



## Noumankhan 21I-2744 La2

Linear Algebra (National University of Computer and Emerging Sciences)

Name : Nouman Khan

Roll no : 21E-2744

Sec : N

Q1. Write the solution set of the given homogenous system  $AX=B$  .... homogenous system.

Sol:

To write the solution in parametric vector form.

$$\begin{bmatrix} 2 & 2 & 4 \\ -4 & -4 & -8 \\ 0 & -3 & -3 \end{bmatrix}$$

Writing the augmented form.

$$\begin{bmatrix} 2 & 2 & 4 & 0 \\ -4 & -4 & -8 & 0 \\ 0 & -3 & -3 & 0 \end{bmatrix}$$

Applying row operations.

$$\begin{array}{l} R \\ \sim \end{array} \begin{bmatrix} 1 & 1 & 2 & 0 \\ -4 & -4 & -8 & 0 \\ 0 & -3 & -3 & 0 \end{bmatrix} \begin{array}{l} \frac{1}{2} R_1 \\ R_2 + 4R_1 \end{array}$$

$$\begin{array}{l} R \\ \sim \end{array} \begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -3 & -3 & 0 \end{bmatrix}$$

$$x_1 + x_2 + 2x_3 = 0 \Rightarrow x_1 = -1 - 2x_3$$

$$-3x_2 - 3x_3 = 0 \Rightarrow x_2 = -x_3$$

S0

$$Y = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_3 \\ -x_3 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} x_3$$

$$= P x_3$$

Vectors whose span give solution

$$\begin{bmatrix} 2 & 2 & 4 \\ -4 & -4 & -8 \\ 0 & -3 & -3 \end{bmatrix} \begin{bmatrix} -2 \\ -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

So  $x_1 = -2, x_2 = -2, x_3 = 2$

When  $Ax=b$  in parameter form.

$$\begin{bmatrix} 2 & 2 & 4 & 8 \\ -4 & -4 & -8 & -16 \\ 0 & -3 & -3 & 12 \end{bmatrix} \begin{array}{l} \frac{1}{2} R_1 \\ R_2 + 4R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & -3 & -3 & 12 \end{bmatrix}$$

$$x_1 + x_2 + 2x_3 = 4 \rightarrow \textcircled{I}$$

$$-3x_2 - 3x_3 = 12 - (2)$$

$$-3x_2 = 12 + 3x_3$$

$$x_2 = \frac{-(12 + 3x_3)}{3} \rightarrow \textcircled{II}$$

$$x_1 = \frac{4 + 12 - 3x_3 - 2x_3}{3}$$

$$x_1 = 8 - x_3$$

$$x_2 = -4 - x_3$$

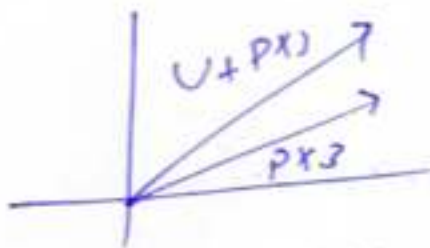
$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 8 - x_3 \\ -4 - x_3 \\ x_3 \end{pmatrix} = \begin{pmatrix} 8 \\ -4 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \quad (2)$$

$$= U + Px_3.$$

Geometric description:

Vector plane

translated and line is parallel to main vectors when there is non-homogeneous eq. The plane is translated and parallel to main vector.



Q2: Find the values of  $h$  if possible for which the vectors are linearly dependent.

$$\begin{bmatrix} 2 & 4 & -2 \\ -2 & -6 & h \\ 4 & 7 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 & -2 \\ -2 & -6 & h \\ 4 & 7 & 2 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{bmatrix} 2 & 4 & -2 & 0 \\ 2 & -6 & h & 0 \\ 4 & 7 & 2 & 0 \end{bmatrix}$$

Row operations.

$$\begin{pmatrix} 2 & 4 & -2 & 0 \\ 4 & 7 & 2 & 0 \\ -2 & -6 & h & 0 \end{pmatrix} \begin{array}{l} R_2 - 2R_1 \\ R_3 + R_1 \end{array}$$

$$\begin{pmatrix} 2 & 4 & -2 & 0 \\ 0 & -1 & 6 & 0 \\ 0 & -2 & h-2 & 0 \end{pmatrix} R_3 - 2R_2$$

$$\begin{pmatrix} 2 & 4 & -2 & 0 \\ 0 & -1 & 6 & 0 \\ 0 & 0 & h+10 & 0 \end{pmatrix}$$

For the vectors to be linearly independent  $h+10 \neq 0$  or  $h \neq -10$



Q3: Let  $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ,  $y_1 = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$

... is not linear.

