

EE401: Advanced Communication Theory

Professor A. Manikas
Chair of Communications and Array Processing

Imperial College London

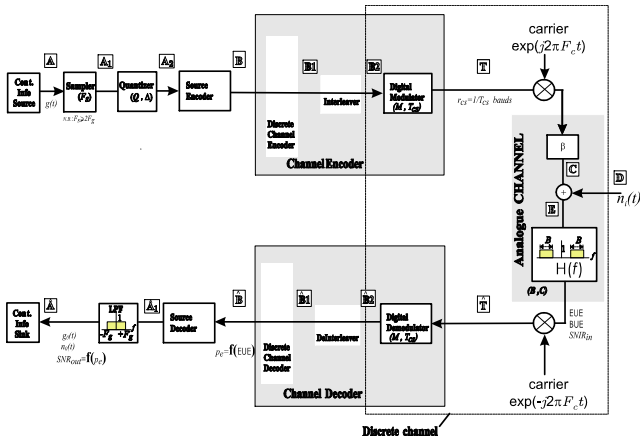
Introductory Concepts

Table of Contents

- 1 Introduction
- 2 Communication Channels: Continuous and Discrete
 - Continuous Channels
 - Discrete Channels
- 3 Communication Systems - Block Diagrams
- 4 Digital Modulators/Demodulators
- 5 Appendices
 - A: Comm Systems: Basic Performance Criteria
 - B: Additive Noise
 - Additive White Gaussian Noise (AWGN)
 - Bandlimited AWGN
 - "I" and "Q" Noise Components
 - Tail function (or Q-function) for Gaussian Signals
 - C: Tail Function Graph
 - D: Fourier Transform Tables

Introduction

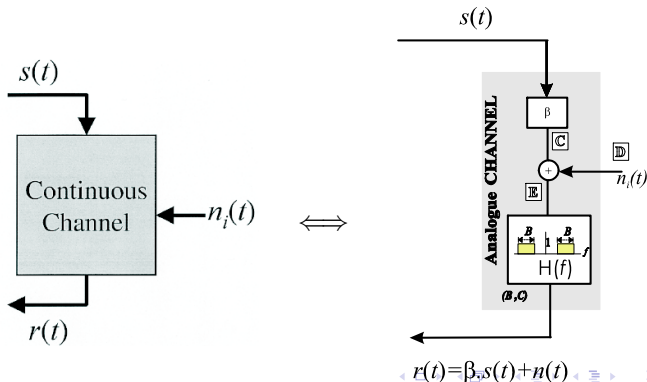
With reference to the following block structure of a Dig. Comm. System (DCS), this topic is concerned with the basics of both continuous and discrete communication channels.



- Just as with sources, communication channels are either
 - ▶ discrete channels, or
 - ▶ continuous channels
 - ① wireless channels (in this case the whole DCS is known as a Wireless DCS)
 - ② wireline channels (in this case the whole DCS is known as a Wireline DCS)
- Note that a continuous channel is converted into (becomes) a discrete channel when a **digital modulator** is used to feed the channel and a **digital demodulator** provides the channel output.
- Examples of channels - with reference to DCS shown in previous page,
 - ▶ discrete channels:
 - ★ input: A_2 - output: \hat{A}_2 (alphabet: levels of quantiser - Volts)
 - ★ input: B_2 - output: \hat{B}_2 (alphabet: binary digits or binary codewords)
 - ▶ continuous channels:
 - ★ input: A_1 - output: \hat{A}_1 , (Volts) - continuous channel (baseband)
 - ★ input: T , - output: \hat{T} (Volts) - continuous channel (baseband),
 - ★ input: T_1 - output: \hat{T}_1 (Volts) - continuous channel (bandpass).

