

# Differential Equations

Ikhan Choi

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## **Part I**

# **Linear ordinary differential equations**

# **Chapter 1**

## **Constant coefficient equations**

**1.1 Characteristic equations**

**1.2 Complex roots**

**1.3 Repeated roots**

## Chapter 2

# Variable coefficient equations

2.1 Series solution

2.2 Fuch's theorem

2.3 Orthogonal polynomials

2.4 Sturm-Liouville theory

2.5 The Frobenius method

Fuch's theorem

## Chapter 3

# Inhomogeneous equations

### 3.1 Method of undetermined coefficients

### 3.2 Variation of parameters

### 3.3 Damped oscillation

### 3.4 The Laplace transform

discontinuous data gluing

## **Part II**

# **Nonlinear ordinary differential equations**



## Chapter 4

# Nonlinear ordinary differential equations

### 4.1 The Picard-Lindelöf theorem

### 4.2 Integrating factors

## Chapter 5

# Dynamical systems

### 5.1 Equilibria

Bifurcations  
Stability theory  
Hamiltonian systems

### 5.2 Planar dynamical systems

Examples from ecology, electrical engineerings  
Poincaré-Bendixon

## Chapter 6

# Chaos

Attractors

## **Part III**

# **Linear partial differential equations**

# Chapter 7

## Laplace's equation

### 7.1 Harmonic functions

7.1 (Mean value property).

7.2 (Maximum principle).

7.3 (Newtonian potential).

7.4 (Dirichlet problem for half space).

7.5 (Dirichlet problem for open ball).

### 7.2 Poisson equation

7.6 (Weak derivative).

7.7 (Dirac delta function). Let  $\Omega$  be an open subset of  $\mathbb{R}^d$ . The *Dirac delta function* is a linear functional  $\delta : C_c^\infty(\Omega) \rightarrow \mathbb{R}$  defined by  $\delta(\varphi) := \varphi(0)$ . We conventionally use the function-like notation  $\delta(x)$  to denote  $\varphi(0)$  by

$$\int \delta(x) \varphi(x) dx.$$

7.8 (Fundamental solution of the Laplace equation). Let  $d \geq 2$ . The *Fundamental solution of the Laplace equation* is a function  $\Phi : \mathbb{R}^d \setminus \{0\} \rightarrow \mathbb{R}$  that solves the boundary value problem

$$\begin{cases} -\Delta \Phi(x) = \delta(x) & \text{in } \mathbb{R}^d, \\ \Phi(x) \rightarrow 0 & \text{as } |x| \rightarrow \infty. \end{cases}$$

(a) The fundamental solution is given by

$$\Phi(x) := \begin{cases} -\frac{1}{2\pi} \log |x| & \text{if } d = 2 \\ \frac{1}{(d-2)\omega_d} \frac{1}{|x|^{d-2}} & \text{if } d \geq 3 \end{cases}.$$

In particular,  $\Phi$  and  $\nabla \Phi$  are locally integrable on  $\mathbb{R}^d$  but  $\nabla^2 \Phi$  is not.

(b) For  $u \in C_0^2(\mathbb{R}^d)$ ,

$$u(x) = - \int \Phi(x-y) \Delta u(y) dy.$$

*Proof.* Note that  $\nabla\Phi(y) \cdot \nabla u(x-y)$  is integrable in  $y$ . Then,

$$\begin{aligned} -\int \Phi(y)\Delta u(x-y)dy &= -\int \nabla\Phi(y) \cdot \nabla u(x-y)dy \\ &= -\lim_{\varepsilon \rightarrow \infty} \int_{|y| \geq \varepsilon} \nabla\Phi(y) \cdot \nabla u(x-y)dy \\ &= -\lim_{\varepsilon \rightarrow \infty} \int_{|y|=\varepsilon} \nabla\Phi(y)u(x-y) \cdot \nu dS. \end{aligned}$$

Since

$$\nabla\Phi(x) = -\frac{1}{\omega_d} \frac{x}{|x|^d}, \quad \nu = \frac{x}{|x|},$$

we get

$$-\int \Phi(y)\Delta u(x-y)dy = \lim_{\varepsilon \rightarrow \infty} \frac{1}{\omega_d \varepsilon^{d-1}} \int_{|y|=\varepsilon} u(x-y) dS_y = u(x).$$

□

**7.9** (Green's function of the Poisson equation). Let  $\Omega$  be a bounded open subset of  $\mathbb{R}^d$  for  $d \geq 2$ . *Green's function of the Poisson equation* is a function  $G : \Omega^2 \setminus \{(x, x) \in \Omega\} \rightarrow \mathbb{R}$  that solves the boundary value problem

$$\begin{cases} -\Delta_y G(x, y) = \delta(x-y) & \text{in } y \in \Omega \setminus \{x\}, \\ G(x, y) = 0 & \text{on } y \in \partial\Omega. \end{cases}$$

for each  $x \in \Omega$ .

Define  $\phi : \Omega^2 \rightarrow \mathbb{R}$  to be a function that solves the boundary value problem

$$\begin{cases} -\Delta_y \phi(x, y) = 0 & \text{in } y \in \Omega, \\ \phi(x, y) = \Phi(x-y) & \text{on } y \in \partial\Omega. \end{cases}$$

for each  $x \in \Omega$ . Assume for the domain  $\Omega$  that there exists a unique  $\phi$ .

(a) Green's function is given by

$$G(x, y) = \Phi(x-y) - \phi(x, y),$$

where  $\Phi$  is the fundamental solution of the Laplace equation. Physically,  $y \mapsto -\phi(x, y)$  has a meaning of the electric potential generated by the induced surface charge of a grounded conductor provided a point charge is at  $x$ .

(b) The *Green representation formula* holds: for  $u \in C^2(\Omega) \cap C(\overline{\Omega})$ ,

$$u(x) = -\int_{\Omega} G(x, y)\Delta u(y)dy - \int_{\partial\Omega} u(y)\nabla_y G(x, y) \cdot \nu dS_y.$$

**7.10** (Existence and uniqueness of Poisson equation). representation formulas describe the solution assuming

## 7.3 Helmholtz equation

## Chapter 8

# Heat equation

8.1 Heat kernel

8.2 Duhamel's principle

8.3 Separation of variables

## Chapter 9

# Wave equation

### 9.1 First order partial differential equations

### 9.2 Initial value problems

d'Alembert

Kirchhoff

odd reflection

### 9.3 Boundary value problems



## **Part IV**

# **Nonlinear partial differential equations**

## Chapter 10

# Fluid dynamics

10.1 Burger's equation

10.2 Euler's equation

10.3 Navier-Stokes equation

## Chapter 11

# Integrable field equations

### 11.1 Korteweg-de Vries equation

### 11.2 Boussinesq equation

### 11.3 Kadomtsev-Petviashvili equation

sine-Gordon equation nonlinear Schrödinger equation

## **Chapter 12**

# **Nonlinear waves and diffusion**

### **12.1 Nonlinear wave equation**

### **12.2 Nonlinear diffusion equation**