

Misspecified Gaussian Process Bandits

Ilija Bogunovic and Andreas Krause

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GP (kernel) bandits

- Problem setup:
 - Unknown reward function $f^*: \mathcal{D} \to \mathbb{R}$, $\mathcal{D} \subset \mathbb{R}^d$ over a known infinite and compact set of actions
 - Interaction over T rounds: Select action $x_t \in \mathcal{D}$ and obtain noisy (sub-Gaussian) observation $y_t = f^*(x_t) + \eta_t$
- Goal: Minimize cumulative regret $R_T = \sum_{t=1}^{T} \left(\max_{x \in D} f^*(x) f^*(x_t) \right)$ (optimizing while learning)

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- Hypothesis class:
 - ▶ Defined via positive semi-definite kernel $k(\cdot,\cdot)$ (e.g., squared exponential, Matern, NTK)
 - ▶ Smooth functions with bounded RKHS norm $\mathscr{F}_k(\mathscr{D}; B) = \{f \in \mathscr{H}_k(\mathscr{D}) : ||f||_k \leq B\}$
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• Applications: Molecular and material design, AutoML, recommender systems and advertising, sensor nets, etc.

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• Realizability assumption may be too restrictive in real applications (kernel mismatch, hyperparameter estimation errors, etc.)

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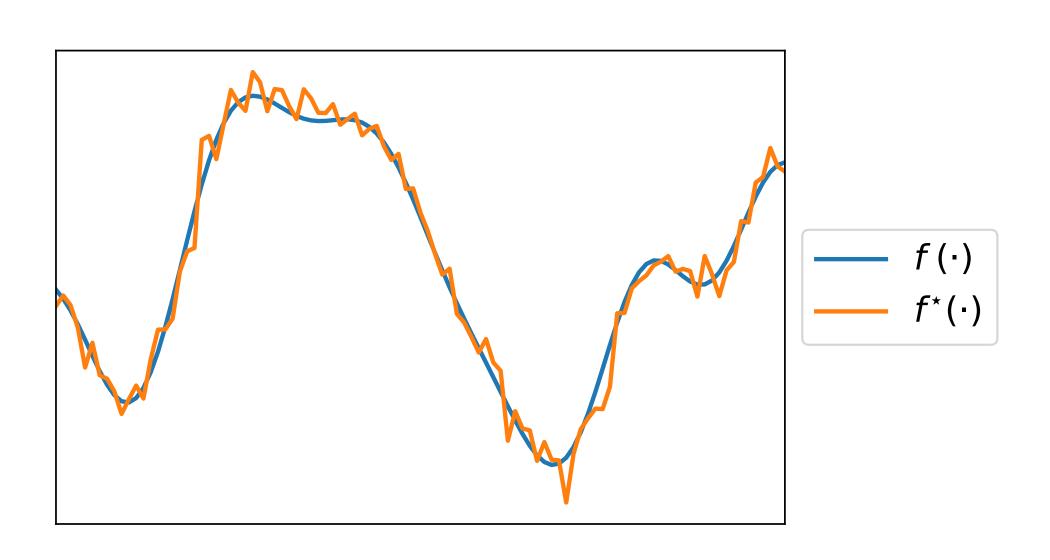
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• Assumption: The reward function can be uniformly approximated by a member from $\mathscr{F}_k(\mathscr{D};B)$

$$\min_{f \in \mathcal{F}_k(\mathcal{D};B)} \|f - f^{\star}\|_{\infty} \leq \epsilon$$

- Misspecification rate $\epsilon > 0$ is unknown to the learner
- Misspecification rate $\epsilon = 0$ recovers the realizable setting