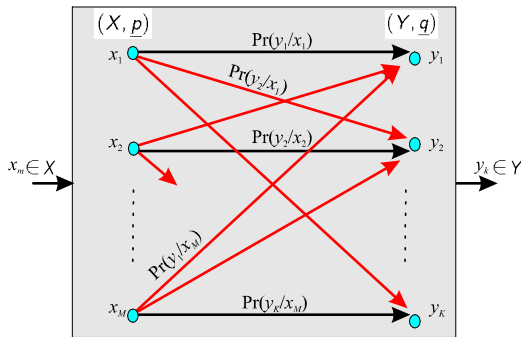
Continuous Channels

- A continuous communication channel (which can be regarded as an analogue channel) is described by
 - ▶ an input ensemble $(s(t), \text{pdf}_s(s))$ and $\text{PSD}_s(f)$
 - ▶ an output ensemble, $(r(t), \text{pdf}_r(r))$
 - ▶ the channel noise (AWGN) $n_i(t)$ and β ,
 - ▶ the channel bandwidth B and channel capacity C .



Discrete Channels

- A discrete communication channel has a discrete input and a discrete output where
 - ▶ the symbols applied to the channel input for transmission are drawn from a finite alphabet, described by an input ensemble (X, \underline{p}) while
 - ▶ the symbols appearing at the channel output are also drawn from a finite alphabet, which is described by an output ensemble (Y, \underline{q})
 - ▶ the channel transition probability matrix \mathbb{F} .

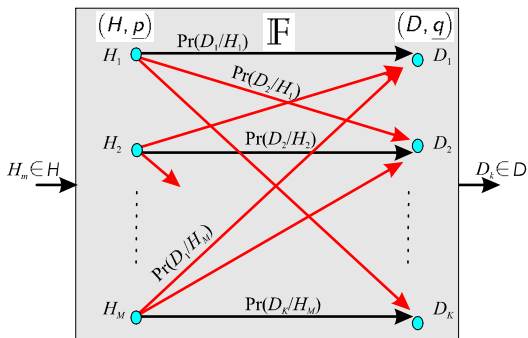


- In many situations the input and output alphabets X and Y are identical but in the general case these are different. Instead of using X and Y , it is common practice to use the symbols H and D and thus define the two alphabets and the associated probabilities as

$$\begin{aligned} \text{input:} \quad H &= \{H_1, H_2, \dots, H_M\} & \underline{p} &= [\overbrace{\Pr(H_1)}^{\triangleq p_1}, \overbrace{\Pr(H_2)}^{\triangleq p_2}, \dots, \overbrace{\Pr(H_M)}^{\triangleq p_M}]^T \\ \text{output:} \quad D &= \{D_1, D_2, \dots, D_K\} & \underline{q} &= [\overbrace{\Pr(D_1)}^{\triangleq q_1}, \overbrace{\Pr(D_2)}^{\triangleq q_2}, \dots, \overbrace{\Pr(D_K)}^{\triangleq q_K}]^T \end{aligned}$$

where p_m abbreviates the probability $\Pr(H_m)$ that the symbol H_m may appear at the input while q_k abbreviates the probability $\Pr(D_k)$ that the symbol D_k may appear at the output of the channel.

- The probabilistic relationship between input symbols H and output symbols D is described by the so-called channel transition probability matrix \mathbb{F} , which is defined as follows:



$$\mathbb{F} = \begin{bmatrix} \Pr(D_1|H_1), & \Pr(D_1|H_2), & \dots, & \Pr(D_1|H_M) \\ \Pr(D_2|H_1), & \Pr(D_2|H_2), & \dots, & \Pr(D_2|H_M) \\ \dots, & \dots, & \dots, & \dots \\ \Pr(D_K|H_1), & \Pr(D_K|H_2), & \dots, & \Pr(D_K|H_M) \end{bmatrix} \quad (1)$$

