

Tutorial - 5

Tutorial 3

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Q1)) What is the difference b/w DFS & BFS. Write applications of both the algorithms.

Answer)

BFS

- (a) It stands for Breadth first search
- (b) It uses queue
- (c) It is more suitable for searching
- (d) BFS considers all neighbours first of therefore not suitable for decision making trees used in games of puzzles.
- (e) Here siblings are visited before children.
- (f) There is no concept of backtracking.
- (g) It requires more memory.

DFS

- (a) It stands for Depth first search
- (b) It uses stack
- (c) It is more suitable when there are solutions away from source.
- (d) DFS is more suitable for game or puzzle problem. We make a decision. then explore all paths through this decision. And if decision leads to unsolvable situations we stop.
- (e) Here children are visited before sibling.
- (f) It is a recursive algorithm that uses backtracking.
- (g) It requires less memory.

Applications :-

- (a) BFS → Bipartite graph and shortest path, peer to peer networking, crawlers in search engine of GPS navigation system.
- (b) DFS → acyclic graph, topological order, scheduling problems, sudoku puzzle.

(PTO)

(Q2) → Which data structure are used to implement DFS and why?

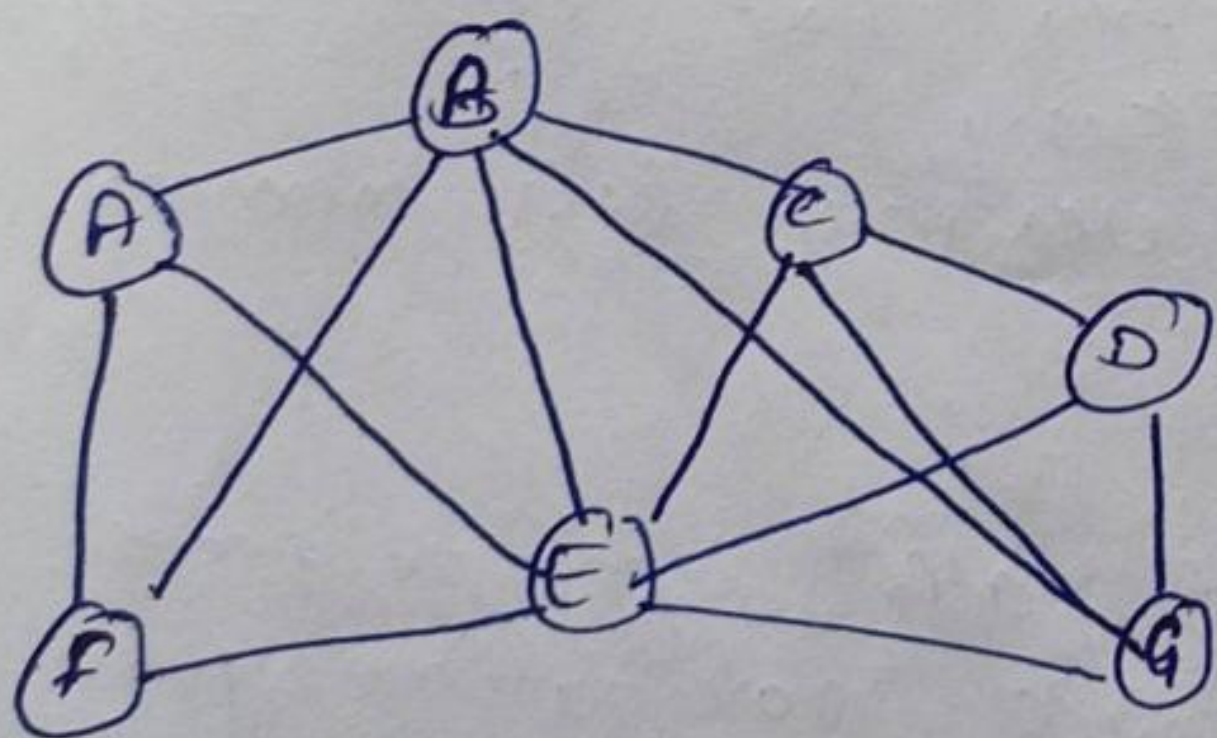
↳ For implementing BFS, we need a queue data structure for finding a shortest path b/w any node. We use queue because things don't have to be processed immediately, but have to be processed in FIFO order like BFS. BFS searches for nodes levelwise i.e. it searches nodes with their distance from root (source). For this queue is better to use in BFS.

