

The effect of Reynolds number on inertial particle dynamics in isotropic turbulence. Part 1. Simulations without gravitational effects

Peter J. Ireland^{1,2}, Andrew D. Bragg^{1,2,†} and Lance R. Collins^{1,2,†}

¹Sibley School of Mechanical and Aerospace Engineering, Cornell University, Ithaca, NY 14853, USA

²International Collaboration for Turbulence Research

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In this study, we analyse the statistics of both individual inertial particles and inertial particle pairs in direct numerical simulations of homogeneous isotropic turbulence in the absence of gravity. The effect of the Taylor microscale Reynolds number, R_λ , on the particle statistics is examined over the largest range to date (from $R_\lambda = 88$ to 597), at small, intermediate and large Kolmogorov-scale Stokes numbers St . We first explore the effect of preferential sampling on the single-particle statistics and find that low- St inertial particles are ejected from both vortex tubes and vortex sheets (the latter becoming increasingly prevalent at higher Reynolds numbers) and preferentially accumulate in regions of irrotational dissipation. We use this understanding of preferential sampling to provide a physical explanation for many of the trends in the particle velocity gradients, kinetic energies and accelerations at low St , which are well represented by the model of Chun *et al.* (*J. Fluid Mech.*, vol. 536, 2005, pp. 219–251). As St increases, inertial filtering effects become more important, causing the particle kinetic energies and accelerations to decrease. The effect of inertial filtering on the particle kinetic energies and accelerations diminishes with increasing Reynolds number and is well captured by the models of Abrahamson (*Chem. Engng Sci.*, vol. 30, 1975, pp. 1371–1379) and Zaichik & Alipchenkov (*Intl J. Multiphase Flow*, vol. 34 (9), 2008, pp. 865–868), respectively. We then consider particle-pair statistics, and focus our attention on the relative velocities and radial distribution functions (RDFs) of the particles, with the aim of understanding the underlying physical mechanisms contributing to particle collisions. The relative velocity statistics indicate that preferential sampling effects are important for $St \lesssim 0.1$ and that path-history/non-local effects become increasingly important for $St \gtrsim 0.2$. While higher-order relative velocity statistics are influenced by the increased intermittency of the turbulence at high Reynolds numbers, the lower-order relative velocity statistics are only weakly sensitive to changes in Reynolds number at low St . The Reynolds-number trends in these quantities at intermediate and large St are explained based on the influence of the available flow scales on the path-history and inertial filtering effects. We find that the RDFs peak near St of order unity, that they exhibit power-law scaling for low and intermediate St and that they are largely independent of Reynolds number for low and intermediate St . We use the model of

† Email address for correspondence: lc246@cornell.edu

‡ Present address: Applied Mathematics and Plasma Physics Group, Los Alamos National Laboratory, Los Alamos, NM 87545, USA.

Zaichik & Alipchenkov (*New J. Phys.*, vol. 11, 2009, 103018) to explain the physical mechanisms responsible for these trends, and find that this model is able to capture the quantitative behaviour of the RDFs extremely well when direct numerical simulation data for the structure functions are specified, in agreement with Bragg & Collins (*New J. Phys.*, vol. 16, 2014a, 055013). We also observe that at large St , changes in the RDF are related to changes in the scaling exponents of the relative velocity variances. The particle collision kernel closely matches that computed by Rosa *et al.* (*New J. Phys.*, vol. 15, 2013, 045032) and is found to be largely insensitive to the flow Reynolds number. This suggests that relatively low-Reynolds-number simulations may be able to capture much of the relevant physics of droplet collisions and growth in the adiabatic cores of atmospheric clouds.

Key words: isotropic turbulence, particle/fluid flow, turbulent flows

1. Introduction

Since the pioneering study of Orszag & Patterson (1972a) over forty years ago, direct numerical simulation (DNS) has been widely used to study turbulent flows. Previous DNS studies have provided a wealth of information about the underlying turbulent flow field, much of which is very difficult to obtain experimentally, including Lagrangian statistics (Yeung & Pope 1989), pressure fluctuations (Spalart 1988) and velocity gradient tensors (Ashurst *et al.* 1987).

Only within the last ten years, however, with the advent of tera- and petascale computing, have DNS at Reynolds numbers comparable to those in the largest laboratory experiments become possible. The highest-Reynolds-number simulations to date (with Taylor microscale Reynolds numbers $R_\lambda \sim 1000$) have been of isotropic turbulence in triperiodic domains and have considered both the Eulerian dynamics of the turbulent flow field and the Lagrangian dynamics of inertialess tracer (i.e. fluid) particles advected by the flow (Kaneda *et al.* 2003; Ishihara *et al.* 2007; Ishihara, Gotoh & Kaneda 2009; Yeung, Donzis & Sreenivasan 2012).

Many industrial and environmental turbulent flows, however, are laden with dense, inertial particles, which can display profoundly different dynamics than inertialess fluid particles. The degree to which the dynamics of inertial particles differs from those of fluid particles depends on their Stokes number St , a non-dimensional measure of particle inertia, which we define based on Kolmogorov-scale turbulence. We summarize the relevant physical mechanisms at small, intermediate and large values of St below.

It is well known from both computational and experimental studies that inertial particles preferentially sample certain regions of the flow (e.g. see Balachandar & Eaton 2010). This preferential sampling is often attributed to the fact that heavy particles are centrifuged out of vortex cores and accumulate in low vorticity and high strain regions (Maxey 1987; Squires & Eaton 1991; Eaton & Fessler 1994), leading to higher collision rates (Sundaram & Collins 1997). However, this centrifuge mechanism is mainly important for small- St particles that are strongly coupled to the underlying flow. As St is increased, the particle dynamics becomes less coupled to the local fluid velocity field and the influence of their path-history interactions with the turbulence becomes increasingly important (e.g. see Bragg & Collins 2014b). Particles with sufficiently large St can therefore come together from different regions

of the flow with large relative velocities, increasing their collision rate (Wilkinson, Mehlig & Bezuglyy 2006; Falkovich & Pumir 2007). Such a process is referred to as ‘caustics’ (Wilkinson *et al.* 2006) and the ‘sling effect’ (Falkovich & Pumir 2007). At high values of St , several studies (e.g. Bec *et al.* 2006a; Ayyalasomayajula, Warhaft & Collins 2008) have shown that particles have a modulated response to the underlying turbulence as they filter out high-frequency flow features (i.e. features with time scales significantly below the particle response time), and they therefore have lower kinetic energies and lower accelerations.

Despite recent advances in simulating high-Reynolds-number turbulent flows, current studies of inertial particles in turbulence are primarily at low and moderate Reynolds numbers ($R_\lambda \lesssim 500$), and only recently have DNSs been conducted of inertial particles in turbulence with a well-defined inertial range (Bec *et al.* 2010a,b; Pan *et al.* 2011; Ray & Collins 2011; Pan & Padoan 2013; Rosa *et al.* 2013). It is vital to understand the effect of Reynolds number on the mechanisms above (preferential sampling, path-history interactions and inertial filtering), particularly at higher Reynolds numbers that are more representative of those in nature. We give two examples to emphasize the importance of developing such an understanding.

The first example, cloud formation, is the primary motivation for this work. For reviews on this subject, see Shaw (2003), Devenish *et al.* (2012), Grabowski & Wang (2013); here we provide a brief overview. It is well known that standard microphysical cloud models overpredict the time required for the onset of precipitation in warm cumulus clouds (e.g. see Shaw 2003). At early stages of cloud formation, particles experience condensational growth. This process slows down quickly with increasing droplet diameter, making condensational growth effective only for droplets with diameters less than approximately 30 μm (Grabowski & Wang 2013). Moreover, gravity is only able to significantly enhance collisional growth for particles with diameters above 80 μm (Pruppacher & Klett 1997; Grabowski & Wang 2013), leaving a ‘size gap’ where neither condensational growth nor gravitational coalescence is very effective. For particles between these two limits, it has been proposed that turbulence-induced collisions are primarily responsible for droplet growth.

It is unclear, however, the extent to which particle collision rates are affected by changes in Reynolds number at conditions representative of those in cumulus clouds (which have $R_\lambda \sim 10\,000$, see Siebert, Lehmann & Wendisch (2006)). Sundaram & Collins (1997) showed that particle collision rates depend on both the degree of clustering and on the relative velocities between particles, and thus many subsequent analyses have considered the Reynolds-number dependence of both of these statistics. While the early study of Wang, Wexler & Zhou (2000) suggested that clustering increases with R_λ , later investigations (Collins & Keswani 2004; Bec *et al.* 2010a; Ray & Collins 2011; Rosa *et al.* 2013) indicate that clustering saturates at higher Reynolds numbers. Other researchers have suggested that caustics become more prevalent at high Reynolds numbers, leading to larger relative velocities and thus more frequent particle collisions (Falkovich, Fouxon & Stepanov 2002; Wilkinson *et al.* 2006). The findings of Bec *et al.* (2010a) and Rosa *et al.* (2013), however, do not seem to support that trend. In all cases, the Reynolds-number range ($R_\lambda \lesssim 500$) leaves open the question of whether the results apply to atmospheric conditions at much higher Reynolds numbers. Laboratory measurements of inertial particle clustering (Salazar *et al.* 2008; Saw *et al.* 2008; Lu, Nordsiek & Shaw 2010; Monchaux, Bourgoin & Cartellier 2010; Saw *et al.* 2012) and relative velocity statistics (de Jong *et al.* 2010; Saw *et al.* 2014) have provided reasonably good confirmation of the DNS; however, they too have been performed over a limited range of Reynolds

numbers, and therefore have not fully addressed the question of how the collision kernel depends upon the Reynolds number.

The second example relates to planetesimal formation. Planetesimals begin to form when small dust grains collide and coalesce in turbulent protoplanetary nebulae (Pan & Padoan 2010). Cuzzi *et al.* (2001) estimated that the turbulence in such nebulae is characterized by $R_\lambda \sim 10^4\text{--}10^6$. It is unclear to what extent the rate of coalescence depends on the Reynolds number, and studies at progressively higher Reynolds numbers are necessary to develop scaling relations for particle collision rates at conditions representative of nebula turbulence. Pan & Padoan (2010) noted that the range of relevant particle sizes in the planetesimal formation process spans approximately nine orders of magnitude, and therefore we expect that the collision rates will be affected by preferential sampling (for small, medium and large particles), path-history interactions (for medium and large particles) and inertial filtering (for medium and large particles).

In this study, we use high-performance computing resources provided by the US National Center for Atmospheric Research (Computational and Information Systems Laboratory 2012) to simulate inertial particles in isotropic turbulence over the range $88 \leq R_\lambda \leq 597$. To our knowledge, the top value represents the highest Reynolds-number flow with particles simulated to date. The overall goal is to improve predictions for the collision kernel at Reynolds numbers more representative of those in atmospheric clouds. Gravitational forces are neglected in this study, but will be considered in detail in Part 2 of this study (Ireland, Bragg & Collins 2016).

The paper is organized as follows: § 2 provides a summary of the numerical methods used and the relevant fluid and particle parameters. In § 3, we study single-particle statistics (small-scale velocity gradients, large-scale velocity fluctuations and also particle accelerations). Many of the results from this section help explain the particle-pair statistics presented in § 4. These statistics include the particle relative velocities, radial distribution functions and collision kernels. Finally, in § 5, we summarize our results and suggest practical implications for the turbulence and cloud physics communities.

2. Overview of simulations

A brief summary of the simulation parameters and numerical methods is provided below. Refer to Ireland *et al.* (2013) for a more detailed description of the code, including integration techniques, parallelization strategies and interpolation methods.

2.1. Fluid phase

We perform DNS of isotropic turbulence on a cubic, triperiodic domain of length $\mathcal{L} = 2\pi$ with N^3 grid points. A pseudospectral method (Orszag & Patterson 1972b) is used to evaluate the continuity and momentum equations for an incompressible flow,

$$\nabla \cdot \mathbf{u} = 0, \quad (2.1)$$

$$\frac{\partial \mathbf{u}}{\partial t} + \boldsymbol{\omega} \times \mathbf{u} + \nabla \left(\frac{p}{\rho_f} + \frac{u^2}{2} \right) = \nu \nabla^2 \mathbf{u} + \mathbf{f}. \quad (2.2)$$

Here, \mathbf{u} is the fluid velocity, $\boldsymbol{\omega} \equiv \nabla \times \mathbf{u}$ is the vorticity, p is the pressure, ρ_f is the fluid density, ν is the kinematic viscosity and \mathbf{f} is a large-scale forcing term that is added to make the flow field statistically stationary. For our simulations, we added

Simulation	I	II	III	IV	V
R_λ	88	140	224	398	597
ν	0.005	0.002	0.0008289	0.0003	0.00013
ϵ	0.270	0.267	0.253	0.223	0.228
ℓ	1.46	1.41	1.40	1.45	1.43
ℓ/η	55.8	107	204	436	812
u'	0.914	0.914	0.915	0.915	0.915
u'/u_η	4.77	6.01	7.60	10.1	12.4
T_L	1.60	1.54	1.53	1.58	1.57
T_L/τ_η	11.7	17.7	26.8	43.0	65.4
T/T_L	15.0	10.4	11.4	11.1	5.75
$k_{max}\eta$	1.59	1.59	1.66	1.60	1.70
N	128	256	512	1024	2048
N_p	262 144	262 144	2 097 152	16 777 216	134 217 728
$N_{tracked}$	32 768	32 768	262 144	2 097 152	16 777 216
N_{proc}	16	16	64	1024	16 384

TABLE 1. Flow parameters for the DNS study. All dimensional parameters are in arbitrary units and all statistics are averaged over time T . All quantities are defined in the text in §§ 2.1 and 2.2.

forcing to wavenumbers with magnitude $\kappa = \sqrt{2}$ in Fourier space in a deterministic fashion to compensate precisely for the energy lost to viscous dissipation (Witkowska, Brasseur & Juvé 1997).

We perform a series of five different simulations, with Taylor microscale Reynolds numbers $R_\lambda \equiv 2k\sqrt{5}/(3\nu\epsilon)$ ranging from 88 to 597, where k denotes the turbulent kinetic energy and ϵ the turbulent energy dissipation rate. Details of the simulations are given in table 1. The simulations are parameterized to have similar large scales, but different dissipation (small) scales. The small-scale resolution for the simulations was held constant, with $\kappa_{max}\eta \approx 1.6\text{--}1.7$, where $\kappa_{max} \equiv \sqrt{2}N/3$ is the maximum resolved wavenumber and $\eta \equiv (\nu^3/\epsilon)^{1/4}$ is the Kolmogorov length scale. Dealiasing is performed using a combination of spherical truncation and phase shifting. Time-averaged energy and dissipation spectra for all five simulations are shown in figure 1. A clear $-5/3$ spectral slope is evident for the three highest Reynolds-number cases ($R_\lambda \geq 224$), indicating the presence of a well-defined inertial subrange. The simulations are performed in parallel on N_{proc} processors, and the P3DFFT library (Pekurovsky 2012) is used for efficient parallel computation of three-dimensional fast Fourier transforms.

2.2. Particle phase

We simulate the motion of small ($d/\eta \ll 1$, where d is the particle diameter), heavy ($\rho_p/\rho_f \gg 1$, where ρ_p is the particle density), spherical particles. Eighteen different particle classes are simulated with Stokes numbers St ranging from 0 to 30. $St \equiv \tau_p/\tau_\eta$ is a non-dimensional measure of a particle's inertia, comparing the response time of the particle $\tau_p \equiv \rho_p d^2/(18\rho_f \nu)$ to the Kolmogorov time scale $\tau_\eta \equiv (\nu/\epsilon)^{1/2}$.