- $\Pr(D_k|H_m)$ denotes the probability that symbol $D_k \in D$ will appear at the channel output, given that $H_m \in H$ was applied to the input.
- The input ensemble (H, \underline{p}) , the output ensemble (D, \underline{q}) and the matrix \mathbb{F} fully describe the functional properties of the channel.
- The following expression describes the relationship between \underline{q} and \underline{p}

$$\underline{q} = \mathbb{F} \cdot \underline{p} \quad (2)$$

- Note that in a **noiseless channel**

$$D = H \quad (3)$$

$$\underline{q} = \underline{p}$$

i.e the matrix \mathbb{F} is an identity matrix

$$\mathbb{F} = \mathbb{I}_M \quad (4)$$

Joint transition Probability Matrix

- The joint probabilistic relationship between input channel symbols $H = \{H_1, H_2, \dots, H_M\}$ and output channel symbols $D = \{D_1, D_2, \dots, D_M\}$, is described by the so-called joint-probability matrix,

$$\mathbb{J} \triangleq \begin{bmatrix} \Pr(H_1, D_1), & \Pr(H_1, D_2), & \dots, & \Pr(H_1, D_K) \\ \Pr(H_2, D_1), & \Pr(H_2, D_2), & \dots, & \Pr(H_2, D_K) \\ \dots, & \dots, & \dots, & \dots \\ \Pr(H_M, D_1), & \Pr(H_M, D_2), & \dots, & \Pr(H_M, D_K) \end{bmatrix}^T \quad (5)$$

- \mathbb{J} is related to the forward transition probabilities of a channel with the following expression (compact form of Bayes' Theorem):

$$\mathbb{J} = \mathbb{F} \cdot \underbrace{\begin{bmatrix} p_1 & 0 & \dots & 0 \\ 0 & p_2 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & p_M \end{bmatrix}}_{\triangleq \text{diag}(\underline{p})} = \mathbb{F} \cdot \text{diag}(\underline{p}) \quad (6)$$

- Note: This is equivalent to a new (joint) source having alphabet

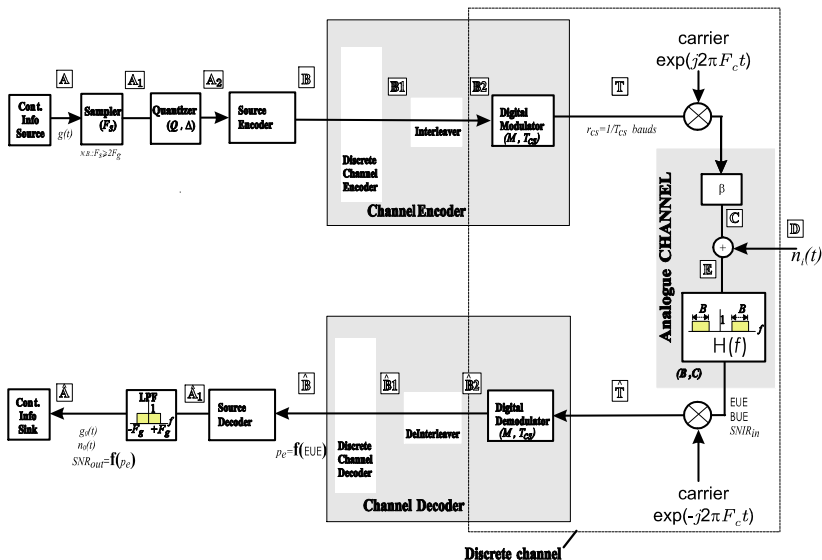
$$\{(H_1, D_1), (H_1, D_2), \dots, (H_M, D_K)\}$$

and ensemble (joint ensemble) defined as follows

$$(H \times D, \mathbb{J}) = \left\{ \begin{array}{l} (H_1, D_1), \Pr(H_1, D_1) \\ (H_1, D_2), \Pr(H_1, D_2) \\ \dots \\ (H_m, D_k), \Pr(H_m, D_k) \\ \dots \\ (H_M, D_K), \Pr(H_M, D_K) \end{array} \right\} \quad (7)$$

