

# Partial Differential Equations

Ikhan Choi

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## **Part I**

# **Sobolev spaces**

# Chapter 1

## Distribution theory

### 1.1 Space of test functions

- 1.1. (a) If a test function  $\varphi$  satisfies  $\langle 1, \varphi \rangle = 0$ , then there is  $v \in \mathbb{R}^d$  and a test function  $\psi$  such that  $\varphi = v \cdot \nabla \psi$ .
- (b) If a distribution has zero derivative, then it is a constant.

1.2 (Weak\* convergence).

### 1.2 Space of distributions

1.3 (Rigged Hilbert space).

### 1.3 Well-posedness

1.4 (Extension of linear operators). Let  $T : \mathcal{D} \rightarrow \mathcal{D}'$  be a continuous linear operator. We can always define the adjoint  $T^* : \mathcal{D} \subset \mathcal{D}'' \rightarrow \mathcal{D}'$ . The most reasonable extension of  $T$  is  $T : (T^*(\mathcal{D}))' \rightarrow \mathcal{D}'$ . For  $f \in (T^*(\mathcal{D}))'$ , we can define  $\langle T(f), \varphi \rangle := \langle f, T^*\varphi \rangle$  for  $\varphi \in \mathcal{D}$ .

Suppose  $T : (\mathcal{D}, \mathcal{T}) \rightarrow (T(\mathcal{D}), \mathcal{S})$  is proved to be continuous. If  $(\mathcal{D}, \mathcal{T}) \rightarrow (T^*(\mathcal{D}))'$  and  $(T(\mathcal{D}), \mathcal{S}) \rightarrow \mathcal{D}'$  are embeddings, then the extension of  $T$  to the completion of  $(\mathcal{D}, \mathcal{T})$  agrees with  $T : (T^*(\mathcal{D}))' \rightarrow \mathcal{D}'$ .

For example, if  $\Phi$  is locally integrable, then since  $(T_\Phi)^* = T_{\tilde{\Phi}}$  and  $\Phi * \varphi \in \mathcal{E} = C^\infty$  for  $\varphi \in \mathcal{D}$ , the convolution operator  $T_\Phi : \mathcal{E}' \rightarrow \mathcal{D}'$  can be defined on the space of compactly supported distributions.

If  $g * f$  is well-defined, is  $f * g$  also well-defined? In other words, if  $f \in (T_{\tilde{g}}(\mathcal{D}))'$  so that  $g * f \in \mathcal{D}'$ , then  $g \in (T_{\tilde{f}}(\mathcal{D}))'$ ? Are they same?

$$\langle g, \tilde{f} * \varphi \rangle =$$

### Exercises

- 1.5. \* Describe the range of the operator  $T : \mathcal{E}'(\mathbb{R}^d) \rightarrow \mathcal{D}'(\mathbb{R}^d)$  defined by  $Tf = \Phi * f$  for  $d \geq 3$ , where  $\Phi$  is the fundamental solution of Laplace's equation.

## Chapter 2

# Sobolev inequalities

### 2.1 Approximations

2.1 (Completeness of Sobolev norms).

2.2 (Difference quotient).

2.3 (Interior approximation).

2.4 (Myers-Serrin theorem).

### 2.2 Extensions and restrictions

2.5 (Lipschitz boundary).

2.6 (Extension theorem).

2.7 (Trace theorem).

2.8 (Vanishing at boundary). zero trace, whole domain

### 2.3 Sobolev embeddings

2.9 (Gagliardo-Nirenberg-Sobolev inequality).

2.10 (Hölder spaces).

2.11 (Morrey inequality).

2.12 (Poincaré inequality). BMO

2.13 (Rellich-Kondrachov theorem). Let  $\Omega$  be bounded open subset of  $\mathbb{R}^d$  with Lipschitz boundary. Let  $1 \leq p < d$  and  $1 \leq q < p^*$  where  $p^* := \frac{dp}{d-p}$  denotes the Sobolev conjugate. Let  $(u_n)_n$  be a bounded sequence in  $W^{1,p}(\Omega)$ . We may assume it is also bounded in  $W^{1,1}(\mathbb{R}^d)$  by the embedding  $W^{1,p}(\Omega) \subset W^{1,1}(\Omega)$  and the extension theorem. Let  $\eta_\varepsilon$  be a standard mollifier.

- (a) There is a subsequence of  $(\eta_\varepsilon * u_n)_n$  that is Cauchy in  $L^q(\Omega)$  for each  $\varepsilon > 0$ .
- (b)  $\sup_n \|\eta_\varepsilon * u_n - u_n\|_{L^1(\Omega)} \rightarrow 0$  as  $\varepsilon \rightarrow 0$ .
- (c)  $\sup_n \|\eta_\varepsilon * u_n - u_n\|_{L^q(\Omega)} \rightarrow 0$  as  $\varepsilon \rightarrow 0$ .