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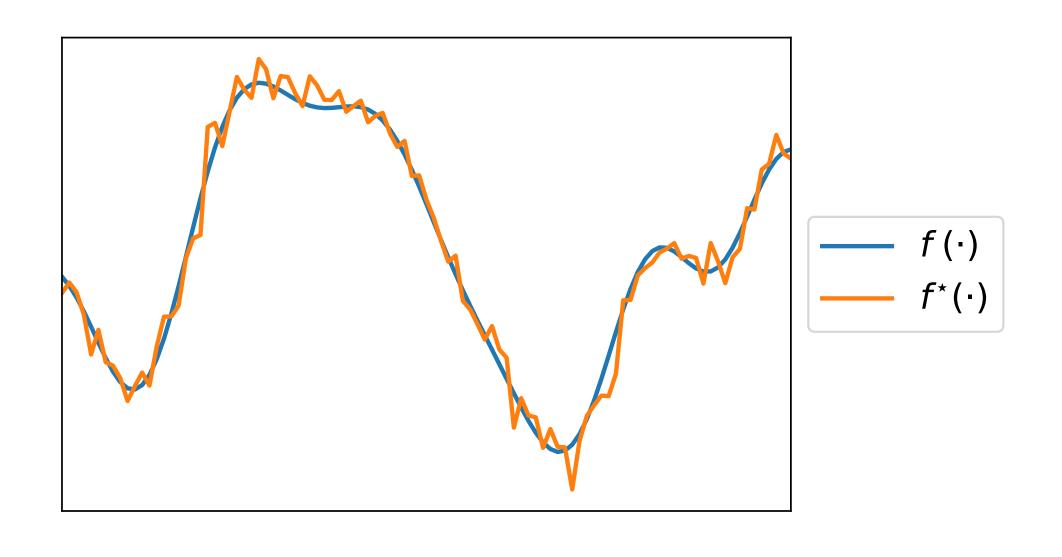
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Note: If $||f-f'||_k$ is small, then $||f-f'||_{\infty}$ is also small.

But the reverse does not need to hold!!