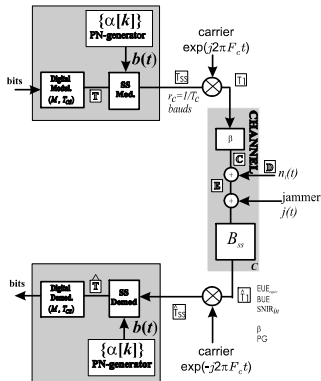
$$= \left\{ \left((H_m, D_k), \underbrace{\Pr(H_m, D_k)}_{=J_{km}} \right), \forall mk : 1 \leq m \leq M, 1 \leq k \leq K \right\}$$

Block Structure of a Digital Comm System

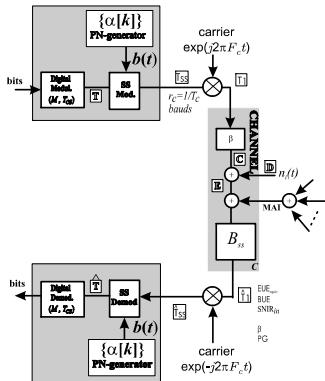


Block Structure of a Spread Spectrum Comm System

SSS:

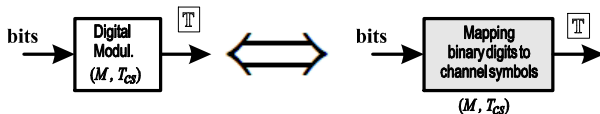


CDMA:

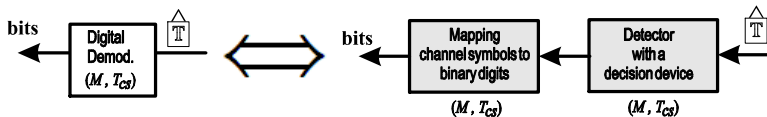


Digital Modulators/Demodulators

- A digital modulator is described by M **different channel symbols**. These channel symbols are **ENERGY SIGNALS** of duration T_{cs} .
- Digital Modulator:

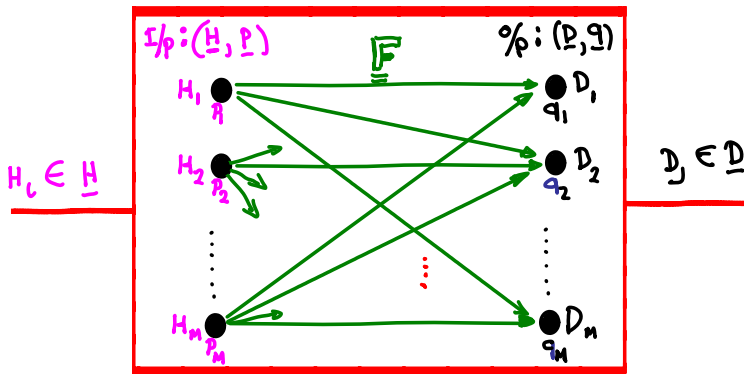


Digital Demodulator:

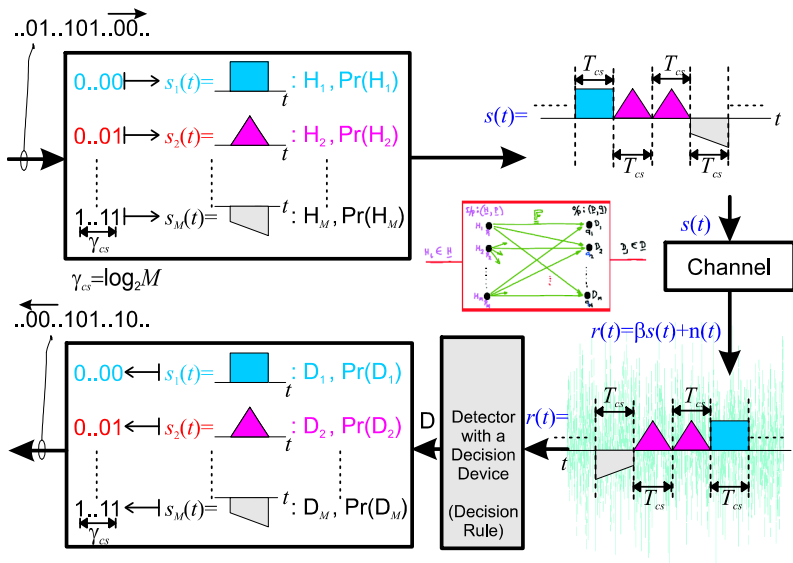


- Note:
It is common practice to ignore the up/down conversion and to work in 'baseband'.

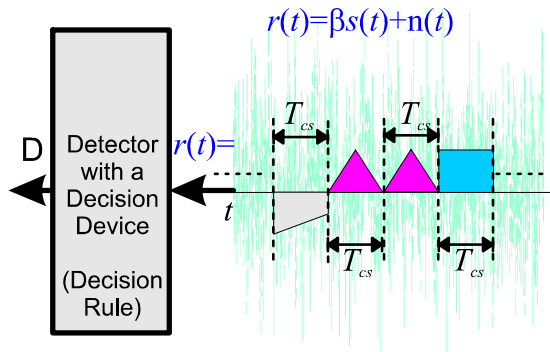
- If $M = 2 \Rightarrow$ **Binary** Digital Modulator \Rightarrow **Binary** Comm. System
- If $M > 2 \Rightarrow$ **M-ary** Digital Modulator \Rightarrow **M-ary** Comm. System



- Note: A continuous channel is converted into (becomes) a discrete channel when a **digital modulator** is used to feed the channel and a **digital demodulator** provides the channel output.

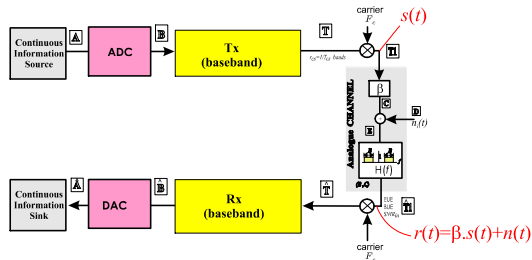


- In this topic we will focus on the following block of a digital communication system ($\beta = 1$ is assumed):



This is the **'heart'** of a communication system and some elements of detection/decision theory will be employed for its investigation.

Appendices - A: Basic Performance Criteria



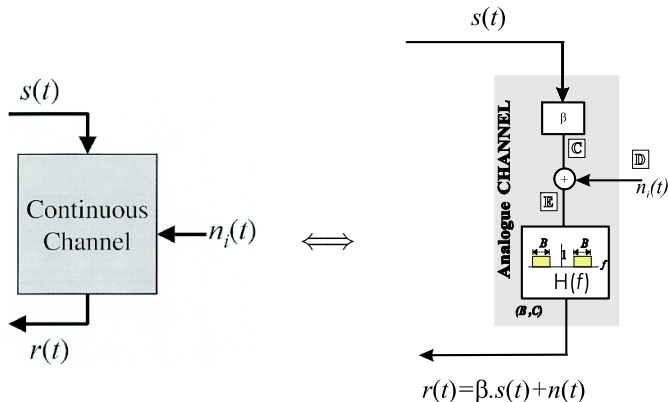
$$\text{SNR}_{in} = \frac{\text{Power of signal at } \hat{T}}{\text{Power of noise at } \hat{T}} = \frac{\mathcal{E} \{ (\beta s(t))^2 \}}{\mathcal{E} \{ n(t)^2 \}} = \frac{\beta^2 P_s}{\underbrace{N_0 B}_{\triangleq P_n}} \quad (8)$$

$$p_e = \text{BER at point } \hat{B} \quad (9)$$

$$\text{SNR}_{out} = \frac{\text{Power of signal at } \hat{A}}{\text{Power of noise at } \hat{A}} = \underbrace{f\{p_e\}} \quad (10)$$

