





Reverberation

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TSIA 206 - Speech and audio processing

Introduction

- Why study room acoustics?
 - ► To understand the quality criteria of a room
 - ► To design rooms that guarantee sound comfort
 - To understand and treat acoustic problems in premises (public places, theaters, homes)
- Impact on the recording and reproduction of sounds
 - Help in placing microphones and loudspeakers
 - Speech intelligibility, especially in sound reinforcement
- Digital processing of the audio signal
 - ► Apply reverberation to an anechoic signal:
 - ► Convolution with a measured Room Impulse Response (RIR)
 - Artificial reverberation
 - Cancel reverberation in a reverberated signal:
 - Dereverberation
 - Speech and music transcription
 - ► Source localization, separation





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Outline

- I Introduction
- II TF properties of reverberation
- III Fundamentals of room acoustics
- IV Geometrical acoustics
- V Measurements
- VI Stochastic reverberation models
- VII Conclusion



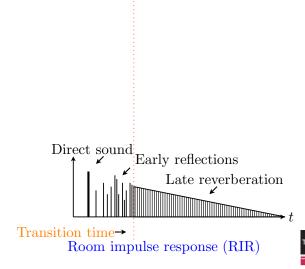


Part II

TF properties of reverberation

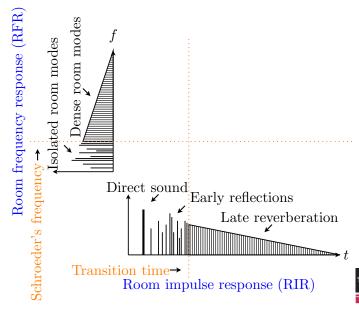






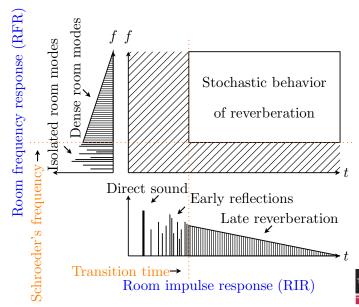








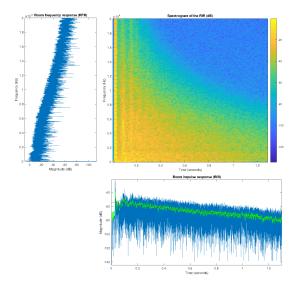








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Part III

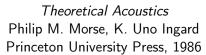
Fundamentals of room acoustics





References







Room Acoustics, Heinrich Kuttruff, CRC Press, 2009





The wave equation

▶ Wave equation: $\forall x \in \mathbb{R}^3, \forall t \in \mathbb{R}$,

$$\Delta p(\mathbf{x},t) - \frac{1}{c^2} \frac{\partial^2 p(\mathbf{x},t)}{\partial t^2} = 0$$
 (1)

- ightharpoonup p(x,t) is the pressure wave at position x and time t
- $ightharpoonup \Delta$ is the Laplacian w.r.t. space, c is the speed of sound.
- Classical solutions:
 - Plane wave $(\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2})$

$$p(\mathbf{x},t) = e^{2i\pi(\mathbf{k}^{\top}\mathbf{x} + ckt)}$$

were \mathbf{k} is the wave vector, $k = \|\mathbf{k}\|_2$ is the wave number, $\lambda = \frac{1}{k}$ is the wave length, and f = ck is the frequency

Spherical wave

$$(\Delta p = \frac{1}{r} \frac{\partial^2}{\partial r^2} (rp) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial p}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 p}{\partial \phi^2})$$

$$p(x,t) = \frac{\phi(t - \frac{\|x\|_2}{c})}{\|x\|_2}$$





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Wave equation with initial conditions

Initial conditions:

$$\forall \mathbf{x} \in \mathbb{R}^3, \begin{cases} p(\mathbf{x},0) = c^2 g(\mathbf{x}) \\ \frac{\partial p}{\partial t}(\mathbf{x},0^+) = 0 \end{cases}$$

