Representation Theory

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Contents

Ι	Finite group representations	3
1	Character theory 1.1 Irreducible representations	4 4 4 5
2	Classification of representations 2.1 Symmetric groups	6 6 6
3	Brauer theory	7
II	Lie algebras	8
4 5	Semisimple Lie algebras 4.1 Linear Lie algebras	9 10 12
6	Representations of Lie algebras6.1 Representations of $\mathfrak{sl}(2,\mathbb{C})$ 6.2 Highest weight theorem6.3 Multiplicity formulas	13 13 13 13
II	Lie groups	14
7	Lie correspondence7.1 Exponential map7.2 Lie's second theorem7.3 Lie's third theorem7.4 Fundamental groups of Lie groups	15 15 15 15 16
8	Compact Lie groups 8.1 Special orthogonal groups	17 17 17 17

9	Representations of Lie groups				
	9.1	Peter-Weyl theorem	18		
	9.2	Spin representations	18		
IV Hopf algebras					
10			20		
11	11 Quantum groups				

Part I Finite group representations

Character theory

1.1 Irreducible representations

- 1.1 (Definition of group representations).
- 1.2 (Intertwining maps).
- 1.3 (Subrepresentations). We say invariant or stable
- 1.4 (Irreducible representations). indecomposable and irreducible
- **1.5** (Maschke's theorem). Let G be a finite group and k be a field. Suppose the characteristic of k does not divide |G|. Let V be a finite-dimensional representation of G over k.
 - (a) Every invariant subspace W of V has a complement W' in V that is also invariant.
 - (b) *V* is isomorphic to the direct sum of irreducible representations of *G* over *k*.
 - (c) If $k = \mathbb{R}$ or \mathbb{C} , then V admits an inner product such that $W \perp W'$ and $\rho_V(g)$ is unitary for all $g \in G$.
- **1.6** (Schur's lemma). Let G be a group and k be a field. Let V and W be irreducible representations of G over k. Let $\psi: V \to W$ be an intertwining map.
 - (a) If $V \not\cong W$, then $\psi = 0$.
 - (b) If $V \cong W$, then ψ is an isomorphism.
 - (c) If k is algebraically closed and $\dim V < \infty$, then every intertwining map $\psi : V \to V$ is a homothety.

1.2 Group algebra

- **1.7** (Modules and representations). ring <-> group module <-> representation finitely generated <-> finite dimensional
- 1.8 (Wedderburn's theorem). central idempotents dimension computation
- **1.9** (Group algebra). regular representation k[G]-module and G-representation correspondence
 - (a) $\mathbb{C}[G]$ is the direct sum of all irreducible representations.
 - (b) $|G| = \sum_{[V] \in \hat{G}} (\dim V)^2$.
- **1.10.** The number of irreducible representations and the number of conjugacy classes double counting on $Z(\mathbb{C}[G])$.

1.3 Characters

- 1.11 (Space of class functions). Ring and inner product structure on the space of class functions.
 - (a) $\dim \hom_G(V, W) = \langle \chi_V, \chi_W \rangle$.
 - (b) Irreducible characters form an orthonormal basis of the space of class functions.
- **1.12** (Characters classify representations). Let G be a finite group and let Rep(G) be the category of finite-dimensional representations of G over \mathbb{C} .

$$Tr : \mathbf{Rep}(G) \rightarrow \{\text{finite sum of irreducible characters}\}\$$

surjectivity: trivial injectivity: Suppose two characters are equal. Maschke -> all characters are sum of irreducible characters Schur -> orthogonality, so the coefficients are all equal irreducible-factor-wisely construct an isomorphism.

1.13 (Character table). computation of matrix elements by character table abelian group, 1dim rep lifting

the dual inner product: conjugacy check relation to normal subgroups center of rep algebraic integer dim of irrep divides group order burnside pq theorem

Classification of representations

2.1 Symmetric groups

young tableux

2.2 Linear groups over finite fields

GL2 and SL2 over finite fields

2.3 Induced representations

induction and restriction of reps (from and to subgroup) frobenius reciprocity, mackey theory tensoring, complex, real symmetric, exterior

Brauer theory

Part II Lie algebras

Semisimple Lie algebras

4.1 Linear Lie algebras

group acts on an algebra A(e.g. End(V)). then its group algebra acts on A. Lie algebra acts on A, and this Lie algebra information is enough to recover the group action. Geometric meaning of Lie algebra action?

