CS120: Intro. to Algorithms and their Limitations Anshu & Hesterberg

Lecture 13: Matchings

Harvard SEAS - Fall 2023 *2023-10-19*

1 Announcements

- Three extra late days for everyone.
- Final exam can replace midterm for purposes of getting to a satisfactory grade.
- Embedded EthiCS Module on Thursday. You are expected to attend; there will be material on ps6 building on the module.
- Please fill out midterm survey (comes with pset 4 survey).

Recommended Reading: Cormen–Leiserson-Rivest–Stein, Sec. 25.1.

2 Loose ends from lecture 12

Theorem 2.1. *If the input intervals are sorted by increasing order of end time b_i, then we have that* `GreedyIntervalScheduling(`x`)` *will find an optimal solution to IntervalScheduling-Optimization, and can be implemented in time $O(n \log n)$.*

Proof.
Intuitively, for any interval scheduling problem (black in Figure 1, we can modify any solution $(i_0^*, i_1^*, \ldots, i_{\ell-1}^*)$ to it (gray boxes) into the greedy solution (i_0, i_1, …, i_{k-1} (white) by "smushing it left", replacing the first j intervals of our solution with the first j intervals of the greedy solution to get a valid solution $(i_0, i_1, \ldots, i_{j-1}, i_j^*, \ldots, i_{\ell-1}^*$. Also, $k \geq \ell$: If not, then Greedy would pick one more interval, since i_ℓ^* would be valid.

Formally, let $S^* = \{i_0^* \leq i_1^* \leq \ldots \leq i_{k^*-1}^*\}$ be an optimal solution to Interval Scheduling (where we say that $i < i'$ for intervals i and i' if i ends before i' begins). Then let $S = \{i_0 \leq i_1 \leq \ldots \leq i_{k-1}\}$ be the solution found by the greedy algorithm. Recall that b_{i_j} is the endtime of interval i_j (and above we sort both solutions on end time).

Claim 2.2 (greedy stays ahead)**.** *For all $j \in \{0, \ldots, k^* - 1\}$, we have:*

1. *$j < k$, i.e. the Greedy Algorithm schedules at least $j + 1$ intervals, and*
2. *$b_{i_j} \leq b_{i_j^*}$, i.e. the j'th interval scheduled by the Greedy algorithm ends no later than the j'th interval scheduled by the optimal solution.*

Proof. For the $j = 0$ base case, since greedy always picks the absolute first interval by end time, the claim follows. Then assuming it holds up to j, we have $b_{i_j} \leq b_{i_j^*} < a_{i_{j+1}^*}$. The second inequality follows since the next interval in the optimal solution must start after the prior interval ending. But this means that interval i_{j+1}^* is *available* to the greedy algorithm after it has picked interval i_j, and since we would only not pick it if there is an available interval ending even earlier, we establish the claim for $j + 1$ and conclude. □