(d) There is a subsequence of  $(u_n)_n$  that is Cauchy in  $L^q(\Omega)$ .

(e)  $W^{k,p}(\Omega) \rightarrow W^{l,q}(\Omega)$  is a compact embedding if

$$\frac{l}{d} - \frac{1}{q} < \frac{k}{d} - \frac{1}{p}.$$

*Proof.* (a) The sequence  $(\eta_\varepsilon * u_n)_n$  is pointwise bounded from

$$\|\eta_\varepsilon * u_n\|_{C_0(\mathbb{R}^d)} \leq \|\eta_\varepsilon\|_{C_0(\mathbb{R}^d)} \|u_n\|_{L^1(\mathbb{R}^d)} \lesssim_\varepsilon 1,$$

and equicontinuous from

$$\|\nabla \eta_\varepsilon * u_n\|_{C_0(\mathbb{R}^d)} \leq \|\nabla \eta_\varepsilon\|_{C_0(\mathbb{R}^d)} \|u_n\|_{L^1(\mathbb{R}^d)} \lesssim_\varepsilon 1.$$

By the Arzela-Ascoli theorem, since  $\overline{\Omega}$  is compact, there is a subsequence  $(\eta_\varepsilon * u_{n_k})_k$  that is Cauchy in  $C(\overline{\Omega})$ , and hence in  $L^q(\Omega)$ .

(b) Write

$$\begin{aligned} \eta_\varepsilon * u_n(x) - u_n(x) &= \frac{1}{\varepsilon^d} \int \eta\left(\frac{x-y}{\varepsilon}\right) (u_n(y) - u_n(x)) dy \\ &= \int \eta(y) (u_n(x - \varepsilon y) - u_n(x)) dy \\ &= \int \eta(y) \int_0^1 \frac{d}{dt} (u_n(x - t\varepsilon y)) dt dy \\ &= \int \eta(y) \int_0^1 (-\varepsilon y) \cdot \nabla u_n(x - t\varepsilon y) dt dy. \end{aligned}$$

Then, since  $|y| \geq 1$  if  $\eta(y) > 0$ ,

$$\|\eta_\varepsilon * u_n - u_n\|_{L^1(\mathbb{R}^d)} \leq \varepsilon \int \eta(y) \int_0^1 \int |\nabla u_n(x - t\varepsilon y)| dx dt dy = \varepsilon \|\nabla u_n\|_{L^1(\mathbb{R}^d)}.$$

(c) The interpolation

$$\|\eta_\varepsilon * u_n - u_n\|_{L^q(\Omega)} \leq \|\eta_\varepsilon * u_n - u_n\|_{L^1(\Omega)}^\theta \|\eta_\varepsilon * u_n - u_n\|_{L^{p^*}(\Omega)}^{1-\theta}$$

for  $q = \frac{\theta}{1} + \frac{1-\theta}{p}$  with  $0 < \theta \leq 1$  and the Gagliardo-Nirenberg-Sobolev inequality

$$\|\eta_\varepsilon * u_n - u_n\|_{L^{p^*}(\Omega)} \lesssim \|\eta_\varepsilon * u_n - u_n\|_{W^{1,p}(\Omega)} \lesssim 1$$

give the  $L^q$  version of the part (b),

$$\sup_n \|\eta_\varepsilon * u_n - u_n\|_{L^q(\Omega)} \rightarrow 0$$

as  $\varepsilon \rightarrow 0$ .

(d) By the part (c), for any  $\delta > 0$ , there is  $\varepsilon > 0$  such that

$$\sup_n \|\eta_\varepsilon * u_n - u_n\|_{L^q(\Omega)} < \frac{\delta}{2},$$

so for a subsequence  $(\eta_\varepsilon * u_{n_k})_k$  that is Cauchy in  $L^q(\Omega)$ , we have

$$\|u_{n_k} - u_{n_{k'}}\|_{L^q(\Omega)} \leq \|\eta_\varepsilon * u_{n_k} - \eta_\varepsilon * u_{n_{k'}}\|_{L^q(\Omega)} + \delta,$$

and by the diagonal argument reducing  $\delta$  to zero, we can construct the desired subsequence.