For implementing DFS we need a stack data structure as it traverses a graph in depthwise motion and uses stack to remember to get the next vertex to start a search, when a dead end occurs in any iteration.

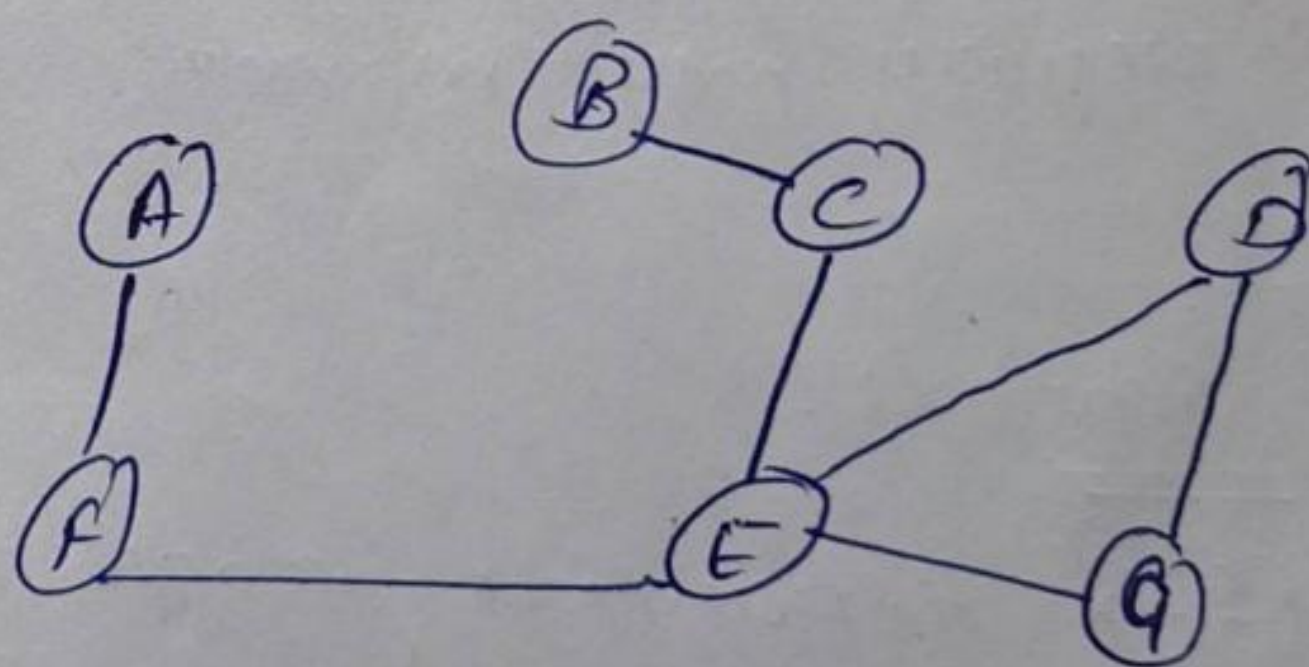
(Q3) What do you mean by sparse graph and dense graph? Which representation of graph is better for sparse and dense graph?

↳ Dense graph is a graph in which no. of edges is close to maximal no. of edges.

Sparse graph is a graph in which no. of edges is very less.



Dense graph



Sparse graph

- (1) for sparse graph it is preferred to use Adjacency List.
- (2) for dense graph it is preferred to use Adjacency Matrix.

→ How can you detect a cycle in a graph BFS & DFS?
→ For detecting cycle in a graph using BFS we need to use Kahn's algorithm for Topological Sorting.

The steps involved are:

- ① Compute in-degree (no. of incoming edges) for each of vertices present in graph & initialize count of visited nodes as 0.
- ② Pick all vertices with in-degree as 0 and add them in queue.
- ③ Remove a vertex from queue and then
 - increment count of visited node by 1.
 - Decrease in-degree by 1 for all its neighbouring nodes.
 - If in-degree of neighbouring nodes is reduced to zero then add to queue.
- ④ Repeat 3) until queue is empty.
- ⑤ If count of visited nodes is not equal to no. of nodes in graph, has cycle, otherwise not.

