

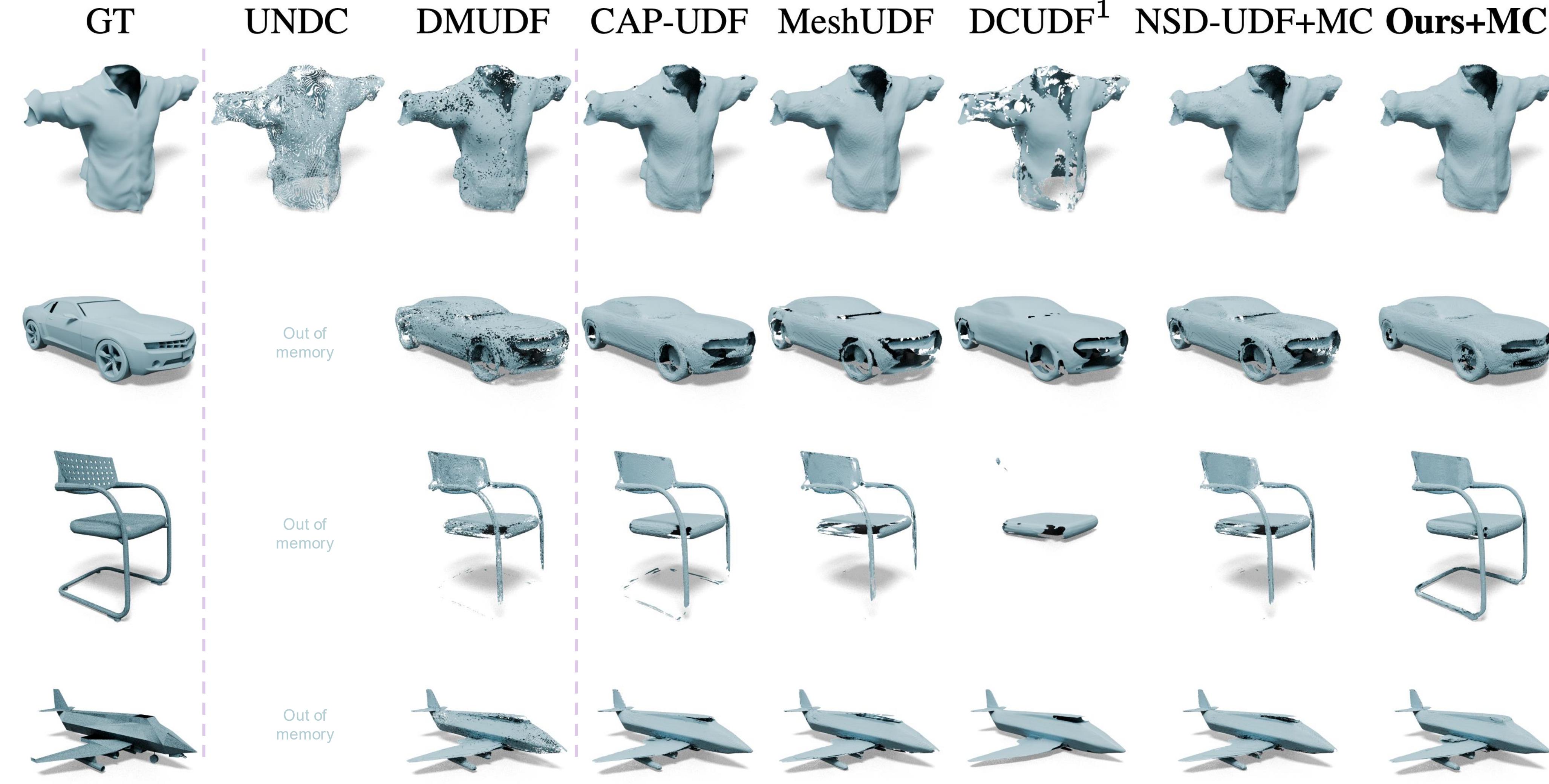
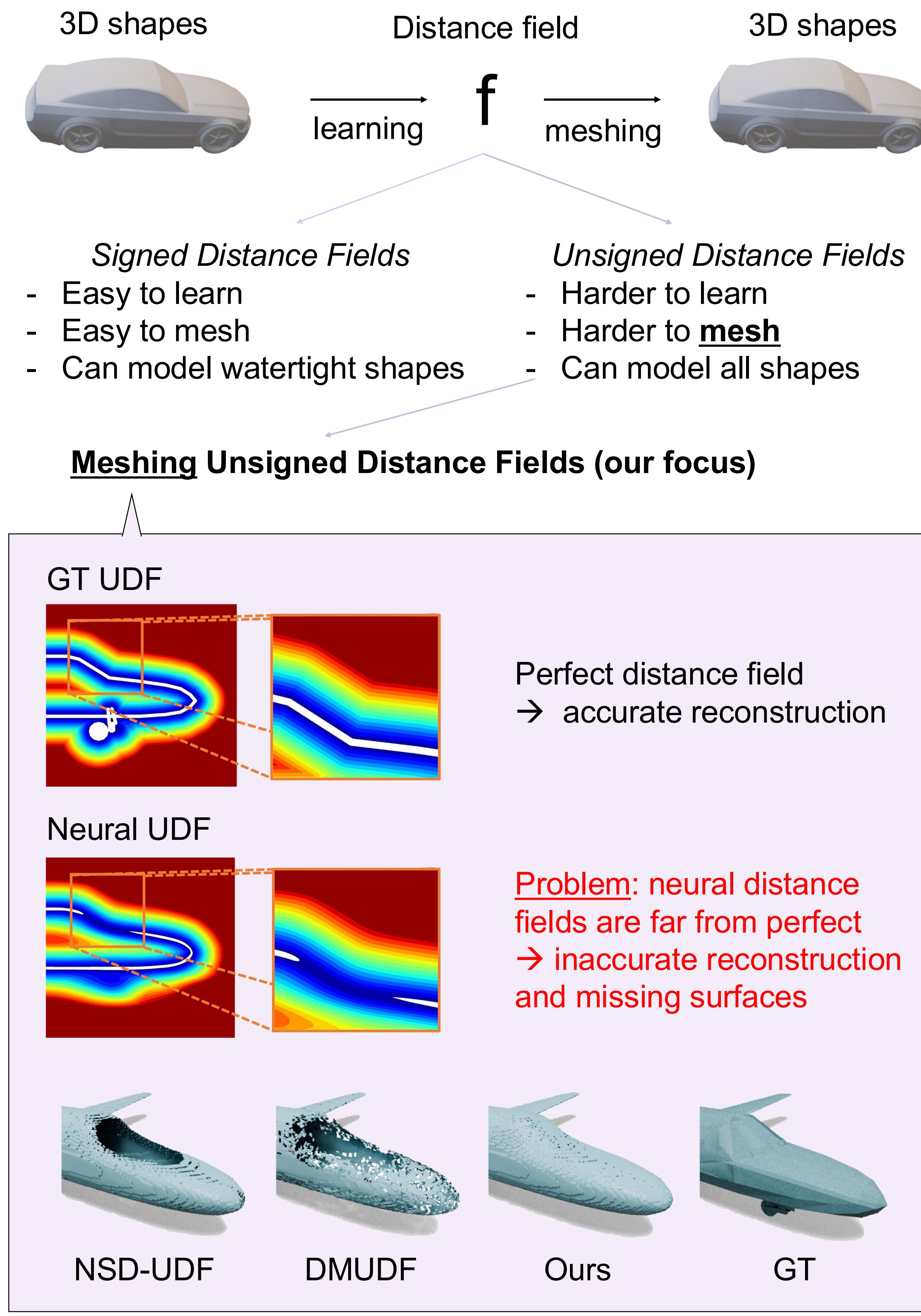
# High Resolution UDF Meshing via Iterative Networks