denotes: a function of p_e

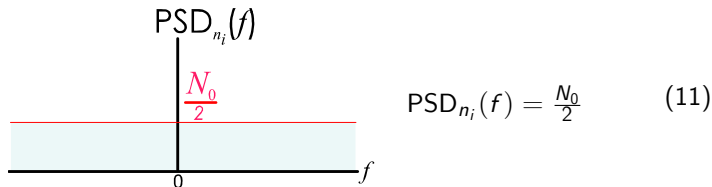
B: Additive Noise



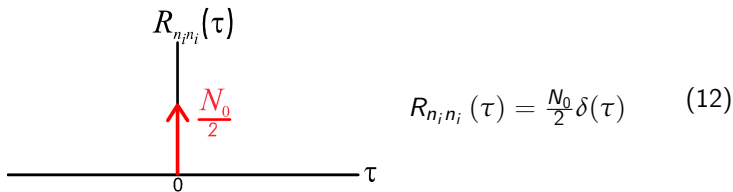
- types of channel signals
 - $s(t), r(t), n(t)$: bandpass
 - $n_i(t) = \text{AWGN}$: allpass

• $n_i(t)$

- ▶ it is a random all-Pass signal
- ▶ its Power Spectral Density is "White" i.e. "flat". That is,



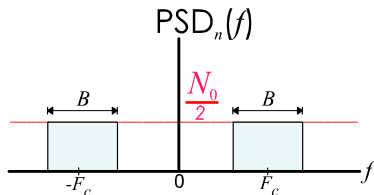
- ▶ its amplitude probability density function is Gaussian
- ▶ its Autocorrelation function (i.e. $\text{FT}^{-1} \{ \text{PSD}(f) \}$) is:



Bandlimited AWGN

• $n(t)$

- ▶ it is a random Band-Pass signal of bandwidth B (equal to the channel bandwidth)
- ▶ its Power Spectral Density is "bandlimited White". That is,



$$PSD_{n_i}(f) = \frac{N_0}{2} \left(\text{rect} \left\{ \frac{f + F_c}{B} \right\} + \text{rect} \left\{ \frac{f - F_c}{B} \right\} \right) \quad (13)$$

- ▶ Its power is:

$$\begin{aligned} P_n &= \sigma_n^2 = \int_{-\infty}^{\infty} PSD_{n_i}(f) \cdot df = \frac{N_0}{2} \times B \times 2 \\ \Rightarrow P_n &= N_0 B \end{aligned} \quad (14)$$

- more on $n(t)$:

- its amplitude probability density function is Gaussian

$$\text{pdf}_n = \mathcal{N}(0, \sigma_n^2 = N_0 B) \quad (15)$$

- It is also known as **bandlimited-AWGN**
- It can be written as follows:

$$n(t) = n_c(t) \cos(2\pi F_c t) - n_s(t) \sin(2\pi F_c t) \quad (16)$$

$$= \underbrace{\sqrt{n_c^2(t) + n_s^2(t)}}_{\triangleq r_n(t)} \cos(2\pi F_c t + \phi_n(t)) \quad (17)$$

where

- ★ $n_c(t)$ and $n_s(t)$ are random signals - with pdf=Gaussian distribution
- ★ $r_n(t)$ is a random signal - with pdf=Rayleigh distribution
- ★ $\phi_n(t)$ is a random signal - with pdf=uniform distribution: $[0, 2\pi]$

N.B.: all the above are low pass signals & appear at Rx's o/p

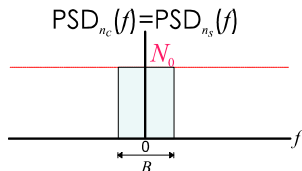


- Equ. 16 is known as **Quadrature Noise Representation**.