We assume that the particles are subjected to only linear drag forces, which is a reasonable approximation when the particle Reynolds number $Re_p \equiv |\mathbf{u}(\mathbf{x}^p(t), t) - \mathbf{v}^p(t)|/\nu < 0.5$ (Elghobashi & Truesdell 1992). Here, $\mathbf{u}(\mathbf{x}^p(t), t)$ denotes the undisturbed fluid velocity at the particle position $\mathbf{x}^p(t)$ and $\mathbf{v}^p(t)$ denotes the velocity of the

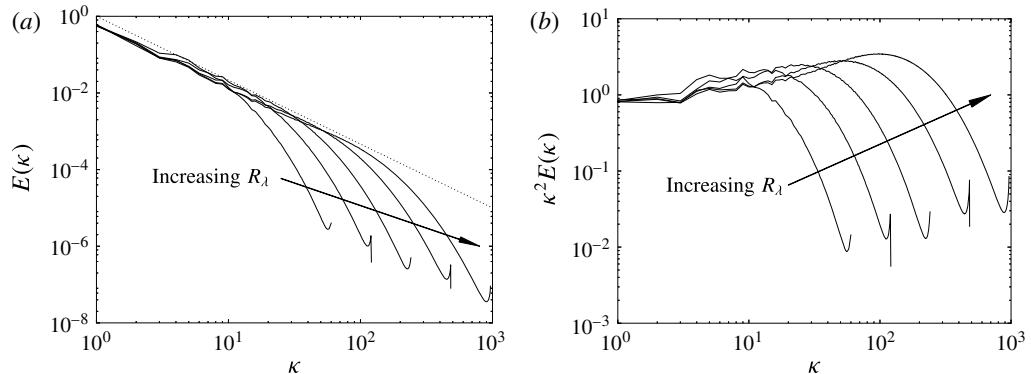


FIGURE 1. (a) Energy and (b) dissipation spectra for the different simulations described in table 1. The diagonal dotted line in (a) has a slope of $-5/3$, the expected spectral scaling in the inertial subrange. All values are in arbitrary units.

particle. (Throughout this study, we use the superscript p on \mathbf{x} , \mathbf{u} , and \mathbf{v} to denote time-dependent Lagrangian variables defined along particle trajectories. Phase-space positions and velocities are denoted without the superscript p .) Though particles with large St experience non-negligible nonlinear drag forces (e.g. Wang & Maxey 1993), the use of a linear drag model for large- St particles provides a useful first approximation and facilitates comparison between several theoretical models that make the same assumption (e.g. Chun *et al.* 2005; Zaichik & Alipchenkov 2009; Gustavsson & Mehlig 2011). We have also neglected the history force in this study. In an earlier work, Elghobashi & Truesdell (1992) showed that the Basset history force is orders of magnitude smaller than the Stokes drag force when $\rho_p/\rho_f \gg 1$ (here our primary focus is on water droplets in air, where $\rho_p/\rho_f \sim 1000$). On this basis, most DNS of inertial particles in turbulence neglect this term, which involves an integral and is very expensive to compute. However, Daitche (2015) showed that the Basset history term can slightly reduce particle clustering and collision rates for higher values of St , and thus while we expect that our particle statistics generally have the correct leading-order behaviour, future studies are needed to systematically assess higher-order corrections to these statistics that result from the inclusion of the history force. The present study also neglects the influence of gravity. Part 2 of this study (Ireland *et al.* 2016) will address the combined effects of gravity and turbulence on particle motion. Finally, since a primary motivation is to understand droplet dynamics in atmospheric clouds, where the particle mass and volume loadings are low (Shaw 2003), we assume that the particle loadings are sufficiently dilute such that interparticle interactions and two-way coupling between the phases are negligible (Elghobashi & Truesdell 1993; Sundaram & Collins 1999).

Under these assumptions, each inertial particle obeys a simplified Maxey–Riley equation (Maxey & Riley 1983),

$$\frac{d^2\mathbf{x}^p}{dt^2} = \frac{d\mathbf{v}^p}{dt} = \frac{\mathbf{u}(\mathbf{x}^p(t), t) - \mathbf{v}^p(t)}{\tau_p}, \quad (2.3)$$

and each fluid (i.e. inertialess) particle is tracked by solving

$$\frac{d\mathbf{x}^p}{dt} = \mathbf{u}(\mathbf{x}^p(t), t). \quad (2.4)$$

To compute $\mathbf{u}^p(t) = \mathbf{u}(\mathbf{x}^p(t), t)$, we need to interpolate from the Eulerian grid to the particle location. While other studies (e.g. see Bec *et al.* 2010a; Durham *et al.* 2013) have done so using trilinear interpolation, Ireland *et al.* (2013) showed that such an approach can lead to errors in the interpolated velocity that are orders of magnitude above the local time-stepping error. In addition, van Hinsberg *et al.* (2013) demonstrated that trilinear interpolation, which possesses only C^0 continuity, leads to artificial high-frequency oscillations in the computed particle accelerations. Ray & Collins (2013) noted that the relative motion of particles at small separations will depend strongly on the interpolation scheme. Since a main focus of this paper is particle motion near contact and its influence on particle collisions, it is crucial to calculate $\mathbf{u}(\mathbf{x}^p(t), t)$ as accurately as possible. To that end, we use an eight-point B-spline interpolation scheme (with C^6 continuity) based on the algorithm in van Hinsberg *et al.* (2012).

The particles were initially placed in the flow with a uniform distribution and velocities \mathbf{v}^p equal to the underlying fluid velocity \mathbf{u}^p . We began computing particle statistics once the particle distributions and velocities became statistically stationary, usually approximately 5 large eddy turnover times $T_L \equiv \ell/u'$ (where ℓ is the integral length scale and $u' \equiv \sqrt{2k/3}$) after the particles were introduced into the flow. Particle statistics were calculated at a frequency of 2–3 times per T_L and were time averaged over the duration of the run T .

For a subset N_{tracked} of the total number of particles in each class N_p , we stored particle positions, velocities and velocity gradients every $0.1\tau_\eta$ for a duration of approximately $100\tau_\eta$. These data are used to compute Lagrangian correlations, accelerations and time scales of the particles.

3. Single-particle statistics

We first consider single-particle statistics from our simulations. These statistics will provide a basis for our understanding of the two-particle statistics presented in § 4. We explore velocity gradient (i.e. small-scale velocity) statistics in § 3.1, kinetic energy (i.e. large-scale velocity) statistics in § 3.2 and acceleration statistics in § 3.3. In each case, we study the effect of the underlying flow topology on these statistics.

3.1. Velocity gradient statistics

We consider the gradients of the underlying fluid velocity at the particle locations, $\mathbf{A}(\mathbf{x}^p(t), t) \equiv \nabla \mathbf{u}(\mathbf{x}^p(t), t)$. These statistics provide us with information about the small-scale velocity field experienced by the particles. (Refer to Meneveau (2011) for a recent review on this subject.) In particular, to understand the interaction of particles with specific topological features of the turbulence, we decompose $\mathbf{A}(\mathbf{x}^p(t), t)$ into a symmetric strain rate tensor $\mathbf{S}(\mathbf{x}^p(t), t) \equiv [\mathbf{A}(\mathbf{x}^p(t), t) + \mathbf{A}^\text{T}(\mathbf{x}^p(t), t)]/2$ and an antisymmetric rotation rate tensor $\mathbf{R}(\mathbf{x}^p(t), t) \equiv [\mathbf{A}(\mathbf{x}^p(t), t) - \mathbf{A}^\text{T}(\mathbf{x}^p(t), t)]/2$.

Due to their inertia, heavy particles are ejected out of regions of high rotation rate and accumulate in regions of high strain rate (e.g. Maxey 1987; Squires & Eaton 1991; Eaton & Fessler 1994), and this is associated with a ‘preferential sampling’ of $\mathbf{A}(\mathbf{x}, t)$. For particles with low inertia ($St \ll 1$), preferential sampling is the dominant mechanism affecting the particle motion (e.g. see Chun *et al.* 2005). As the particle inertia increases, the particle motion becomes increasingly decoupled from the local fluid turbulence, and the effect of the preferential sampling on the particle dynamics decreases. At the other limit ($St \gg 1$), preferential sampling vanishes and the particles

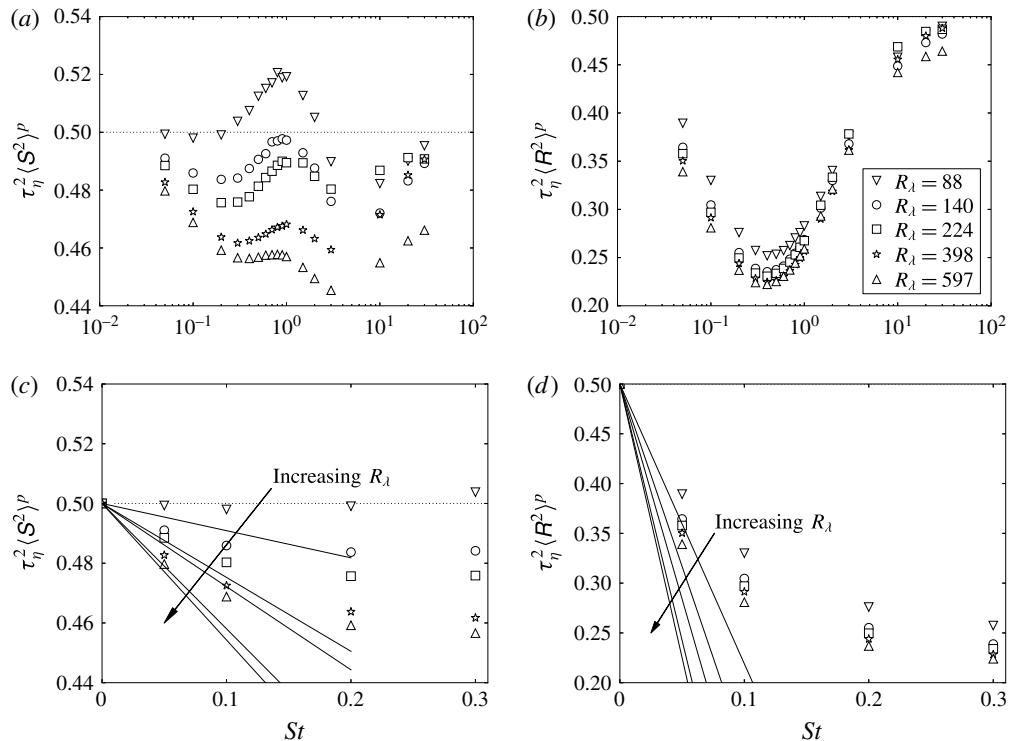


FIGURE 2. Data for $\langle S^2 \rangle^p$ (a,c) and $\langle R^2 \rangle^p$ (b,d) sampled at inertial particle positions as function of St for different values of R_λ . The data are shown at low St in (c,d) to highlight the effect of preferential sampling in this regime. The solid lines in (c,d) are the predictions from (3.3) for $St \ll 1$. DNS data are shown with symbols.

have a damped response to the underlying flow which leads them to sample the turbulence more uniformly (e.g. see Bec *et al.* 2006a).

We first consider the average of the second invariants of the strain rate and rotation rate tensors evaluated at the inertial particle positions

$$\langle S^2 \rangle^p \equiv \langle \mathbf{S}(\mathbf{x}^p(t), t) : \mathbf{S}(\mathbf{x}^p(t), t) \rangle, \quad (3.1)$$

and

$$\langle R^2 \rangle^p \equiv \langle \mathbf{R}(\mathbf{x}^p(t), t) : \mathbf{R}(\mathbf{x}^p(t), t) \rangle. \quad (3.2)$$

By definition, for fully mixed fluid particles ($St = 0$) in homogeneous turbulence, $\tau_\eta^2 \langle S^2 \rangle^p = \tau_\eta^2 \langle R^2 \rangle^p = 0.5$.

Since small- St particles are centrifuged out of regions of high rotation, we expect that $\tau_\eta^2 \langle R^2 \rangle^p$ will decrease with increasing St ; their accumulation in high strain regions would also lead to the expectation that $\tau_\eta^2 \langle S^2 \rangle^p$ will increase with increasing St . In figure 2 we see that while $\tau_\eta^2 \langle R^2 \rangle^p$ is more strongly affected by changes in R_λ than is $\tau_\eta^2 \langle S^2 \rangle^p$, both quantities decrease with increasing St (for $St \ll 1$). This surprising result is consistent with other DNS (Collins & Keswani 2004; Chun *et al.* 2005; Salazar & Collins 2012a). Our data also show that both $\tau_\eta^2 \langle S^2 \rangle^p$ and $\tau_\eta^2 \langle R^2 \rangle^p$ decrease with increasing R_λ for $St \ll 1$, in agreement with Collins & Keswani (2004).

We use the formulation given in Chun *et al.* (2005) (and rederived in Salazar & Collins (2012a)) to model the effect of preferential sampling on $\tau_\eta^2 \langle S^2 \rangle^p$ and $\tau_\eta^2 \langle R^2 \rangle^p$ in limit of $St \ll 1$. Chun *et al.* (2005) and Salazar & Collins (2012a) showed that for an arbitrary quantity ϕ , the average value of ϕ sampled along a particle trajectory $\langle \phi \rangle^p$ can be reconstructed entirely from fluid particle statistics using the relation,

$$\langle \phi(St) \rangle^p = \langle \phi(St=0) \rangle^p + \tau_\eta \sigma_\phi^p St (\rho_{S^2\phi}^p \sigma_{S^2}^p T_{S^2\phi}^p - \rho_{R^2\phi}^p \sigma_{R^2}^p T_{R^2\phi}^p). \quad (3.3)$$

Here, σ_Y^p denotes the standard deviation of a variable Y along a fluid particle trajectory, ρ_{YZ}^p is the correlation coefficient between Y and Z ,

$$\rho_{YZ}^p \equiv \frac{\langle [Y(\mathbf{x}^p(t), t) - \langle Y(\mathbf{x}^p(t), t) \rangle][Z(\mathbf{x}^p(t), t) - \langle Z(\mathbf{x}^p(t), t) \rangle] \rangle}{\sigma_Y^p \sigma_Z^p} \quad (3.4)$$

and T_{YZ}^p is the Lagrangian correlation time,

$$T_{YZ}^p \equiv \frac{\int_0^\infty \langle [Y(\mathbf{x}^p(0), 0) - \langle Y(\mathbf{x}^p(0), 0) \rangle][Z(\mathbf{x}^p(s), s) - \langle Z(\mathbf{x}^p(s), s) \rangle] \rangle ds}{\langle [Y(\mathbf{x}^p(0), 0) - \langle Y(\mathbf{x}^p(0), 0) \rangle][Z(\mathbf{x}^p(0), 0) - \langle Z(\mathbf{x}^p(0), 0) \rangle] \rangle}. \quad (3.5)$$

The predictions from (3.3) for small St are shown by the solid lines in figure 2(c,d). The data at the highest Reynolds numbers provide the first test of the predictions from Chun *et al.* (2005) for flows with a well-defined inertial range. In the limit of small St , (3.3) is able to capture the decrease in both $\tau_\eta^2 \langle S^2 \rangle^p$ and $\tau_\eta^2 \langle R^2 \rangle^p$ with increasing St , and also the decrease in these quantities with increasing R_λ . It is uncertain whether the quantitative differences between the DNS data and the model are due to shortcomings of the model or the fact that the smallest inertial particles ($St = 0.05$) are too large for the model (which assumes $St \ll 1$) to hold.

An important implication of these results is that the degree of preferential sampling (and thus indirectly, the amount of clustering) of inertial particles can be predicted using experimental or DNS data measured along fluid particle trajectories. Such data are generally more widely available at even higher Reynolds numbers than those simulated here and could provide an indication of the trends in preferential sampling at such conditions.

Despite the success of the model of Chun *et al.* (2005) in reproducing the trends in the DNS, the physical explanation for the changes in the mean strain and rotation rates remains unclear. In figure 3(a), we plot joint probability density functions (PDFs) of the strain and rotation rates sampled by both $St = 0$ and $St = 0.1$ particles to better understand the specific topological features of the regions of the flow contributing to these changes. Following the designations given in Soria *et al.* (1994), we refer to regions with high strain and high rotation (indicated by ‘A’ in figure 3a) as ‘vortex sheets’, regions of low rotation and high strain (indicated by ‘B’) as ‘irrotational dissipation’ areas, and regions of high rotation and low strain (indicated by ‘C’) as ‘vortex tubes.’

We see that the inertial particle PDFs differ from those of fluid particles in three primary ways. First, inertial particles are less likely to occupy vortex sheets (A) and are more likely to occupy regions of moderate rotation and moderate strain (A'). This undersampling of vortex sheets has only recently been discussed in the literature (Salazar & Collins 2012a). Second, inertial particles are more likely to be found in irrotational dissipation regions, where they preferentially sample regions of higher

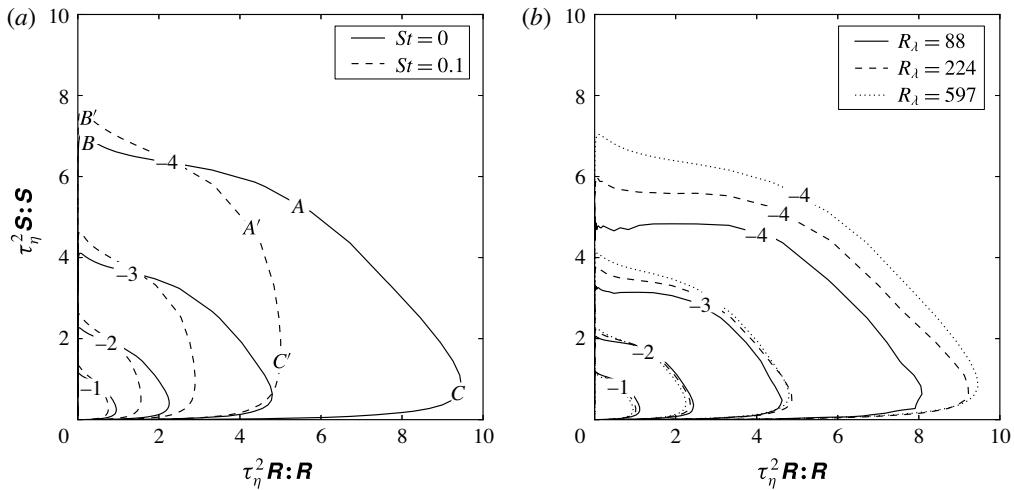


FIGURE 3. (a) Joint PDFs of $\tau_\eta^2 \mathbf{S} : \mathbf{S}$ and $\tau_\eta^2 \mathbf{R} : \mathbf{R}$ for $R_\lambda = 597$ for $St = 0$ and $St = 0.1$ particles. Certain regions of the flow are labelled to aid in the discussion of the trends. (b) Joint PDFs of $\tau_\eta^2 \mathbf{S} : \mathbf{S}$ and $\tau_\eta^2 \mathbf{R} : \mathbf{R}$ for different R_λ for $St = 0$ particles. In both plots, the exponents of the decade are indicated on the contour lines.

strain (e.g. compare B and B'). Third, inertial particles are less likely to be found in vortex tubes (C) and more likely to be found in regions of lower rotation and higher strain (C'). Evidently, this first trend is primarily responsible for the decrease in $\tau_\eta^2 \langle S^2 \rangle^p$ at small St , as suggested in Salazar & Collins (2012a), and the first and third trends both contribute to the decrease in $\tau_\eta^2 \langle R^2 \rangle^p$. We will revisit these three trends in relation to the particle kinetic energies (§ 3.2) and the particle accelerations (§ 3.3).

