

## Lecture 15: Logic

Harvard SEAS - Fall 2023

2023-10-26

## 1 Announcements

- Active Learning Exercise on Thursday. 3 more SREs, so everyone sender for 2/3.
- SEC trick-or-treat day this Friday 3pm-5pm

Recommended Reading (good for practice problems, too):

- Lewis-Zax Ch. 9–10.
- Roughgarden IV, Sec. 21.5, Ch. 24.

## 2 Propositional Logic

**Motivation:** Logic is a fundamental building block of computation (e.g. digital circuits), and is also a very expressive language for encoding computational problems we want to solve.

**Definition 2.1** (informal). A *boolean formula*  $\varphi$  is a formula built up from a finite set of variables, say  $x_0, \dots, x_{n-1}$ , using the logical operators  $\wedge$  (AND),  $\vee$  (OR), and  $\neg$  (NOT), and parentheses.

Every boolean formula  $\varphi$  on  $n$  variables defines a boolean function, which we'll abuse notation and also denote by  $\varphi : \{0, 1\}^n \rightarrow \{0, 1\}$ , where we interpret 0 as false and 1 as true, and give  $\wedge, \vee, \neg$  their usual semantics (meaning).

See the Lewis-Zax text for formal, inductive definitions of boolean formulas and the corresponding boolean functions.

**Examples:**

$$\varphi_{maj}(x_0, x_1, x_2) = (x_0 \wedge x_1) \vee (x_1 \wedge x_2) \vee (x_2 \wedge x_0)$$

is a boolean formula. It evaluates to 1 if at least two of its inputs are 1. For instance,  $\varphi_{maj}(1, 1, 0) = 1$  and  $\varphi_{maj}(1, 0, 0) = 0$ .

$$\varphi_{pal}(x_0, x_1, x_2, x_3) = ((x_0 \wedge x_3) \vee (\neg x_0 \wedge \neg x_3)) \wedge ((x_1 \wedge x_2) \vee (\neg x_1 \wedge \neg x_2))$$

is a boolean formula. It evaluates to 1 if the input  $x_0x_1x_2x_3$  is a palindrome.

**Definition 2.2.** A *literal* is a variable (e.g.  $x_i$ ) or its negation ( $\neg x_i$ ).

A boolean formula is in *disjunctive normal form (DNF)* if it is the OR of a sequence of *terms*, each of which is the AND of a sequence of literals.

A boolean formula is in *conjunctive normal form (CNF)* if it is the AND of a sequence of *clauses*, each of which is the OR of a sequence of literals.

Note terms and clauses may contain duplicate literals, but if a term or clause contains multiple copies of a variable  $x$ , it's equivalent to a term or clause with just one copy (since  $x \vee x = x$  and  $x \wedge x = x$ ). We can also remove any clause or term with both a variable  $x$  and its negation  $\neg x$ , as that clause or term will be always true (in the case of a clause) or always false (in the case of a term). We define a function `Simplify` which takes a clause and performs those simplifications: that is, given a clause  $B$ , `Simplify( $B$ )` removes duplicates of literals from clause  $B$ , and returns 1 if  $B$  contains both a literal and its negation. Also, if we have an order on variables (e.g.  $x_0, x_1, \dots$ ), `Simplify( $B$ )` also sorts the literals in order of their variables.

Also by convention, an empty term is always true and an empty clause is always false.

**Lemma 2.3.** *For every boolean function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , there are boolean formulas  $\varphi$  and  $\psi$  in DNF and CNF, respectively, such that  $f \equiv \varphi$  and  $f \equiv \psi$ , where we use  $\equiv$  to indicate equivalence as functions, i.e.  $f \equiv g$  iff  $\forall x : f(x) = g(x)$ .*

*Proof.* For a function  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , we can define the DNF

$$\varphi(x_0, \dots, x_{n-1}) = \bigvee_{\alpha \in \{0,1\}^n : f(\alpha)=1} ((x_0 = \alpha_0) \wedge (x_1 = \alpha_1) \wedge \dots \wedge (x_{n-1} = \alpha_{n-1})).$$

Note that  $x_i = \alpha_i$  can be rewritten as either  $x_i$  (with  $\alpha_i = 1$ ) or  $\neg x_i$  (with  $\alpha_i = 0$ ). For example, applying to the palindrome function on 4 bits, we get

$$\varphi(x_0, x_1, x_2, x_3) = (x_0 \wedge x_1 \wedge x_2 \wedge x_3) \vee (x_0 \wedge \neg x_1 \wedge \neg x_2 \wedge x_3) \vee (\neg x_0 \wedge x_1 \wedge x_2 \wedge \neg x_3) \vee (\neg x_0 \wedge \neg x_1 \wedge \neg x_2 \wedge \neg x_3),$$

where the terms correspond to the satisfying assignments  $(1, 1, 1, 1)$ ,  $(1, 0, 0, 1)$ ,  $(0, 1, 1, 0)$ , and  $(0, 0, 0, 0)$ .

