

Differential Equations

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Part I

Linear ordinary differential equations

Chapter 1

Initial value problems

1.1 Constant coefficient equations

existence uniqueness system of equations characteristic equations complex roots repeated roots

1.2 Variable coefficient equations

existence uniqueness series solution Frobenius method Fuch's theorem

Chapter 2

Boundary value problems

2.1 Second order linear equations

Helmholtz Bessel Legendre Hermite Laguerre

2.2 Orthogonal polynomials

L^2 space

2.3 Sturm-Liouville theory

Eigenvalue problems boundary conditions

Exercises

2.1 (Rayleigh-Ritz principle).

Chapter 3

Inhomogeneous problems

3.1 Method of undetermined coefficients

3.2 Variation of parameters

3.3 Laplace transform

discontinuous data gluing

Exercises

3.1 (Damped oscillation).

Part II

Nonlinear ordinary differential equations

Chapter 4

First order nonlinear equations

4.1 Local existence theorems

4.1 (Picard-Lindelöf theorem). Consider the following initial value problem:

$$x'(t) = f(t, x(t)), \quad x(0) = x_0.$$

Construct an approximate solution $(x_n)_{n=0}^\infty$ defined inductively such that $x_0(t) \equiv x_0$ and

$$x'_{n+1}(t) = f(t, x_n(t)), \quad x_{n+1}(0) = x_0.$$

Suppose f satisfies

$$|f(t, x)| \leq \frac{R}{T}, \quad |f(t, x) - f(t, y)| \lesssim |x - y|$$

on the cylinder $[0, T] \times \overline{B(x_0, R)}$.

- (a) x_n is in $C^1([0, T], \overline{B(x_0, R)})$.
- (b) x_n is Cauchy in $C^1([0, T], \overline{B(x_0, R)})$.
- (c) The equation has a unique solution in $C^1([0, T], \overline{B(x_0, R)})$.

Proof. (a) It clearly follows from the explicit formula

$$x_{n+1}(t) = x_0 + \int_0^t f(s, x_n(s)) ds.$$

(b) Since

$$|x_1(t) - x_0(t)| \leq \int_0^t |f(s, x_0)| ds \leq Mt$$

and

$$\begin{aligned} |x_{n+1}(t) - x_n(t)| &\leq \int_0^t |f(s, x_n(s)) - f(s, x_{n-1}(s))| ds \\ &\leq K \int_0^t |x_n(s) - x_{n-1}(s)| ds \\ &\leq MK^n \int_0^t \frac{s^n}{n!} ds \\ &= MK^n \frac{t^{n+1}}{(n+1)!}, \end{aligned}$$

we have the convergent series

$$\sum_{n=0}^{\infty} \|x_{n+1} - x_n\|_{\infty} \leq TM \frac{e^{KT} - 1}{KT}.$$

Also,

$$|x'_{n+1}(t) - x'_n(t)| \leq |f(t, x_n(t)) - f(t, x_{n-1}(t))| \leq K|x_n(t) - x_{n-1}(t)| \leq MK^{n+1} \frac{t^{n+1}}{(n+1)!}.$$

(c) Limiting check.

□

4.2 (Cauchy-Peano theorem).

4.3 (Carathéodory existence theorem).

4.2 Implicit equations

integrating factor, separable equations, exact equations

4.3 Global existence

4.4 (Gronwall's inequality).

4.5 (A priori estimate).

Chapter 5

Dynamical systems

5.1 Equilibrium and stability

Bifurcations

Stability theory Lyapunov, invariant set

5.2 Autonomous systems

5.3 Hamiltonian systems

5.4 Planar systems

periodic orbit

5.1 (Poincaré-Bendixon).

Exercises

5.2 (Undamped pendulum).

$$x''(t) + \sin x(t) = 0$$

5.3 (Approximated pendulum).

$$x''(t) + x(t) - \frac{1}{6}x(t)^3 = \alpha$$

5.4 (Van der Pol oscillator).

$$x''(t) - \mu(1 - x(t)^2)x'(t) + x(t) = 0$$

5.5 (Lotka-Volterra model). Also known as predator-prey equations.

Chapter 6

Chaos

Attractors

Part III

Linear partial differential equations

Chapter 7

Laplace's equation

7.1 Harmonic functions

7.1 (Mean value property).

7.2 (Maximum principle).

7.3 (Newtonian potential).

7.4 (Dirichlet problem for half space).

7.5 (Dirichlet problem for open ball).

7.2 Poisson equation

7.6 (Weak derivative).