Figure 3(b) shows the PDF map for fluid particles at three values of the Reynolds number. Notice that as R_λ increases, the probability of encountering a vortex sheet (overlapping high strain and high rotation) increases. This finding is consistent with the results of Yeung *et al.* (2012), who observed that high strain and rotation events increasingly overlap in isotropic turbulence as the Reynolds number increases. It is thus likely that with increasing Reynolds number, rotation and strain events become increasingly intense and the resulting vortex sheets become increasingly efficient at expelling particles, causing both $\tau_\eta^2 \langle S^2 \rangle^p$ and $\tau_\eta^2 \langle R^2 \rangle^p$ to decrease (cf. figure 2).

Maxey (1987) noted that at low St , the compressibility of the particle field (and hence the degree of particle clustering) is directly related to the difference between the rates of strain and rotation sampled by the particles, $\tau_\eta^2 \langle S^2 \rangle^p - \tau_\eta^2 \langle R^2 \rangle^p$. From figure 4, we see that at low St , $\tau_\eta^2 \langle S^2 \rangle^p - \tau_\eta^2 \langle R^2 \rangle^p$ increases with increasing R_λ , suggesting that the degree of clustering may also increase here. We will test this hypothesis in § 4.2 when we directly measure particle clustering at different values of St and R_λ .

We finally consider the Lagrangian strain and rotation time scales, which will be useful for understanding the trends in particle clustering in § 4.2. Since the fluid and particle phases are isotropic, we will have nine statistically equivalent strain time scales: $T_{S_{11}S_{11}}^p$, $T_{S_{11}S_{22}}^p$, $T_{S_{11}S_{33}}^p$, $T_{S_{12}S_{12}}^p$, $T_{S_{13}S_{13}}^p$, $T_{S_{22}S_{22}}^p$, $T_{S_{23}S_{23}}^p$ and $T_{S_{33}S_{33}}^p$. We take the strain time scale T_{SS}^p to be the average of these nine components. We similarly take the rotation time scale T_{RR}^p to be the average of three statistically equivalent components: $T_{R_{12}R_{12}}^p$, $T_{R_{13}R_{13}}^p$ and $T_{R_{23}R_{23}}^p$.

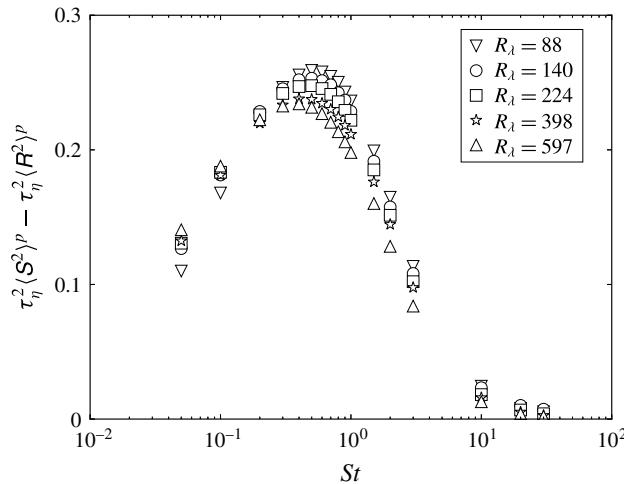


FIGURE 4. The difference between the mean rates of strain and rotation sampled by the particles as a function of St for different values of R_λ .

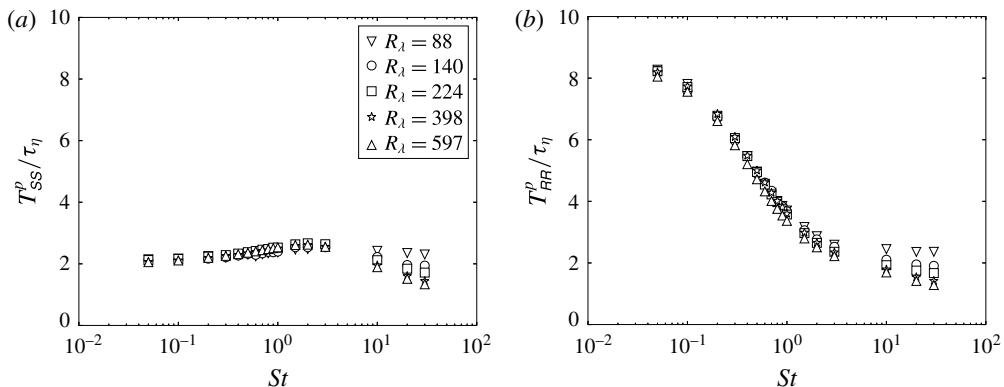


FIGURE 5. Lagrangian time scales of a single component of the strain rate (a) and rotation rate (b) tensors, plotted as a function of St for different values of R_λ .

We see that T_{SS}^p / τ_η is independent of R_λ for $St < 10$, and decreases weakly with increasing R_λ for $St \geq 10$. On the other hand, T_{RR}^p / τ_η tends to decrease with increasing R_λ for all values of St , and this decrease becomes more pronounced as St increases. We also see that T_{RR}^p is much more sensitive to changes in St than T_{SS}^p , suggesting that the dominant effect of inertia is to cause particles to spend less time in strongly rotating regions. As a result, the particles will generally have less time to respond to fluctuations in the rotation rate, causing $\langle R^2 \rangle^p$ to be strongly reduced with increasing St , as was seen above.

3.2. Particle kinetic energy

We now move from small-scale velocity statistics to large-scale velocity statistics. Figure 6 shows the average particle kinetic energy $k^p(St) \equiv \langle \mathbf{v}^p(t) \cdot \mathbf{v}^p(t) \rangle / 2$ (normalized by the average fluid kinetic energy k) for different values of R_λ .

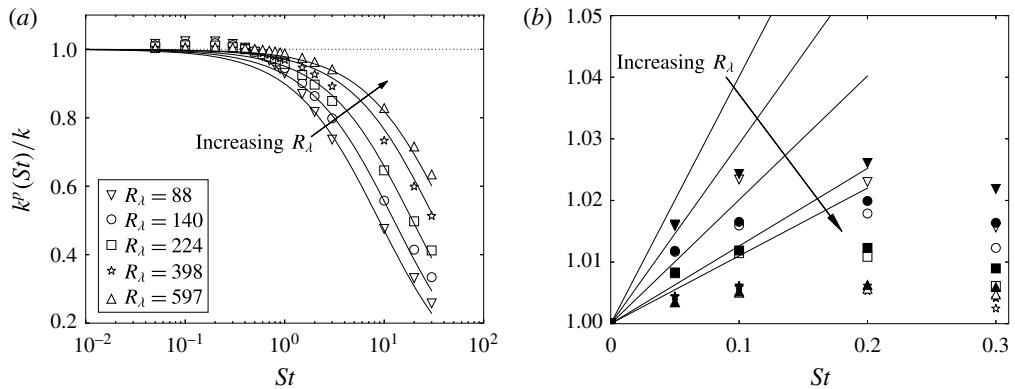


FIGURE 6. (a) The ratio between the average particle kinetic energy $k^p(St)$ and the average fluid kinetic energy k for different values of R_λ . DNS data are shown with symbols and the predictions of the filtering model in (3.6) are shown with solid lines. (b) The ratio between $k^p(St)$ and k (open symbols) and the ratio between the average fluid kinetic energy at the particle locations $k^fp(St)$ and k (filled symbols), shown at low St to highlight the effects of preferential sampling. Also shown is the prediction from the preferential sampling model given in (3.3) (solid lines).

We first consider the effect of inertial filtering on this statistic and then examine the effect of preferential sampling. It is well known that filtering leads to a reduction in the particle turbulent kinetic energy for large values of St . This reduction is the strongest for the lowest Reynolds numbers and the weakest for the highest Reynolds numbers, as seen in figure 6(a). These trends are captured by the model in Abrahamson (1975), which assumes an exponential decorrelation of the Lagrangian fluid velocity. Under this assumption, the ratio between the particle and fluid kinetic energies can be expressed as

$$\frac{k^p(St)}{k} \approx \frac{1}{1 + \tau_p/\tau_\ell} = \frac{1}{1 + St(\tau_\eta/\tau_\ell)}, \quad (3.6)$$

where τ_ℓ is the Lagrangian correlation time of the fluid, which we approximate using the relation given in Zaichik, Simonin & Alipchenkov (2003). The model predictions of $k^p(St)/k$ are included in figure 6(a) and are in good agreement with the DNS at large St , where filtering is dominant. The trends with R_λ are also reproduced well.

We thus have the following physical explanation of inertial filtering on the particle kinetic energies: for low-Reynolds-number flows, the response time of the largest particles exceeds the time scales of many large-scale flow features. The result is a filtered response to the large-scale turbulence and an overall reduction in the particle kinetic energy. As the Reynolds number is increased (and the particle response time is fixed with respect to the small-scale turbulence), more flow features are present with time scales that exceed the particle response time, and hence the effect of inertial filtering is diminished with increasing R_λ , as predicted by (3.6).

To highlight the effect of preferential sampling on the particle kinetic energy, figure 6(b) shows both the average particle kinetic energy $k^p(St)$ and the average kinetic energy of the fluid sampled along an inertial particle trajectory, $k^fp(St) \equiv \langle \mathbf{u}(\mathbf{x}^p(t), t) \cdot \mathbf{u}(\mathbf{x}^p(t), t) \rangle / 2$. As is evident in figure 6(b), the particle kinetic energy exceeds k for low values of St . By comparing k^p to k^fp , we see that the increased

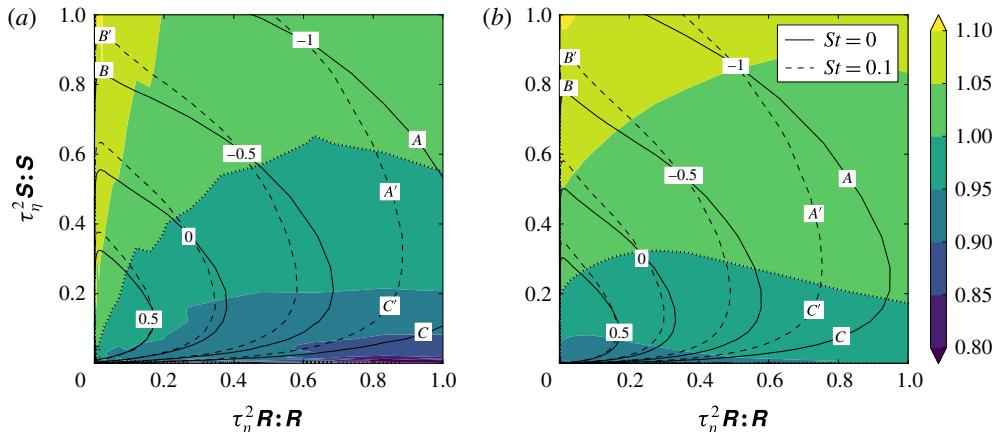


FIGURE 7. (Colour online) Filled contours of the fluid kinetic energy conditioned on S^2 and R^2 , k_{S^2, R^2} , normalized by the unconditioned mean fluid kinetic energy k at (a) the lowest Reynolds number and (b) the highest Reynolds number. The dotted contour lines indicate $k_{S^2, R^2} / k = 1$. Isocontours of particle concentration for $St = 0$ and $St = 0.1$ particles are included for reference, with the exponents of the decade indicated on the contour lines. Certain regions of the flow are labelled to aid in the discussion of the trends.

kinetic energy of the smallest particles is due almost entirely to preferential sampling of the flow field. While Salazar & Collins (2012b) were the first to show an increase in $k^p(St)/k$ for low St (which they attributed to preferential sampling), this trend is also suggested by the early study of Squires & Eaton (1991), in which the authors observed that small inertial particles preferentially sample certain high kinetic energy regions they referred to as ‘streaming zones.’ Figure 6(b) also shows that at small values of St , $k^p(St)/k$ decreases with increasing Reynolds number.

The solid lines in figure 6(b) show the predictions of the particle kinetic energy from (3.3). In the limit of small St , the model of Chun *et al.* (2005) is able to capture qualitatively both the increase in $k^p(St)/k$ with increasing St and the decrease in $k^p(St)/k$ with increasing R_λ .

To further elucidate the physical mechanisms leading to these trends, we plot the mean kinetic energy of the fluid conditioned on S^2 and R^2 , k_{S^2, R^2} , in figure 7. Isocontours of the concentrations of $St = 0$ and $St = 0.1$ particles are shown for comparison. (To reduce the statistical noise in the conditional averages and to focus on the regions where most particles are present, we consider a narrower range of S^2 and R^2 than in figure 3. The trends discussed below, however, are still evident when we consider the same range of S^2 and R^2 as before.) While the data contain considerable statistical noise, we can draw a few conclusions about the qualitative trends.

From figure 7(a), we see that the change in kinetic energy at $R_\lambda = 88$ can be divided into the three mechanisms discussed in § 3.1. First, particles are less likely to sample vortex sheets (A) and are more likely to sample moderate rotation and moderate strain regions (A'). This behaviour generally tends to decrease the particle kinetic energy. Second, as St increases, particles preferentially sample regions of higher strain (B'), which are characterized by higher kinetic energy. Third, some inertial particles are less likely to occupy vortex tubes (C), which are characterized by lower kinetic energies,

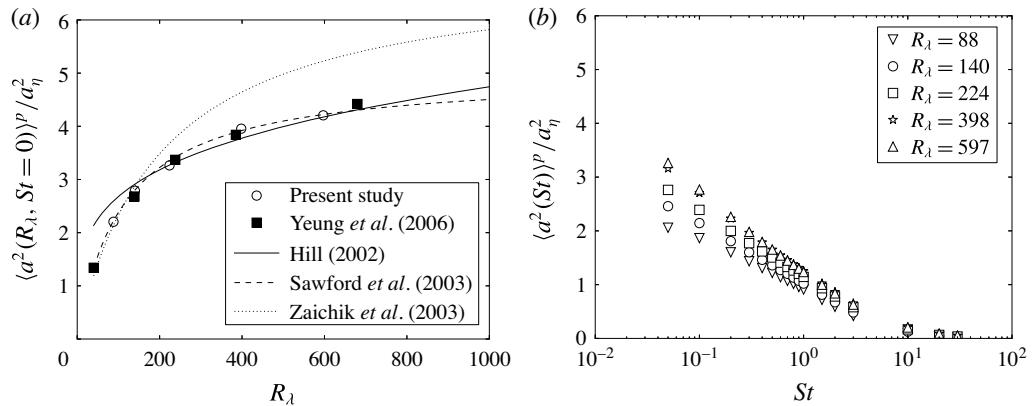


FIGURE 8. (a) The acceleration variance of Lagrangian fluid particles as a function of R_λ . The results from the present study (open circles) are compared to DNS data from Yeung *et al.* (2006) (filled squares) and several theoretical predictions (lines). (b) The acceleration variance of inertial particles as a function of St for different values of R_λ .

and are more likely to occupy lower rotation and higher strain regions (C'), which have higher kinetic energies. The observed increase in $k^p(St)/k$ must therefore be due to the second and third trends.

At high Reynolds numbers, however, overlapping high rotation/high strain regions of the flow occur with a higher probability (as shown in § 3.1), and inertial particles tend to avoid these regions. The first trend (which tends to decrease the kinetic energy) therefore plays a larger role. Also, at $R_\lambda = 597$, high rotation and low strain regions (e.g. see region C in figure 7b) are no longer associated with very low kinetic energies, causing the third trend to be less effective at increasing the particle kinetic energy. The overall result is a decrease in $k^p(St)/k$ with increasing Reynolds number at small values of St .

3.3. Particle accelerations

In this section, we analyse fluid and inertial particle accelerations $\mathbf{a}^p(t) \equiv d\mathbf{v}^p(t)/dt$. Fluid particle accelerations are known to be strongly intermittent (e.g. see Voth *et al.* 2002; Ishihara *et al.* 2007), with the probability of intense acceleration events increasing with the Reynolds number. Before accounting for inertial effects, we consider the effect of R_λ on the acceleration variance $\langle a^p \rangle^p \equiv \langle \mathbf{a}^p(t) \cdot \mathbf{a}^p(t) \rangle / 3$ of Lagrangian fluid particles in figure 8(a). To facilitate comparison between the different Reynolds numbers, we have normalized $\langle a^p \rangle^p$ by the Kolmogorov acceleration variance $a_\eta^2 \equiv \sqrt{\epsilon^3/\nu}$. The DNS data from Yeung *et al.* (2006) and the theoretical predictions of Hill (2002), Sawford *et al.* (2003) and Zaichik *et al.* (2003) are shown for comparison. We see that our DNS data agrees well with Yeung *et al.* (2006), and that the model of Sawford *et al.* (2003) best reproduces the trends in the DNS. Hill (2002) breaks down at low R_λ while Zaichik *et al.* (2003) fails at high R_λ .