Federico Stella<sup>1</sup>, Nicolas Talabot<sup>1</sup>, Hieu Le<sup>2</sup>, and Pascal Fua<sup>1</sup>

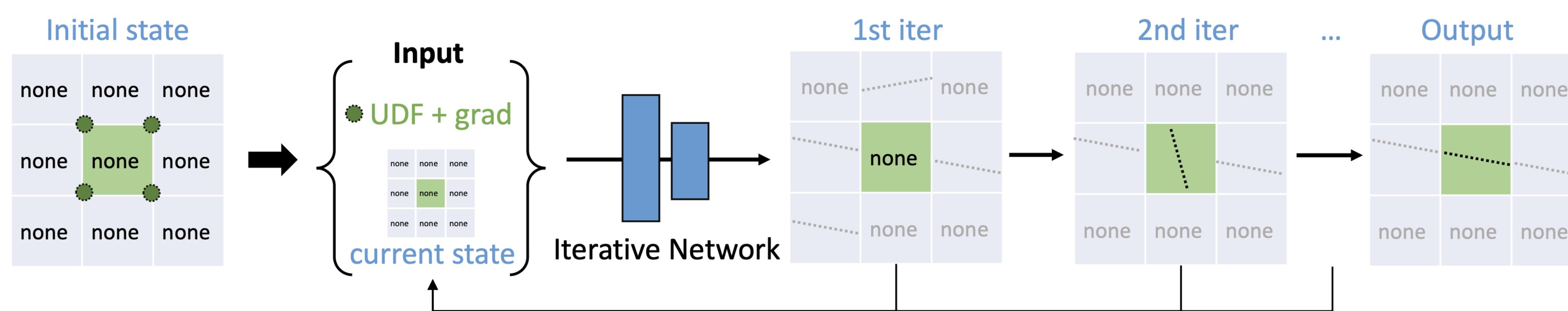
<sup>1</sup>EPFL, <sup>2</sup> UNC-Charlotte