For the CNF, we define

$$\psi(x_0, \dots, x_{n-1}) = \bigwedge_{\alpha \in \{0,1\}^n : f(\alpha)=0} ((x_0 \neq \alpha_0) \vee (x_1 \neq \alpha_1) \vee \dots \vee (x_{n-1} \neq \alpha_{n-1})).$$

For example, the majority function on 3 bits can be written as:

$$\psi(x_0, x_1, x_2) = (x_0 \vee x_1 \vee x_2) \wedge (\neg x_0 \vee x_1 \vee x_2) \wedge (x_0 \vee \neg x_1 \vee x_2) \wedge (x_0 \vee x_1 \vee \neg x_2),$$

with the clauses corresponding to the 4 non-satisfying assignments  $(0, 0, 0)$ ,  $(1, 0, 0)$ ,  $(0, 1, 0)$ ,  $(0, 0, 1)$ . This example shows that the DNF and CNF given by the general construction are not necessarily the smallest ones possible for a given function, as the majority function can also be expressed by the following simpler CNF formula:

$$(x_0 \vee x_1) \wedge (x_0 \vee x_2) \wedge (x_1 \vee x_2).$$

□

### 3 Computational Problems in Propositional Logic

<b>Input</b>	: A boolean formula $\varphi$ on $n$ variables
<b>Output</b>	: An $\alpha \in \{0, 1\}^n$ such that $\varphi(\alpha) = 1$ , or $\perp$ if no satisfying assignment exists

**Computational Problem** Satisfiability

It is common to restrict the boolean formulas to ones in CNF or DNF.

**Input** : A CNF formula  $\varphi$  on  $n$  variables  
**Output** : An  $\alpha \in \{0, 1\}^n$  such that  $\varphi(\alpha) = 1$ , or  $\perp$  if no satisfying assignment exists

**Computational Problem CNF-Satisfiability**

**Input** : A DNF formula  $\varphi$  on  $n$  variables  
**Output** : An  $\alpha \in \{0, 1\}^n$  such that  $\varphi(\alpha) = 1$ , or  $\perp$  if no satisfying assignment exists

**Computational Problem DNF-Satisfiability**

**One of these problems is algorithmically very easy. Which one?**

DNF satisfiability is easy - since we only need to satisfy a single term and then we are done, the only difficulties are when we have zero terms (in which case the problem is defined to be 0), or every term has a contradiction (both a variable and its negation). On the other hand, satisfiability can be reduced to CNF-satisfiability<sup>1</sup>, so when we say “SAT,” we refer to CNF-Satisfiability by default whenever it’s convenient.

## 4 Modelling using Satisfiability

One of the reasons for the importance of Satisfiability is its richness for encoding other problems. Thus any effort gone into optimizing algorithms for Satisfiability (aka “SAT Solvers”) can be easily be applied to other problems we want to solve.

**Theorem 4.1.** *Graph  $k$ -Coloring on graphs with  $n$  nodes and  $m$  edges can be reduced in time  $O(n + km)$  to SAT on CNF formulas with  $kn$  variables and  $n + km$  clauses.*

*Proof.*

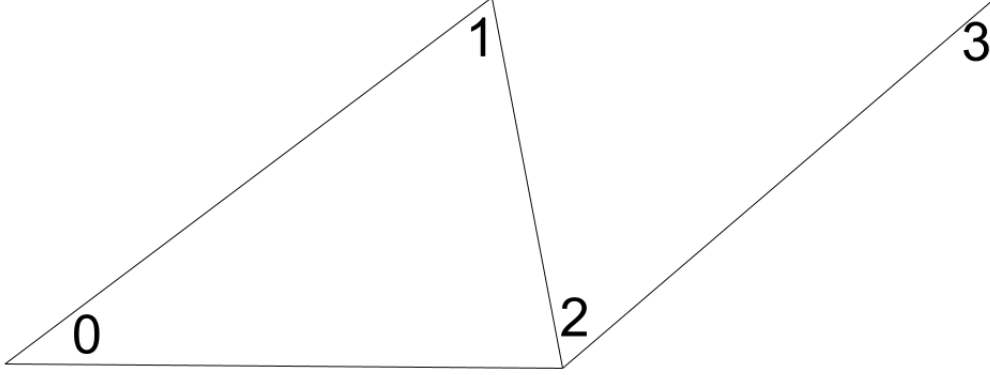
Given  $G = (V, E)$  and  $k \in \mathbb{N}$ , we will construct a CNF  $\phi_G$  that captures the graph  $k$ -coloring problem. In  $\phi_G$ , we construct variables  $x_{v,i}$  where  $v \in V$  and  $i \in [k]$ . Intuitively,  $x_{v,i}$  captures vertex  $v$  being assigned to color  $i$ . We then have a few types of clauses:

1.  $(x_{v,0} \vee x_{v,1} \vee \cdots \vee x_{v,k-1})$  for all  $v \in V$ . (Each vertex must be assigned a color)
2.  $(\neg x_{u,i} \vee \neg x_{v,i})$  for every edge  $\{u, v\} \in E$  and every color  $i \in [k]$ . From De Morgan’s Law, this is equivalent to the more intuitive  $\neg(x_{u,i} \wedge x_{v,i})$ . (The endpoints of an edge cannot be assigned the same color.)
3. In addition, we can require all vertices to be assigned at most one color (right now a valid solution could assign multiple colors). To avoid this, we can include clauses  $(\neg x_{v,i} \vee \neg x_{v,j})$  for  $i, j \in [k]$  where  $i \neq j$ . But we don’t actually need to include these, and doing so would increase the number of clauses to  $nk^2$ .

For instance, if  $G$  is the graph below,

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<sup>1</sup>If you want to try to figure out the reduction, we recommend looking at the Lewis-Zax text’s formal inductive definition of Boolean formulas.



then we make the following SAT instance  $\phi_G$ :

$$\begin{aligned}
& (x_{0,0} \vee x_{0,1} \vee x_{0,2}) \wedge (x_{1,0} \vee x_{1,1} \vee x_{1,2}) \wedge (x_{2,0} \vee x_{2,1} \vee x_{2,2}) \wedge (x_{3,0} \vee x_{3,1} \vee x_{3,2}) \wedge \\
& (\neg x_{0,0} \vee \neg x_{1,0}) \wedge (\neg x_{0,1} \vee \neg x_{1,1}) \wedge (\neg x_{0,2} \vee \neg x_{1,2}) \wedge \\
& (\neg x_{0,0} \vee \neg x_{2,0}) \wedge (\neg x_{0,1} \vee \neg x_{2,1}) \wedge (\neg x_{0,2} \vee \neg x_{2,2}) \wedge \\
& (\neg x_{2,0} \vee \neg x_{1,0}) \wedge (\neg x_{2,1} \vee \neg x_{1,1}) \wedge (\neg x_{2,2} \vee \neg x_{1,2}) \wedge \\
& (\neg x_{3,0} \vee \neg x_{1,0}) \wedge (\neg x_{3,1} \vee \neg x_{1,1}) \wedge (\neg x_{3,2} \vee \neg x_{1,2}) \wedge \\
& (\neg x_{2,0} \vee \neg x_{3,0}) \wedge (\neg x_{2,1} \vee \neg x_{3,1}) \wedge (\neg x_{2,2} \vee \neg x_{3,2})
\end{aligned}$$

We then run the SAT oracle on  $\phi_G$  and get an assignment  $\alpha$ . If  $\alpha = \perp$ , we say  $G$  is not  $k$ -colorable. Otherwise, we construct and output the coloring

$$f_\alpha = \min\{i \in [k] : \alpha_{v,i} = 1\}.$$

(The minimum is just being used to pick out one of the colors  $i$  such that  $\alpha_{v,i} = 1$  in case there are multiple, since we didn't include Clauses of Type 3.)

The runtime essentially follows from our description. If we start by removing isolated vertices (i.e. those with no adjacent edges), we have  $n' \leq 2m$  actual vertices under consideration in our SAT clause, and so have a runtime of  $O(n) + O(n'k) + O(mk) = O(n + km)$ .

For correctness, we make two claims:

**Claim 4.2.** *If  $G$  has a valid  $k$  coloring,  $\phi_G$  is satisfiable.*

$\implies$  don't incorrectly output  $\perp$ .

**Claim 4.3.** *If  $\alpha$  satisfies  $\phi_G$ , then  $f_\alpha$  is a proper  $k$ -coloring of  $G$ .*

$\implies$  if we output a coloring, it will be proper.

Both of these claims are worth checking. Note that  $f_\alpha$  is *well-defined* because  $\alpha$  satisfies clauses of type 1 and is *proper* due to clauses of type 2.

□

Unfortunately, the fastest known algorithms for Satisfiability have worst-case runtime exponential in  $n$ . However, enormous effort has gone into designing heuristics that complete much more quickly on many real-world instances. In particular, SAT Solvers—with many additional optimizations—were used to solve large-scale graph coloring problems arising in the 2016 US Federal Communications Commission (FCC) auction to reallocate wireless spectrum. Roughly, those instances had  $k = 23$  (corresponding to UHF channels 14–36),  $n$  in the thousands (corresponding to television stations being reassigned to one of the  $k$  channels),  $m$  in the tens of thousands (corresponding to pairs of stations with overlapping broadcast areas — similarly to how you are viewing interval scheduling on ps7). Over the course of the one-year auction, tens of thousands of coloring instances were produced, and roughly 99% of them were solved within a minute!

Thus motivated, we will now turn to algorithms for Satisfiability, to get a taste of some of the ideas that go into SAT Solvers.