▶ Plane wave representation of the solution: $\forall t > 0$,

$$p(\mathbf{x},t) = c^2 H(t) Re \int_{\mathbf{k} \in \mathbb{R}^3} \widehat{g}(\mathbf{k}) e^{2i\pi (\mathbf{k}^\top \mathbf{x} + ckt)} d\mathbf{k}$$

where H(t) denotes the Heaviside function, such that $H(t) = 1 \ \forall t > 0 \ \text{and} \ H(t) = 0 \ \forall t < 0$

▶ Spherical wave representation of the solution: $\forall t \geq 0$,

$$p(\mathbf{x},t) = \frac{1}{4\pi} \int_{\mathbf{x}_0 \in \mathbb{R}^3} \frac{\dot{\delta}\left(t - \frac{\|\mathbf{x} - \mathbf{x}_0\|_2}{c}\right)}{\|\mathbf{x} - \mathbf{x}_0\|_2} g(\mathbf{x}_0) d\mathbf{x}_0$$

▶ Remark: this solution coincides on $t \in \mathbb{R}_+^*$ with the causal solution of the **inhomogeneous** wave equation: $\forall t \in \mathbb{R}$,

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- ▶ Presence of a point source at $x_0 \in V$ emitting at t = 0.
- ▶ The wave equation (1) becomes inhomogeneous: $\forall t \in \mathbb{R}$,

$$\Delta p(\mathbf{x},t) - \frac{1}{c^2} \frac{\partial^2 p(\mathbf{x},t)}{\partial t^2} = -Q \rho_0 \delta(\mathbf{x} - \mathbf{x}_0) \dot{\delta}(t)$$

- ho_0 is the static value of the gas density
- Q is volume velocity of the point source
- Causal solution in free space:

$$p(\mathbf{x},t) = \frac{Q\rho_0}{4\pi} \frac{\dot{\delta}\left(t - \frac{\|\mathbf{x} - \mathbf{x}_0\|_2}{c}\right)}{\|\mathbf{x} - \mathbf{x}_0\|_2} \\ = Q\rho_0 c^2 H(t) Re \int_{\mathbf{k} \in \mathbb{R}^3} e^{2i\pi \left(\mathbf{k}^\top (\mathbf{x} - \mathbf{x}_0) + c\|\mathbf{k}\|_2 t\right)} d\mathbf{k}$$

► The signal emitted by a point source is the *derivative* of a Dirac





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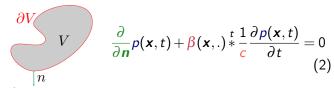
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Boundary condition of the wave equation

▶ Boundary condition in an enclosure $V: \forall x \in \partial V, \forall t \in \mathbb{R}$,

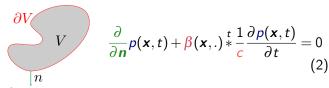


- $\widehat{\beta}(x,f) \in \mathbb{C}$, is the **specific admittance**, function of the position x and frequency f, such that $Re(\widehat{\beta}(x,f)) > 0$
- $ightharpoonup rac{\partial}{\partial n}$ denotes partial differentiation in the direction of the outward normal to the wall
- ▶ Reflection on a plane wall P with uniform admittance $\widehat{\beta}(f)$:
 - ▶ If the incident wave is a plane wave: $p_i(x,t) = e^{2i\pi(k_i^\top x + ft)}$
 - ► The reflected wave is: $p_r(\mathbf{x},t) = R(f) e^{2i\pi(\mathbf{k}_r^\top \mathbf{x} + ft)}$ (if $0 \in P$)
 - ▶ $R(f) \in \mathbb{C}$ is the reflection factor
 - $ightharpoonup k_r$ is the flipped wave vector w.r.t. reflection of plane P
 - ► Relation with the admittance: $R(f) = \frac{\cos(\theta) + \hat{\beta}(f)}{\cos(\theta) \hat{\beta}(f)}$ where θ is the angle between k_i (or k_r) and the normal to the wall