## 1. Meshing Unsigned Distance Fields

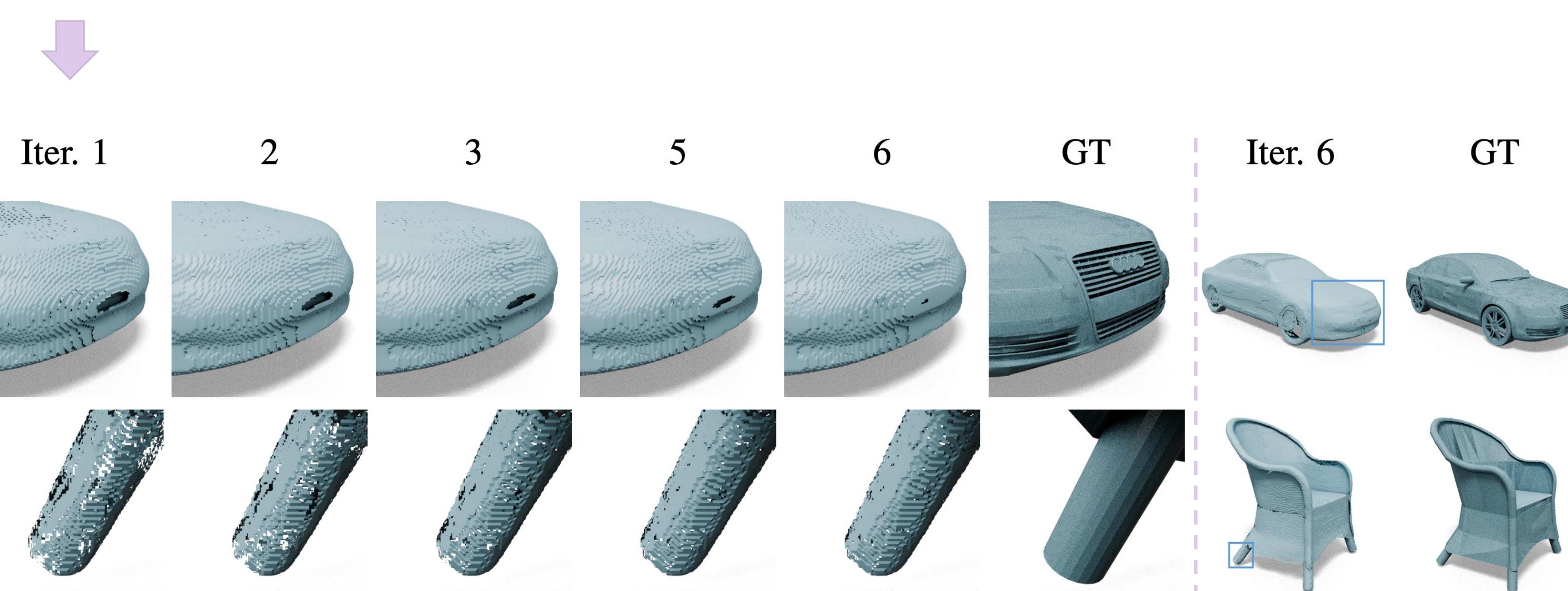


## 3. Proposed Method



- We formulate high-resolution meshing as an iterative process: each iteration takes the previous output state as input and refines it
- The mesh is improved over multiple iterations, where each step integrates newly detected surfaces, distance values, and gradients from neighboring cells

$$\begin{aligned} \mathbf{y}_{S,c}^{(i)} &= f_{\theta} \left( U_S(c), \nabla U_S(c), \sigma(\mathbf{y}_{S,N_c}^{(i-1)}) \right), \\ \mathbf{y}_{S,N_c}^{(i-1)} &= \parallel_{c' \in N_c} \mathbf{y}_{S,c'}^{(i-1)}, \\ \mathbf{y}_{S,c}^{(0)} &= [0, 0, \dots, 0], \end{aligned}$$



## 4. Results

### a) MC-based methods

Res.	Method	MGN <sup>2</sup>			ShapeNet cars			ShapeNet chairs			ShapeNet planes		
		CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑
128	CAP-UDF	16.2	69.4	70.4	33.9	51.3	85.2	37.8	50.9	70.3	14.0	69.5	80.6
	MeshUDF	2.45	82.9	94.1	11.3	57.7	88.6	7.43	67.6	88.0	6.82	6.82	81.0
	DCUDF	13500	2.50	6580	7.74	14.7	17000	15.9	13.9	1880	27.6	24.5	
	DCUDF	90.8	2.86	87.3	50.3	58.0	87.3	2104	64.1	82.9	144	68.8	77.2
	DCUDF-T	1.44	83.9	94.7	6.7	59.6	88.5	6.11	67.8	88.4	3.00	79.5	84.8
	NSD-UDF+MC	2.04	81.9	94.1	5.64	59.6	88.5	3.68	66.7	88.4			
256	CAP-UDF	1.66	86.8	91.8	34.0	61.2	87.6	114	70.5	82.0	5.50	83.7	85.4
	MeshUDF	0.958	89.7	95.0	13.6	62.3	88.6	27.8	72.9	87.3	3.47	85.8	85.2
	DCUDF	14400	4.76	3.71	346	52.6	78.2	3530	49.9	54.3	27.9	84.7	82.0
	DCUDF-T	4.65	86.8	95.4	347	52.6	78.2	3560	50.0	54.3	47.8	84.7	
	DCUDF-T	1.000	90.0	95.2	5.23	65.0	89.2	10.9	72.3	85.2	2.91	87.3	86.0
	Ours + MC	0.878	88.9	94.9	5.23	65.0	89.2	5.14	72.8	88.8	1.84	87.0	
512	CAP-UDF	0.872	90.6	94.6	31.8	61.7	87.5	63.9	71.7	82.0	5.94	87.5	86.2
	MeshUDF	0.798	90.6	95.0	21.6	68.1	95.2	34.4	45.5	79.0	12.1	9.6	84.6
	DCUDF	4.37	88.3	91.1	22.5	56.5	84.2	295	55.0	70.1	48.7	85.5	82.2
	DCUDF-T	4.38	88.2	91.1	223	56.5	84.2	200	55.0	70.1	63.5	85.4	81.3
	DCUDF-T	0.784	90.8	94.8	4.3	60.4	85.6	29	64.7	75.7	10.0	89.4	85.1
	Ours + MC	0.722	90.6	94.8	8.84	65.6	88.9	8.76	74.5	87.2	2.37	90.9	87.1

