

# Low Dimensional Topology

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## **Part I**

# **Topology of 3-manifolds**

# Chapter 1

## Chapter 2

## Chapter 3

## **Part II**

# **Geometry of 3-manifolds**

# Chapter 4

## Hyperbolization

### 4.1 Geometric structures

**4.1 (Space forms).** Let  $X$  be a simply connected homogeneous Riemannian manifold. A *space form* of  $X$  is an orbit space  $X/\Gamma$  of a subgroup  $\Gamma \leq \text{Isom}(X)$  such that  $X \rightarrow X/\Gamma$  is a covering. If  $M$  is a space form of  $X$ , we say  $M$  is *modelled on*  $X$ .

- (a) A complete finite-volume Riemannian manifold is locally isometric to  $X$  is a space form of  $X$ .
- (b)  $X/\Gamma$  is a space form of  $X$  if and only if  $\Gamma$  acts properly discontinuously and freely on  $X$ . (if  $X$  is locally compact?)
- (c)  $X/\Gamma$  is a space form of  $X$  if and only if  $\Gamma$  is a discrete torsion-free subgroup of  $\text{Isom}(X)$ . (if every periodic isometry of  $X$  has a fixed point)
- (d) There is a following one-to-one correspondence:

$$\begin{array}{ccc} \frac{\{\text{space forms of } X\}}{\text{isometry}} & \xrightarrow{\sim} & \frac{\{\text{discrete torsion-free subgroups of } \text{Isom}(X)\}}{\text{conjugacy}}, \\ X/\Gamma & \mapsto & \Gamma. \end{array}$$

*Proof.*

□

**4.2 (Model geometry).** A *model geometry* is a simply connected homogeneous Riemannian manifold  $X$  that has a space form of finite-volume.

- (a) There are three model geometries of dimension two, up to isometry.
- (b) There are eight model geometries of dimension three, up to isometry.

*Proof.*

□

**4.3 (( $G, X$ )-manifolds).** Let  $X$  be a topological space. A *pseudogroup*  $\Gamma$  on  $X$  is a wide subgroupoid of  $\text{Homeo}(X)$  such that  $U \mapsto \{g \in \Gamma : \text{dom } g = U\}$  is a sheaf on the topology of  $X$ . Let  $\Gamma$  be a pseudogroup on  $X$ , and  $M$  be a topological space. A  $\Gamma$ -*atlas* on  $M$  is an atlas whose charts have  $X$  as the codomain and transition maps belong to  $\Gamma$ . A  $\Gamma$ -*structure* on  $M$  is defined as an equivalence class of  $\Gamma$ -atlases on  $M$ .

- (a)  $(G, X) := \{g|_U : g \in G, U \in \mathcal{T}\}$  is a pseudogroup on  $X$  for  $G \leq \text{Homeo}(X)$ .
- (b) ... Note that  $G$  does not act on  $(G, X)$ -manifold  $M$ .

**4.4 (Developing and holonomy).** Complete  $(G, X)$ -manifolds



**4.5** ((Isom( $X$ ),  $X$ )-manifolds). Let  $X$  be a simply connected homogeneous Riemannian manifold. We will show that a complete  $(G, X)$ -structure on a connected manifold corresponds to a geometric structure modelled on  $X$ . In this regard, we will call a  $(G, X)$ -structure that is not complete as *incomplete geometric structure*.

(a)  $M$  is a connected complete (Isom( $X$ ),  $X$ )-manifold if and only if  $M$  is a space form of  $X$ .

## 4.2 Poincaré polyhedron theorem

**4.6** (Fundamental polyhedron).

**4.7** (Side pairing). We want to develop a method for obtaining geometric 3-manifolds by gluing tetrahedra. Let  $X$  be a model geometry and  $X/\Gamma$  be a space form of  $X$  with finite volume.