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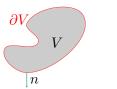


- ► Rigid walls: $\widehat{\beta}(x, f) = 0$ (R(f) = 1)
- ► Helmholtz equation: $\forall x \in \mathbb{R}^3$,

$$\Delta \phi(\mathbf{x}) + 4\pi^2 \mathbf{k}^2 \phi(\mathbf{x}) = 0 \tag{3}$$

where $k \in \mathbb{C}$ is the wave number

Boundary condition in an enclosure $V: \forall x \in \partial V$,



$$\frac{\partial}{\partial \mathbf{n}} \phi(\mathbf{x}) = 0. \tag{4}$$

- The set of wave numbers k_n and unit eigenfunctions $\phi_n(x)$ solutions to (3) and (4) is discrete, indexed by an integer n
- ▶ Both the wave numbers k_n and eigenfunctions $\phi_n(x)$ are real
- ► The set $\{\phi_n(\mathbf{x})\}_{n\in\mathbb{N}}$ forms a **Hilbert** basis of $L^2(V)$





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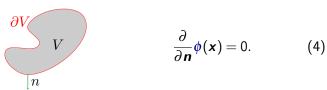


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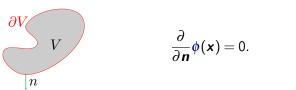


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(4)

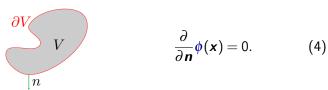


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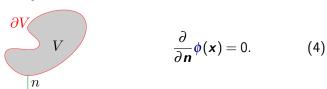


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- ▶ Presence of a point source at $x_0 \in V$ emitting at t = 0.
- ▶ The wave equation (1) becomes inhomogeneous: $\forall t \in \mathbb{R}$,

$$\Delta p(\mathbf{x},t) - \frac{1}{c^2} \frac{\partial^2 p(\mathbf{x},t)}{\partial t^2} = -Q \rho_0 \delta(\mathbf{x} - \mathbf{x}_0) \dot{\delta}(t)$$

- \triangleright ρ_0 is the static value of the gas density
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- Causal solution in an enclosure with rigid walls:

$$p(\mathbf{x},t) = Q \rho_0 c^2 H(t) \sum_{n \in \mathbb{N}} \phi_n(\mathbf{x}_0) \phi_n(\mathbf{x}) \cos(2\pi c k_n t)$$

Principle of reciprocity: switching the source and receiver positions x_0 and x leads to the same solution





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Principle of reciprocity: switching the source and receiver positions x_0 and x leads to the same solution





- ▶ Presence of a point source at $x_0 \in V$ emitting at t = 0.
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Room impulse response (rigid walls)

▶ The room impulse response (RIR) h, between a punctual source position $x_0 \in V$ and a punctual receiver position $x \in V$, is defined as the Green's function of (1), which is the unique causal solution of the following inhomogeneous wave equation:

$$\forall t \in \mathbb{R}, \ \Delta h(\mathbf{x}, t) - \frac{1}{c^2} \frac{\partial^2 h(\mathbf{x}, t)}{\partial t^2} = -\delta(\mathbf{x} - \mathbf{x}_0)\delta(t)$$
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with the same boundary condition (2).