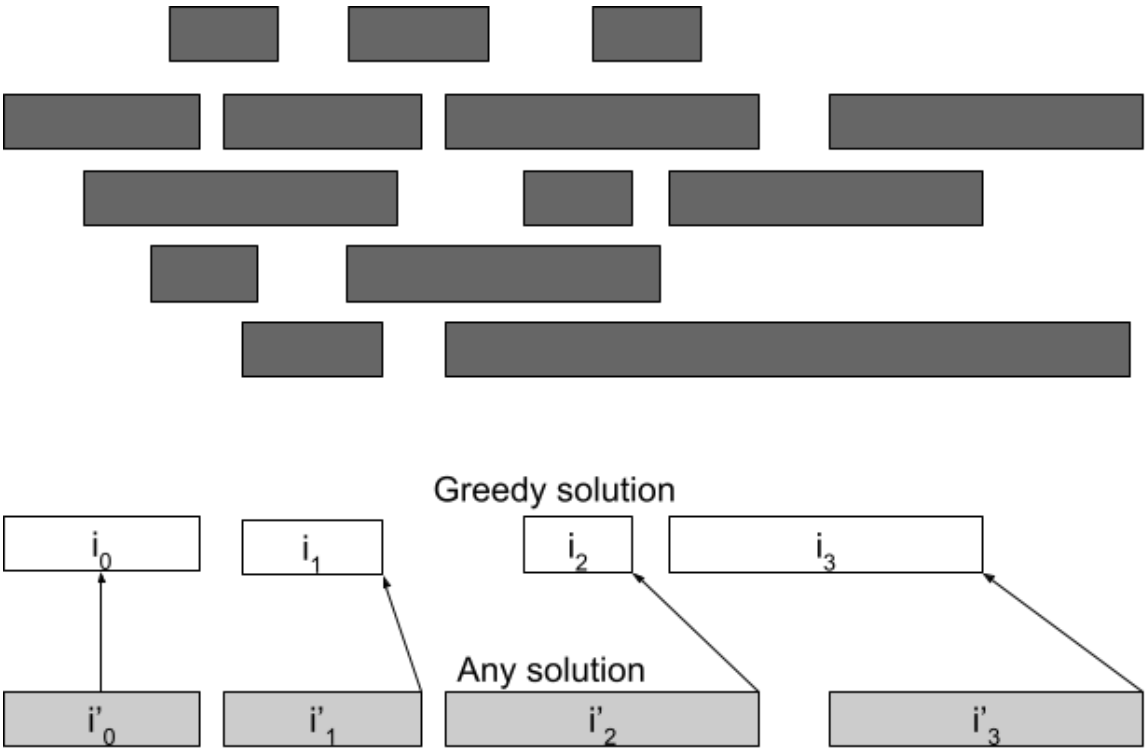


Figure 1: Transforming any interval scheduling solution into the greedy one.

Then from this claim we establish that $k^* - 1 < k$ and so the Greedy Algorithm schedules $k \geq k^*$ intervals. Since k^* is the optimal (maximum) number of intervals that can be scheduled, we conclude that $k = k^*$ and the Greedy Algorithm schedules an optimal number of intervals.

For the runtime, we can order the intervals by increasing end time by sorting in time $O(n \log n)$. Next we observe that in Line **??** we only need to check that the start time a_i of the current interval is later than the end time of b_j of the most recently scheduled interval (since all others have earlier end time), so we can carry out this check in constant time. Thus the loop can be implemented in time $O(n)$, for a total runtime of $O(n \log n) + O(n) = O(n \log n)$. □

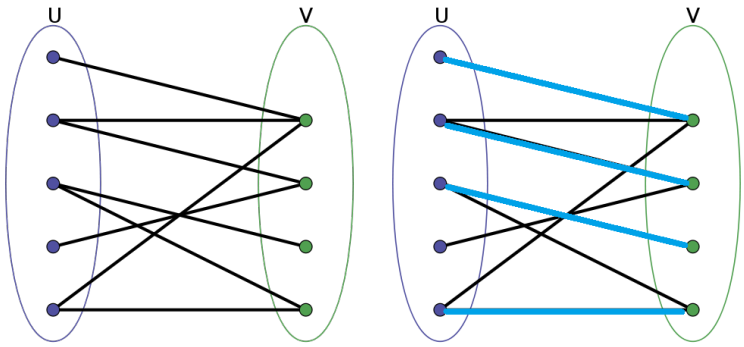
3 Definitions

Motivating Problem: Kidney Exchange. Collection of patients (who need a kidney) and donors (willing to donate a kidney). Each donor can only donate one kidney (they need their other one to survive!) and only to certain patients (due to blood type and HLA type compatibilities). This is a large-scale real-world problem, in which algorithms like what we will cover play a significant role. There nearly 100,000 patients currently on the kidney waiting list in the US, with a little over 25,000 donations happening per year, and patients spending an average of about 3.6 years on the waiting list.