"I" and "Q" Noise Components

- $n_c(t)$ (i.e. "I") and $n_s(t)$ (i.e. "Q")

- ▶ their Power Spectral Densities are:



$$PSD_{n_c}(f) = PSD_{n_s}(f) = N_0 \text{rect} \left\{ \frac{f}{B} \right\} \quad (18)$$

- ▶ their power are:

$$\begin{aligned} P_{n_c} &= \sigma_{n_c}^2 = \int_{-\infty}^{\infty} PSD_{n_c}(f).df = N_0 \times B \\ \Rightarrow P_{n_c} &= P_{n_s} = P_n = N_0 B \end{aligned} \quad (19)$$

- ▶ Amplitude probability density functions: Gaussian,

$$\text{pdf}_{n_c} = \text{pdf}_{n_s} = \mathcal{N}(0, N_0 B) \quad (20)$$

- ▶ are uncorrelated i.e. $\mathcal{E} \{n_c(t).n_s(t)\} = 0$

Tail function (or Q-function) for Gaussian Signals

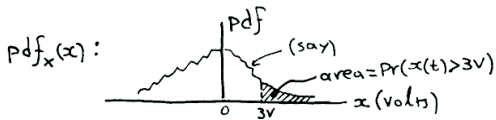
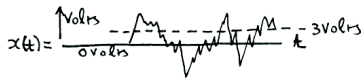
Probability and Probability-Density-Function (pdf)

- Consider a random signal $x(t)$ with a known amplitude probability density function $\text{pdf}_x(x)$ - not necessarily Gaussian. Then the probability that the amplitude of $x(t)$ is greater than A Volts (say) is given as follows:

$$\Pr(x(t) > A) = \int_A^{\infty} \text{pdf}_x(x) \cdot dx \quad (21)$$

- e.g.

if $A = 3V \Rightarrow \Pr(x(t) > 3V) = \int_3^{\infty} \text{pdf}_x(x) \cdot dx = \text{highlighted area}$



Gaussian pdf and Tail function

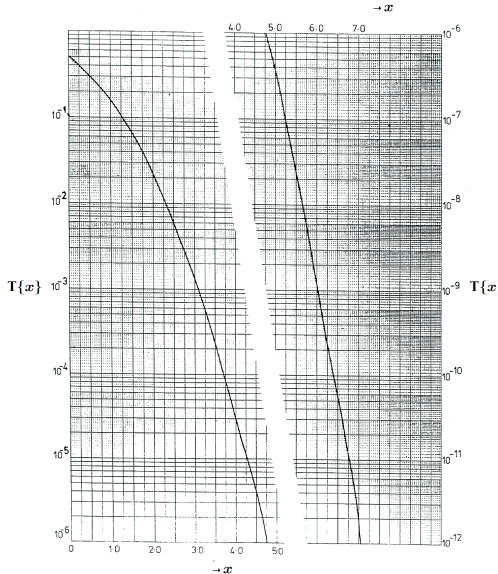
- If $\text{pdf}_x(x) = \text{Gaussian of mean } \mu_x \text{ and standard deviation } \sigma_x$
(notation used: $\text{pdf}_x(x) = N(\mu_x, \sigma_x^2)$), then the above area is defined
as the Tail-function (or Q-function)

$$\Pr(x(t) > A) = \int_A^{\infty} \text{pdf}_x(x).dx \triangleq T\left\{\frac{|A - \mu_x|}{\sigma_x}\right\} \quad (22)$$

- e.g.
 - ▶ if $\text{pdf}_x(x) = N(1, 4)$ - i.e. $\mu_x = 0, \sigma_x = 2$ - and $A = 3V$
then $\Pr(x(t) > 3V) = \int_3^{\infty} \text{pdf}_x(x).dx \triangleq T\left\{\frac{|3-1|}{2}\right\} = T\{1\}$
 - ▶ if $\text{pdf}_x(x) = N(0, 1)$ and $A = 3V$
then $\Pr(x(t) > 3V) = \int_3^{\infty} \text{pdf}_x(x).dx \triangleq T\{3\}$
- The Tail function graph is given in the next page