▶ This solution is a linear combination of the eigenfunctions ϕ_n :

$$\forall \mathbf{x} \in V, h(\mathbf{x}, t) = c^2 H(t) \left(\frac{t}{|V|} + \sum_{n \in \mathbb{N}^*} \phi_n(\mathbf{x}_0) \phi_n(\mathbf{x}) \frac{\sin(2\pi f_n t)}{2\pi f_n} \right)$$

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► Shoebox room: $V=[0, L_x] \times [0, L_y] \times [0, L_z]$

$$\phi_{n_x,n_y,n_z}(\mathbf{x}) = \frac{2^{\delta_0(n_x) + \delta_0(n_y) + \delta_0(n_z)}}{8\sqrt{|V|}} \sum_{\mathbf{s}_x,\mathbf{s}_y,\mathbf{s}_z = \pm 1} e^{2i\pi \mathbf{k}_{\mathbf{s}_x n_x,\mathbf{s}_y n_y,\mathbf{s}_z n_z}^{\mathsf{T}} \mathbf{x}}$$

- wave vectors $\mathbf{k}_{n_x,n_y,n_z} = \left[\frac{n_x}{2L_x}, \frac{n_y}{2L_y}, \frac{n_z}{2L_z}\right]$ for $(n_x, n_y, n_z) \in \mathbb{Z}^3$
- ▶ wave numbers $k_{n_x,n_y,n_z} = \frac{1}{2} \sqrt{\frac{n_x^2}{L_x^2} + \frac{n_y^2}{L_v^2} + \frac{n_z^2}{L_z^2}}$





Eigenmodes in 1D

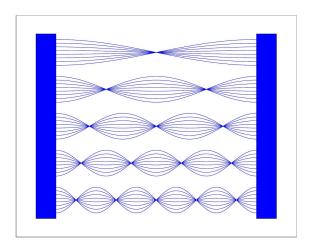


Figure: The first 5 modes of a tube closed at the ends



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Eigenmodes in 2D

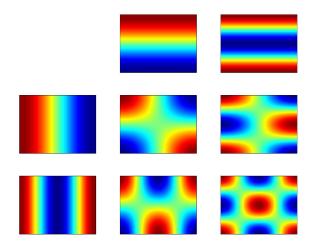


Figure: First modes of a rectangular room





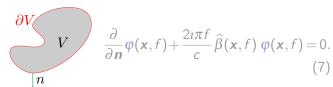
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▶ Helmholtz equation: $\forall x \in \mathbb{R}^3$,

$$\Delta \varphi(\mathbf{x}, f) + 4\pi^2 \kappa(f)^2 \varphi(\mathbf{x}, f) = 0$$
 (6)

where $\kappa(f) \in \mathbb{C}$ is the wave number

▶ Boundary condition in an enclosure $V: \forall x \in \partial V$,



- The set of wave numbers $\kappa_n(f)$ and unit eigenfunctions $\varphi_n(\mathbf{x}, f)$ solutions to (6) and (7) is discrete, indexed by n
- $\forall n \neq 0$, both $\kappa_n(f)$ and $\varphi_n(x, f)$ are complex and $Im(\kappa_n) > 0$
- The set $\{\varphi_n(\mathbf{x}, f)\}_{n \in \mathbb{Z}}$ forms a Riesz basis of $L^2(V)$: it admits a dual basis $\{\widetilde{\varphi}_n(\mathbf{x}, f) = \overline{\varphi_n(\mathbf{x}, f)}\}_{n \in \mathbb{Z}}$, such that $\forall \mathbf{x}, \mathbf{y} \in V$,

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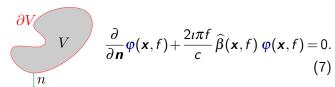


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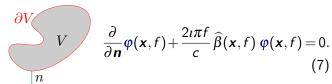


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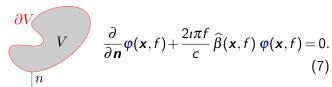


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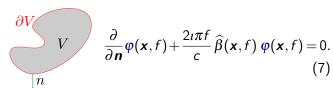