We turn our attention to inertial particle accelerations in figure 8(b). The observed trend for inertial particles is analogous to that for fluid particles: at each value of St considered, the particle acceleration variance (normalized by Kolmogorov units) monotonically increases with R_λ (cf. Bec *et al.* 2006a). As St increases, the acceleration variance decreases, presumably as a result of both preferential sampling of the flow field and inertial filtering.

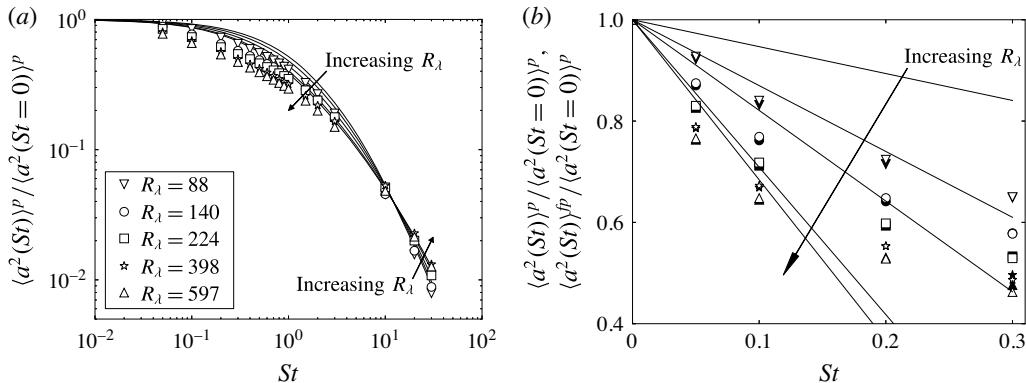


FIGURE 9. (a) Inertial particle acceleration variances scaled by the fluid particle acceleration variance (open symbols). The solid lines and arrows indicate the predictions from the filtering model of Zaichik & Alipchenkov (2008). (b) The variance of the inertial particle accelerations (open symbols) and the fluid accelerations sampled at the inertial particle positions (filled symbols), shown at low St to highlight the effect of preferential sampling. The solid lines indicate the predictions from the preferential sampling model given in (3.3).

We now seek to understand and model how inertia changes the accelerations of particles through the filtering and preferential sampling effects. To do so, we rescale the inertial particle acceleration variance by that of fluid particles and plot the results in figure 9. In figure 9(a), we compare the rescaled acceleration variance to the model of Zaichik & Alipchenkov (2008), which only accounts for inertial filtering of the underlying flow. The model of Zaichik & Alipchenkov (2008) is able to capture all the qualitative trends in R_λ and St , and the model predictions provide remarkably good quantitative agreement with the DNS at the largest values of St , where filtering is the dominant mechanism. At lower values of St , the rescaled particle acceleration variance decreases with increasing R_λ . In this case, as R_λ increases, the underlying flow is subjected to increasingly intermittent acceleration events, and the inertial particles filter a larger fraction of these events. At the largest values of St , most intermittent accelerations are filtered, and a particle's acceleration variance is determined by its interaction with the largest turbulence scales. Since the range of available large scales increases with R_λ , the rescaled particle acceleration variance increases with R_λ for the largest values of St .

We now consider the effect of preferential sampling on the acceleration variances. To do so, we also compute the acceleration of the fluid sampled by inertial particles, defined as

$$\mathbf{a}^{fp}(t) \equiv \frac{\partial \mathbf{u}(\mathbf{x}^p(t), t)}{\partial t} + \mathbf{u}(\mathbf{x}^p(t), t) \cdot \nabla \mathbf{u}(\mathbf{x}^p(t), t). \quad (3.7)$$

The variance of \mathbf{a}^{fp} is denoted as $\langle a^2 \rangle^{fp} \equiv \langle \mathbf{a}^{fp}(t) \cdot \mathbf{a}^{fp}(t) \rangle / 3$. In figure 9(b), we plot both $\langle a^2 \rangle^p$ and $\langle a^2 \rangle^{fp}$ (scaled by the acceleration variance of $St=0$ particles). As expected, for $St \ll 1$, where preferential sampling is the dominant mechanism, inertial particle accelerations are almost equivalent to the accelerations of the underlying flow sampled at inertial particle positions. The model of Chun et al. (2005) (equation (3.3) above) is able to reproduce all the qualitative trends correctly in the limit of small St . The scaled variances decrease with increasing R_λ , and we expect that this trend is due

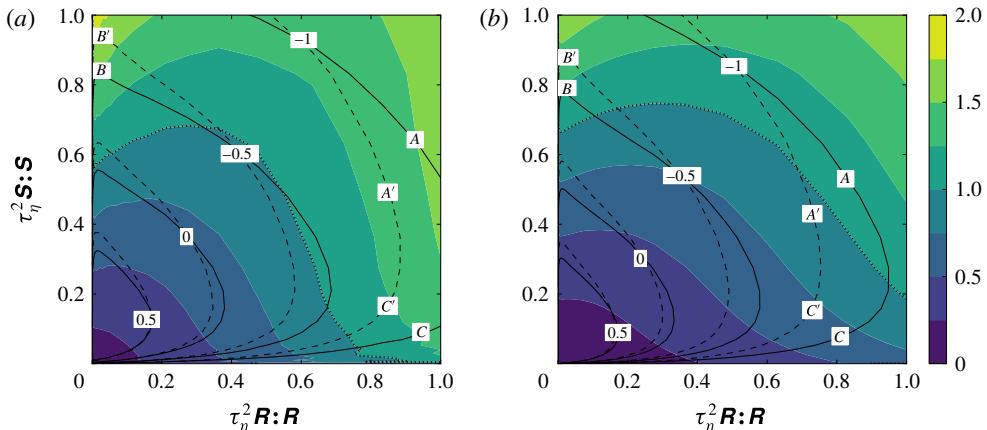


FIGURE 10. (Colour online) Filled contours of the variance of the fluid particle accelerations conditioned on S^2 and R^2 , $\langle a^2 \rangle_{S^2, R^2}^p$, normalized by the unconditioned fluid particle acceleration variance $\langle a^2 \rangle^p$, at (a) $R_\lambda = 88$ and (b) $R_\lambda = 597$. The dotted contour lines indicate $\langle a^2 \rangle_{S^2, R^2}^p / \langle a^2 \rangle^p = 1$. Isocontours of particle concentration for $St = 0$ and $St = 0.1$ particles are included for reference, with the exponents of the decade indicated on the contour lines. Certain regions of the flow are labelled to aid in the discussion of the trends.

to the fact that high vorticity regions are associated with high accelerations (Biferale *et al.* 2005) and become increasingly efficient at ejecting particles (refer to § 3.1).

We test this expectation in figure 10 by plotting the acceleration variance for fluid particles conditioned on S^2 and R^2 , $\langle a^2 \rangle_{S^2, R^2}^p$, and normalized by the unconditioned variance $\langle a^2 \rangle^p$. We see that inertial particles do indeed undersample high vorticity regions (both vortex sheets and vortex tubes) and preferentially sample lower vorticity regions (e.g. compare A and A' and C and C') and that these high vorticity regions are marked by very large accelerations. Though some inertial particles experience higher accelerations as they preferentially sample irrotational straining regions with higher strain rates (e.g. compare B and B'), this effect is relatively weak and the overall trend is a decrease in the particle accelerations with increasing inertia.

To investigate the intermittency of inertial particle accelerations, we plot the kurtosis of the particle accelerations, $\langle a^4 \rangle^p / (\langle a^2 \rangle^p)^2$, in figure 11, where $\langle a^4 \rangle^p \equiv \langle a_1^p(t)^4 + a_2^p(t)^4 + a_3^p(t)^4 \rangle^p / 3$. (Note that a Gaussian distribution has a kurtosis of 3, as indicated in figure 11 by a dotted line.) As expected, the particle accelerations are highly intermittent, with the degree of intermittency increasing with increasing R_λ . We note that this trend in the kurtosis with R_λ seems to be entirely due to the fluid flow intermittency. In fact, when we divide the acceleration kurtosis values of inertial particles by those of fluid particles (not shown), we observe the opposite trend with R_λ , suggesting that inertial particles are affected less by intermittent events than fluid particles are. This is consistent with our explanations for trends in the particle acceleration variances given above, as well as with Bec *et al.* (2006c), who found that inertial particles undersample the most highly intermittent turbulent events in the fluid.

The kurtosis decreases very rapidly as St increases. Figure 11(b) indicates that the kurtosis of very small particles ($St = 0.05$) at the highest value of R_λ is over a

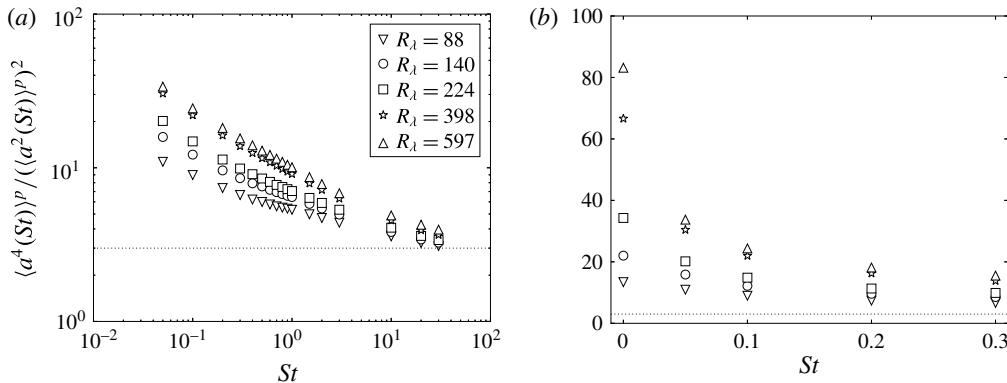


FIGURE 11. Particle acceleration kurtosis as a function of St for different values of R_λ . The dotted line indicates a kurtosis of 3, the value for a Gaussian distribution. Values over the whole range of non-zero St are shown in (a). (b) Shows only small- St results on a linear plot to emphasize the rapid reduction in kurtosis as St increases from 0.

factor of two smaller than that of fluid particles. The largest- St particles have kurtosis values approaching those of a Gaussian distribution. These trends can be explained by the fact that both preferential sampling and inertial filtering decrease the probability of high-intensity acceleration events. Standardized moments of up to order 10 (not shown) were also analysed and found to exhibit the same trends.

We should note that the grid resolution study in Yeung *et al.* (2006) suggests that the acceleration moments from our DNS may be underpredicted. Yeung *et al.* (2006) showed that at $R_\lambda \approx 140$, increasing the grid resolution $k_{max}\eta$ from 1.5 to 12 led to a 10 % increase in the fluid acceleration variance and a 30 % increase in the fluid acceleration kurtosis. It is unclear how these trends will change at higher R_λ , but it suggests that the quantitative results reported here should be interpreted with caution. (The velocity gradients presented earlier are likely reliable, however, since Yeung *et al.* (2006) found that such statistics are less dependent on the grid resolution.)

4. Two-particle statistics

We now consider two-particle statistics relevant for predicting inertial particle collisions. We analyse particle relative velocities in § 4.1, clustering in § 4.2 and use these data to compute the collision kernel in § 4.3. (The mean-squared separation of inertial particle pairs was also studied from these data and is the topic of a separate publication (Bragg, Ireland & Collins 2016).)

4.1. Particle relative velocities

We study particle relative velocities as a function of both St and R_λ . The relative velocities for inertial particles are defined by the relation

$$w_{\parallel,\perp}^p(t) \equiv [\mathbf{v}_2^p(t) - \mathbf{v}_1^p(t)] \cdot \mathbf{e}_{\parallel,\perp}^p(t). \quad (4.1)$$

Here, \mathbf{v}_1^p and \mathbf{v}_2^p indicate the velocities of particles 1 and 2, respectively, which are separated from each other by a distance $r^p(t) = |\mathbf{r}^p(t)|$. The subscripts \parallel and \perp indicate directions parallel (longitudinal) to the separation vector or perpendicular

(transverse) to the separation vector, respectively, and $\mathbf{e}_{\parallel,\perp}^p$ denotes the unit vector in the corresponding direction. (We use the method discussed in Pan & Padoan (2013) to compute the transverse components. Pan & Padoan (2013) set up a local coordinate system for each particle pair, and choose one unit vector of the coordinate system to align with the separation vector between the particles. They then apply two successive rotations to this unit vector to define two transverse unit vectors, which are used to compute two statistically equivalent transverse relative velocity components.)

We will also examine the velocity differences of the fluid at the particle locations, defined as

$$\Delta u_{\parallel,\perp}^p(t) \equiv [\mathbf{u}_2^p(t) - \mathbf{u}_1^p(t)] \cdot \mathbf{e}_{\parallel,\perp}^p(t), \quad (4.2)$$

where \mathbf{u}_1^p and \mathbf{u}_2^p are the velocities of the fluid underlying particles 1 and 2, respectively. Note that for uniformly distributed fluid ($St = 0$) particles, the particle velocity statistics are equivalent to the underlying fluid velocity statistics.

Following the nomenclature in Bragg & Collins (2014a,b), we denote particle relative velocity moments of order n as

$$S_{n\parallel}^p(r) \equiv \langle [w_{\parallel}^p(t)]^n \rangle_r, \quad (4.3)$$

for the components parallel to the separation vector, and as

$$S_{n\perp}^p(r) \equiv \langle [w_{\perp}^p(t)]^n \rangle_r, \quad (4.4)$$

for components perpendicular to the separation vector. In these expressions $\langle \cdot \rangle_r$ denotes an ensemble average conditioned on $r^p(t) = r$.

For the purposes of computing the collision kernel (see § 4.3), we are also interested in the mean inward relative velocity parallel to the separation vector, defined as

$$S_{-\parallel}^p(r) \equiv - \int_{-\infty}^0 w_{\parallel} p(w_{\parallel}|r) dw_{\parallel}, \quad (4.5)$$

where $p(w_{\parallel}|r) = \langle \delta(w_{\parallel}^p(t) - w_{\parallel}) \rangle_r$ is the PDF for the longitudinal particle relative velocity conditioned on $r^p(t) = r$.

Finally, in some cases we are also interested in moments of the fluid velocity differences. We use a superscript fp to denote the moments of fluid velocity differences at the particle locations, and a superscript f to denote the moments of fluid velocity differences at fixed points with separation r . We therefore have

$$S_{n\parallel}^{fp}(r) \equiv \langle [\Delta u_{\parallel}(r^p(t), t)]^n \rangle_r, \quad (4.6)$$

and

$$S_{n\parallel}^f(r) \equiv \langle [\Delta u_{\parallel}(r, t)]^n \rangle. \quad (4.7)$$

The components perpendicular to the separation vector are defined analogously.

In figure 12, we plot the relative velocity variances $S_{2\parallel}^p$ and $S_{2\perp}^p$ versus r/η at $R_\lambda = 597$. The mean inward relative velocity (not shown) has the same qualitative trends and will be considered later in this section. For the purposes of the following discussion, we define the dissipation range as the region over which the fluid velocity variances follow r^2 -scaling, which is seen to be $0 \leq r/\eta \lesssim 10$ in figure 12, in agreement with Ishihara *et al.* (2009).

