

# Skew braces and solutions to the Yang–Baxter equation

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The notes correspond to the series of lectures on *Skew braces and solutions to the Yang–Baxter equation* taught as part of the conference Introduction to Modern Advances in Algebra.

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**Lecture 1. 21/02/2024**

**§ 1.1. The Yang–Baxter equation.** The Yang–Baxter equation (YBE) is one important equation in mathematical physics. It first appeared in two independent papers of Yang [4] and Baxter [1].

**DEFINITION 1.1.** A solution of the *Yang–Baxter equation* is a bijective linear map  $R : V \otimes V \rightarrow V \otimes V$ , where  $V$  is a vector space such that

$$R_{12}R_{13}R_{23} = R_{23}R_{13}R_{12}$$

where  $R_{ij}$  denotes the map  $V \otimes V \otimes V \rightarrow V \otimes V \otimes V$  acting as  $R$  on the  $(i, j)$  factor and as the identity on the remaining factor.

Let  $\tau : V \otimes V \rightarrow V \otimes V$  be the map  $\tau(u \otimes v) = v \otimes u$  for  $u, v \in V$ . It's easy to check (try!) that  $R : V \otimes V \rightarrow V \otimes V$  is a solution of the Yang–Baxter equation if and only if  $\bar{R} := \tau R$  satisfies

$$\bar{R}_{12}\bar{R}_{23}\bar{R}_{12} = \bar{R}_{23}\bar{R}_{12}\bar{R}_{23}.$$

An interesting class of solutions of the Yang–Baxter equation arises when  $V$  has a  $R$ -invariant basis  $X$ . In such a case the solution is said to be set-theoretic.

**§ 1.2. The set-theoretic version.** Drinfeld in [2] observed it makes sense to consider the Yang–Baxter equation in the category of sets and stated that

*it would be interesting to study set-theoretic solutions.*

These lectures will focus on set-theoretic solutions to the Yang–Baxter equation and their connection with known and “new” algebraic structures.

**DEFINITION 1.2.** A *set-theoretic solution to the Yang–Baxter equation* is a pair  $(X, r)$  where  $X$  is a non-empty set and  $r : X \times X \rightarrow X \times X$  is a bijective map such that

$$(1.1) \quad (r \times \text{id})(\text{id} \times r)(r \times \text{id}) = (\text{id} \times r)(r \times \text{id})(\text{id} \times r)$$

**CONVENTION 1.** If  $(X, r)$  is a set-theoretic solution to the Yang–Baxter equation, we write

$$r(x, y) = (\lambda_x(y), \rho_y(x))$$

where  $\lambda_x, \rho_x : X \rightarrow X$ .

**DEFINITION 1.3.** Let  $(X, r)$  be a set-theoretic solution to the Yang–Baxter equation. We say that

- $(X, r)$  is *finite* if  $X$  is finite.
- $(X, r)$  is *non-degenerate* if  $\lambda_x, \rho_x$  are bijective for all  $x \in X$ .

**§ 1.3. Set-theoretic solutions to the Yang–Baxter equation and III Reidemeister move.** Let us represent the map  $r : X \times X \rightarrow X \times X$  as a crossing and the identity on  $X$  as a straight line, see Figure 1.

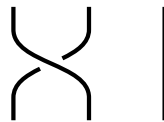


FIGURE 1. The map  $r$  represented as a crossing and the identity as a straight line.

Then the Yang–Baxter equation can be pictured as in Figure 2.

Moreover, under the assumption of  $(X, r)$  being non-degenerate we have the following lemma.

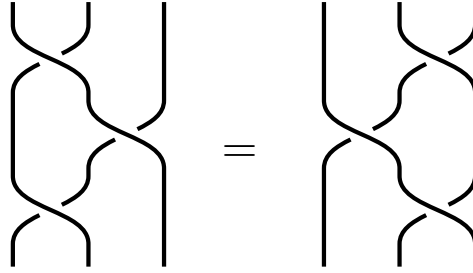


FIGURE 2. The Yang–Baxter equation.

LEMMA 1.4. *Let  $(X, r)$  be a solution to the Yang–Baxter equation.*

- 1) *Given  $x, u \in X$ , there exist unique  $y, v \in X$  such that  $r(x, y) = (u, v)$ .*
- 2) *Given  $y, v \in X$ , there exist unique  $x, u \in X$  such that  $r(x, y) = (u, v)$ .*

PROOF. For the first claim take  $y = \lambda_x^{-1}(u)$  and  $v = \rho_y(x)$ . For the second,  $x = \rho_y^{-1}(v)$  and  $u = \lambda_x(y)$ .  $\square$

So, the bijectivity of  $r$  means that any row in Figure 3 determines the whole square. By Lemma 1.4 we have that non-degeneracy means that any column in Figure 3 also determines the whole square.