**4.8** (Elliptic cycle condition). Tessellation of  $\mathbb{S}^2$  about vertices and edges, but edges are redundant.

**4.9** (Parabolic cycle condition). Tessellation of  $\mathbb{E}^2$  about ideal vertices.

## 4.3 Hyperbolic Dehn surgery

**4.10** (Cusp and horoball).

**4.11** (Thick-thin decomposition). Margulis constant.

**4.12** (Thurston's hyperbolic Dehn surgery).

## 4.4 Mostow rigidity

Kleinian groups Several topological invariants: volume, trace fields, etc.

## 4.5 Orbifolds

### Exercises

**4.13** (Action of compact stabilizer). Let  $M$  be a connected smooth manifold. Recovering metric from action of compact stabilizers...? We want to establish the following one-to-one correspondence.

$$\left\{ \begin{array}{c} \text{Homogeneous} \\ \text{Riemannian metrics} \end{array} \right\} \xrightarrow{\sim} \left\{ \begin{array}{c} \text{Maximal} \\ \text{homogeneous smooth group actions} \\ \text{of compact stabilizers} \end{array} \right\}.$$

(a) If  $g$  is a homogeneous Riemannian metric on  $M$ , the group action on  $M$  by  $\text{Isom}(M, g)$  is maximal among smooth group actions with compact stabilizers.

(b) If a smooth group action on  $M$  by  $G$  is maximal among smooth group actions with compact stabilizers, then there is a homogeneous Riemannian metric on  $M$  such that  $G \cong \text{Isom}(M, g)$ .

*Proof.*

□

**4.14** (Hyperbolization of punctured surfaces). Euler characteristic  $\chi$ .

**4.15** (Figure-eight knot complement). Find an ideal triangulation. Find the angle condition for the two ideal tetrahedra. Find the generators of  $\Gamma$ .

**4.16** (Geometrically finiteness).

**4.17** (Siegel theorem).

## Chapter 5

# Teichmüller theory

### 5.1

## **Chapter 6**

# **Geometric group theory**

### **6.1**

## **Part III**

# **Topology of 4-manifolds**

## Chapter 7

# Surgery theory

Why 4-manifolds are difficult?

## **Chapter 8**

# **Intersection forms**

## **Chapter 9**

# **Kirby calculus**



## **Part IV**

# **Geometry of 4-manifolds**

## Chapter 10

## Chapter 11

# Seiberg-Witten theory

**11.1.** Let  $V$  be a real inner product space. In  $\text{Spin}(4) \subset \text{Cl}^{\text{ev}}(4) \cong \text{Cl}(3) \cong \mathbb{H} \oplus \mathbb{H}$ , the spin group  $\text{Spin}(4)$  is isomorphic to  $S^3 \times S^3$ .

If  $V$  is even-dimensional, then  $\text{Cl}(V)$  has a unique finite-dimensional irreducible complex graded representation  $\text{Cl}(V) \rightarrow \text{End}_{\mathbb{C}}(S(V))$  such that the complexification induces an isomorphism  $\text{Cl}(V) \otimes_{\mathbb{R}} \mathbb{C} \cong \text{End}(S(V)) = S(V) \otimes S(V)^*$ .

If  $V$  is odd-dimensional, then  $\text{Cl}(V)$  has two non-isomorphic finite-dimensional irreducible complex representations  $\text{Cl}(V) \rightarrow \text{End}_{\mathbb{C}}(S_+(V \oplus \mathbb{R}))$  and  $\text{Cl}(V) \rightarrow \text{End}_{\mathbb{C}}(S_-(V \oplus \mathbb{R}))$  obtained from the direct sum decomposition of  $\text{Cl}(V) = \text{Cl}^0(V \oplus \mathbb{R}) \subset \text{Cl}^0(V \oplus \mathbb{R}) \otimes_{\mathbb{R}} \mathbb{C} \cong \text{End}_{\mathbb{C}}(S(V \oplus \mathbb{R}))$ .

## Chapter 12