At small separations, the relative velocity variances parallel to the separation vector (figure 12a) increase monotonically with St and deviate from r^2 -scaling, while the relative velocity variances perpendicular to the separation vector decrease for $St \lesssim 0.1$

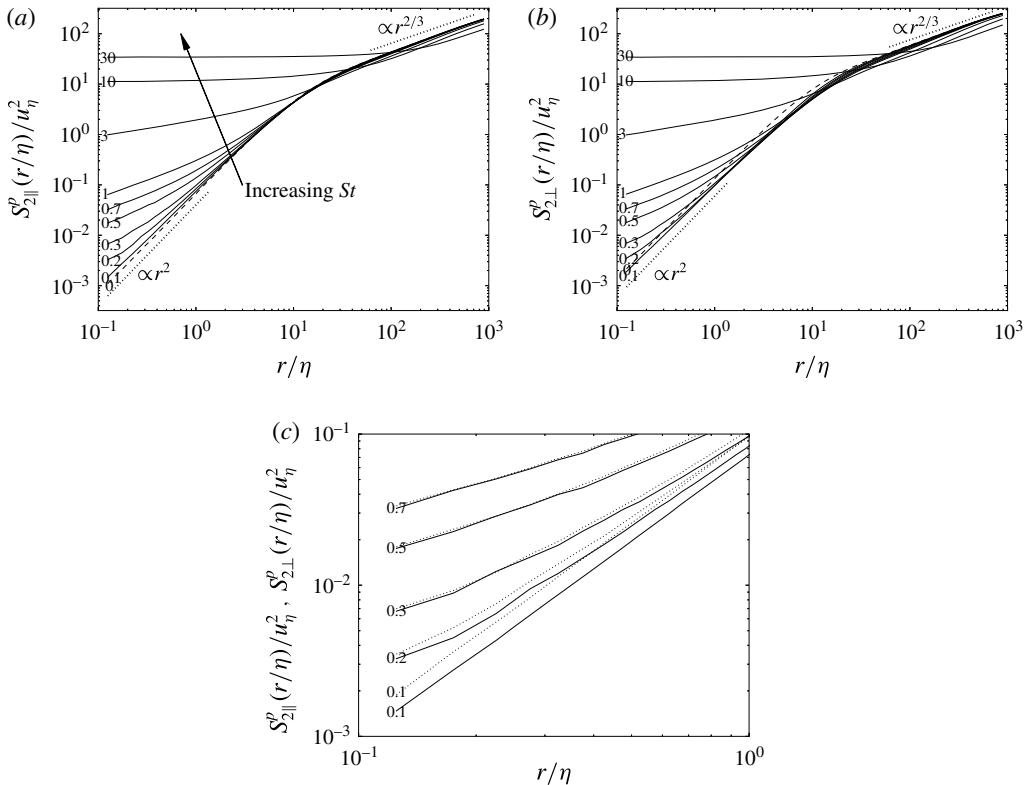


FIGURE 12. The particle relative velocity variances parallel to the separation vector (a) and perpendicular to the separation vector (b), plotted as a function of the separation r/η for $R_\lambda = 597$. The Stokes numbers are indicated by the line labels, and the $St = 0$ curves are shown with dashed lines for clarity. The expected dissipation and inertial range scalings (based on Kolmogorov 1941) are included for reference. In (c), we have included parallel and perpendicular relative velocities at small St and small separations to highlight the behaviour in this regime. $S_{2\parallel}^p$ values are plotted with solid lines, and $S_{2\perp}^p$ values with dotted lines. The Stokes numbers are indicated by the line labels.

and then increase monotonically with St for $St \gtrsim 0.1$ (figure 12b). We expect that the trends at small separations and small St are primarily due to preferential sampling of the underlying flow, which also dictates much of the single-particle dynamics for small St (refer to § 3).

To test this expectation, we compare the particle relative velocity variances to those of the fluid sampled by the particles in figure 13. In all cases, the velocity variances are normalized by those of $St = 0$ particles. At $St = 0.05$ (figure 13a,b), the effect of preferential sampling is dominant at all separations, as evidenced by the fact that $S_{2\parallel}^{fp}$ and $S_{2\perp}^{fp}$ are close to $S_{2\parallel}^p$ and $S_{2\perp}^p$, respectively. We note that for small St and small r/η , preferential sampling leads to an increase in $S_{2\parallel}^{fp}$ with increasing St and to a decrease in $S_{2\perp}^{fp}$ with increasing St . This is consistent with the trends observed in figure 12 and with our argument (§ 3.1) that inertia causes particles to be ejected from high rotation regions of the flow. We expect that two particles in a high rotation region will experience small relative velocities parallel to the particle separation vector and large relative velocities perpendicular to the particle separation vector,

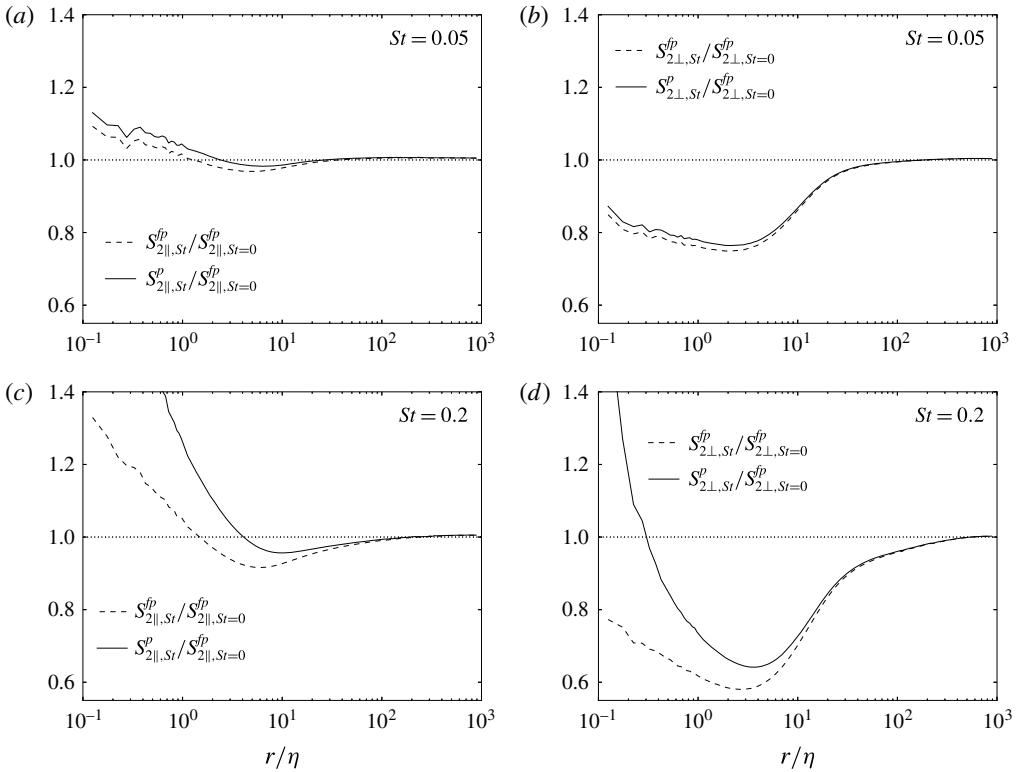


FIGURE 13. The parallel (*a,c*) and perpendicular (*b,d*) relative velocity variances of inertial particles ($S_{2\parallel}^p$ and $S_{2\perp}^p$, solid lines) and of the fluid at inertial particle positions ($S_{2\parallel}^{fp}$ and $S_{2\perp}^{fp}$, dashed lines) for $R_\lambda = 597$. All quantities are normalized by the relative velocity variances of $St = 0$ particles. $St = 0.05$ results are shown in (*a,b*), and $St = 0.2$ results are shown in (*c,d*).

as suggested by figure 14(*a*). We also expect that the parallel relative velocities will increase as particles accumulate in straining regions of the flow as a result of their inertia, while the perpendicular relative velocities will decrease, as shown in figure 14(*b*). Interestingly, we observe an opposite trend in the parallel relative velocities at $r/\eta \sim 10$. We notice that $S_{2\parallel,St}^p/S_{2\parallel,St=0}^{fp}$ is slightly below 1, indicating that inertial particles have smaller parallel relative velocities than fluid particles. While the reason for this trend is unclear, since $S_{2\parallel,St}^p/S_{2\parallel,St=0}^{fp}$ and $S_{2\parallel,St}^{fp}/S_{2\parallel,St=0}^{fp}$ are approximately equal here, it must be related in some way to preferential sampling effects. At the largest separations, the relative velocities for inertial and fluid particles become equivalent, as expected, indicating that preferential sampling effects vanish in this limit.

For $St = 0.2$, the particle relative velocities are much larger than the underlying fluid velocity differences at small separations, as is evident in figure 13(*c,d*). This difference is due to path-history effects (see Bragg & Collins 2014*a,b*). That is, as inertial particles approach each other, they retain a memory of more energetic turbulence scales along their path histories, leading to relative velocities that exceed the local fluid velocity difference. These path-history effects imply that inertial particles can come together from different regions in the flow, occupy the same

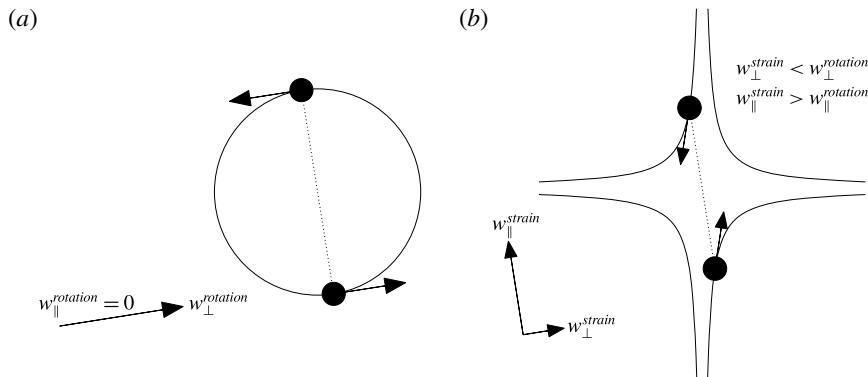


FIGURE 14. An illustration of the effect of preferential sampling on the parallel relative velocity w_{\parallel} and the perpendicular relative velocity w_{\perp} . In (a), two particles are in a rotating region of the flow. In this case, w_{\parallel} is small and w_{\perp} is large. In (b), the particles have been ejected from the rotating region as a result of their inertia and are in a straining region of flow. The two particles have a small value of w_{\perp} and a large value of w_{\parallel} .

position in the flow at the same time and yet have different velocities due to their differing path histories. This effect is referred to as ‘caustics’, ‘crossing trajectories’ or ‘the sling effect’, causes a departure from r^2 -scaling in the second-order structure functions at small separations and can lead to large relative velocities (Yudine 1959; Falkovich *et al.* 2002; Wilkinson & Mehlig 2005; Wilkinson *et al.* 2006; Falkovich & Pumir 2007). (Also note that while caustics are instantaneous events, the statistical manifestation of caustics is known as ‘random, uncorrelated motion’ and is discussed in IJzermans, Meneguz & Reeks (2010).) Since the time scale over which the particles retain a memory of their interactions with turbulence increases with increasing inertia, caustics become more prevalent as St increases.

One effect of caustics is to make the parallel and perpendicular relative velocity components nearly the same in the dissipation range, as can be seen in figure 12(c) for $St \gtrsim 0.3$. (Note that fluid particles do not experience caustics and have $2S_{2\parallel}^p = S_{2\perp}^p$ for $r/\eta \ll 1$ as a result of continuity (e.g. see Pope 2000).) For $St \geq 10$, the relative velocities are almost unaffected by the underlying turbulence in the dissipation range. As a result, the relative velocities are nearly independent of r/η in this range.

The effect of caustics can also be clearly seen in figure 15, where we plot the parallel relative velocities at a given separation as a function of St . From this figure, it is evident that the particle relative velocities at the smallest separation sharply increase as St exceeds approximately 0.2. The rapid increase in the particle relative velocities with St is consistent with the notion that caustics take an activated form (Wilkinson *et al.* 2006) and that they are negligible below a critical value of St (IJzermans *et al.* 2010; Salazar & Collins 2012b). Our data suggest a critical Stokes number for caustics of approximately 0.2–0.3, in agreement with Falkovich & Pumir (2007) and Salazar & Collins (2012b). The increase in the relative velocities occurs at higher values of St as the separation increases. In this case, the particles are subjected to larger-scale turbulence, and hence the particles must have more inertia for their motion to deviate significantly from that of the underlying flow.

We now examine the Reynolds-number dependence of the relative velocities, restricting our attention to the component parallel to the separation vector. From figure 15, we see that the relative velocities of the largest particles ($St \gtrsim 10$) increase

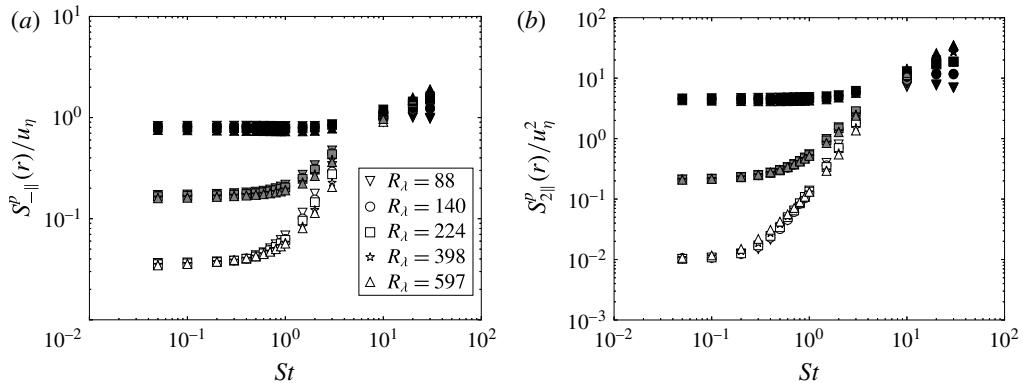


FIGURE 15. (a) The mean inward relative velocities and (b) the relative velocity variances, plotted as a function of St for small separations and different values of R_λ . Open symbols denote $r = 0.25\eta$, grey filled symbols denote $r = 1.75\eta$ and black filled symbols denote $r = 9.75\eta$.

strongly with increasing R_λ . There are two reasons for this trend. The first is that the effect of filtering on the larger turbulence scales decreases as R_λ is increased (see § 3.2). The second is that u'/u_η increases with increasing R_λ , indicating that large- St particles in the dissipation range carry a memory of increasingly energetic turbulence (relative to the Kolmogorov scales) in their path history as R_λ is increased.

For smaller values of St ($St \leq 3$), the relative velocities in figure 15 are only weakly dependent on R_λ , in agreement with previous DNS studies (Wang *et al.* 2000; Bec *et al.* 2010a; Onishi, Takahashi & Vassilicos 2013; Rosa *et al.* 2013; Onishi & Vassilicos 2014) and the model of Pan & Padoan (2010). To highlight any small Reynolds-number effects in this range, we therefore divide the relative velocities at $r = 0.25\eta$ and a certain R_λ by their value at $R_\lambda = 88$ and plot the results in figure 16. We have included 95 % confidence intervals about the predicted values to provide an indication of the statistical significance of these weak Reynolds-number effects.

For $St = 0.3$, the relative velocity variances increase weakly with increasing R_λ (see figure 16b). As R_λ increases, the range of velocity scales u'/u_η increases, allowing some particle pairs in this Stokes-number range to sample more energetic turbulence as they converge to small separations, and causing the relative velocity variances to increase with increasing Reynolds number. Furthermore, turbulence intermittency, which also increases with increasing Reynolds number, may also contribute to the trend in the relative velocity statistics. We note that the mean inward velocities (figure 16a) are less affected by changes in Reynolds number, presumably because the mean inward velocity is a lower-order statistic that is less influenced by the relatively rare events described above.

For $St = 3$, we also expect the increased scale separation, the increased intermittency of the turbulence or both to act to increase the relative velocities. However, we observe an overall decrease in the relative velocities with increasing R_λ here, in agreement with Bec *et al.* (2010a), Rosa *et al.* (2013). These reduced relative velocities are likely linked to the decrease in the Lagrangian rotation time scales T_{RR}^p/τ_η with increasing R_λ observed in § 3.1. That is, as T_{RR}^p/τ_η decreases with increasing R_λ , the particles have a shorter memory of fluid velocity differences along their path histories, which in turn causes the relative velocities to decrease.

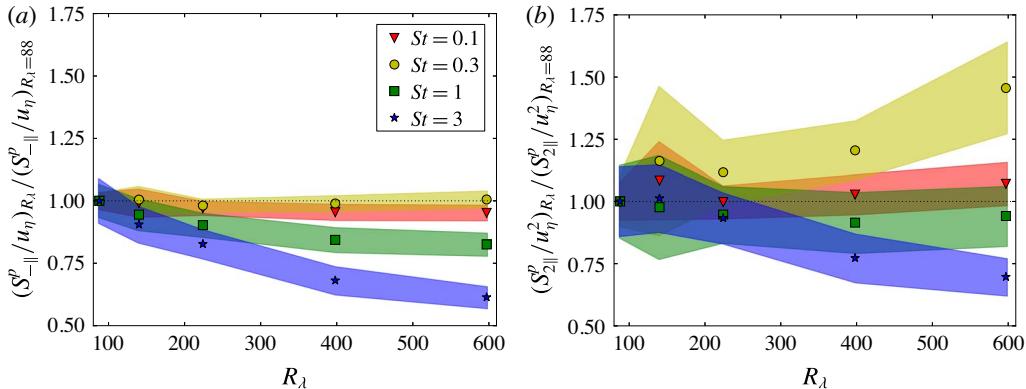


FIGURE 16. (Colour online) (a) The mean inward relative velocities and (b) the relative velocity variances, plotted as function of R_λ . The relative velocities are shown at $r/\eta = 0.25$, and the quantities at a given Reynolds number are divided by their corresponding value at $R_\lambda = 88$. Shaded contours denote 95 % confidence intervals about the sample mean.