For detecting cycle in a graph use DFS, do the following, DFS for a connected graph produces a tree. There is cycle in graph if there is a back edge present in the graph. A back edge is an edge that is from a node to itself (self-loop) or one of its ancestors in the tree produced by DFS. For a disconnected graph get DFS forest as output. To detect cycle, check for a cycle in individual trees by checking back edges. To detect a back edge, keep track of vertices currently in recursive stack for DFS traversal.

(Q6) → What do you mean by disjoint set data type structure?
Explain 3 operations along with examples which can be performed on disjoint set.

Ans → A disjoint set is a data structure that keeps track of set of elements partitioned into several disjoint subsets. In other words, a disjoint set is a group of sets where no item can be in more than one set.

(operations):

① find → Can be implemented by recursively traversing the parent array until we hit a node who is parent itself.

```
eg → int find (int i) {  
    if (parent[i] == i) {  
        return i;  
    }  
    else {  
        return find (parent[i]);  
    }  
}
```

② Union → It takes 2 elements as input. And find representation of this set using the find operation and finally puts either one of the trees under root node of the other tree, effectively merging the trees and sets.

```
eg) → void union (int i, int j) {  
    int irep = this.find(i);  
    int jrep = this.find(j);  
    this.parent[irep] = jrep;  
}
```

③ Union by Rank → We need a new array `rank[]`, size of array same as parent array. If `i` is representative of set, `rank[i]` is height of tree. We need to minimize height of tree. If we are merging 2 trees, we call them left and right.

• If rank of left is less than right then it's best to move left under right of vice versa.

• If ranks are equal, rank of result will always be one greater than rank of tree.

```
eg) → void union (int i, int j) {  
    int irep = this.find(i);  
    int jrep = this.find(j);  
    if (irep == jrep) return;  
    i_rank = rank[irep];  
    j_rank = rank[jrep];  
    if (i_rank < j_rank) {  
        parent[irep] = jrep;  
    }  
    else if (i_rank > j_rank) {  
        parent[jrep] = irep;  
    }  
    else {  
        parent[jrep] = irep;  
        rank[irep]++;  
    }  
}
```

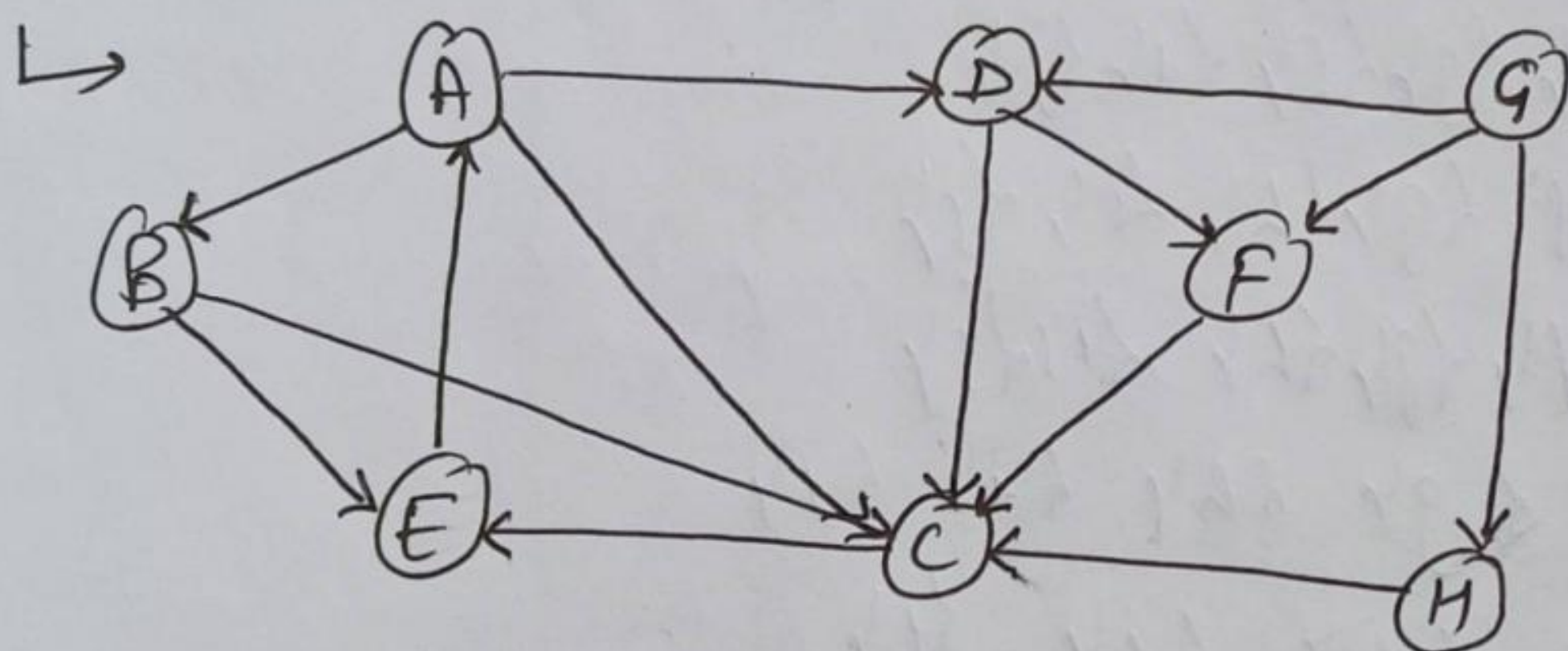


```

jrank = Rank[jrep];
if iRank < jrank
    this.parent[irep] = jrep;
else if (jrank < iRank)
    this.parent[jrep] = irep;
else {
    this.parent[irep] = jrep;
    Rank[jrep]++;
}
}