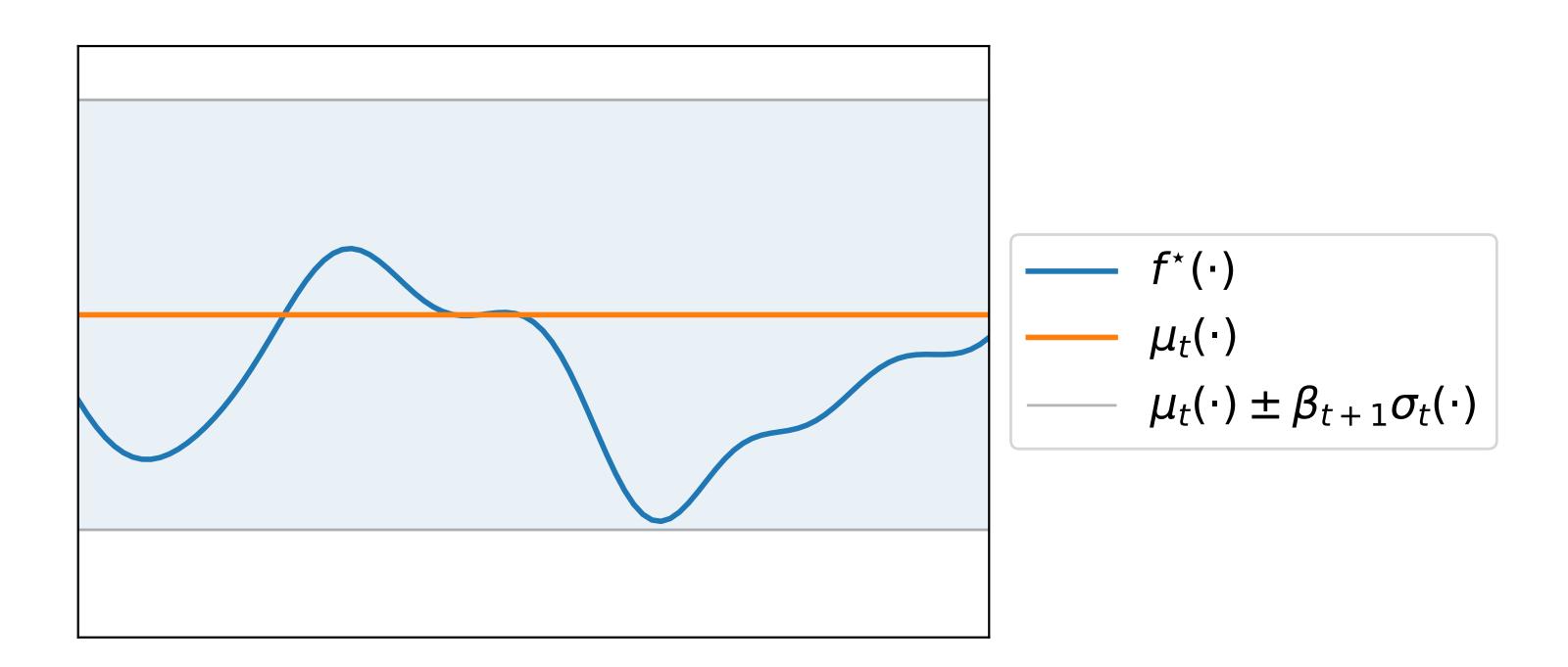
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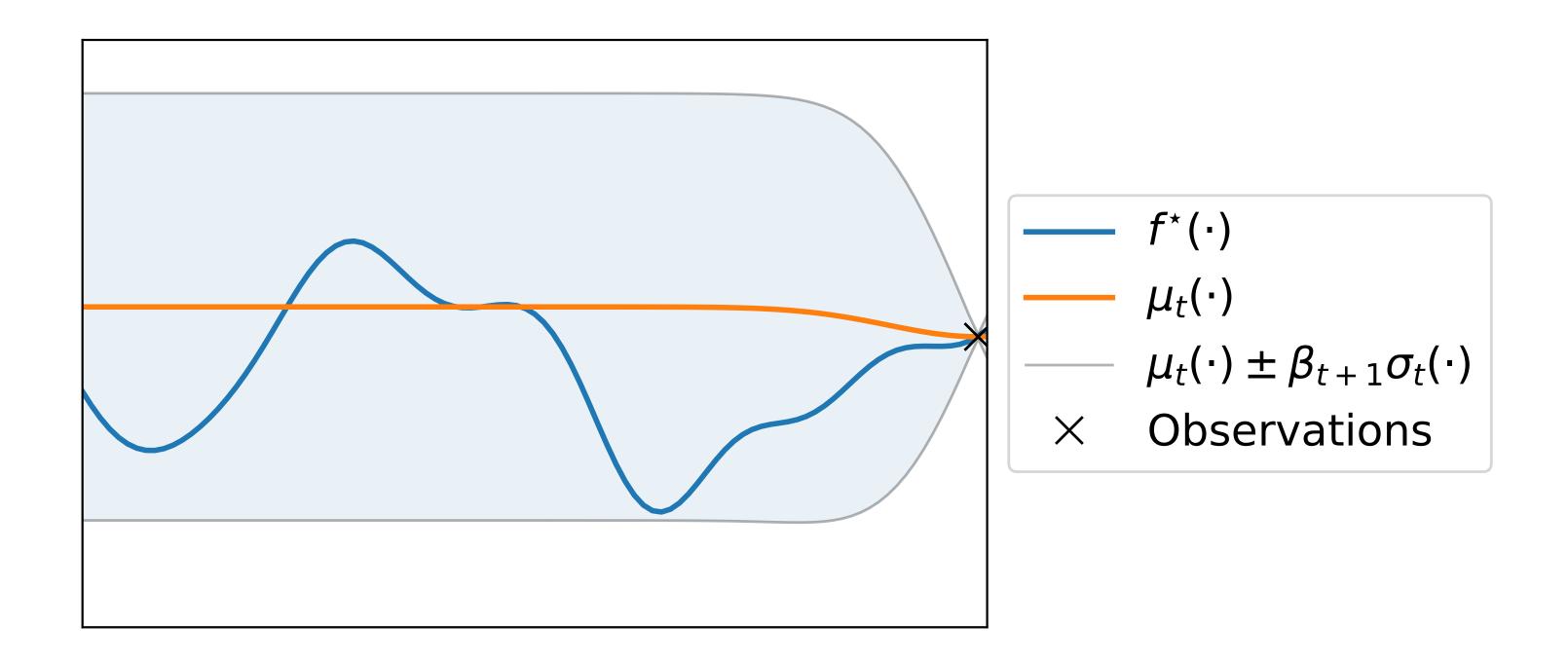