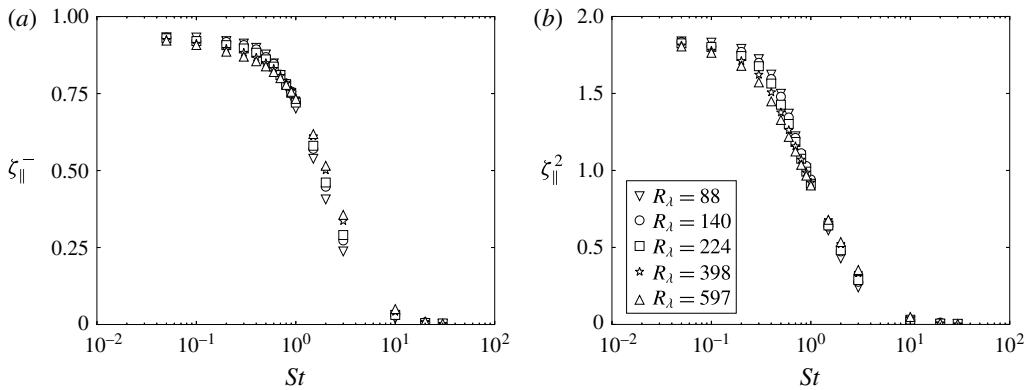


FIGURE 17. Dissipation range scaling exponents for $S_{-\parallel}^p$ (a) and $S_{2\parallel}^p$ (b) for various values of St and R_λ . The exponents are computed from linear least-squares regression for $0.75 \leq r/\eta \leq 2.75$.

We now examine the behaviour of the scaling exponents of $S_{-\parallel}^p \propto r^{\zeta_{\parallel}^-}$ and $S_{2\parallel}^p \propto r^{\zeta_{\parallel}^2}$ at small separations. (These scaling exponents will also be used in § 4.2 to understand and predict the trends in the particle clustering.) We compute ζ_{\parallel}^- and ζ_{\parallel}^2 using a linear least-squares regression for $0.75 \leq r/\eta \leq 2.75$ at different values of St and R_λ . Note that while using such a large range of r/η will necessarily introduce finite-separation effects, there is generally too much noise in the data to accurately compute the scaling exponents over smaller separations.

The scaling exponents are plotted in figure 17. We note that the scaling exponents are below those predicted by Kolmogorov (1941) (hereafter ‘K41’) for fluid ($St = 0$) particles ($\zeta_{\parallel}^- = 1$ and $\zeta_{\parallel}^2 = 2$) and, like the relative velocities themselves, vary only slightly as R_λ changes.

For $St \geq 10$, the scaling exponents are approximately zero, indicating that the relative velocities are generally independent of r , as explained above. The scaling

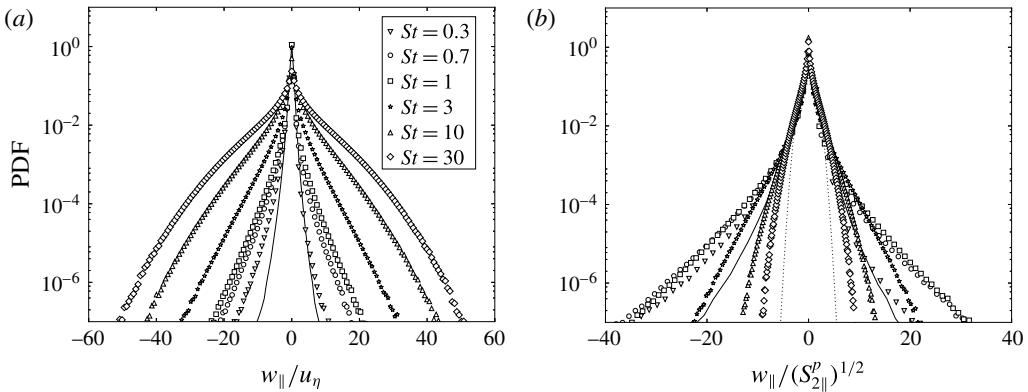


FIGURE 18. PDFs of the particle relative velocities w_{\parallel}^p for separations $0 \leq r/\eta \leq 2$ and $R_{\lambda} = 597$. The relative velocities are normalized by both u_{η} (a) and $(S_{2\parallel}^p)^{1/2}$ (b). The solid lines denote the relative velocity PDFs for $St = 0$ particles, and the dotted line in (b) indicates a standard normal distribution.

exponents for $1 \lesssim St \lesssim 3$ generally increase with increasing R_{λ} , since path-history interactions (which generally decrease the scaling exponents) become less important, as explained above. Finally, we note that ζ_{\parallel}^2 decreases with increasing R_{λ} for $St \lesssim 1$, since intermittent path-history effects are expected to be more important here.

We next consider the PDFs of the relative velocities in the dissipation range. Figure 18 shows the PDFs for $0 \leq r/\eta \leq 2$ and $R_{\lambda} = 597$. In figure 18(a), we see that as St increases, the tails of the PDF of w_{\parallel}^p/u_{η} become more pronounced, indicating that larger relative velocities become more frequent, in agreement with our observations above.

We show PDFs in standardized form in figure 18(b) to analyse the extent to which they deviate from that of a Gaussian distribution. It is evident that the degree of non-Gaussianity peaks for $St \sim 1$ and becomes smaller as St increases. The physical explanation for this intermittency at $St \sim 1$ is that the motion of these particles is affected by both the small-scale underlying turbulence and by the particles' memory of large-scale turbulent events in their path histories. This combination of contributions from both large- and small-scale events leads to strong intermittency. We also see that the underlying fluid is itself quite intermittent at this small separation, as expected (e.g. see Gotoh, Fukayama & Nakano 2002).

We now use three statistical measures to quantify the shape of the PDFs. The first is the ratio between the mean inward relative velocities and the standard deviation of the relative velocities, $S_{-||}^p/(S_{2||}^p)^{1/2}$; the second is the skewness of the relative velocities, $S_{3||}^p/(S_{2||}^p)^{3/2}$; and the third is the kurtosis of the relative velocities, $S_{4||}^p/(S_{2||}^p)^2$. (Due to insufficient statistics, we will not consider data from these latter two quantities for $r/\eta < 1.75$.)

We show the ratio $S_{-||}^p/(S_{2||}^p)^{1/2}$ in figure 19. One motivation for looking at this ratio is that existing theories (e.g. see Zaichik *et al.* 2003; Pan & Padoan 2010) only predict the relative velocity variance, and by assuming the relative velocities have a Gaussian distribution, relate this variance to the mean inward relative velocity. For a Gaussian distribution, this ratio is approximately 0.4. At all values of St , R_{λ} and r/η , our data indicate that the ratio is below 0.4 and thus that the particle relative velocities are intermittent (see also Wang *et al.* 2000; Pan & Padoan 2013). The degree of

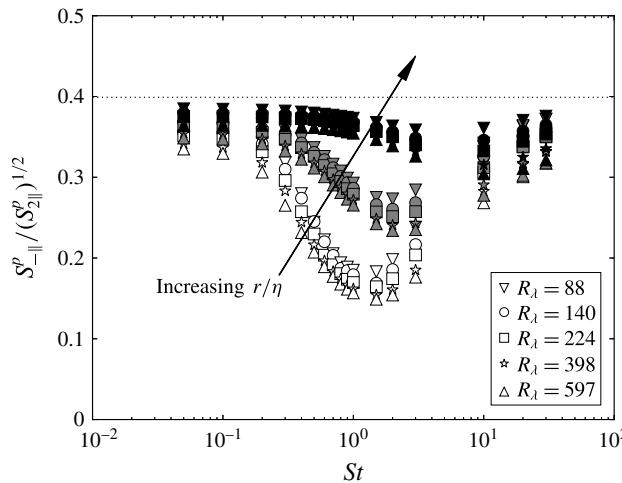


FIGURE 19. The ratio between mean inward relative velocities and the standard deviation of the relative velocities as a function of St for small separations and different values of R_λ . Open symbols denote $r = 0.25\eta$, grey filled symbols denote $r = 1.75\eta$, and black filled symbols denote $r = 9.75\eta$. The horizontal dotted line indicates that value of this quantity for a Gaussian distribution.

intermittency peaks for order unity St , high R_λ and small r/η , and using a Gaussian prediction in this regime would lead to predictions of the mean inward velocity which are in error by more than a factor of 2.

We next consider the skewness, $S_{3||}^p / (S_{2||}^p)^{3/2}$, to provide information about the asymmetry of the relative velocities. Figure 20(a) indicates that the relative velocities are negatively skewed (Wang *et al.* 2000; Ray & Collins 2011). This skewness is a result of two contributions. First, the velocity derivatives of the underlying turbulence are negatively skewed, a consequence of the energy cascade (Tavoularis, Bennett & Corrsin 1978). Second, additional skewness arises from the path-history effect described earlier (see also Bragg & Collins 2014b). Figure 20(a) shows by implication that at $St \sim 1$ it is the latter effect that dominates the skewness behaviour. At even larger values of St , the effect of both mechanisms decreases because, with increasing Stokes number, the particle velocity dynamics becomes increasingly decoupled from the small-scale fluid velocity field and their motion becomes increasingly ballistic in the dissipation range.

Finally, we consider the kurtosis of the relative velocities, $S_{4||}^p / (S_{2||}^p)^2$, in figure 20(b) to quantify the contributions from intermittent events in the tails of the PDFs. The trends are similar to those in $S_{-||}^p / (S_{2||}^p)^{1/2}$, as expected, indicating that contributions from intermittent events become strongest for intermediate St , the smallest separations and the highest Reynolds numbers. In all cases, the kurtosis is above that for a Gaussian distribution ($S_{4||}^p / (S_{2||}^p)^2 = 3$).

Finally we close this section with two comments. We first note that the recent study by Saw *et al.* (2014) that compares experimentally measured relative velocities of inertial particles with DNS found that while the Stokes drag model is able to capture all of the qualitative trends observed in the experiments, it is unable to provide quantitative predictions for the tails of the relative velocity PDFs, suggesting that some of the neglected terms in the Maxey & Riley (1983) particle equation of motion may be required to yield quantitatively correct higher-order relative velocity statistics.

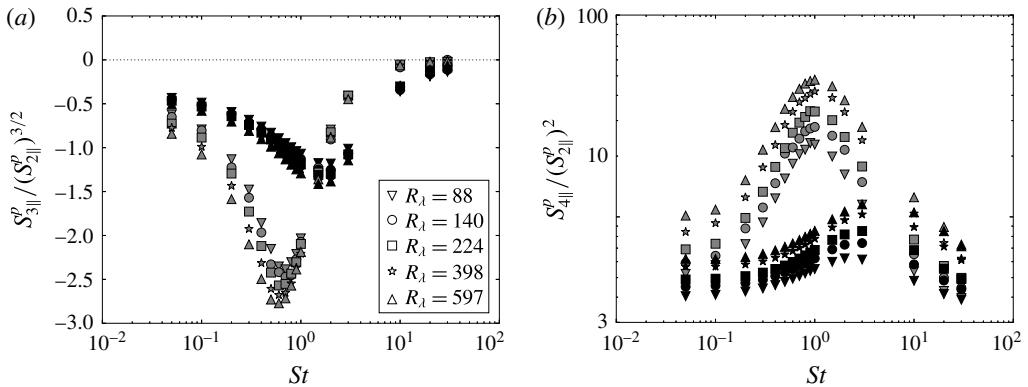


FIGURE 20. The (a) skewness and (b) kurtosis of the relative velocities as a function of St for separations in the dissipation range and different values of R_λ . Grey filled symbols denote $r = 1.75\eta$, and black filled symbols denote $r = 9.75\eta$.

The second comment is related to the inertial range structure functions. It is a common practice to report the power-law exponents of higher-order velocity structure functions for fluid particles (e.g. see Kerr, Meneguzzi & Gotoh 2001; Gotoh *et al.* 2002; Shen & Warhaft 2002; Ishihara *et al.* 2009). Salazar & Collins (2012*b*) reported the corresponding exponents for inertial particles. However, as shown by Bragg, Ireland & Collins (2015), in a turbulent flow with infinite Reynolds number, and $r/\eta \gg St^{3/2}$, the inertial particle structure functions reduce to those of fluid particles. Yet for those same particles in the range $1 \ll r/\eta \ll St^{3/2}$, inertial effects cause systematic deviations between inertial particle and fluid particle structure functions. The existence of two scaling regions for inertial particles in high-Reynolds-number turbulence implies that no single exponent can capture the entire inertial range. Thus, the results reported in Salazar & Collins (2012*b*) are most likely an artefact of the relatively low Reynolds number of the study ($R_\lambda \leqslant 120$).

4.2. Particle clustering

As discussed in § 1, inertial particles form clusters when placed in a turbulent flow. We first consider a theoretical framework for understanding this clustering (§ 4.2.1), and then analyse the clustering using DNS (§ 4.2.2).

4.2.1. Theoretical framework for particle clustering

A variety of measures have been proposed to study particle clustering, including Voronoï diagrams (Monchaux *et al.* 2010), Lyapunov exponents (Bec *et al.* 2006*b*), Minkowski functionals (Calzavarini *et al.* 2008) and radial distribution functions (RDFs) (McQuarrie 1976). These methods provide insight into particle clustering in a variety of different ways. As pointed out by a referee, Minkowski functionals and Voronoï diagrams provide information about nearest-neighbour particles, while Lyapunov exponents are capable of providing information about the entire small-scale distribution of particles. The RDF has distinct advantages over these other methods for our purposes. The RDF, unlike both Minkowski functionals (Calzavarini *et al.* 2008) and Voronoï diagrams (Tagawa *et al.* 2012), is not biased by the number of particles simulated. Also, as Bec *et al.* (2006*b*) noted, the accurate computation of

Lyapunov exponents is numerically infeasible for high-Reynolds-number simulations, while computation of the RDF is relatively straightforward. Finally, the RDF, unlike the other measures, has a direct relevance to particle collisions, since it precisely corrects the collision kernel for particle clustering (Sundaram & Collins 1997) in the limit of vanishing particle concentration. Since our simulations are performed with very dilute particle seedings, we neglect higher-order corrections to the collision kernel that result from particle collision histories and triple correlations.

The RDF $g(r)$ is defined as the ratio of the number of particle pairs at a given separation r to the expected number of particle pairs in a uniformly distributed particle field,

$$g(r) \equiv \frac{N_i/V_i}{N/V}. \quad (4.8)$$

Here, N_i is the number of particle pairs that lie within a shell with an average radius r and a radial width Δr , V_i is the volume of the shell and N is the total number of particle pairs located in the total volume V . An RDF of unity corresponds to uniformly distributed particles, while an RDF in excess of one indicates a clustered particle field.

Based on the findings of Bragg & Collins (2014a), we use the model of Zaichik & Alipchenkov (2009) as a framework for understanding the physical mechanisms governing particle clustering. We will validate this model against DNS data in § 4.2.2. In the following discussion, we non-dimensionalize all variables by Kolmogorov units and use \hat{Y} to denote the non-dimensionalized form of a variable Y .

From Zaichik & Alipchenkov (2009), the equation describing $g(\hat{r})$ at steady state for an isotropic system is

$$0 = -St(\hat{S}_{2\parallel}^p + \hat{\lambda}_\parallel)\nabla_{\hat{r}}g - Stg(\nabla_{\hat{r}}\hat{S}_{2\parallel}^p + 2\hat{r}^{-1}[\hat{S}_{2\parallel}^p - \hat{S}_{2\perp}^p]), \quad (4.9)$$

where $\hat{\lambda}_\parallel$ is a diffusion coefficient describing the effect of the turbulence on the dispersion of the particle pairs (e.g. see Bragg & Collins 2014a). We now consider (4.9) in different St -regimes to consider the effect of changes in R_λ within these regimes.

In the limit $St \ll 1$, (4.9) can be reduced to (see Bragg & Collins 2014a),

$$0 = -\hat{r}^2B_{nl}\nabla_{\hat{r}}g - \frac{St}{3}\hat{r}g(\langle\hat{S}^2\rangle^p - \langle\hat{R}^2\rangle^p), \quad (4.10)$$

where B_{nl} is a St -independent, non-local diffusion coefficient (see Chun *et al.* 2005; Bragg & Collins 2014a). The first term on the right-hand side is associated with an outward particle diffusion which reduces clustering, while the second term on the right-hand side is responsible for an inward particle drift which increases clustering.

We therefore see that if B_{nl} is independent of R_λ , the diffusion will be independent of R_λ . The drift is dependent on $\tau_\eta^2\langle S^2\rangle^p - \tau_\eta^2\langle R^2\rangle^p$, and we see from § 3.1 that $\tau_\eta^2\langle S^2\rangle^p - \tau_\eta^2\langle R^2\rangle^p$ increases weakly with R_λ for $St \ll 1$. We therefore expect the degree of clustering at low St to increase weakly as R_λ increases. We will test this expectation against DNS data in § 4.2.2.

For particles with intermediate values of St , we are generally unable to simplify (4.9), since all terms are of comparable magnitude, and the clustering in this range is due to both preferential sampling and path-history effects. Bragg & Collins (2014a) showed that path-history effects induce an asymmetry in the particle inward and outward motions, causing particles to come together more rapidly than they separate,

generating a net inward drift and increased clustering. The precise range of St over which path-history effects increase clustering will likely vary with R_λ , but a rough guideline (based on Bragg & Collins 2014a) is $0.2 \lesssim St \lesssim 0.7$. Below this range, path-history effects have a negligible impact on particle clustering, and above this range, the path-history mechanism acts to diminish clustering. For the upper end of this St range, path-history effects are the dominant particle clustering mechanism (Bragg & Collins 2014a).