How many patients can we give kidneys to?

Q: How to formulate graph-theoretically?

Create a graph with $u_1, \ldots, u_t$ representation potential donors, and $v_1, \ldots, v_l$ representing potential recipients. Then, for u_i, v_j we place an (undirected) edge connecting the two if they are compatible.



Definition 3.1. For a graph $G = (V, E)$, a *matching* in G is a subset $M \subseteq E$ such that every vertex $v \in V$ is incident to at most one edge in M.[1] Equivalently, no two edges in M share an endpoint.

Input	: A graph $G = (V, E)$
Output	: A matching $M \subseteq E$ in G of maximum size

Computational Problem Maximum Matching

Additional considerations in real-life kidney exchange (to be discussed more in Embedded EthiCS Module on Thurs!):

- Priority: We may want to give higher priority to some patients, like those who have been waiting longest, or have more advanced kidney disease, or are organ donors themselves.
- Donor preference: most kidney donors sign up because they have a loved one who needs a kidney, but aren't compatible with each other. So they are only willing to donate their kidney if their loved one receives a kidney from someone else.
- Chains: due to the donor preference above, and laws disallowing contracts around organ donations, a donor may only want to do their donation if it is nearly simultaneous with their loved one receiving a kidney. This leads to simultaneous or near-simultaneous surgeries, with the longest chain to date (Dec 2020) involving 35 donations (70 surgeries) over multiple locations.
- Location: It is easiest and most cost effective if the exchange happens in the same hospital, though it has become common to ship the kidneys on ice from the donor's hospital to the patient's hospital!

[1] Saying a vertex v is *incident* to an edge e is another way of saying v is an endpoint of e. It is more symmetric, in that we would also say that e is incident to v.

4 Matching vs. Independent Sets

This section will not be covered in lecture, and is optional (but recommended) material.

Maximum Matching can be viewed as a special case of the Independent Set problem we studied last time, i.e. there is an efficient reduction from Maximum Matching to Independent Set:

Given a matching instance $G = (V, E)$, want to reduce to an independent set instance $G' = (V', E')$. In max matching, we want to find a set of edges that don't conflict, whereas independent set tries to find a set of vertices that don't conflict. Thus, let

$$V' = E \quad \text{and} \quad E' = \{\{e, e'\} : e, e' \text{ share an endpoint}\}.$$

(The graph G' is known as the *line graph* of G.)

Unfortunately, the fastest known algorithm for Independent Set runs in time approximately $O(1.2^n)$. However, as we saw last time for IntervalScheduling-Optimization, special cases of IndependentSet can be solved more quickly. Matching is another example!

5 Maximum Matching Algorithm

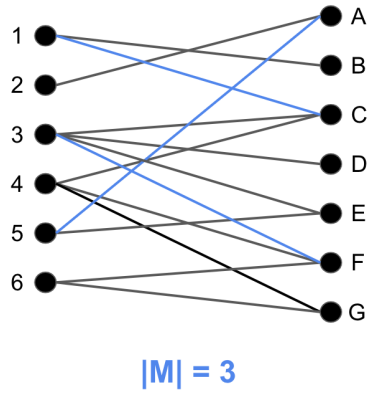
Like in a greedy strategy, we will try to grow our matching M on step at a time, building a sequence $M_0 = \emptyset, M_1, M_2, \ldots$, with $|M_k| = k$. However, to get M_k from M_{k-1} we will sometimes do more sophisticated operations than just adding an edge.

Definition 5.1. Let $G = (V, E)$ be a graph, and M be a matching in G. Then:

1. An *alternating walk* W in G with respect to M is a walk $(v_0, v_1, \ldots, v_\ell)$ in G such that for every $i = 1, \ldots, \ell - 1$, $\{v_{i-1}, v_i\} \in M \Leftrightarrow \{v_i, v_{i+1}\} \in E \setminus M$.