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- ▶ The room impulse response h is still defined as the unique causal solution to (5), with the boundary condition (2).
- Now this solution is obtained by inverse Fourier transform:

$$\forall \mathbf{x} \in V, \forall t \in \mathbb{R}, h(\mathbf{x}, t) = \int_{f \in \mathbb{R}} \left(\sum_{n \in \mathbb{N}} \frac{\varphi_n(\mathbf{x}_0, f) \varphi_n(\mathbf{x}, f)}{4\pi^2 \left(\frac{f^2}{c^2} - \kappa_n(f)^2\right)} \right) e^{2i\pi f t} df$$
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- ▶ The integral can be calculated with the residue theorem:
 - Suppose that $\forall n \in \mathbb{N}$, a root of the equation $f = c \kappa_n(f)$ is $v_n = f_n + i\gamma_n$ with $f_n, \gamma_n > 0$.
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- Then applying the residue theorem to (8) leads to:

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- Assume that $\widehat{\beta}(\mathbf{x}, f) = \widehat{\beta}_{0p}(f)$ on the face orthogonal to axis p and going through $x_p = 0$, and $\widehat{\beta}(\mathbf{x}, f) = \widehat{\beta}_{Lp}(f)$ on the face orthogonal to axis p and going through $x_p = L_p$.
- Let $\varphi(\mathbf{x}, f) = \prod_{p=1}^{3} \varphi_p(x_p)$. Then $\forall p \in \{1, 2, 3\}$, we have

$$\varphi_p(x_p) = a_p e^{-2\imath \pi \kappa_p(f)x_p} + b_p e^{2\imath \pi \kappa_p(f)x_p}$$

- At $x_p = 0$, $\dot{\varphi}_p(0) = \frac{2i\pi f}{c} \hat{\beta}_{0p}(f) \varphi_p(0)$
- At $x_p = L_p$, $\dot{\varphi}_p(L_p) = -\frac{2i\pi f}{c} \hat{\beta}_{Lp}(f) \varphi_p(L_p)$
- ▶ By zeroing the determinant of this 2×2 linear system, we get

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$$\varphi_p(x_p) = a_p e^{-2\imath \pi \kappa_p(f)x_p} + b_p e^{2\imath \pi \kappa_p(f)x_p}$$

- At $x_p = 0$, $\dot{\varphi}_p(0) = \frac{2i\pi f}{c} \widehat{\beta}_{0p}(f) \varphi_p(0)$
- At $x_p = L_p$, $\dot{\varphi}_p(L_p) = -\frac{2i\pi f}{c} \hat{\beta}_{Lp}(f) \varphi_p(L_p)$
- ▶ By zeroing the determinant of this 2×2 linear system, we get

$$\frac{\left(\kappa_{\rho}(f) - \frac{f}{c}\widehat{\beta}_{0\rho}(f)\right)\left(\kappa_{\rho}(f) - \frac{f}{c}\widehat{\beta}_{L\rho}(f)\right)}{\left(\kappa_{\rho}(f) + \frac{f}{c}\widehat{\beta}_{0\rho}(f)\right)\left(\kappa_{\rho}(f) + \frac{f}{c}\widehat{\beta}_{L\rho}(f)\right)} = e^{4\iota\pi\kappa_{\rho}(f)L_{\rho}}$$

- ▶ When $\widehat{\beta} \to 0$, with $\kappa_p(f) = \frac{n_p}{2L_p} + \varepsilon_p(f)$, we get:
 - ▶ If $n_p \neq 0$: $\kappa_p(f) = \frac{n_p}{2L_p} + i \frac{f(\widehat{\beta}_{0p}(f) + \widehat{\beta}_{Lp}(f))}{\pi c n_p} + O(|\widehat{\beta}|^2)$
 - $\blacktriangleright \text{ If } n_p = 0: \ \kappa_p(f) = \sqrt{\frac{\iota f(\widehat{\beta}_{0p}(f) + \widehat{\beta}_{Lp}(f))}{2\pi c L_p}} + O(|\widehat{\beta}|^2)$

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Part IV

Geometrical acoustics





Ray-tracing in geometric acoustics

- ▶ Representing the reflection of waves on a plane surface as an optical reflection on a mirror.
- ► Holds only in the rigid walls case
- ▶ This leads to the concept of image source:

https://interactiveacoustics.info/html/GA_IS.html

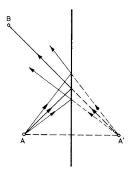


Figure: Construction of an image source



Diffuse reflections

▶ If the rays are scattered, the concept of mirror source no longer applies, it is necessary to take into account the angles of incidence in the ray tracing.