We next simplify (4.9) when $St \gtrsim 1$. As noted in § 4.1, at sufficiently large St and small r/η , the relative particle velocities are dominated by path-history effects and $S_{2\parallel}^p \approx S_{2\perp}^p$. Furthermore, $\lambda_\parallel \ll S_{2\parallel}^p$ in this regime (see Bragg & Collins 2014b). Using these results we can simplify (4.9) in the dissipation range to the form,

$$0 \approx -St\hat{S}_{2\parallel}^p \nabla_{\hat{r}} g - Stg \nabla_{\hat{r}} \hat{S}_{2\parallel}^p. \quad (4.11)$$

The overall changes in the particle clustering at high St will therefore be determined by the extent to which the drift coefficient ($\nabla_{\hat{r}} \hat{S}_{2\parallel}^p$) and the diffusion coefficient ($\hat{S}_{2\parallel}^p$) are influenced by changes in R_λ . That is, if the ratio between the drift and diffusion coefficients increases (decreases) with increasing R_λ , the RDFs are expected to increase (decrease).

We therefore take the ratio between the drift and diffusion coefficients in the dissipation range and obtain

$$\frac{\nabla_{\hat{r}} \hat{S}_{2\parallel}^p}{\hat{S}_{2\parallel}^p} = \frac{\zeta_\parallel^2}{\hat{r}}, \quad (4.12)$$

where ζ_\parallel^2 is the scaling exponent of the longitudinal relative velocity variance. Equation (4.12) implies that increases (decreases) in ζ_\parallel^2 are fundamentally linked to increases (decreases) in the RDFs at high St . From § 4.1, we see that ζ_\parallel^2 increases with increasing R_λ for $1 \lesssim St \lesssim 3$, which suggests that $g(r/\eta)$ will increase with increasing R_λ here.

We also note that (4.12) can only be used to predict the trends in clustering for particles with finite ζ_\parallel^2 . Particles with sufficiently large St have $\zeta_\parallel^2 = 0$, and for such particles the effect of R_λ on the RDFs in the dissipation range is controlled exclusively by the boundary condition for g at the edge of the dissipation range. This boundary condition depends upon the inertial range clustering of particles and cannot be inferred from the behaviour of ζ_\parallel^2 . We will examine the RDFs for $St > 3$ from DNS data in § 4.2.2.

In summary, at small St , clustering may increase with increasing R_λ depending upon whether B_{nl} varies with R_λ . Clustering at intermediate values of St will be due to both preferential sampling and path-history effects, though it is unclear the degree to which $g(r/\eta)$ will change with R_λ . At high St , the degree of clustering is determined by the influence of path-history effects on the scaling of the relative velocity variances, which in turn affects the relative strengths of the drift and diffusion mechanisms. Based on our relative velocity data in § 4.1, we expect that clustering will increase with increasing R_λ here. We next consider DNS data to test these predictions.

4.2.2. Particle clustering results

In figure 21, we plot the RDFs for the different values of St considered at three different Reynolds numbers. Note that as the size of the simulation (and thus R_λ)

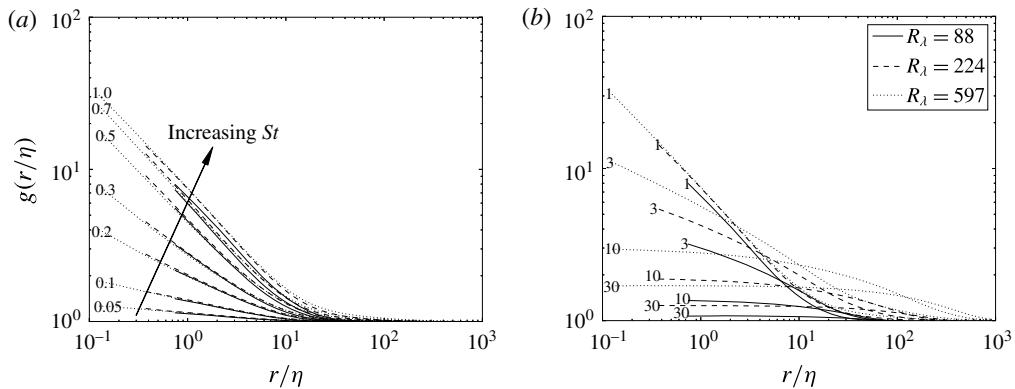


FIGURE 21. RDFs for (a) low- St particles and (b) high- St particles at three different values of R_λ , plotted as a function of the radial separation r/η . The Stokes numbers are indicated by the line labels.

increases, we are able to calculate $g(r/\eta)$ statistics accurately at progressively smaller values of r/η .

In agreement with past studies (e.g. see Wang & Maxey 1993; Sundaram & Collins 1997; Balachandar & Eaton 2010), we see that particle clustering peaks for $St \sim 1$ at all Reynolds numbers shown. Figure 21 also indicates that the largest particles ($St \geq 10$) exhibit clustering outside of the dissipation range of turbulence and that the degree of clustering is independent of separation in the dissipation range. This is because large- St particles are unresponsive to the dissipative range scales and so move almost ballistically at these separations. The clustering that is observed for these particles is due almost entirely to eddies in the inertial range with time scales similar to the particle response time (Goto & Vassilicos 2006; Bec *et al.* 2010*b*). If we make that assumption, along with the standard K41 approximations for the inertial range, we expect the clustering will depend only on ϵ and r and will occur at length scales of the order of $\eta St^{3/2}$ (ElMaihy & Nicolleau 2005; Bec *et al.* 2010*b*). We test this in figure 22 by plotting the RDFs for $St = 20$ and $St = 30$ particles as a function of $r/(\eta St^{3/2})$ at the three highest Reynolds numbers. (The two lower Reynolds numbers do not have a well-defined inertial range, as noted in § 2.1, and hence the above argument would not hold.) We see that the RDFs decrease rapidly near $r/(\eta St^{3/2}) \sim 1$, suggesting that the particles are indeed clustering due to the influence of turbulent eddies in the inertial range with a time scale of the order of τ_p . Refer to Bragg *et al.* (2015) for a recent theoretical and computational analysis of particle clustering in the inertial range of turbulence.

We now discuss how the RDFs change with the Reynolds number. For $St \gtrsim 1$, the RDFs increase with increasing R_λ , as is clearly evident in figures 21(b) and 22. This is in agreement with our expectations in § 4.2.1. At lower values of St , however, the trends with R_λ are at most weak and are not obvious from figure 21(a). We therefore plot the RDFs at $r/\eta = 0.25$ as a function of R_λ in figure 23 and normalize the RDFs at a given Reynolds number by their corresponding value at $R_\lambda = 88$. We have included 95 % confidence intervals for the RDFs to provide an indication of the statistical significance of any weak Reynolds-number effects.

In § 4.2.1, we argued that $g(r/\eta)$ might increase weakly with R_λ for $St \ll 1$, since $\tau_\eta^2 \langle S^2 \rangle^p - \tau_\eta^2 \langle R^2 \rangle^p$ increases with R_λ in this limit. In figure 23, however, we observe

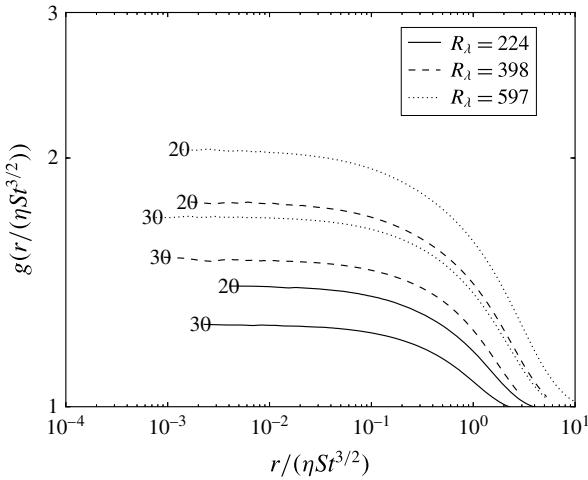


FIGURE 22. RDFs for $St = 20$ and $St = 30$ particles at the three highest values of R_λ . The separations are scaled by $\eta St^{3/2}$ to test for inertial range scaling. The Stokes numbers are indicated by the line labels.

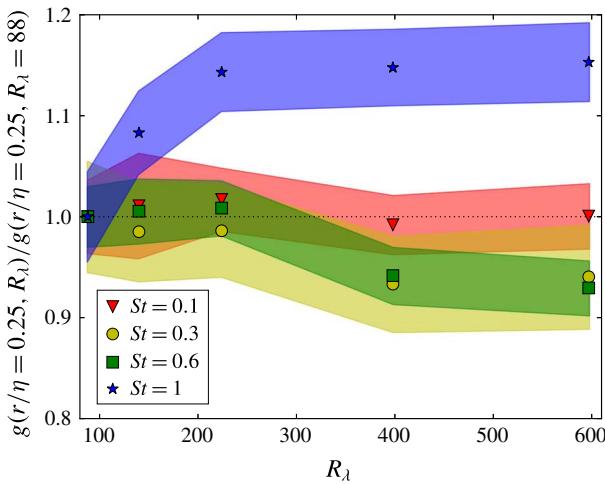


FIGURE 23. (Colour online) The normalized RDFs at $r/\eta = 0.25$, plotted as a function of R_λ . The RDFs at a given Reynolds number are normalized by their corresponding value at $R_\lambda = 88$ to highlight any slight Reynolds-number effects. Shaded contours denote 95 % confidence intervals for the RDFs.

that $g(r/\eta)$ is essentially independent of R_λ for $St < 1$, which implies that the non-local correction coefficient B_{nl} in (4.10) must increase weakly with R_λ in a compensating way. Several authors have also found the level of particle clustering to be independent of R_λ at small St (without gravity), including Collins & Keswani (2004) (from data at $65 \leq R_\lambda \leq 152$), Bec *et al.* (2007) ($65 \leq R_\lambda \leq 185$), Bec *et al.* (2010a) ($185 \leq R_\lambda \leq 400$), Ray & Collins (2011) ($95 \leq R_\lambda \leq 227$) and Rosa *et al.* (2013) ($28 \leq R_\lambda \leq 304$). Our data confirms this point up to $R_\lambda = 597$. The fact that $g(r/\eta)$ is independent of R_λ for small Stokes numbers implies that the clustering mechanism is driven almost entirely

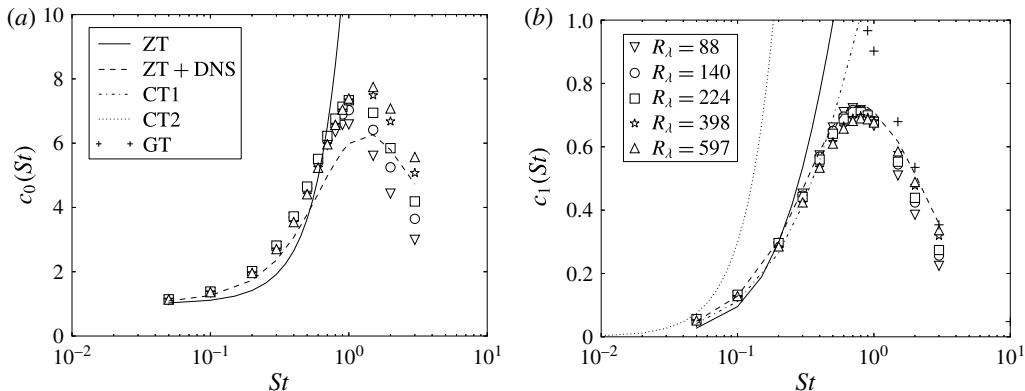


FIGURE 24. Power-law fits for $g(r/\eta)$ from (4.13): (a) shows the coefficient c_0 , and (b) shows the exponent c_1 . DNS data are shown with symbols, and the theoretical predictions from Zaichik & Alipchenkov (2009) ('ZT' and 'ZT + DNS'), Chun *et al.* (2005) ('CT1' and 'CT2') and Gustavsson & Mehlig (2011) ('GT') at $R_\lambda = 597$ are shown with lines and plus signs. The details of each of the theoretical models are discussed in the text.

by the small-scale turbulence, independent of any intermittency in the turbulence that occurs at higher Reynolds numbers. From figure 23, we notice that the RDFs increase weakly with R_λ for $St \gtrsim 1$, with Reynolds-number effects saturating at the higher Reynolds numbers. Our findings confirm the hypothesis of Collins & Keswani (2004) that the degree of clustering saturates as the Reynolds number increases.

We note that two recent studies (Onishi *et al.* 2013; Onishi & Vassilicos 2014) found that $g(r/\eta)$ decreases weakly with increasing R_λ over the range $81 \leq R_\lambda \leq 527$ at $St = 0.4$ and $St = 0.6$. Our results at $St = 0.6$ in figure 23 are consistent with this trend, but it should be emphasized that the Reynolds-number dependencies here are extremely weak (in comparison with the statistical deviations) and should be viewed with caution.

It is important to note, however, that just because $g(r/\eta)$ is almost entirely invariant with R_λ for low- St particles does not necessarily imply that higher-order moments of clustering are also independent of R_λ . For example, $g(r/\eta)$ is related to the variance of the particle density field (Shaw, Kostinski & Larsen 2002). Higher-order moments or PDFs of the particle density field (e.g. see Pan *et al.* 2011) could also be compared at different values of R_λ . However, we found that the number of particles in our simulations was insufficient to compute such statistics accurately at small separations. We would likely need about an order of magnitude more particles to test the Reynolds-number dependence of these higher-order clustering moments. Refer to Yoshimoto & Goto (2007) for a more complete discussion on the number of particles necessary for accurate higher-order clustering statistics.

Following Reade & Collins (2000a), we fit the RDFs by a power law of the form

$$g(r/\eta) \approx c_0 \left(\frac{\eta}{r} \right)^{c_1}. \quad (4.13)$$

(Note that c_1 is related to the correlation dimension \mathcal{D}_2 (Bec *et al.* 2007) by the relation $c_1 = 3 - \mathcal{D}_2$.) This allows us to compare the DNS data to several theoretical predictions in figure 24. For each value of R_λ , we computed c_0 and c_1 by fitting $g(r/\eta)$ in the range $0.75 \leq r/\eta \leq 2.75$ using linear least-squares regression. For $St \geq 10$, we

do not observe power-law scaling for the RDF, and thus no values of c_0 and c_1 are plotted here.

To verify the arguments presented in § 4.2.1, we compare the DNS values of c_0 and c_1 to the predicted values from Zaichik & Alipchenkov (2009) at $R_\lambda = 597$. The comparisons are performed in two ways. In the first way (which we denote as ‘ZT’), we use the model of Zaichik & Alipchenkov (2009) to compute the relative velocities and then use these predicted relative velocities in (4.9) to solve for the RDFs. In this manner, we can test the quantitative predictions of the model when no additional inputs are used. In the second approach (which we denote as ‘ZT + DNS’), we solve (4.9) with the particle velocities and the strain rate time scales along particle trajectories specified using DNS data. (The strain rate time scales are used in evaluating the dispersion tensor λ . To maintain consistency in the model, we also adjusted the inertial range time scales through (18) in Zaichik & Alipchenkov (2003).) In both cases, we used the non-local diffusion correction discussed in Bragg & Collins (2014a), with $B_{nl} = 0.056$.

As expected, ‘ZT’ is only able to provide a reasonable prediction for c_0 and c_1 for $St \lesssim 0.3$. Above this point, inaccuracies in the predicted relative velocities lead to inaccurate clustering predictions, as discussed in Bragg & Collins (2014a). However, ‘ZT + DNS’ predicts c_1 almost perfectly, with only slight discrepancies at $St \sim 1$, in agreement with the findings of Bragg & Collins (2014a) at a lower Reynolds number. We expect that these discrepancies are due to an additional drift term that was omitted in Zaichik & Alipchenkov (2009), as discussed in Bragg & Collins (2014a). ‘ZT + DNS’ also provides reasonable predictions for c_0 , though the agreement is not as good as that for c_1 , possibly because c_0 is influenced by the inertial range scales, which are generally more difficult to model. From these comparisons, we see that the model presented in § 4.2.1 is accurate, validating its use in interpreting the physical mechanisms responsible for particle clustering.

We next compare our results for c_1 against two relations derived in Chun *et al.* (2005) in the limit of small St . The first (which we denote as ‘CT1’) uses DNS data for the strain and rotation rates sampled along inertial particle trajectories to compute c_1 , giving

$$c_1 = \frac{St\tau_\eta^2}{3B_{nl}} (\langle S^2 \rangle^p - \langle R^2 \rangle^p). \quad (4.14)$$

The second (which we denote as ‘CT2’) requires only DNS data for quantities sampled along fluid particle trajectories and predicts,

$$c_1 = \frac{St^2}{12B_{nl}} \left[\frac{(\sigma_{S^2}^p)^2}{(\langle S^2 \rangle^p)^2} \frac{T_{S^2 S^2}^p}{\tau_\eta} - \rho_{S^2 R^2}^p \frac{\sigma_{S^2}^p}{\langle S^2 \rangle^p} \frac{\sigma_{R^2}^p}{\langle R^2 \rangle^p} \left(\frac{T_{S^2 R^2}^p}{\tau_\eta} + \frac{T_{R^2 S^2}^p}{\tau_\eta} \right) + \frac{(\sigma_{R^2}^p)^2}{(\langle R^2 \rangle^p)^2} \frac{T_{R^2 R^2}^p}{\tau_\eta} \right]. \quad (4.15)$$

‘CT1’ agrees well with the DNS up to $St \approx 0.5$, while ‘CT2’ only agrees well for $St = 0.05$, in agreement with Chun *et al.* (2005), Bragg & Collins (2014a). At higher values of St , both models from Chun *et al.* (2005) overpredict c_1 . As explained in Bragg & Collins (2014a), this overprediction is because the theory of Chun *et al.* (2005) fails to account for the contribution of the path-history effects on the drift and diffusion mechanisms that govern the clustering.

