

12345

SYSTEM INTEGRATION DIAGRAM (SID)

* FLUID POWER IS NOT USED

Anderson Powerpole
(MATE Power Supply)

SW1
Emergency Stop

Power Meter

DC-DC Converter

LX200V20EVB Topside

12V IN

12V OUT

7V OUT

7V IN

0FDM

110VAC

Monitor PSU

Monitor

Computer PSU

Computer

Controller

Router

TETHER

IP Camera 1

LX200V20EVB Aquatic

MUREX Power Board

Murata DCDC

MUREX ESC Carrier

MUREX ESCs 8x

Blue Robotics T200 8x

IP Camera 2

MUREX Ethernet Switch

MUREX Carrier Board

USB Camera

M4 Servo

M3 Servo

M2 Servo

M1 Servo

USB

5VDC

GND

UART (MASCP)

BLDC Phases

Wireless

7VDC

110VAC

PSUs DC

12VDC

Ethernet

3.3VDC

PWM

ELEC-008R Requirements

8 thrusters	2.5A each = 20A
3 cameras	0.2A each = 0.6A
8 ESCs	0.05A each = 0.4A
1 ethernet switch	0.1A = 0.1A
1 control board	0.2A = 0.2A
4 servos	0.8A each = 3.2A
2 PLC modules	0.1A each = 0.2A
Total Amps	24.7A * 150% = 37.1A
Fuse Selected:	25A ATO

SID Legend

110VAC	USB
PSUs DC	5VDC
12VDC	GND
Ethernet	UART (MASCP)
3.3VDC	BLDC Phases
PWM	Wireless
	7VDC

MUREX ROV V3
SYSTEM INTEGRATION DIAGRAM (SID)

MUREX ROBOTICS

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File: SID.kicad_sch

Title: System Integration Diagram

Size: User	Date: 2024-05-11	Rev: V3
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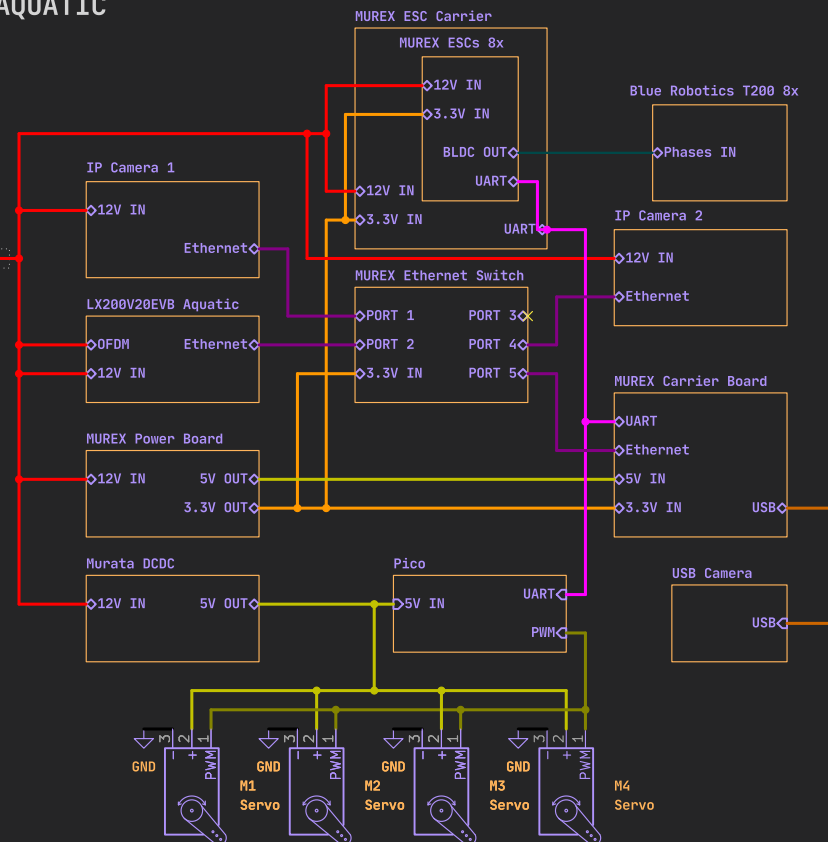
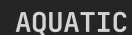
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2 PLC modules	0.1A each = 0.2A

Total Amps $24.7A * 150\% = 37.1A$

Fuse Selected: 25A AT0

110VAC	5VDC
PSUs DC	GND
12VDC	UART (MASCSP)
Ethernet	BLDC Phases
3.3VDC	Wireless
PWM	7VDC



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