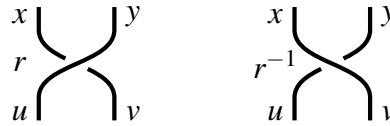


FIGURE 3. Any row or column determines the whole square.

### § 1.4. First examples.

EXAMPLES 1.5. Let  $X$  be a non-empty set.

- 1) The pair  $(X, \text{id}_{X \times X})$  is a set-theoretic solution to the Yang–Baxter equation. Note that  $(X, \text{id}_{X \times X})$  is not non-degenerate, since  $\lambda_x(y) = x$  and  $\rho_y(x) = y$ , for all  $x, y \in X$ .
- 2) Let  $\tau : X \times X \rightarrow X \times X$  be the flip map, i.e.  $\tau(x, y) = (y, x)$  for all  $x, y \in X$ . Then, the pair  $(X, \tau)$  is a set-theoretic solution to the Yang–Baxter equation. Moreover, it is non-degenerate since  $\lambda_x = \rho_x = \text{id}_X$  for all  $x \in X$ .
- 3) Let  $\lambda, \rho$  be permutations of  $X$ . Then  $r(x, y) = (\lambda(y), \rho(x))$  is a non-degenerate set-theoretic solution to the Yang–Baxter equation if and only if  $\lambda\rho = \rho\lambda$ . Moreover,  $(X, r)$  is involutive if and only if  $\rho = \lambda^{-1}$ . The solution  $(X, r)$  is called a *permutational solution* or a *Lyubashenko's solution*.

If on the set  $X$  we have a bit more structure we can define some more sophisticated solutions.

EXAMPLE 1.6. Let  $G$  be a group and let

$$\begin{aligned} r_1(x, y) &= (y, y^{-1}xy) \\ r_2(x, y) &= (x^2y, y^{-1}x^{-1}y). \end{aligned}$$

Then  $(X, r_1)$  and  $(X, r_2)$  are bijective non-degenerate set-theoretic solutions to the Yang–Baxter equation.

### § 1.5. A characterisation.

PROPOSITION 1.7. *Let  $X$  be a non-empty set and  $r : X \times X \rightarrow X \times X$  be a map, written as  $r(x, y) = (\lambda_x(y), \rho_y(x))$ . Then  $r$  satisfies equation 1.1 if and only if*

- 1)  $\lambda_x \lambda_y = \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}$
- 2)  $\lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y) = \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y)$
- 3)  $\rho_z \rho_y = \rho_{\rho_z(y)} \rho_{\lambda_y(z)}$

for all  $x, y, z \in X$ .

In particular,  $(X, r)$  is a solution to the Yang–Baxter equation when  $r$  is bijective.

PROOF. Let us write  $r_1 = r \times \text{id}$  and  $r_2 = \text{id} \times r$ . Then

$$\begin{aligned} r_1 r_2 r_1(x, y, z) &= r_1 r_2(\lambda_x(y), \rho_y(x), z) \\ &= r_1(\lambda_x(y), \lambda_{\rho_y(x)}(z), \rho_z \rho_y(x)) \\ &= (\lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z), \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y), \rho_z \rho_y(x)), \end{aligned}$$

and

$$\begin{aligned} r_2 r_1 r_2(x, y, z) &= r_2 r_1(x, \lambda_y(z), \rho_z(y)) \\ &= r_2(\lambda_x \lambda_y(z), \rho_{\lambda_y(z)}(x), \rho_z(y)) \\ &= (\lambda_x \lambda_y(z), \lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y), \rho_{\rho_z(y)} \rho_{\lambda_y(z)}(x)). \end{aligned}$$

Therefore  $r_1 r_2 r_1 = r_2 r_1 r_2$  if and only if 1), 2) and 3) hold. □

EXERCISE 1.8. Let  $(X, r)$  be a set-theoretic solution to the Yang–Baxter equation. Define for all  $x, y \in X$

$$\bar{r}(x, y) = \tau r \tau(x, y) = (\rho_x(y), \lambda_y(x)).$$

Then  $(X, \bar{r})$  is a set-theoretic solution to the Yang–Baxter equation.