Lie algebra can only considered as a quantization of Poisson bracket. How can the Poisson bracket embodies the group action?

Following Humphrey's book, let L be always finite dimensional Lie algebra unless stated.

4.1. Every associative algebra is a Lie algebra, where the Lie bracket is given by the commutator. For a Lie algebra, we are

Intuitions of subalgebras, ideals, derivations. Intuitions of solvable, nilpotent, and semisimple Lie algebras. Constructing representations, trace forms,

The general linear Lie algebra $\mathfrak{gl}(V)$ is just $\operatorname{End}(V)$ with a Lie bracket [x,y] := xy - yx.

4.2 (Derivations). Let L be a Lie algebra. A *derivation* of L is a linear map $\delta: L \to L$ such that

$$\delta(\lceil x, y \rceil) = \lceil \delta(x), y \rceil + \lceil x, \delta(y) \rceil$$

for all $x, y \in L$. The set of derivations Der(L) of L is a subalgebra of $\mathfrak{gl}(L)$, and we have the *adjoint* representation $L \to Der(L) \le \mathfrak{gl}(L)$ of L. If I is an ideal, then we have a faithful representation ad : $L \to \operatorname{ad} L \le \operatorname{Der}(I) \le \mathfrak{gl}(I)$.

4.3 (Inner derivations and automorphisms). Let L be a Lie algebra.

The linear map ad $x = [x, -]: L \to L$ for $x \in L$ is derivation, and derivation of this form is called *inner*, and they form an ideal of Der(L).

Automorphisms of the form $\exp(\operatorname{ad} x)$ with nilpotent $\operatorname{ad} x$ generates a normal subgroup of $\operatorname{Aut}(L)$, and each generator is called *inner automorphisms*.

4.4 (Solvable Lie algebras). Let L be a Lie algebra. If the *derived series* $L^{(0)} = L$, $L^{(n)} = [L^{(n-1)}, L^{(n-1)}]$ eventually vanishes, then we call L solvable.

If L is solvable, then its subalgebras and quotient algebras are all solvable. If I is a solvable ideal of L such that L/I is solvable, then L is solvable. The sum of two solvable ideals is also solvable.

4.5 (Nilpotent Lie algebras). Let L be a Lie algebra. If the *lower central series* $L^0 = L$, $L^n = [L, L^{n-1}]$ eventually vanishes, then we call L *nilpotent*. It is a stronger notion than solvability.

If *L* is nilpotent, then its subalgebras and quotient algebras are all nilpotent. If $L/Z(L) \cong \operatorname{ad}(L) \subset \mathfrak{gl}(L)$ is nilpotent, then *L* is nilpotent. If *L* is non-zero and nipotent, then Z(L) is non-trivial.

- **4.6** (Engel's theorem). .
 - (a) A linear Lie algebra $L \subset \mathfrak{gl}(V)$ consists of nilpotent endomorphisms if and only if $L \subset \mathfrak{n}(V)$ for a certain basis of V.
 - (b) An abstract Lie algebra L is nilpotent if and only if ad(L) consists of nilpotent endomorphisms.
 - (c) If $L \subset \mathfrak{gl}(V)$ is nilpotent in End(V), then there is a *common eigenvector* $v \in V$ such that [L, v] = 0, i.e. there is a flag V_i such that $xV_i \subset V_{i-1}$...?

Proof. Let L be an ad-nilpotent Lie algebra. Then, every element of ad $L \subset \mathfrak{gl}(L)$ is a nilpotent endomorphism, so there is $x \in L$ such that [L, x] = 0, which implies $Z(L) \neq 0$. Since L/Z(L) is also ad-nilpotent, and by induction on dimension, L/Z(L) is nilpotent. Therefore, L is nilpotent.

- **4.7** (Lie's theorem). Let \mathbb{F} have characteristic zero and be algebraically closed.
 - (a) A linear Lie algebra $L \subset \mathfrak{gl}(V)$ is solvable if and only if $L \subset \mathfrak{t}(V)$ for a certain basis of V.
 - (b) If *L* is solvable, then there is a flag V_i such that $xV_i \subset V_i$.
 - (c) Let L be an abstract Lie algebra. L is solvable if and only if [L, L] is nilpotent.
 - (d) Every finite-dimensional irreduciable representation of a solvable Lie algebra is one-dimensional.