7.7 (Dirac delta function). Let Ω be an open subset of \mathbb{R}^d . The *Dirac delta function* is a linear functional $\delta : C_c^\infty(\Omega) \rightarrow \mathbb{R}$ defined by $\delta(\varphi) := \varphi(0)$. We conventionally use the function-like notation $\delta(x)$ to denote $\varphi(0)$ by

$$\int \delta(x) \varphi(x) dx.$$

7.8 (Fundamental solution of the Laplace equation). Let $d \geq 2$. The *Fundamental solution of the Laplace equation* is a function $\Phi : \mathbb{R}^d \setminus \{0\} \rightarrow \mathbb{R}$ that solves the boundary value problem

$$\begin{cases} -\Delta \Phi(x) = \delta(x) & \text{in } \mathbb{R}^d, \\ \Phi(x) \rightarrow 0 & \text{as } |x| \rightarrow \infty. \end{cases}$$

(a) The fundamental solution is given by

$$\Phi(x) := \begin{cases} -\frac{1}{2\pi} \log |x| & \text{if } d = 2 \\ \frac{1}{(d-2)\omega_d} \frac{1}{|x|^{d-2}} & \text{if } d \geq 3 \end{cases}.$$

In particular, Φ and $\nabla \Phi$ are locally integrable on \mathbb{R}^d but $\nabla^2 \Phi$ is not.

(b) For $u \in C_0^2(\mathbb{R}^d)$,

$$u(x) = - \int \Phi(x-y) \Delta u(y) dy.$$

Proof. Note that $\nabla\Phi(y) \cdot \nabla u(x-y)$ is integrable in y . Then,

$$\begin{aligned} -\int \Phi(y)\Delta u(x-y)dy &= -\int \nabla\Phi(y) \cdot \nabla u(x-y)dy \\ &= -\lim_{\varepsilon \rightarrow \infty} \int_{|y| \geq \varepsilon} \nabla\Phi(y) \cdot \nabla u(x-y)dy \\ &= -\lim_{\varepsilon \rightarrow \infty} \int_{|y|=\varepsilon} \nabla\Phi(y)u(x-y) \cdot \nu dS. \end{aligned}$$

Since

$$\nabla\Phi(x) = -\frac{1}{\omega_d} \frac{x}{|x|^d}, \quad \nu = \frac{x}{|x|},$$

we get

$$-\int \Phi(y)\Delta u(x-y)dy = \lim_{\varepsilon \rightarrow \infty} \frac{1}{\omega_d \varepsilon^{d-1}} \int_{|y|=\varepsilon} u(x-y) dS_y = u(x).$$

□

7.9 (Green's function of the Poisson equation). Let Ω be a bounded open subset of \mathbb{R}^d for $d \geq 2$. *Green's function of the Poisson equation* is a function $G : \Omega^2 \setminus \{(x, x) \in \Omega\} \rightarrow \mathbb{R}$ that solves the boundary value problem

$$\begin{cases} -\Delta_y G(x, y) = \delta(x-y) & \text{in } y \in \Omega \setminus \{x\}, \\ G(x, y) = 0 & \text{on } y \in \partial\Omega. \end{cases}$$

for each $x \in \Omega$.

Define $\phi : \Omega^2 \rightarrow \mathbb{R}$ to be a function that solves the boundary value problem

$$\begin{cases} -\Delta_y \phi(x, y) = 0 & \text{in } y \in \Omega, \\ \phi(x, y) = \Phi(x-y) & \text{on } y \in \partial\Omega. \end{cases}$$

for each $x \in \Omega$. Assume for the domain Ω that there exists a unique ϕ .

(a) Green's function is given by

$$G(x, y) = \Phi(x-y) - \phi(x, y),$$

where Φ is the fundamental solution of the Laplace equation. Physically, $y \mapsto -\phi(x, y)$ has a meaning of the electric potential generated by the induced surface charge of a grounded conductor provided a point charge is at x .

(b) The *Green representation formula* holds: for $u \in C^2(\Omega) \cap C(\overline{\Omega})$,

$$u(x) = -\int_{\Omega} G(x, y)\Delta u(y)dy - \int_{\partial\Omega} u(y)\nabla_y G(x, y) \cdot \nu dS_y.$$

7.10 (Existence and uniqueness of Poisson equation). representation formulas describe the solution assuming

7.3 Eigenvalue problems

Chapter 8

Heat equation

8.1 Heat kernel

8.2 Duhamel's principle

8.3 Separation of variables

Chapter 9

Wave equation

9.1 First order partial differential equations

9.2 Initial value problems

d'Alembert

Kirchhoff

odd reflection

9.3 Boundary value problems

Part IV

Nonlinear partial differential equations

Chapter 10

Fluid dynamics

10.1 Conservation laws

10.2 Navier-Stokes equation

10.3 Euler's equation

10.4 Burger's equation

Chapter 11

Integrable field equations

11.1 Korteweg-de Vries equation

11.2 Boussinesq equation

11.3 Kadomtsev-Petviashvili equation

sine-Gordon equation nonlinear Schrödinger equation

Chapter 12

Nonlinear waves and diffusion

12.1 Nonlinear wave equation

12.2 Nonlinear diffusion equation