2. An *augmenting path* P in G with respect to M is an alternating walk in which v_0 and v_ℓ are respectively unmatched by M, and in which all of the vertices in the walk are distinct, and $\ell \geq 1$.

For example, consider the following graph with $M = \{\{1, C\}, \{3, F\}, \{5, A\}\}$.



We check whether the following sequences of vertices constitute an alternating walk or an augmenting path.

Path	Alternating Walk	Augmenting Path
$2, A, 5$	Yes	No
$G, 4$	Yes	Yes
$3, F, 4, C, 3$	No	N/A
$1, C, 6$	No	N/A
$6, F, 3, C, 1, B$	Yes	Yes

Let's see why augmenting paths are useful.

Lemma 5.2. *Given a graph $G = (V, E)$, a matching M, and an augmenting path P with respect to M, we can construct a matching M' with $|M'| = |M| + 1$ in time $O(n)$.*

Proof.
Let $P = (v_0, \ldots, v_\ell)$ be an augmenting path. We have that $\{v_0, v_1\} \in E \setminus M$ since v_0 is unmatched, and $\{v_{\ell-1}, v_\ell\} \in E \setminus M$ since v_ℓ is unmatched. Thus, let

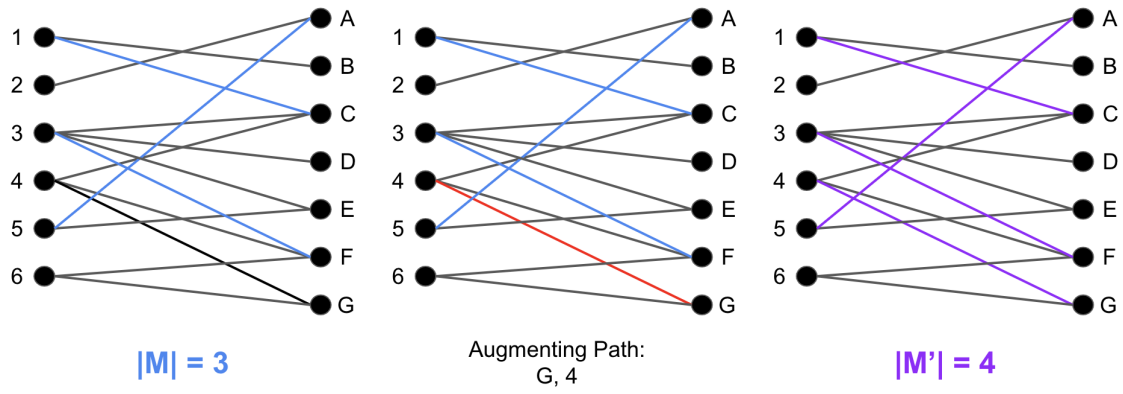
$$M' = (M - \{\{v_1, v_2\}, \{v_3, v_4\}, \ldots, \{v_{\ell-2}, v_{\ell-1}\}\}) \cup \{\{v_0, v_1\}, \{v_2, v_3\} \ldots, \{v_{\ell-1}, v_\ell\}\}.$$

In words, we "flip" each of the edges in this augmenting path: any edge of the augmenting path originally in the matching M is now not in the matching M', and any edge of the augmenting path not in M is in M'. We can show that $|M'| = |M| + 1$ via a counting argument. To show M' is a matching, note that v_0 only appears in the first edge when we insert it into our matching (since the path has no duplicate vertices). Since v_1 was only connected to one prior edge $\{v_1, v_2\}$ (since M was a matching), removing it must ensure $\{v_0, v_1\}$ can be added to M. Then an equivalent argument holds for the other vertices in the path.

