

Integration, Differentiation and Linear Systems

DUE: NOVEMBER 27TH

- 01.** If the interval $[a, b]$ is subdivided into n subinterval $[x_i, x_{i+1}]$, $1 \leq i \leq n$ of equal length $h = \frac{b-a}{n}$, and if Simpson's rule is successively applied to each of those intervals, one gets the n -interval Composite Simpson's Rule, denoted by $Q_s^{c,n}(f)$
- a.** Show that

$$Q_s^{c,n}(f) = \frac{h}{6} (f(a) + f(b)) + \frac{h}{3} \left(f(a+h) + f(a+2h) + \dots + f(a+(n-1)h) \right) + \frac{2h}{3} \left(f(a+\frac{h}{2}) + f(a+3\frac{h}{2}) + \dots + f(a+(2n-1)\frac{h}{2}) \right)$$

- b.** Show that if $f(t)$ has a continuous fourth derivative, then

$$\int_a^b f(t) dt = Q_s^{c,n}(f) - \frac{(b-a)^5}{2880n^4} f^{(4)}(\theta), \quad \theta \in [a, b]$$

- c.** Suppose $-9 \leq f^{(4)}(t) \leq 2$, in the interval $[0, 2]$. Find the smallest number of intervals n , to guarantee that

$$\left| \int_0^2 f(t) dt - Q_s^{c,n}(f) \right| \leq 10^{-5}$$

- 02.** Write a MATLAB function `Composite_Simpson()` that implements the composite Simpson's rule. The function should take the following arguments

- `fname` the handle of the function $f(t)$ whose definite integral is being computed.
 - `a` and `b`, the end points of the interval of integration.
 - `n` the number of intervals into which the $[a, b]$ gets subdivided.
- `Composite_Simpson()` should return the value of the integral.

Test your function for $n = 1, 2, 3$ on the integrals

- $\int_0^1 x^k dx$, $k = 0, 1, 2, 3$, to make sure the degree of precision is 3
- $\int_0^1 e^{3x} dx$, to make sure that $Q_s^{c,n}(f)$ is close to the exact value of the integral.

- 03.** Derive a difference formula that approximates $f'(x_0)$, and uses the points

$$x_0 - 2h, x_0 - h, x_0 + h, x_0 + 2h$$

What is the order of convergence of the formula?

- 04.** Let $f(x)$ be a function with as many derivatives as needed at and around the point x_0 . Find the error term for the difference formula

$$f''(x_0) \approx \frac{-f(x_0 + 3h) + 4f(x_0 + 2h) - 5f(x_0 + h) + 2f(x_0)}{h^2}$$

- 05.** Use hand calculations to find an \mathbf{LU} factorization with partial pivoting of the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & -1 & 2 \\ 2 & 2 & 4 & 5 \\ 1 & -1 & 1 & 7 \\ 2 & 3 & 4 & 6 \end{bmatrix}, \text{ then use it to solve the system } \mathbf{Ax} = \mathbf{b}, \text{ where } \mathbf{b} = \begin{bmatrix} 6 \\ 21 \\ 25 \\ 23 \end{bmatrix}$$

- 06.** Consider the matrix $\mathbf{A} = \begin{bmatrix} 4 & 1 & 1 & 1 \\ 1 & 3 & 0 & -1 \\ 1 & 0 & 2 & 1 \\ 1 & -1 & 1 & 4 \end{bmatrix}$. Use hand calculations to find

- a.** an \mathbf{LDL}^t factorization of \mathbf{A} **b.** a Cholesky factorization of \mathbf{A}