### § 1.6. Shelves and racks.

EXERCISE 1.9. Let  $X$  be a non-empty set. Let  $\triangleleft : X \times X \rightarrow X$  be a binary operation and define  $r : X \times X \rightarrow X \times X$  such that  $r(x, y) = (y, x \triangleleft y)$ . Then  $r$  satisfies equation 1.1 if and only if  $(x \triangleleft y) \triangleleft z = (x \triangleleft z) \triangleleft (y \triangleleft z)$  holds for all  $x, y, z \in X$ . Moreover,  $r$  is bijective if and only if the maps  $\rho_y : X \rightarrow X, x \mapsto x \triangleleft y$  are bijective.

DEFINITION 1.10. A (right) shelf is a pair  $(X, \triangleleft)$  where  $X$  is a non-empty set and  $\triangleleft$  is a binary operation such that

$$(x \triangleleft y) \triangleleft z = (x \triangleleft z) \triangleleft (y \triangleleft z).$$

If, in addition, the maps  $\rho_y : X \rightarrow X, x \mapsto x \triangleleft y$  are bijective for all  $y \in X$ , then  $(X, \triangleleft)$  is called a (right) rack.

PROPOSITION 1.11. *Let  $X$  be a non-empty set with a binary operation  $\triangleleft : X \times X \rightarrow X$ . Then  $r(x, y) = (y, x \triangleleft y)$  is a set-theoretic solution to the Yang–Baxter equation if and only if  $(X, \triangleleft)$  is a rack.*

PROOF. Follows from exercise 1.9. □

EXERCISE 1.12. Let  $G$  be a group. Then  $(G, r)$  where  $r(x, y) = (y, y^{-1}xy)$  is a non-degenerate set-theoretic solution to the Yang–Baxter equation.

CONVENTION 2. From now on, a *solution* will always mean a non-degenerate set-theoretic solution to the Yang–Baxter equation.

**§ 1.7. An intriguing connection between group actions and solutions.** The following theorem is the core result of the paper [3] by Lu, Yan Zhu.

THEOREM 1.13. *Let  $G$  be a group, let  $\lambda : G \times G \rightarrow G, (x, y) \mapsto \lambda_x(y)$  a left group action of  $G$  on itself as a set and  $\rho : G \times G \rightarrow G, (x, y) \mapsto \rho_y(x)$  a right group action of  $G$  on itself as a set. If the “compatibility” condition*

$$(1.2) \quad uv = \lambda_u(v)\rho_v(u)$$

*holds, then  $(G, r)$ , where*

$$r : G \times G \rightarrow G \times G, \quad (x, y) \mapsto (\lambda_x(y), \rho_y(x))$$

*is a solution.*

EXERCISE 1.14. Prove Theorem 1.13

### Some solutions

1.9. For every  $x, y \in X$  let us write  $\lambda_x = \text{id}_X$  and  $\rho_y(x) = x \triangleleft y$ . We want to apply Proposition 1.7. First note that clearly  $\lambda_x \lambda_y = \text{id}_X = \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}$ , i.e. (1) is satisfied. Moreover,  $\lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y) = \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y)$  reduce to the trivial identity  $\rho_z(y) = \rho_z(y)$ . Finally,  $\rho_z \rho_y(x) = \rho_{\rho_z(y)} \rho_{\lambda_y(z)}(x)$  is equivalent to  $(x \triangleleft y) \triangleleft z = (x \triangleleft z) \triangleleft (y \triangleleft z)$ .

Now assume that  $r$  is bijective. If  $x_1, x_2 \in X$  such that  $\rho_y x_1 = \rho_y x_2$ , then  $r(x_1, y) = r(x_2, y)$  and so  $x_1 = x_2$ , i.e.  $\rho_y$  is injective. Now, let  $z \in X$  and let  $x \in X$  such that  $r(x, y) = (y, z)$ . It follows that  $\rho_y(x) = z$  and  $\rho_y$  is bijective. Similarly one obtains the converse.

1.14. Let us write  $r_1 = r \times \text{id}$  and  $r_2 = \text{id} \times r$ ,

$$\begin{aligned} r_1 r_2 r_1(x, y, z) &= (\lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z), \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y), \rho_z \rho_y(x)) \\ &= (u_1, v_1, w_1), \end{aligned}$$

and

$$\begin{aligned} r_2 r_1 r_2(x, y, z) &= (\lambda_x \lambda_y(z), \lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y), \rho_{\rho_z(y)} \rho_{\lambda_y(z)}(x)) \\ &= (u_2, v_2, w_2). \end{aligned}$$