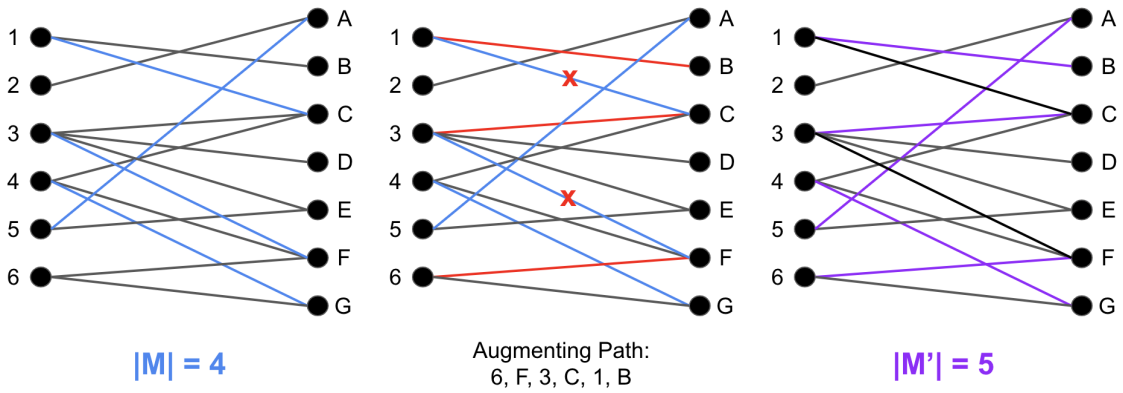
□

Example:

For example, we can run our maximum matching algorithm on the graph. We first consider the augmenting path $(G, 4)$ and grow our matching accordingly.



Next, we add the augmenting path $(6, F, 3, C, 1, B)$. Note that $\{3, F\}$ and $\{1, C\}$ are not in M', since they were part of the original matching M.



This suggests a natural algorithm for maximum matching: repeatedly try to find an augmenting path and use it to grow our matching. We will be able to make this idea work in *bipartite* graphs, like the donor–patient graphs in kidney exchange.

Definition 5.3. A graph $G = (V, E)$ is *bipartite* if it is 2-colorable. That is, there is a partition of vertices $V = V_0 \cup V_1$ (with $V_0 \cap V_1 = \emptyset$) such that all edges in E have one endpoint in V_0 and one endpoint in V_1.

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MaxMatchingAugPaths(G)
  Input  : A bipartite graph G = (V, E)
  Output : A maximum-size matching M ⊆ E
Remove isolated vertices from G;
Let V_0, V_1 be the bipartition (i.e. 2-coloring) of V;
M = ∅;
repeat
    Let U be the vertices unmatched by M, U_0 = V_0 ∩ U, U_1 = V_1 ∩ U;
    Try to find an augmenting path P that starts in U_0 and ends in U_1;
    if P ≠ ⊥ then augment M using P via Lemma 5.2;
until P = ⊥;
return M
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How do we know that augmenting paths always exist and how can we find them efficiently?

Theorem 5.4 (Berge's Theorem)**.** *Let $G = (V, E)$ be a graph, and $M \subseteq E$ be a matching. If (and only if) M is not a maximum-size matching, then G has an augmenting path with respect to M.*

Lemma 5.5. *Let $G = (V_0 \cup V_1, E)$ be bipartite and let M be a matching in G that is not of maximum size. Let U be the vertices that are not matched by M, and $U_0 = V_0 \cap U$ and $U_1 = V_1 \cap U$. Then:*

1. *G has an alternating walk with respect to M that starts in U_0 and ends in U_1.*
2. *Every shortest alternating walk from U_0 to U_1 is an augmenting path.*

Before proving these lemmas, let's see how they suffice for us to analyze the correctness and runtime of Algorithm 10.