(e)

□

## Chapter 3

# Generalizations of Sobolev spaces

### 3.1 Fractional Sobolev spaces

### 3.2 Fourier transform methods

### 3.3 Almost everywhere differentiability

Lipschitz, Rademacher

### 3.4 Vector-valued functions



## **Part II**

# **Elliptic equations**

## Chapter 4

# Harmonic functions

### 4.1 Mean value property

mean value property maximum principle Harnack inequality  
potential estimate Hölder estimate

### 4.2 Potential theory

### 4.3 Weyl's lemma

## Chapter 5

# Existence theory

### 5.1 Variational methods

### 5.2 Lax-Milgram theorem

5.1 (Poisson equation). Let  $\Omega$  be a bounded open subset of  $\mathbb{R}^d$ . Consider the problem

$$\begin{cases} -\Delta u(x) = f(x) & , \text{ in } x \in \Omega, \\ u(x) = 0 & , \text{ on } x \in \partial\Omega. \end{cases}$$

Define a bilinear form  $B$  on  $H_0^1(\Omega)$  such that

$$B(u, v) := \int \nabla u(x) \cdot \nabla v(x) dx.$$

- (a) If  $u \in H_0^1(\Omega)$  and  $f \in \mathcal{D}'(\Omega)$  satisfy  $B(u, \varphi) = \langle f, \varphi \rangle$  for all  $\varphi \in \mathcal{D}(\Omega)$ , then  $-\Delta u = f$ .
- (b)  $B$  is another inner product equivalent to  $\langle -, - \rangle_{H_0^1(\Omega)}$ .
- (c) For  $f \in H^{-1}(\Omega)$ , there is  $u \in H_0^1(\Omega)$  such that  $-\Delta u = f$ .

### 5.3 Fredholm alternative

### 5.4 Perron's method

### 5.5 Eigenvalue problems

## Chapter 6

# Elliptic regularity theory

### 6.1 $L^p$ theory

**6.1** (Interior regularity in  $H^2$ ). Let  $\Omega$  be bounded open subset of  $\mathbb{R}^d$  and  $L : \mathcal{D}'(\Omega) \rightarrow \mathcal{D}'(\Omega)$  a uniformly elliptic operator given by

$$Lu := -\partial_j(a^{ij}\partial_i u) + b^i\partial_i u + cu$$

for  $a^{ij} \in C^1(\Omega)$ ,  $b^i \in L^\infty(\Omega)$ , and  $c \in L^\infty(\Omega)$ .

Fix an open subset  $U \Subset \Omega$  and  $\zeta \in C_c^\infty(\Omega)$  a cutoff function such that  $\zeta = 1$  in  $U$ . Let  $\varphi := -\partial_k^{-h}(\zeta^2 \partial_k^h u)$  for  $k = 1, \dots, d$  and sufficiently small  $h > 0$ .

(a) We have

$$\|\nabla u\|_{L^2(U)} \lesssim \|Lu\|_{L^2(\Omega)} + \|u\|_{L^2(\Omega)}$$

for all  $u$  such that  $Lu, u \in L^2(\Omega)$

(b) We have

$$\int \zeta^2 |\partial_k^h \nabla u|^2 \lesssim \int a^{ij} \partial_i u \partial_j \varphi + \|\nabla u\|_{L^2(\Omega)}$$

for all  $u \in H^1(\Omega)$ .

(c) We have

$$\int \zeta^2 |\partial_k^h \nabla u|^2 \lesssim \|Lu\|_{L^2(\Omega)} + \|u\|_{H^1(\Omega)}$$

for all  $u$  such that  $Lu \in L^2(\Omega)$  and  $u \in H^1(\Omega)$ .

(d) We have

$$\|u\|_{H^2(U)} \lesssim \|Lu\|_{L^2(\Omega)} + \|u\|_{L^2(\Omega)}$$

for all  $u$  such that  $Lu, u \in L^2(\Omega)$ .

*Proof.* (a) Since  $\zeta^2 u \in H_0^1(\Omega)$ ,

$$\begin{aligned}
\int \zeta^2 |\nabla u|^2 &\lesssim \int a^{ij} \zeta^2 \partial_i u \partial_j u \\
&= \int a^{ij} \partial_i u \partial_j (\zeta^2 u) - \int a^{ij} \partial_i u \partial_j (\zeta^2) u \\
&= \int (Lu - b^i \partial_i u - cu) \zeta^2 u - \int a^{ij} \partial_i u 2\zeta \partial_j \zeta u \\
&\lesssim \int (|Lu| + |u| \zeta |\nabla u| + |u|^2 + |u| \zeta |\nabla u|) \\
&\lesssim \int (|Lu|^2 + |u|^2) + \frac{1}{\varepsilon} \int |u|^2 + \varepsilon \int \zeta^2 |\nabla u|^2.
\end{aligned}$$

Taking small  $\varepsilon > 0$ , we are done.