### b) DC-based methods

Res.	Method	MGN <sup>2</sup>			ShapeNet cars			ShapeNet chairs			ShapeNet planes		
		CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑	CD ↓	FI ↑	IC ↑
128	UND	1.09	90.6	94.1	13.5	61.7	86.4	29.9	69.4	81.9	2.50	82.0	86.1
	DualMesh-UDF	216	68.1	68.4	952	34.4	45.5	79.0	12.1	9.08	11.2	74.3	76.1
	NSD-UDF+DualMesh-UDF	0.806	89.9	95.4	5.56	63.5	89.5	5.34	75.1	89.1	1.96	84.3	87.5
	Ours + DualMesh-UDF	0.787	90.5	94.9	4.80	66.2	89.7	3.79	72.8	88.9	1.56	87.7	88.2
	UND	0.931	89.1	91.5	82.4	52.3	71.4	29.3	54.2	57.8	11.6	83.6	80.7
	DualMesh-UDF	0.772	91.2	95.1	10.6	64.1	87.0	22.8	72.2	84.1	2.43	88.2	87.0
256	NSD-UDF+DualMesh-UDF	0.816	90.3	95.0	4.93	64.5	89.0	4.93	72.6	88.9	2.93	87.6	85.6
	UND	2.39	84.8	82.8	-	-	-	8190	11.8	9.07	11.1	77.6	74.2
	DualMesh-UDF	167	63.7	63.9	870	32.5	43.0	870	63.7	72.2	4.77	88.9	84.0
	NSD-UDF+DualMesh-UDF	0.827	90.2	93.2	37.8	58.3	79.2	72.7	63.7	72.2	2.01	88.7	85.3
	Ours + DualMesh-UDF	0.726	89.7	92.8	9.65	63.0	85.6	10.1	70.4	81.9	2.51	90.1	88.8
	UND	1.09	87.1	94.1	13.5	61.7	86.4	29.9	69.4	81.9	2.50	82.0	86.1
512	UND	1.09	87.1	94.1	13.5	61.7	86.4	29.9	69.4	81.9	2.50	82.0	86.1
	DualMesh-UDF	0.722	91.2	95.1	10.6	64.1	87.0	22.8	72.2	84.1	2.43	88.2	87.0
	NSD-UDF+DualMesh-UDF	0.827	90.2	93.2	37.8	58.3	79.2	72.7	63.7	72.2	2.01	88.7	85.3
	Ours + DualMesh-UDF	0.726	89.7	92.8	9.65	63.0	85.6	10.1	70.4	81.9	2.51	90.1	88.8

### c) Filtering strategies and speed

Res.	Filtering	Inference time ↓		
		CD ↓	IC ↑	Inference time ↓
256	Without filtering	5.26	89.2	7m
	Low confidence	5.24	89.2	1.5m
	UDF < 0.1 and low confidence	5.24	89.2	30s
512	Without filtering	8.91	88.9	