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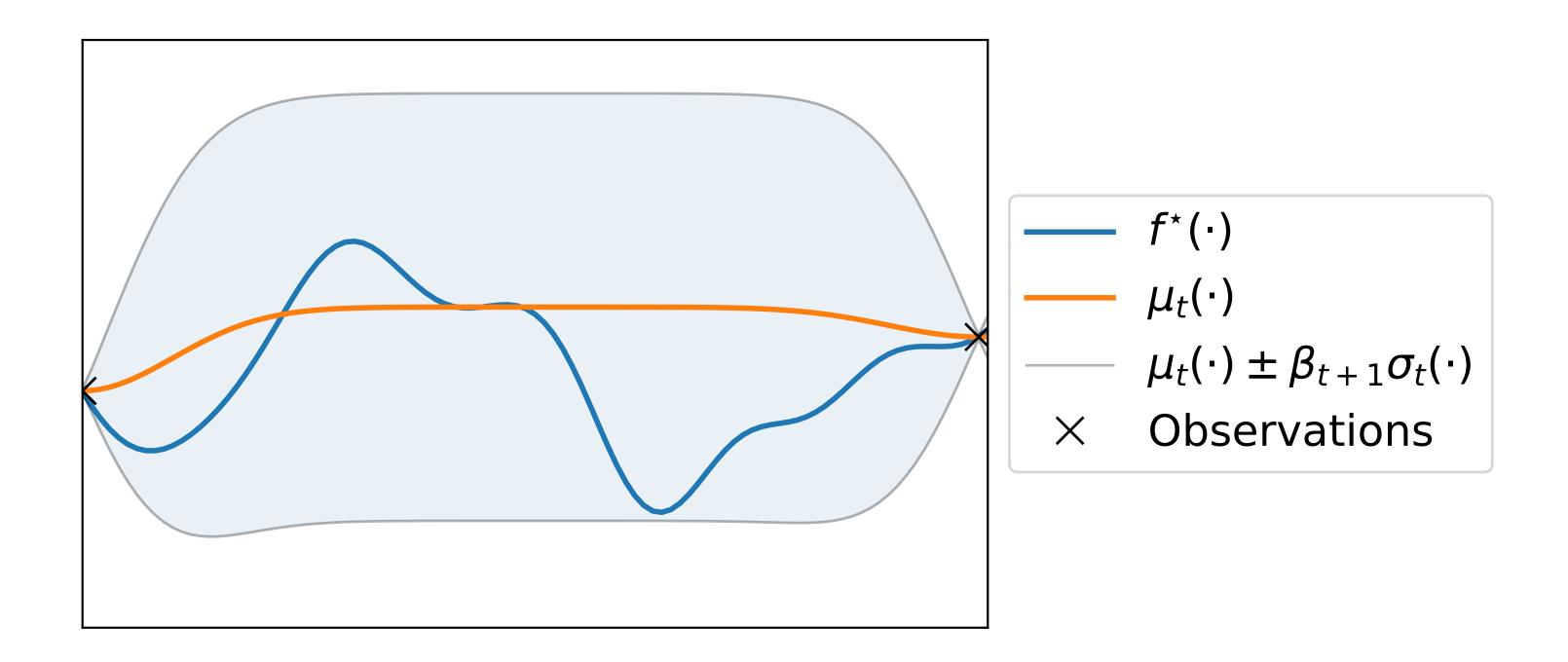
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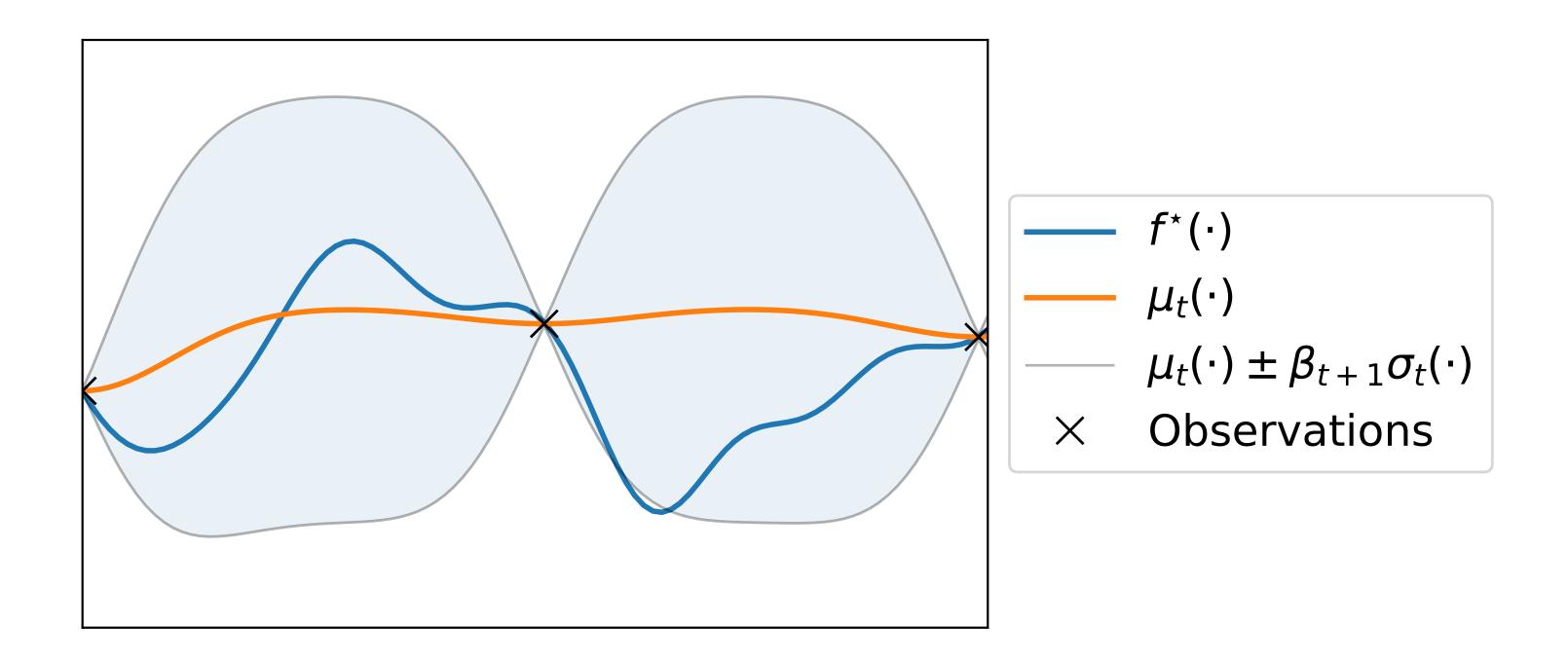