Sol:

As given

$$T(e_1) = \begin{bmatrix} 2 \\ 5 \end{bmatrix}, T(e_2) = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

So the matrix A is

$$A = \begin{bmatrix} 2 & -1 \\ 5 & 6 \end{bmatrix}$$

As we know that

$$T(x) = A(x) = b$$



(3)

Nouman - Khan

21E-2744 Sec-N

$$T \begin{bmatrix} 5 \\ -3 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 5 & 6 \end{bmatrix} \begin{bmatrix} 5 \\ -3 \end{bmatrix} = \begin{bmatrix} 13 \\ 7 \end{bmatrix}$$

$$T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 5 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 - x_2 \\ 5x_1 + 6x_2 \end{bmatrix}$$

Transformation:

For the transformation to be linear this condition must be satisfied.

$$T(x_1, x_2) = T(x_1) + T(x_2)$$

$$\text{let } x_1 (2, 5), x_2 (-1, 6)$$

Given that

$$(x_1 - 2x_2, 2x_1 - 5x_2)$$

$$x_1 + x_2 = (1, 1)$$

$$T(\vec{x}_1 + \vec{x}_2) = T(1, 1) = (1 - 2, 2 - 5)$$

$$= (-1, -3)$$

$$T(x_1) = (2, 5) = (2 - 10, 4 - 25) = (-8, -21)$$

$$T(x_2) = (-1, 6) = (-2 - 12, -2 - 36) = (-14, -38)$$

$$T(x_1) + T(x_2) = (-8, -21) + (-14, -38)$$

$$= (-22, -59)$$

A condition is satisfied so it is

linear transformation and statement is wrong.

Q4 Let  $T: \mathbb{R}_2 \rightarrow \mathbb{R}_2$  be a linear transformation ..... one linear trans?

Sol.

$$\begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

Augmented form becomes

$$\begin{bmatrix} 1 & -2 & 1 \\ 4 & 5 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & 13 & -1 \end{bmatrix} R_2 - 4R_1$$

$$\text{So } x_1 = 11/13, x_2 = -1/13$$

$$y = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 11/13 \\ -1/13 \end{bmatrix}$$

One to one:-

$$\begin{aligned} T \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} &= \begin{bmatrix} 1 & -2 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & -2 & 1 \\ 4 & 5 & 3 \end{bmatrix} \end{aligned}$$

For the transformation to be one solution must be trivial i.e.  $Ax=0$ , or vectors are linearly independent by theorem so this transformation is not one to one.

(4)

Nouman Khan  
21E-2744  
Sec. N.

Onto:

$$\begin{bmatrix} 1 & -2 & 1 \\ 4 & 5 & 3 \end{bmatrix}$$

$$R_2 - 4R_1 = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 13 & -1 \end{bmatrix}$$

Q3 There exists two pivots in  $R_2$  or every column has its pivot  
So by theorem 4 it is onto because  $A$  spans  $\mathbb{R}^2$ .

Q5:

Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation ...  $\phi = \pi/6$ .

Sol:

1) Rotate by  $\pi/4$ :

The standard form is  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$   
When rotate by  $\pi/2$

$$A_{\text{rotate}} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

2) Reflect by  $y = x$ :

When reflect general matrix is

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$



$$J \cdot A = A_{\text{ref}} \times A_{\text{rot}}$$

$$A = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & \sqrt{3}/2 \end{pmatrix}$$

$$A = A_{\text{ref}} \phi \times A_{\text{rot}} \odot$$

$$A = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} \times \begin{pmatrix} \sqrt{3}/2 & -1/2 \\ 1/\sqrt{2} & \sqrt{3}/2 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{\sqrt{3} + \sqrt{2}}{2\sqrt{2}} & \frac{\sqrt{3} - 1}{2\sqrt{2}} \\ \frac{\sqrt{3} - \sqrt{2}}{2\sqrt{2}} & \frac{-\sqrt{3} - 1}{2\sqrt{2}} \end{pmatrix}$$

Ans.



End :