(b) Write

$$\begin{aligned}
\int a^{ij} \partial_i u \partial_j \varphi &= - \int a^{ij} \partial_i u \partial_j \partial_k^{-h} (\zeta^2 \partial_k^h u) \\
&= \int \partial_k^h (a^{ij} \partial_i u) \partial_j (\zeta^2 \partial_k^h u) \\
&= \int \partial_k^h a^{ij} \partial_i u \partial_j (\zeta^2) \partial_k^h u + \int \partial_k^h a^{ij} \partial_i u \zeta^2 \partial_j \partial_k^h u \\
&\quad + \int a^{ij} \partial_k^h \partial_i u \partial_j (\zeta^2) \partial_k^h u + \int a^{ij} \partial_k^h \partial_i u \zeta^2 \partial_j \partial_k^h u.
\end{aligned}$$

The last term out of the four terms controls the difference quotient  $|\partial_k^h \nabla u|$  as

$$\int a^{ij} \partial_k^h \partial_i u \zeta^2 \partial_j \partial_k^h u \gtrsim \int \zeta^2 |\partial_k^h \nabla u|^2,$$

and the absolute values of other three terms are estimated up to constant by

$$\begin{aligned}
&\int \zeta |\nabla u| |\partial_k^h u| + \int \zeta^2 |\nabla u| |\partial_k^h \nabla u| + \int \zeta |\partial_k^h \nabla u| |\partial_k^h u| \\
&\lesssim \left(1 + \frac{1}{\varepsilon}\right) \int \zeta^2 |\nabla u|^2 + \left(1 + \frac{1}{\varepsilon}\right) \int |\partial_k^h u|^2 + \varepsilon \int \zeta^2 |\partial_k^h \nabla u|^2 \\
&\lesssim \left(1 + \frac{1}{\varepsilon}\right) \int |\nabla u|^2 + \varepsilon \int \zeta^2 |\partial_k^h \nabla u|^2.
\end{aligned}$$

Therefore,

$$\int \zeta^2 |\partial_k^h \nabla u|^2 \lesssim \int a^{ij} \partial_i u \partial_j \varphi + \left(1 + \frac{1}{\varepsilon}\right) \int |\nabla u|^2 + \varepsilon \int \zeta^2 |\partial_k^h \nabla u|^2,$$

and taking small  $\varepsilon > 0$ , we are done.

(c) Note that

$$\int a^{ij} \partial_i u \partial_j \varphi = \int (Lu - b^i \partial_i u - cu) \varphi$$

since  $\varphi \in H_0^1(\Omega)$ . Because

$$\int (Lu - b^i \partial_i u - cu) \varphi \lesssim \frac{1}{\varepsilon} \int (|Lu|^2 + |\nabla u|^2 + |u|^2) + \varepsilon \int |\varphi|^2$$

and

$$\begin{aligned}
\int |\varphi|^2 &= \int |\partial_k^{-h}(\zeta^2 \partial_k^h u)|^2 \\
&\lesssim \int |\nabla(\zeta^2 \partial_k^h u)|^2 \\
&\lesssim \int |\partial_k^h u|^2 + \int \zeta^2 |\partial_k^h \nabla u|^2 \\
&\lesssim \int |\nabla u|^2 + \int \zeta^2 |\partial_k^h \nabla u|^2,
\end{aligned}$$

we obtain

$$\int (Lu - b^i \partial_i u - cu) \varphi \lesssim \frac{1}{\varepsilon} \int (|Lu|^2 + |u|^2) + \left( \varepsilon + \frac{1}{\varepsilon} \right) \int |\nabla u|^2 + \varepsilon \int \zeta^2 |\partial_k^h \nabla u|^2.$$

Taking small  $\varepsilon > 0$ , we are done. □

## 6.2 Schauder theory

## 6.3 De Giorgi-Nash-Moser theory

## 6.4 Viscosity solutions

## **Part III**

# **Evolution equations**

## Chapter 7

# Parabolic equations

### 7.1 Galerkin approximation

### 7.2 Semigroup theory



## **Chapter 8**

# **Hyperbolic equations**

## Chapter 9

# Local and global existence

### 9.1 Local existence

contraction mapping

### 9.2 Global existence

a priori estimates gronwall inequality

### 9.3 Weak convergence

## **Part IV**

# **Nonlinear equations**

## Chapter 10

## Chapter 11

# Hamilton-Jacobi equations

optimal control viscosity solution

## Chapter 12

# Conservation laws

shocks NS