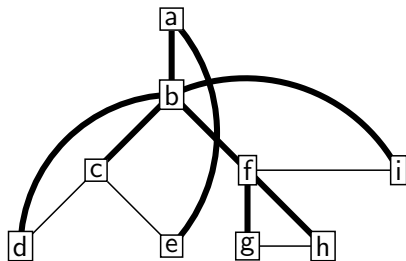
A **spanning tree** T of a graph G is a subgraph that contains

- Every vertex $v \in V$
- Edges $e \in E$ such that T is a tree – acyclic.

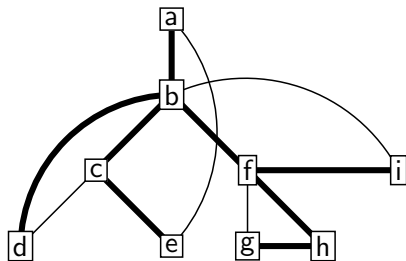
Example of Spanning Trees - DFS



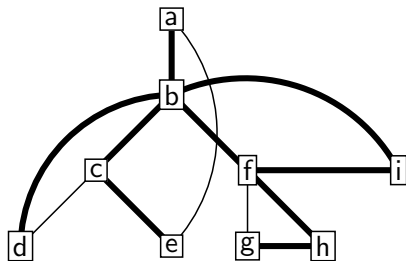
Example of Spanning Trees - BFS



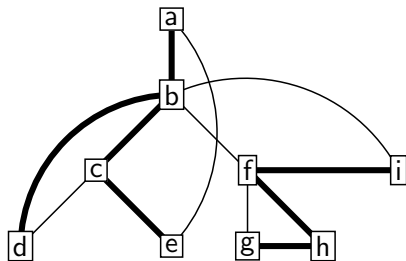
Example of Spanning Trees - Other



Not a Spanning Tree

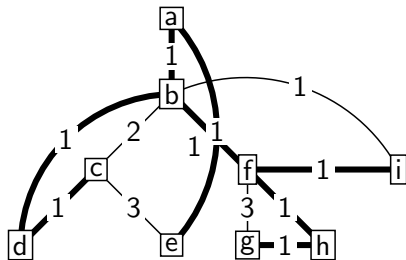


Not a Spanning Tree



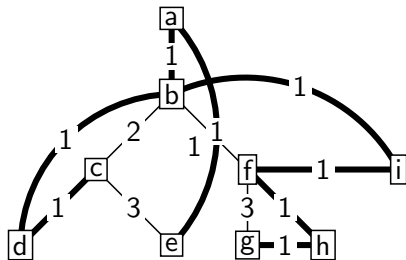
Minimum Spanning Tree

If the edges $e \in E$, have weights, a **minimum spanning tree** is a spanning tree with minimal cost.



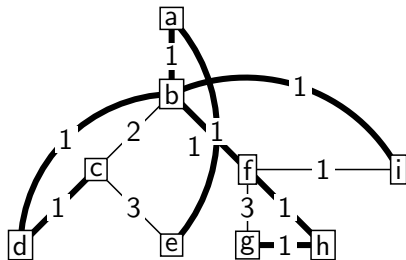
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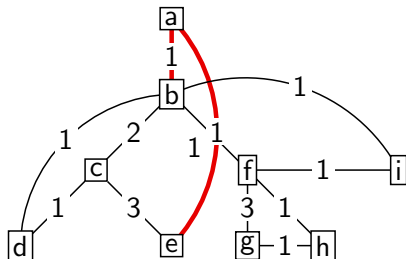
Minimum Spanning Tree Algorithm

Proposition: Start at any node. Include the lowest cost “fringe” edge

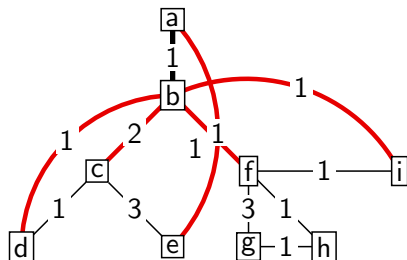
Claim: This greedy choice works.

Prim's Algorithm

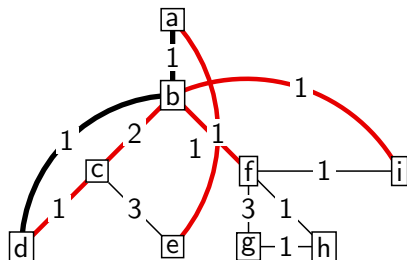
Example of Prim's Algorithm



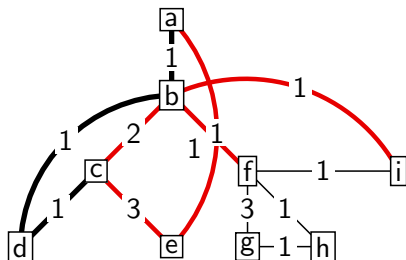
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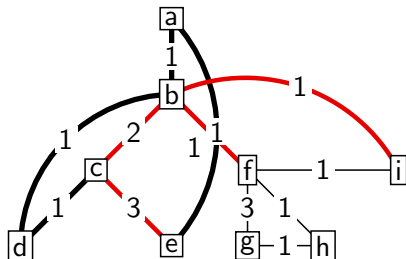
Example of Prim's Algorithm