```

Q6) → Run BFS and DFS on graph shown below;



BFS

Child	G	H	D	F	C	E	A	B
Parent		G	G	G	H	C	E	A

Path → G → H → C → E → A → B

DFS

~~G~~
~~D~~
~~H~~
~~F~~
~~C~~
~~E~~
~~A~~
~~B~~

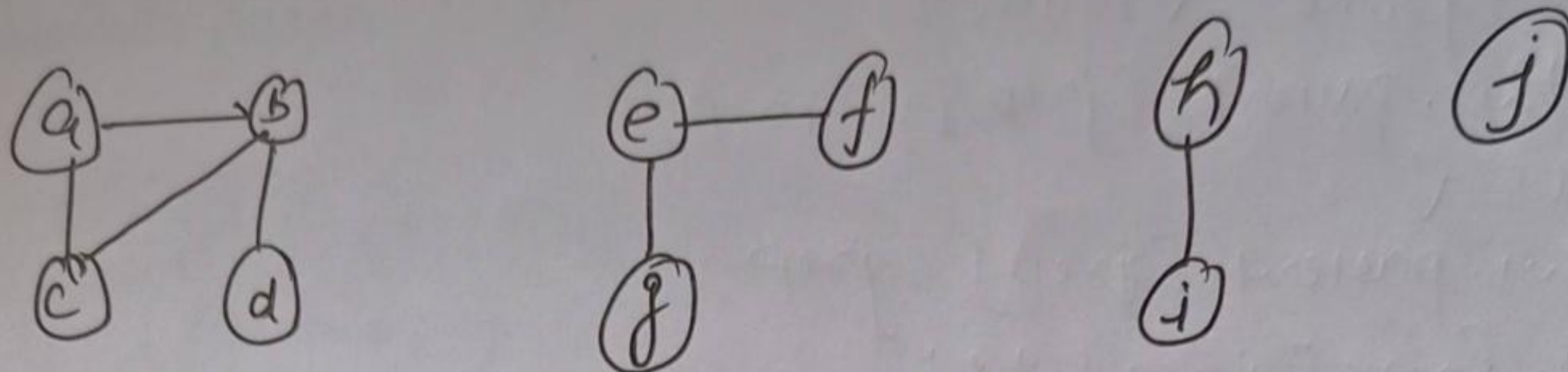
NODES
 VISITED

G
 F
 C
 E
 A
 B

STACK

Path G → F → C → E → A → B

Q7) find out no. of connected components and component using disjoint set data structure