Then we obtain

$$\begin{aligned} u_1 v_1 w_1 &= \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z) \rho_{\lambda_{\rho_y(x)}(z)} \lambda_x(y) \rho_z \rho_y(x) \\ &\stackrel{(1.2)}{=} \lambda_x(y) \lambda_{\rho_y(x)}(z) \rho_z \rho_y(x) \\ &\stackrel{(1.2)}{=} \lambda_x(y) \rho_y(x) z \\ &\stackrel{(1.2)}{=} xyz \end{aligned}$$

and, similarly

$$\begin{aligned} u_2 v_2 w_2 &= \lambda_x \lambda_y(z) \lambda_{\rho_{\lambda_y(z)}(x)} \rho_z(y) \rho_{\rho_z(y)} \rho_{\lambda_y(z)}(x) \\ &\stackrel{(1.2)}{=} \lambda_x \lambda_y(z) \rho_{\lambda_y(z)}(x) \rho_z(y) \\ &\stackrel{(1.2)}{=} x \lambda_y(z) \rho_z(y) \\ &\stackrel{(1.2)}{=} xyz. \end{aligned}$$

Hence

$$(1.3) \quad u_1 v_1 w_1 = xyz = u_2 v_2 w_2.$$

Moreover, since  $\lambda$  is a left action of  $G$  on itself, we get

$$u_1 = \lambda_{\lambda_x(y)} \lambda_{\rho_y(x)}(z) = \lambda_{\lambda_x(y) \rho_y(x)}(z) \stackrel{(1.2)}{=} \lambda_{xy}(z) = \lambda_x \lambda_y(z) = u_2.$$

Similarly, since  $\rho$  is a right action

$$w_2 = \rho_{\rho_z(y)} \rho_{\lambda_y(z)}(x) = \rho_{\lambda_y(z) \rho_z(y)}(x) \stackrel{(1.2)}{=} \rho_{yz}(x) = \rho_z \rho_y(x) = w_1.$$

From (1.3) and  $G$  being a group it follows that also  $v_1 = v_2$ . Moreover,  $\lambda_x$  and  $\rho_x$  are bijective maps by assumption. It is left to prove that  $r$  is bijective. First let us write  $r(u, v) = (x, y)$ , hence

$\lambda_u(v) = x$ ,  $\rho_v(u) = y$ , and  $uv = xy$ . Now, since  $\lambda$  is an action and in particular  $\lambda_v^{-1} = \lambda_{v^{-1}}$ , we get

$$\lambda_y(v^{-1})u = \lambda_y(v^{-1})\rho_v^{-1}(y) = \lambda_y(v^{-1})\rho_{v^{-1}}(y) \stackrel{(1.2)}{=} yv^{-1} = x^{-1}u = (\lambda_u(v))^{-1}u,$$

and so

$$(1.4) \quad (\lambda_u(v))^{-1} = \lambda_{\rho_v(u)}(v^{-1}).$$

Similarly, expanding  $v\rho_x(u^{-1})$  one proves

$$(1.5) \quad (\rho_v(u))^{-1} = \rho_{\lambda_u(v)}(u^{-1}).$$

Define

$$r'(x, y) = ((\rho_{x^{-1}}(y^{-1}))^{-1}, (\lambda_{y^{-1}}(x^{-1}))^{-1}).$$

Then

$$\begin{aligned} rr'(x, y) &= (\lambda_{(\rho_{x^{-1}}(y^{-1}))^{-1}}((\lambda_{y^{-1}}(x^{-1}))^{-1}), \rho_{(\lambda_{y^{-1}}(x^{-1}))^{-1}}((\rho_{x^{-1}}(y^{-1}))^{-1})) \\ &\stackrel{(1.4)\&(1.5)}{=} (\lambda_{\rho_{x^{-1}}(y^{-1})}^{-1} \lambda_{\rho_{x^{-1}}(y^{-1})}(x), \rho_{\lambda_{y^{-1}}(x^{-1})}^{-1} \rho_{\lambda_{y^{-1}}(x^{-1})}(y)) \\ &= (x, y). \end{aligned}$$

And

$$\begin{aligned} r'r(x, y) &= ((\rho_{(\lambda_x(y))^{-1}}((\rho_y(x))^{-1}))^{-1}, (\lambda_{(\rho_y(x))^{-1}}((\lambda_x(y))^{-1}))^{-1}) \\ &\stackrel{(1.4)\&(1.5)}{=} ((\rho_{\lambda_x(y)}^{-1} \rho_{\lambda_x(y)}(x^{-1}))^{-1}, (\lambda_{\rho_y(x)}^{-1} \lambda_{\rho_y(x)}(y^{-1}))^{-1}) \\ &= ((x^{-1})^{-1}, (y^{-1})^{-1}) = (x, y). \end{aligned}$$

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