Theorem 5.6. *Maximum Matching can be solved in time $O(mn)$ on bipartite graphs with m edges and n vertices.*

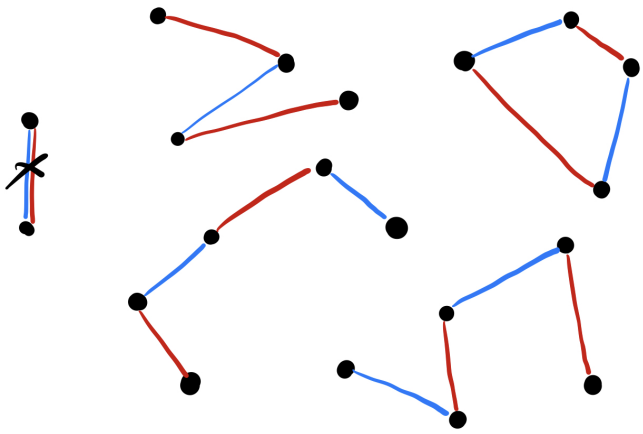
Proof.
Lemma 5.5 implies the correctness of Algorithm 10. If M is not a maximum matching, then there is an augmenting path from U_0 to U_1, which we will find and use to increase the size of M by 1. Since a matching can have at most $n/2$ edges, Algorithm 10 will always halt within $n/2$ iterations of the loop, and when it does, it will output a maximum-size matching (since no augmenting path from U_0 to U_1 exists).

For runtime, Lemma 5.5 implies that we can find augmenting paths by finding shortest alternating walks. An alternating walk is a special case of a 2-rotating walk (PS4), and thus a shortest alternating walk can be found in time $O(m)$. (After removing isolated vertices, we have $n \leq 2m$, so $O(n+m) = O(m)$.) Augmenting the matching M using the augmenting path P takes time $O(n) \leq O(m)$ by Lemma 5.2. Since we already argued that the loop is executed at most $n/2$ times, our total run time is $(n/2) \cdot O(m) = O(mn)$. □

6 Omitted Proofs

These proofs were not covered in lecture and are included here as optional reading, according to your interest.

Proof of Theorem 5.4.



Suppose we have a matching M and a larger matching M'. Then consider $G_\Delta = (V, M \Delta M')$ where $M \Delta M'$ contains the edges in *exactly one* of M and M'. Note that G_Δ has degree at most 2. This is since an edge has to come from M or M', and both of those have degree at most 1. Furthermore, every path or cycle in this graph alternates between edges in M and M'. Finally, at least one path must start and end with an edge in M'. This is because M' is bigger. Every cycle in G_Δ contains an equal number of edges from M and M', so there must be some path with more M' edges than M edges, and this is only possible if both endpoints are in M'. But this path is an augmenting path by definition, so we are done.

The "only if" part of Theorem5.4 follows from Lemma 5.2. □

Proof of Lemma 5.5.

1. By Theorem 5.4, we know that G has an augmenting path P, with vertices $v_0, v_1, \ldots, v_\ell$. Since v_0 and v_ℓ are unmatched, the edges $\{v_0, v_1\}$ and $\{v_{\ell-1}, v_\ell\}$ are not in M. Since the path is alternating between edges from $E - M$ and from M, the path must then be of odd length ℓ. Since paths in a bipartite graph alternate between V_0 and V_1, we have either $v_0 \in U_0$ and $v_1 \in U_1$ or $v_0 \in U_1$ and $v_1 \in U_0$. So either P or the reverse of P is an alternating walk starting in U_0 and ending in U_1.

2. Let W be a shortest alternating walk $v_0, v_1, \ldots, v_\ell$ with $v_0 \in U_0$ and $v_\ell \in U_1$. Assume for sake of contradiction that W has a repeated vertex, i.e. $v_i = v_j$ for some $i < j$. Since the graph is bipartite, $j - i$ must be even. Thus if we remove the vertices $v_{i+1}, \ldots, v_j$ from the W, the path W will still be alternating (since the portion we remove will either begin with M and end with $E - M$ or vice-versa), but will be of shorter length. This contradicts our hypothesis that W was a shortest alternating walk. Thus, our assumption that W has a repeated vertex must have been incorrect.

□

Note that this lemma is the only place where we used the assumption that the graph is bipartite.