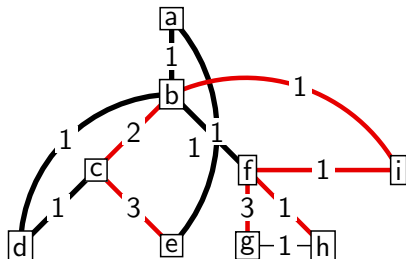
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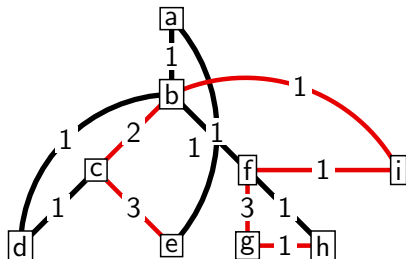
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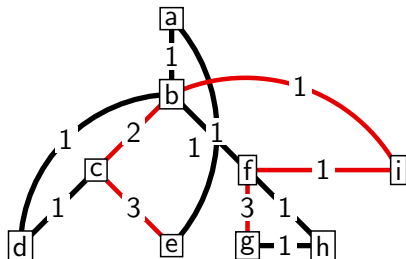
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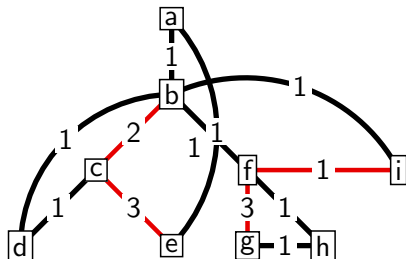
Example of Prim's Algorithm



Example of Prim's Algorithm



Example of Prim's Algorithm



Prim's Algorithm

MST-Prim(G, w, r)

```
for  $u \in V[G]$  do  
     $key[u] = \infty; \pi[u] \leftarrow \emptyset$   
end for  
 $key[r] \leftarrow 0$   
 $Q \leftarrow V[G]$   
while  $Q \neq \emptyset$  do  
     $u \leftarrow ExtractMin(Q)$   
    for  $v \in Adjacent(u)$  do  
        if  $v \in Q$  and  $w(u, v) < key[v]$  then  
             $key[v] = w(u, v); \pi[v] \leftarrow u$   
        end if  
    end for  
end while
```

Proof of Generic MST Algorithm

Greedy Strategy for a Generic MST growth.

Manage a set of edges A , such that prior to each iteration of the algorithm, A is the subset of a minimum spanning tree.

- At each step, identify an edge (u, v) that can be added to A without violating the invariant.
- We call (u, v) a **safe edge**.

How do we identify **safe edges**?

Identifying safe edges

Safe edges

Let G be a connected, undirected graph with weight functions w defined on E . Let A be a subset of E that is included in a MST. Let $(S, V - S)$ be any *cut* of G that *respects* A . Let (u, v) be a *light edge crossing* $(S, V - S)$. Then (u, v) is safe for A .

- A **cut** $(S, V - S)$ of an undirected graph G , is a partition of V .
- An edge **crosses** a cut if one of the end points are in S , and the other is in V .
- A cut **respects** a set of edges A if no edges in A cross the cut.
- A edge that crosses the cut is a **light edge**, if its weight is minimal crossing the cut.

Safe edges proof

- Let T be a MST that includes A , but doesn't include light edge (u, v) . (If it does, we're done.)
- We will construct another MST T' that includes $A \cup (u, v)$ using the cut-and-paste technique. Showing that (u, v) is a **safe edge** for A .
- Assume the edge (u, v) forms a cycle with the edges on the unique path p from u to v in T .
- Thus, there is some edge (x, y) on the path p that also crosses the cut.
 - (x, y) is not in A because the cut respects A .
- Since, (x, y) is on the unique path removing (x, y) separates T into two components.
- Adding (u, v) connects these two components, forming a new spanning tree T' .

- Now we need to show that T' is Minimal.
- Since (u, v) is a light edge crossing the cut $(S, V - S)$, and (x, y) also crosses the cut, $w(u, v) \leq w(x, y)$.
- Thus:
 - $w(T') = w(T) - w(x, y) + w(u, v) \leq w(T)$
- Since T was a minimum spanning tree, so is T' .
- Since T' is a minimum spanning tree containing (u, v) , (u, v) is safe for A .

Prim's algorithm

In Prim's algorithm, we identify the cut $(S, V - S)$, by starting at one node, and building up A by including light edges, and expanding A .

Next time:

- Another way to identify safe edges and build up A – Kruskal's Algorithm

- Next time
 - Another Minimum Spanning Tree Algorithm: Kruskal's
 - Shortest Paths: Bellman-Ford.