The graph below shows the Tail function $T\{x\}$ which represents the area from x to ∞ of the Gaussian probability density function $N(0,1)$, i.e.

$$T\{x\} = \int_x^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{y^2}{2}\right) dy$$



Note that if $x > 6.5$ then $T\{x\}$ may be approximated by $T\{x\} \approx \frac{1}{\sqrt{2\pi} \cdot x} \exp\left\{-\frac{x^2}{2}\right\}$

Fourier Transform Tables

| | Description | Function | Transformation |
|----|-----------------------------|---|--|
| 1 | Definition | $g(t)$ | $G(f) = \int_{-\infty}^{\infty} g(t) \cdot e^{-j2\pi ft} dt$ |
| 2 | Scaling | $g\left(\frac{t}{T}\right)$ | $ T \cdot G(fT)$ |
| 3 | Time shift | $g(t - T)$ | $G(f) \cdot e^{-j2\pi fT}$ |
| 4 | Frequency shift | $g(t) \cdot e^{j2\pi ft}$ | $G(f - F)$ |
| 5 | Complex conjugate | $g^*(t)$ | $G^*(-f)$ |
| 6 | Temporal derivative | $\frac{d}{dt} g(t)$ | $(j2\pi f)^n \cdot G(f)$ |
| 7 | Spectral derivative | $(-j2\pi t)^n \cdot g(t)$ | $\frac{d}{df} G(f)$ |
| 8 | Reciprocity | $G(t)$ | $g(-f)$ |
| 9 | Linearity | $A \cdot g(t) + B \cdot h(t)$ | $A \cdot G(f) + B \cdot H(f)$ |
| 10 | Multiplication | $g(t) \cdot h(t)$ | $G(f) * H(f)$ |
| 11 | Convolution | $g(t) * h(t)$ | $G(f) \cdot H(f)$ |
| 12 | Delta function | $\delta(t)$ | 1 |
| 13 | Constant | 1 | $\delta(f)$ |
| 14 | Rectangular function | $\text{rect}\{t\} \triangleq \begin{cases} 1 & \text{if } t < \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$ | $\text{sinc}\{f\} \triangleq \frac{\sin(\pi f)}{\pi f}$ |
| 15 | Sinc function | $\text{sinc}(t)$ | $\text{rect}\{f\}$ |
| 16 | Unit step function | $u(t) \triangleq \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$ | $\frac{1}{2}\delta(f) - \frac{j}{2\pi f}$ |
| 17 | Signum function | $\text{sgn}(t) \triangleq \begin{cases} 1 & t > 0 \\ -1 & t < 0 \end{cases}$ | $-\frac{j}{\pi f}$ |
| 18 | decaying exp (two-sided) | $e^{- t }$ | $\frac{2}{1 + (2\pi f)^2}$ |
| 19 | decaying exp (one-sided) | $e^{- t } \cdot u(t)$ | $\frac{1 - j2\pi f}{1 + (2\pi f)^2}$ |
| 20 | Gaussian function | $e^{-\pi t^2}$ | $e^{-\pi f^2}$ |
| 21 | Lambda function | $\Lambda\{t\} \triangleq \begin{cases} 1 - t & \text{if } 0 \leq t \leq 1 \\ 1 + t & \text{if } -1 \leq t \leq 0 \end{cases}$ | $\text{sinc}^2\{f\}$ |
| 22 | Repeated function | $\text{rep}_T\{g(t)\} = g(t) * \text{rep}_T\{\delta(t)\}$ | $\left \frac{1}{T}\right \text{comb}_{\frac{1}{T}}\{G(f)\}$ |
| 23 | Sampled function | $\text{comb}_T\{g(t)\} = g(t) \cdot \text{rep}_T\{\delta(t)\}$ | $\left \frac{1}{T}\right \text{rep}_{\frac{1}{T}}\{G(f)\}$ |