Ans) $V = \{a, b, c, d, e, f, g, h, i, j\}$

$E = \{a,b, a,c, b,c, b,d, e,f, e,g, h,i, j\}$

(a,b) $\{a,b, c, d, e, f, g, h, i, j\}$

(a,c) $\{a,b,c, d, e, f, g, h, i, j\}$

(b,c) $\{a,b,c, d, e, f, g, h, i, j\}$

(b,d) $\{a,b,c,d, e, f, g, h, i, j\}$

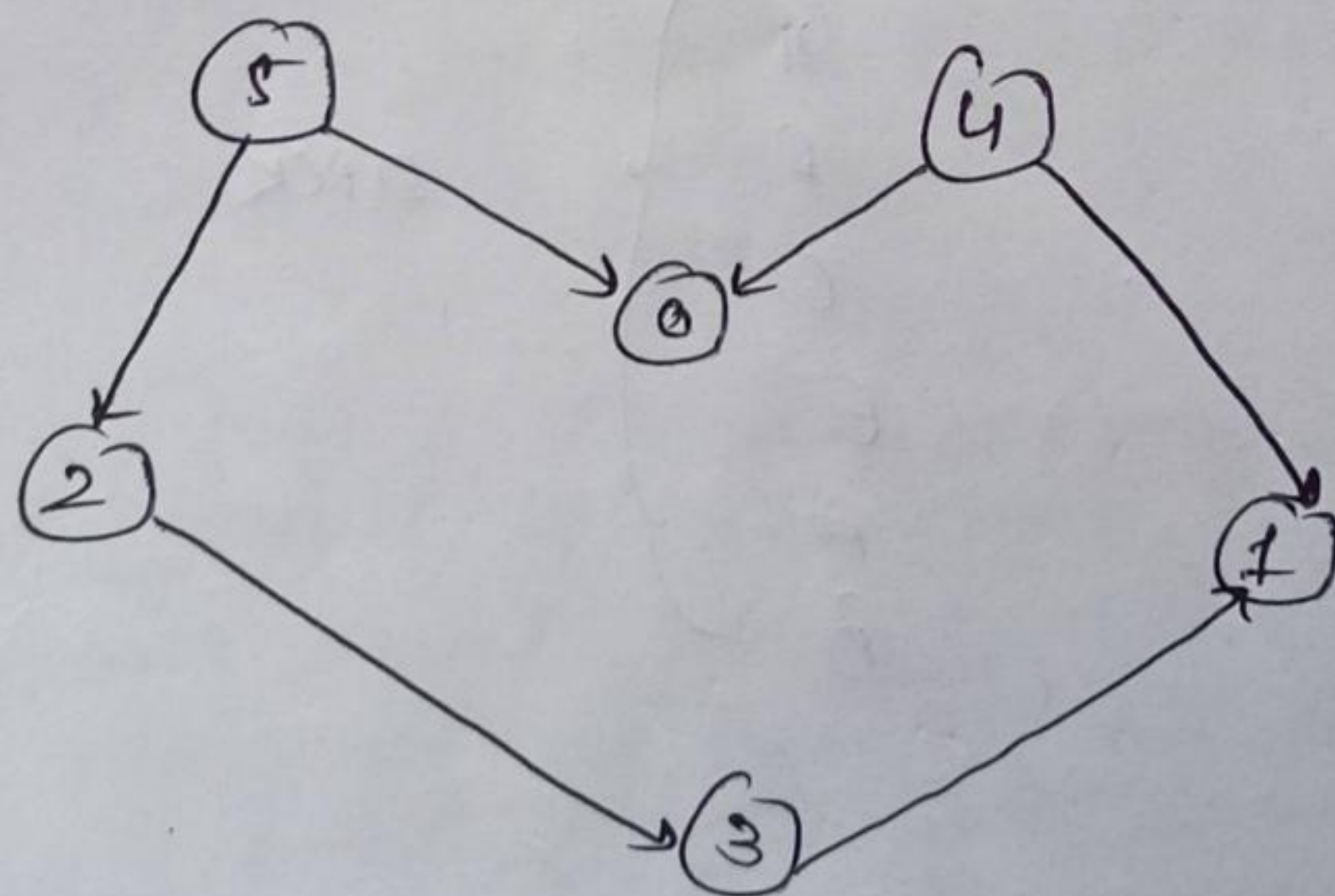
(e,f) $\{a,b,c,d, e, f, g, h, i, j\}$

(e,g) $\{a,b,c,d, e, f, g, h, i, j\}$

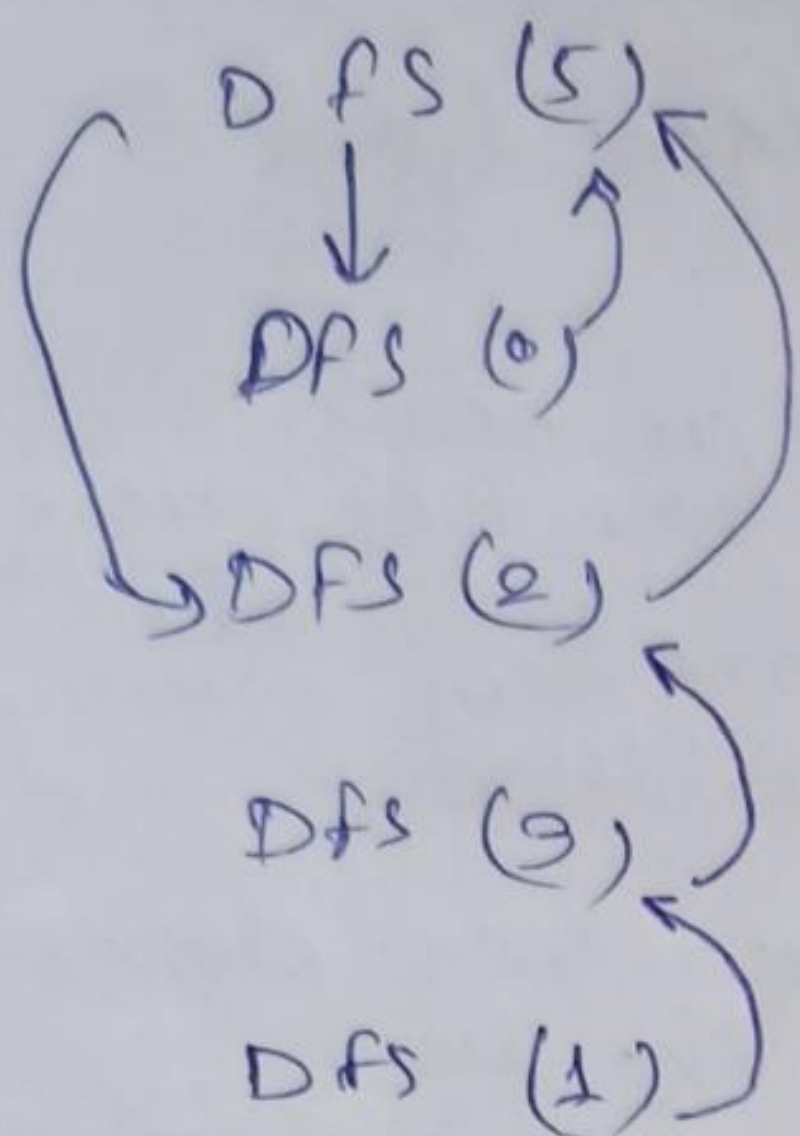
(h,i) $\{a,b,c,d, e, f, g, h, i, j\}$

No. of connected components = 3 \rightarrow Ans

Q8) \rightarrow Apply topological sort of DFS on graph having vertices from 0 to 5.



We take source node as 5
Applying Topological sort



DFS (4)
↓
Not possible

DFS

4
5
2
3
1
0

Stack

4 → 5 → 2 → 3 → 1 → 0

Ans

(Q9) Heap data structure can be used to implement priority queue. Name few graph algorithms where you need to use priority queue and why?

Ans → Yes, the statement is true. It will take $O(\log N)$ time to insert and delete each element in priority queue. Based on heap structure, priority queue has two types: max priority queue based on max heap and min priority based on min heap. Heaps provide better performance comparison to array of linked list.

The graph like Dijkstra's shortest path algorithm, Prim's min. Spanning Tree use Priority Queue.

- Dijkstra's Algorithm → When graph is stored in the form of adjacency list or matrix, priority queue is used to extract minimum efficiently when implementing the algorithm.

• Prim's Algorithm → It is used to store keys of nodes
extract minimum key node at every step.

(Q10) Difference b/w Min-Heap and Max heap.

Min heap

→ In min-heap, Key present at root node must be less than or equal to among keys present at all of its children.

→ The minimum key element is present at root.

→ It uses ascending priority.

→ The smallest element has priority while construction of min-heap.

→ The smallest element is the first to be popped from the heap.

Max heap

→ In max-heap the key present at root node must be greater than or equal to among keys present at all of its children.

→ The maximum key element is present at the root.

→ It uses descending priority.

→ The largest element has priority, while construction of Max heap.

→ The largest element is the first to be popped from the heap.