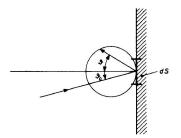
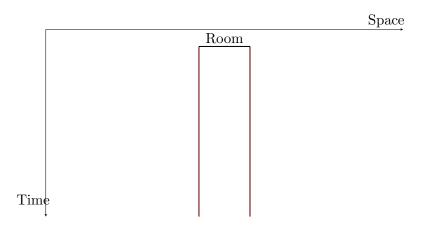


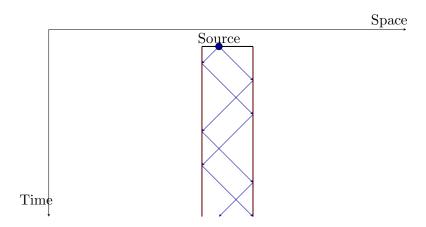
Figure: Ideal scattering model during a reflection





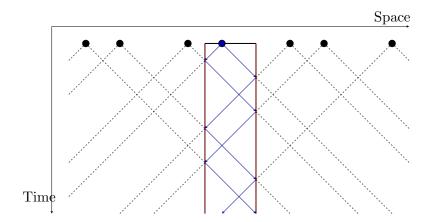






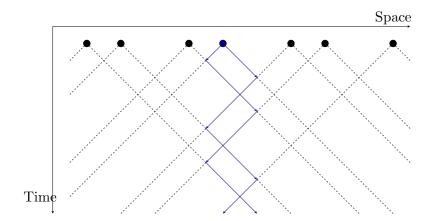
















- ► The concept of image sources still applies when angles between edges or faces are of the form $\theta = \frac{\pi}{n}$ with $n \in \mathbb{N}^*$
- ► Cristallographic restriction theorem (in 2D and 3D):
 - Admissible angles for a polygon or polyhedron are $\frac{\pi}{2}$, $\frac{\pi}{3}$, $\frac{\pi}{4}$, $\frac{\pi}{6}$
- ▶ 2D solutions: admissible polygons are the:
 - ► Rectangle (angles of $\frac{\pi}{2}$ only)
 - lsosceles right triangle (angles of $\frac{\pi}{2}$ and $\frac{\pi}{4}$)
 - Equilateral triangle (angles of $\frac{\pi}{3}$ only)
 - ► Hemi-equilateral triangle (angles of $\frac{\pi}{2}$, $\frac{\pi}{3}$, and $\frac{\pi}{6}$)
- ➤ 3D solutions: admissible polyhedra are right prisms with bases among 2D solutions
- ► For all other room shapes, geometrical acoustics is a high-frequency approximation, and involves *occlusion* of the image sources in parts of the room





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Reverberation

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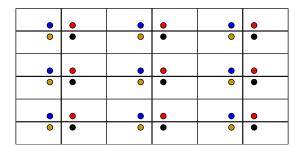
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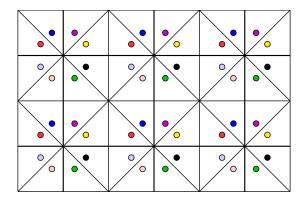