Proof. Use induction on dimension. Since L/[L,L] is a non-trivial commutative Lie algebra, in which every subspace is an ideal, we can show the existence of an ideal K of L with codimension one by pullback.

By the induction assumption, we have a common eigenvector in V for K so that we have the "eigenvalue" linear functional $\kappa: K \to \mathbb{F}$ such that the "eigenspace" of κ as

$$V_{\kappa} := \{ \nu \in V : x\nu = \kappa(x)\nu \text{ for } x \in K \}$$

is non-trivial.

Let $L = I + \mathbb{F}z$ with $z \in \mathfrak{gl}(V)$. If V_{κ} is invariant by L, then V_{κ} contains an eigenvector of z by the fact that \mathbb{F} is algebraically closed, so we can extend κ to obtain $\lambda : L \to \mathbb{F}$ such that $(V_{\kappa})_{\lambda}$ is non-trivial.

We now show that V_{κ} is invariant by L. Let $\nu \in V_{\kappa}$ and $x \in L$. Since

$$yxv - \lambda(y)xv = \lambda([x, y])v$$

for $y \in K$, we have to show $\lambda([x, y]) = 0$.

4.8.

There is a linear functional $\lambda: L \to \mathbb{F}$ such that $\lambda|_{[L,L]} = 0$ and V_{λ} is non-trivial. V_{κ}

For a representation V of \mathfrak{g} , then a weight of V is a linear functional $\lambda : \mathfrak{h} \to \mathbb{F}$ such that the weight space V_{λ} is non-trivial.

4.2 Semisimple Lie algebras

- **4.9.** Therefore, L admits a unique maximal solvable ideal, called radical. If the radical is trivial, then we say L is semisimple. Since the center is a solvable ideal, the center of a semisimple Lie algebra is trivial.
 - (a) A canonical example of a solvable Lie algebra is the Lie algbera of upper triangular matrices.
 - (b) The radical of $\mathfrak{gl}(n,\mathbb{F})$ is $\mathfrak{sl}(n,\mathbb{F})$.(\mathbb{F} cahracteristic zero?) Upper triangular matrices do not form an ideal of $\mathfrak{gl}(n,\mathbb{F})$.

- (c) [t, t] = n, $t = 0 \otimes n$. t is a solvable subalgebra of \mathfrak{gl} , but not a solvable ideal.
- (d) $\mathfrak{sl}(n, \mathbb{F})$ is simple if char $\mathbb{F} = 0$.
- **4.10** (Jordan-Chevalley decomposition). Let char \mathbb{F} be arbitrary. We say $x \in \operatorname{End}(V)$ is called *semisim-ple* if the roots of its minimal polynomial are all distinct. If \mathbb{F} is algebraically closed, $x \in \operatorname{End}(V)$ is semisimple if and only if it is diagonalizable. Let $x \in \operatorname{End} V$. Even if \mathbb{F} is not algebraically closed, we have a generalization of Jordan decomposition as follows:
 - (a) There exist unique $x_s, x_n \in \text{End } V$ such that $x = x_s + x_n$ and x_s semisimple, x_n nilpotent.
 - (b) x_s and x_n are polynomials in x.
 - (c) If x maps B to A, then x_s and x_n also map B to A for subspaces $A \le B \le V$.
- 4.11 (Cartan's criterion). We will show a powerful criterion for solvability.
 - (a) Let $A \subset B$ be two subspaces of $\mathfrak{gl}(V)$, V finite dimensional. Let

$$M := \{ x \in \mathfrak{gl}(V) : [x, B] \subset A \}.$$

If $x \in M$ satisfies Tr(xy) = 0 for all $y \in M$, then x is nilpotent.

- (b) Let $L \subset \mathfrak{gl}(V)$, V finite dimensional. If Tr(xy) = 0 for all $x \in [L, L]$ and $y \in L$, then L is solvable.
- **4.12** (Killing forms). Let L be a Lie algebra.

$$\kappa(x, y) := \operatorname{Tr}(\operatorname{ad} x \operatorname{ad} y)$$

is a symmetric bilinear form on L, which is called the *Killing form* on L, i.e. it is the trace form for the adjoint representation.