Finally, we compare our DNS values for c_1 against the theory from Gustavsson & Mehlig (2011), here denoted as ‘GT’. The theory in Gustavsson & Mehlig (2011) predicts that in the limit of small r/η ,

$$S_{n\parallel}^p \propto r^{c_1}, \quad (4.16)$$

for $n > c_1$. (Note that the predictions of Zaichik & Alipchenkov (2009) and Gustavsson & Mehlig (2011) are equivalent when St is large, as explained in Bragg & Collins (2014a).) It therefore follows that for sufficiently small r/η , $c_1 = \zeta_{\parallel}^2$, where ζ_{\parallel}^2 is the scaling exponent of the relative velocity variance in the dissipation range, as computed in § 4.1.

We include the prediction $c_1 = \zeta_{\parallel}^2$ in figure 24, and see that while ‘GT’ is in excellent agreement with the DNS for $St = 2, 3$, significant discrepancies exist at low St , as explained in Bragg & Collins (2014a).

4.3. Collision kernel

We now consider the kinematic collision kernel K for inertial particles, which has been shown to depend on both the radial distribution function and the radial relative velocities,

$$K(d) = 4\pi d^2 S_{-\parallel}^p(r=d)g(r=d), \quad (4.17)$$

where d is the particle diameter (see Sundaram & Collins 1997; Wang, Wexler & Zhou 1998). While we simulate only point particles (refer to § 2.2), we compute d from St by assuming a given ρ_p/ρ_f . To study the dependence of $K(d)$ on ρ_p/ρ_f , we consider three different values for this parameter: 250, 1000 and 4000. (Note that for droplets in atmospheric clouds, $\rho_p/\rho_f \approx 1000$.)

In general, we do not have adequate statistics to calculate $g(r)$ or $S_{-\parallel}^p(r)$ at $r=d$ at low values of St ($St \leq 3$ for $\rho_p/\rho_f = 250$ and 1000 and $St \leq 10$ for $\rho_p/\rho_f = 4000$) and so we extrapolate from the power-law fits in §§ 4.1 and 4.2.2 down to these separations, as was also done in Rosa *et al.* (2013). For larger St ($St \geq 10$ for $\rho_p/\rho_f = 250$ and 1000 and $St \geq 20$ for $\rho_p/\rho_f = 4000$), the particle diameters are sufficiently large such that we can compute $g(d)$ and $S_{-\parallel}^p(d)$ by interpolating between data at smaller and larger separations.

Following Voßkuhle *et al.* (2014), we compute the non-dimensional collision kernel $\hat{K}(d) \equiv K(d)/(d^2 u_{\eta}) = 4\pi g(d)S_{-\parallel}^p(d)/u_{\eta}$. Figure 25 shows $\hat{K}(d)$ for different values of ρ_p/ρ_f . Results from Rosa *et al.* (2013) (deterministic forcing scheme, no gravity, $\rho_p/\rho_f = 1000$) are included in the inset to figure 25.

For $St \geq 10$, the collision kernels increase strongly with increasing R_{λ} , since both the relative velocities and the RDFs increase with R_{λ} here (see §§ 4.1 and 4.2.2). $\hat{K}(d)$ is also independent of ρ_p/ρ_f here. The physical explanation is that while changes in ρ_p/ρ_f lead to changes in d , $S_{-\parallel}^p(d)/u_{\eta}$ and $g(d)$ are largely independent of d here (see §§ 4.1 and 4.2.2).

Such particles, however, are generally above the size range of droplets in atmospheric clouds (e.g. see Ayala *et al.* 2008), and thus our primary focus is on the collision rates of smaller ($St \lesssim 3$) particles. $\hat{K}(d)$ is independent of ρ_p/ρ_f for $1 \lesssim St \leq 3$, in agreement with the findings of Voßkuhle *et al.* (2014). In this case, while both $g(d)$ and $S_{-\parallel}^p/d$ are dependent on d , these two quantities have opposite scalings (see § 4.2.2), causing their product to be independent of d (and thus of ρ_p/ρ_f).

For $St \lesssim 3$, our data show very little effect of R_{λ} on the collision rates, and are in good agreement with the collision statistics from Rosa *et al.* (2013) at $\rho_p/\rho_f = 1000$ (shown in the inset to figure 25). However, since the Reynolds numbers in clouds ($R_{\lambda} \sim 10\,000$) are at least an order of magnitude larger than those in the DNS, it is important to discern even weak trends in the collision kernel with the Reynolds number. We therefore plot the ratio of $\hat{K}(d)$ at a given Reynolds number to that at $R_{\lambda} = 88$ for $St \leq 3$ in figure 26.

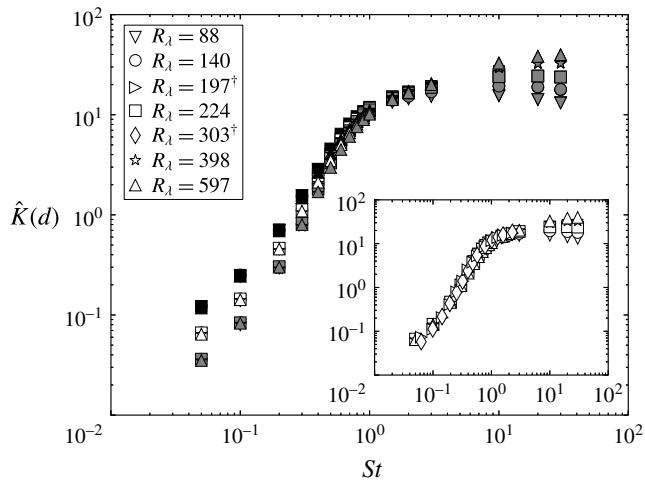


FIGURE 25. The non-dimensional collision kernel $\hat{K}(d)$ as a function of St for different values of R_λ . Data are shown for $\rho_p/\rho_f = 250$ (filled black symbols), $\rho_p/\rho_f = 1000$ (open symbols) and $\rho_p/\rho_f = 4000$ (filled grey symbols). Legend entries marked with \dagger indicate data taken from Rosa *et al.* (2013) (deterministic forcing scheme, no gravity) at $\rho_p/\rho_f = 1000$. These data are only included in the inset, where they are compared with our results at $\rho_p/\rho_f = 1000$.

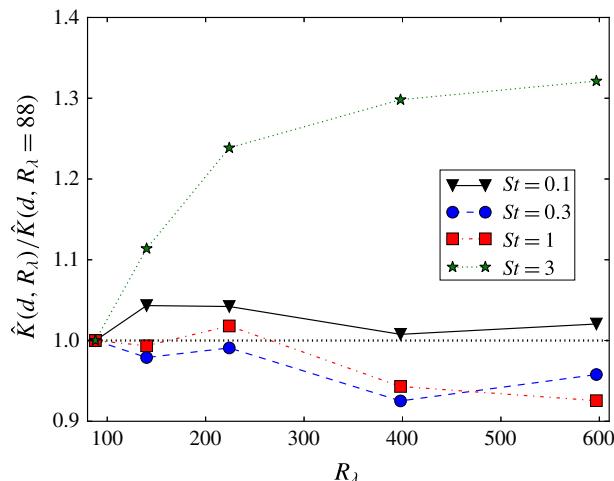


FIGURE 26. (Colour online) The ratio between $\hat{K}(d)$ at a given value of R_λ to that at $R_\lambda = 88$, to highlight any Reynolds-number effects for $St \leq 3$. All data correspond to $\rho_p/\rho_f = 1000$.

For $St \leq 1$, the collision statistics are almost completely independent of R_λ . This Reynolds-number independence is expected at $St = 0.1$ and $St = 0.3$, since both $S_{\perp\parallel}^p/u_\eta$ and g are independent of R_λ here (refer to §§ 4.1 and 4.2.2). For $St = 1$, $S_{\perp\parallel}^p/u_\eta$ decreases with increasing R_λ (see § 4.1), while g increases with increasing R_λ (see § 4.2.2). These two trends apparently offset each other, causing the collision kernel to be essentially independent of Reynolds number at $St = 1$. Finally, for $St = 3$, the

collision kernel increases weakly as R_λ increases. In this case, the increase in the RDFs with increasing R_λ (§ 4.2.2) more than compensates for the decrease in the relative velocities (§ 4.1), causing the collision kernel to increase weakly.

These findings suggest that lower-Reynolds-number studies may in fact capture the essential physics responsible for droplet collisions in highly turbulent clouds. However, the results must be interpreted with caution for two reasons. First, the collision rates for $St \leq 3$ were computed by extrapolating power-law fits to very small separations, and it is not known if the functional form of the relative velocities and the RDFs remains the same at these separations. Second, even the highest Reynolds numbers in this study are still at least an order of magnitude smaller than those in atmospheric clouds. It is thus possible that the turbulence could exhibit different characteristics at much higher Reynolds numbers, or that the above trends in the Reynolds number, though weak, could lead to substantially different collision rates when R_λ is increased by another order of magnitude.

5. Conclusions

We have studied the effect of particle inertia and the flow Reynolds number on particle dynamics at the highest Reynolds number ($R_\lambda \approx 600$) and largest number of particles (~ 2.5 billion) to date. These simulations have provided new insights into both single- and two-particle statistics in homogeneous isotropic turbulence.

We first analysed the statistics of individual inertial particles. At large St , the particle motions were seen to be influenced primarily by inertial filtering. The theoretical models of Abrahamson (1975) and Zaichik & Alipchenkov (2008) were able to quantify the effect of filtering on kinetic energies and particle accelerations, respectively, in this limit, and provided us with a clear physical understanding of the effect of Reynolds number on these quantities.

In the opposite limit ($St \ll 1$), the particle motions were influenced primarily by preferential sampling, and we used the theoretical model of Chun *et al.* (2005) to understand and predict the statistics here. For $St \ll 1$, the mean rotation rate sampled by the particles decreased with increasing St and R_λ , since intense rotation regions became more prevalent and more efficient at ejecting particles (see Collins & Keswani 2004). As R_λ increased, intense rotation regions tended to occur together with intense strain regions in ‘vortex sheets’, in agreement with Yeung *et al.* (2012), and particles were also ejected from these regions, decreasing the mean strain rate sampled by the particles. In agreement with Salazar & Collins (2012b), the particle kinetic energy increased with St for $St \ll 1$ due to preferential sampling of the flow field. However, since ejections from vortex sheets tend to reduce the particle kinetic energy, this trend was reduced as the Reynolds number was increased. Fluid particle accelerations were seen to be extremely intermittent at high R_λ , and the trends in the acceleration variance were well captured by the model of Sawford *et al.* (2003). The particle acceleration variances decreased rapidly with increasing St , as inertial particles tended to be ejected from vortex tubes and vortex sheets, which were both characterized by very high fluid accelerations.

We then studied the relative velocity, clustering and collision statistics of inertial particles. For $St \ll 1$, preferential sampling led to an increase in the longitudinal relative velocities and to a decrease in the transverse relative velocities, and the relative velocities were generally independent of R_λ for $St \lesssim 0.1$. At higher values of St , the particle motions were influenced more by path-history interactions, leading to a sharp increase in the relative velocities with increasing St . While the mean inward

relative velocities were generally independent of R_λ for $St = 0.3$, the relative velocity variances increased weakly with increasing R_λ here, a trend we attributed to either the increased scale separation at higher Reynolds numbers, the increased intermittency of the turbulence at higher Reynolds numbers or some combination of the two. For $St = 3$, the relative velocities decreased with increasing R_λ , which we argued was related to the decrease in the Lagrangian rotation time scales with increasing R_λ . We observed that the relative velocities of particles with $St \gtrsim 10$ increased with increasing R_λ , since inertial filtering effects diminish and u'/u_η increases as the Reynolds number increases.

We also analysed the dissipation range scaling exponents of the relative velocities, and found that particles with higher relative velocities generally had lower scaling exponents, since the particles were more influenced by path-history effects. Relative velocities in the dissipation range were seen to be strongly non-Gaussian, with the degree of non-Gaussianity being largest for $St \sim 1$, $r/\eta \rightarrow 0$, and high R_λ , suggesting that theories which assume a Gaussian distribution to relate the velocity variances to the mean inward velocities provide poor predictions for the mean inward relative velocities at particle contact. Higher-order inertial range structure functions were also examined and were observed to follow similar trends to those reported in Salazar & Collins (2012b).

We then used these trends in the relative velocities to predict the degree of clustering through the model of Zaichik & Alipchenkov (2009), and compared the results to DNS data. The trends in the RDFs at low St were tied to preferential sampling effects, which increased the inward particle drift, as was found in Chun *et al.* (2005). The RDFs were independent of R_λ here, in agreement with Collins & Keswani (2004), Ray & Collins (2011), Rosa *et al.* (2013), suggesting that the non-local coefficient B_{nl} (see Chun *et al.* 2005; Bragg & Collins 2014a) must weakly increase as R_λ increases. (We were unable to test higher-order measures of clustering to determine if they were affected by changes in R_λ due to the limitations in the number of particles that could be simulated.)

At high St , the degree of clustering was tied to the influence of path-history effects on the particle drift and diffusion, as explained in Bragg & Collins (2014a). By simplifying the model of Zaichik & Alipchenkov (2009) in this limit, we showed that changes in the scaling exponents of the relative velocity variances directly affected the drift and diffusion mechanisms, which in turn altered the clustering. The scaling exponents generally increased with increasing R_λ (suggesting that path-history effects became less important), which in turn led to increased levels of clustering. For $St \gtrsim 10$ and $R_\lambda \gtrsim 224$, particles were seen to cluster in the inertial range of turbulence and the separation at which clustering decreased was predicted accurately by inertial range scaling arguments.

For $St \lesssim 3$, the RDFs exhibited power-law scaling, consistent with Reade & Collins (2000a). The full model of Zaichik & Alipchenkov (2009) (without any inputs from the DNS) was able to predict the power-law coefficient c_0 and power-law exponent c_1 accurately only for $St \lesssim 0.4$ due to errors in the predicted relative velocities. However, when these relative velocities (and the associated Lagrangian time scales) were specified from the DNS, the model in Zaichik & Alipchenkov (2009) provided excellent predictions for c_1 and reasonable predictions for c_0 , as was also found in Bragg & Collins (2014a) at a lower Reynolds number. We also tested the DNS against two model predictions from Chun *et al.* (2005), one which required only fluid particle statistics from the DNS and one which required strain and rotation statistics along particle trajectories. The former prediction was in acceptable agreement with

the DNS only for $St = 0.05$, while the latter prediction was in good agreement up to $St \approx 0.5$, in agreement with Chun *et al.* (2005), Bragg & Collins (2014a). Finally, we found that the theory of Gustavsson & Mehlig (2011) was able to predict c_1 well for $St = 2$ and $St = 3$.

We used the relative velocity and RDF data to compute the kinematic collision kernel for inertial particles (Sundaram & Collins 1997), and found that this quantity varied only slightly with Reynolds number (under 35% when R_λ changed by a factor of 7) for $0 < St \leq 3$. Our collision kernels were in good agreement with those computed by Rosa *et al.* (2013).

As mentioned in § 1, one of the primary motivations for this study was to determine the extent to which turbulence-induced collisions are responsible to the rapid growth rate of droplets observed in warm, cumulus clouds. Our observations indicate that the collision rates of like particles are generally unaffected by changes in the Reynolds number, which suggests that relatively low-Reynolds-number simulations may allow us to study the essential physics of droplet collisions in highly turbulent atmospheric clouds. One promising avenue of future work would be to determine the droplet growth rates predicted by these collision kernels, either by solving an associated kinetic equation (Xue, Wang & Grabowski 2008; Wang & Grabowski 2009) or by simulating the particle collision and coalescence process directly (Reade & Collins 2000b).

Experimental data to support these findings would also be very useful. Experimental data on particle clustering, relative velocity and collision statistics is not yet available over a wide range of Reynolds number under tightly controlled experimental conditions. Future work could be undertaken to produce such data in order to test the validity of the conclusions drawn herein.

Finally, we note that it is unclear to what extent these conclusions would be altered if gravity were incorporated in the particle dynamics, since the introduction of gravity will likely cause particles to preferentially sample certain regions of the flow, and will alter the residence time of particles around certain flow features (e.g. see Wang & Maxey 1993; Dávila & Hunt 2001; Good *et al.* 2014). We will analyse the effect of gravity on inertial particle motion in turbulence in Part 2 (Ireland *et al.* 2016).

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