Rectangular room





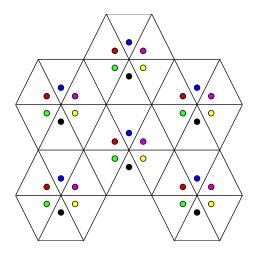
Isosceles right triangle







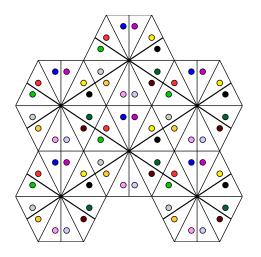
Equilateral triangle







Hemi-equilateral triangle







Part V

Measurements





Measurement tools

- Direct measurement of reverberation time
 - Excitation by pink noise
 - Analysis by octave or third of octave
- Measurement of the room response by a Dirac pulse
 - Use of a gun firing blanks
- Measurements of the response by pseudo random excitation
 - MLS sequences
 - Golav sequences
- Measurements with modulated sinusoidal excitation
 - Equivalent to pulse synthesis (radar)
 - Logarithmic modulation, nonlinear kernels





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Room response (1)

Note the exponential decrease of the response and its duration

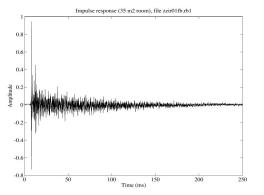


Figure: Measured response in a room of 35 m²





Room response (2)

Zoom on the early part of the same response

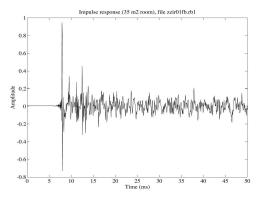


Figure: First milliseconds of the same response (room of 35 m²)



- ► EDC = Energy Decay Curve
- Excitation of a loudspeaker by white noise until t=0:

$$e(t) \sim \mathcal{N}\left(0, \sigma^2\right)$$
 for $t \leq 0$ and $e(t) = 0$ for $t > 0$

Calculation of the energy of the signal captured on a microphone:

$$C(t) = \mathbb{E}\left[\left|\int_{\tau=0}^{\infty} h(\tau)e(t-\tau)d\tau\right|^{2}\right] = \sigma^{2}\int_{\tau=t}^{\infty} h(\tau)^{2}d\tau$$

▶ Reverberation time: measures the time T60 that it takes for the reverberation to decrease by 60dB:

$$-60=10\log\left(e^{-2\bar{\gamma}T_{60~\mathrm{dB}}}
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Characterization of the response

From the energy decay curve:

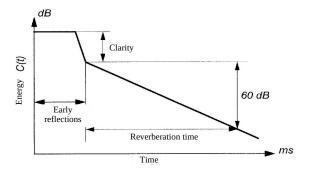


Figure: Parameters extracted from the energy decay curve (EDC)





Part VI

Stochastic reverberation models





Schroeder (1962) and Moorer (1979): the RIR is modeled as

$$h(t) = b(t)e^{-at}H(t)$$

- \triangleright b(t) is a centered white Gaussian process
- ightharpoonup a > 0 is related to the reverberation time: $RT_{60} = \frac{3 \ln(10)}{a}$
- ▶ H(t) is the Heaviside function: $H(t)=1 \ \forall t \geq 0$, $H(t)=0 \ \forall t < 0$

Manfred R. Schroeder. Frequency-correlation functions of frequency responses in rooms.

The Journal of the Acoustical Society of America, 34(12):1819–1823, 1962

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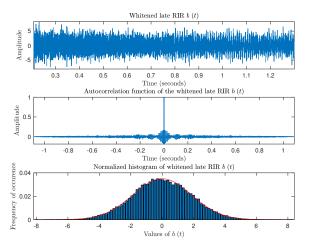
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Validation of time model (classroom)







▶ Moorer (1979): the RIR is modeled as

$$h(t) = b(t)e^{-at}H(t)$$

▶ The RFR is the Fourier transform of the RIR:

$$\widehat{h}(f) = \int_{t \in \mathbb{R}} h(t) e^{-2i\pi f t} dt$$

- Schroeder (1962): $\hat{h}(f)$ is a wide sense stationary process
- ► Complex autocorrelation function of $\hat{h}(f)$:

$$\operatorname{corr}\left[\widehat{h}(f_1), \, \widehat{h}(f_2)\right] = \frac{1}{1 + \iota \pi^{\frac{f_1 - f_2}{2}}}$$