- (a) On an ideal $I \subset L$, the Killing form is given by restriction.
- (b) The kernel of κ is contained in the radical of L, and triviality is equivalent; L is semisimple if and only if L is non-degenerate. (Here we use Cartan's criterion)
- (c) If L is semisimple, then it is the direct sum of simple ideals.
- (d) If *L* is semisimple, then every derivation is inner.
- (e) If L is semisimple, then L = [L, L] and every subalgebras and quotients are semisimple.

Levi decomposition

- **4.13** (Casimir element). For a faithful representation $\varphi: L \to \mathfrak{gl}(V)$, we can associate non-degenerate trace form. Then, the *Casimir element* of the representation φ is $C_{\varphi} := \sum_{i} \varphi(x_{i}) \varphi(y_{i}) \in \operatorname{End}(V)$ where i runs over dual bases relative to the trace form.
- **4.14** (Weyl's theorem). Finite dimensional representation of a semisimple Lie algebra is completely reducible. Preservation of Jordan decomposition.
- 4.15 (Toral subalgebras). Cartan subalgebra uniqueness? (conjugacy theorem)

Root systems

root space decomposition integrality Weyl group Coxeter graph Dynkin diagram Real forms Isomorphism theorem Existence theorem Universal enveloping algebra PBW theorem Verma module

Representations of Lie algebras

6.1 Representations of $\mathfrak{sl}(2,\mathbb{C})$

6.1 (Pauli matrices). Pauli matrices are

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

- (a) $\{\sigma_1, \sigma_2, \sigma_3\}$ is a basis of complex Lie algebra $\mathfrak{sl}(2, \mathbb{C})$, and $\{i\sigma_1, i\sigma_2, i\sigma_3\}$ is a basis of real Lie algebra $\mathfrak{so}(3)$.
- (b) For a unit vector $n = (n_1, n_2, n_3) \in \mathbb{R}^3$, $n_1\sigma_1 + n_2\sigma_2 + n_3\sigma_3$ has eigenvalues ± 1 .

6.2 Highest weight theorem

6.3 Multiplicity formulas

Exercises

6.2 (Triplets and quadraplets). Let (π_2, V_2) be the irreducible representation of $\mathfrak{sl}(2, \mathbb{C})$ of degree two. Consider $V_2 \otimes V_2$. Cartan element S_z . $V_2^{\otimes 3}$.

6.3 (Casimir element). Casimir element decomposes a representation into irreducible representations.

Part III

Lie groups

Lie correspondence

7.1 Exponential map

- 7.1 (Exponential map).
- 7.2 (Surjectivity of exponential map).
- **7.3** (Lie functor).

7.2 Lie's second theorem

7.4 (Derivative of the exponential map). Let G be a Lie group.

(a)

$$\frac{d}{ds}\exp(sX) = \exp(sX)X$$

for $s \in \mathbb{R}$ and $X \in \mathfrak{g}$.

(b)

$$\frac{\partial}{\partial s}$$

7.5 (Baker-Campbell-Hausdorff formula). Let G be a Lie group. Let $X,Y \in \mathfrak{g}$ such that $\exp(X)\exp(Y)$ Define

$$Z(t) := \log(\exp(X)\exp(tY))$$

7.6. (a) The Lie functor

$$\text{Lie}: \text{LieGrp}_{simple} \rightarrow \text{LieAlg}_{\mathbb{R}}$$

is fully faithful.

7.3 Lie's third theorem

7.7 (Ado's theorem).

7.8 (Lie's third theorem). Also called the Cartan-Lie theorem.

(a) The Lie functor

$$\operatorname{Lie}: \operatorname{LieGrp}_{simple} \to \operatorname{LieAlg}_{\mathbb{R}}$$

is essentially surjective.

7.4 Fundamental groups of Lie groups

Compact Lie groups

- 8.1 Special orthogonal groups
- 8.2 Special unitary groups
- 8.3 Symplectic groups

Exercises

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8.1 (Lorentz group). SL(2,\mathbb{C}) \rightarrow SO^+(1,3)
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(a) O(1,3) has four components and $SO^+(1,3)$ is the identity component. Orthochronous $O^+(1,3)$, proper SO(1,3).

Representations of Lie groups

- 9.1 Peter-Weyl theorem
- 9.2 Spin representations

Clifford algebra

Part IV Hopf algebras

Quantum groups