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Paris

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▶ Spectrogram of b(t):



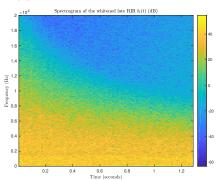


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- Polack (1988): b(t) is a centered stationary Gaussian process, whose power spectral density (PSD) B(f) has slow variations
- ▶ Polack (1988): the Wigner distribution of the RIR is

$$W_h(t,f) = B(f)e^{-2at}H(t)$$

- Auto-covariance function: $\gamma_h(t_1, t_2) = \text{cov}(h(t_1), h(t_2))$
- ▶ Wigner distribution of the random process *h*:

$$W_h(t,f) = \int_{\mathbb{R}} \gamma_h(t+\frac{u}{2},t-\frac{u}{2})e^{-2\imath\pi f u}du$$

J. D. Polack. La transmission de l'énergie sonore dans les salles (The transmission of sound energy in rooms).

PhD thesis, Université du Maine, Le Mans, France, 1988





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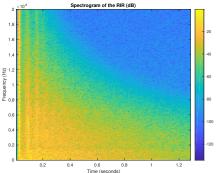
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▶ Time-frequency profile of h(t):



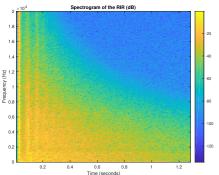
► Polack (1988): the attenuation actually depends on the frequency:

$$W_h(t,f) = B(f)e^{-2a(f)t}H(t)$$





ightharpoonup Time-frequency profile of h(t):



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Space-frequency domain: diffuse model

Correlation at freq. f between sensors (Cook et al., 1955):

$$\operatorname{corr}\left[\widehat{h}(\boldsymbol{x}_1, f), \widehat{h}(\boldsymbol{x}_2, f)\right] = \operatorname{sinc}\left(\frac{2\pi f D}{c}\right)$$

- $D = \|\mathbf{x}_1 \mathbf{x}_2\|_2$ is the distance between sensors
- \triangleright c is the speed of sound in the air (\approx 343 m/s)
- Assumption: diffuse acoustic field
 - Sum of plane waves
 - Equal weights assigned to all directions

R.K. Cook, R.V. Waterhouse, R.D. Berendt, S. Edelman, and M.C. Thompson.

Measurement of correlation coefficients in reverberant sound fields. The Journal of the Acoustical Society of America, 27(6):1072–1077, 1955





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► Correlation at freq. f between sensors (Cook et al., 1955):

$$\operatorname{corr}\left[\widehat{h}(\boldsymbol{x}_1, f), \widehat{h}(\boldsymbol{x}_2, f)\right] = \operatorname{sinc}\left(\frac{2\pi f D}{c}\right)$$

- $D = \|\mathbf{x}_1 \mathbf{x}_2\|_2$ is the distance between sensors
- ightharpoonup c is the speed of sound in the air (\approx 343 m/s)
- Assumption: diffuse acoustic field
 - Sum of plane waves
 - Equal weights assigned to all directions

 $R.K.\ Cook,\ R.V.\ Waterhouse,\ R.D.\ Berendt,\ S.\ Edelman,\ and\ M.C.\ Thompson.$

Measurement of correlation coefficients in reverberant sound fields. The Journal of the Acoustical Society of America, 27(6):1072–1077, 1955





Part VII

Conclusion





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 - Complete in simple cases
 - Only quantitative in complicated (and realistic) cases
 - Highlights resonance modes and reverberation (modal approach)
 - ► Highlights the temporal structure of the response (geometrical approach)
- ► Empirical characterization
 - ► Reverberation time
 - Energy decay curve, clarity
- Artificial reverberation
 - ► Geometrical acoustics for early reflections
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