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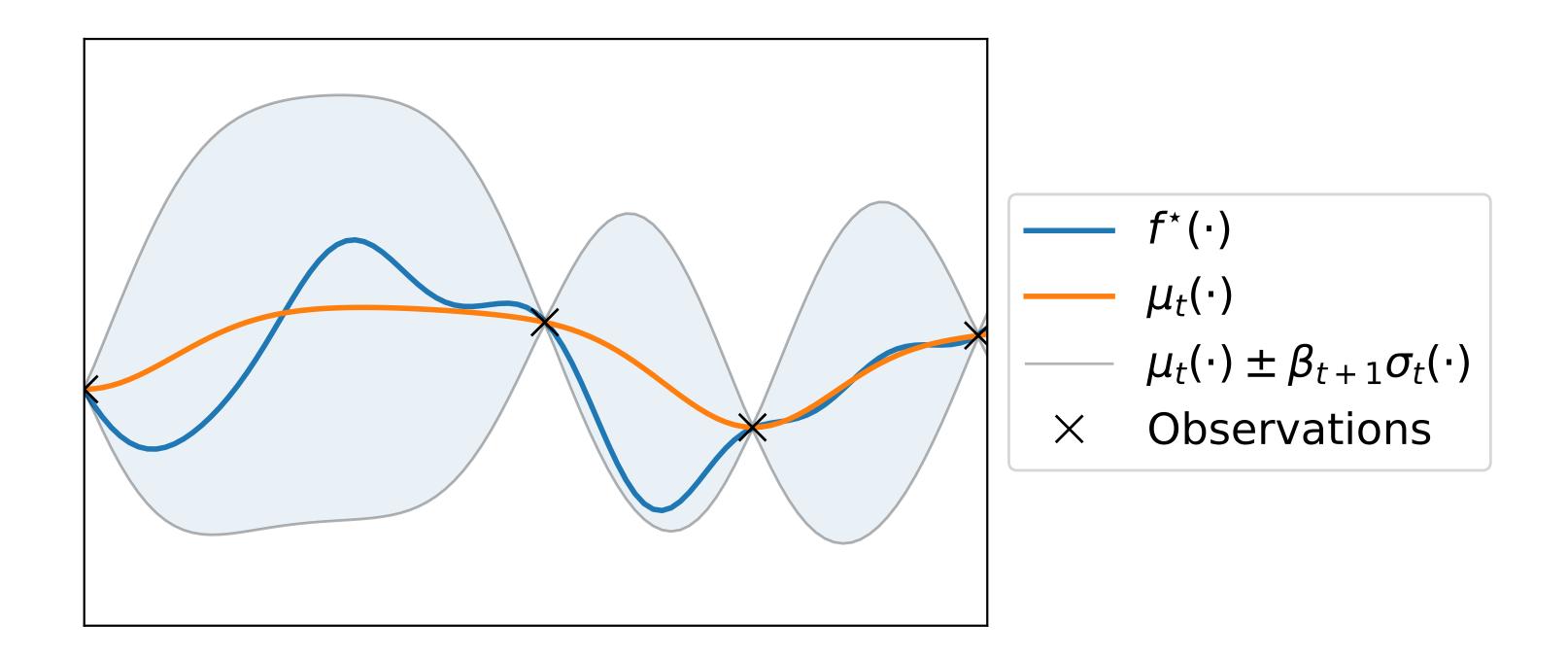
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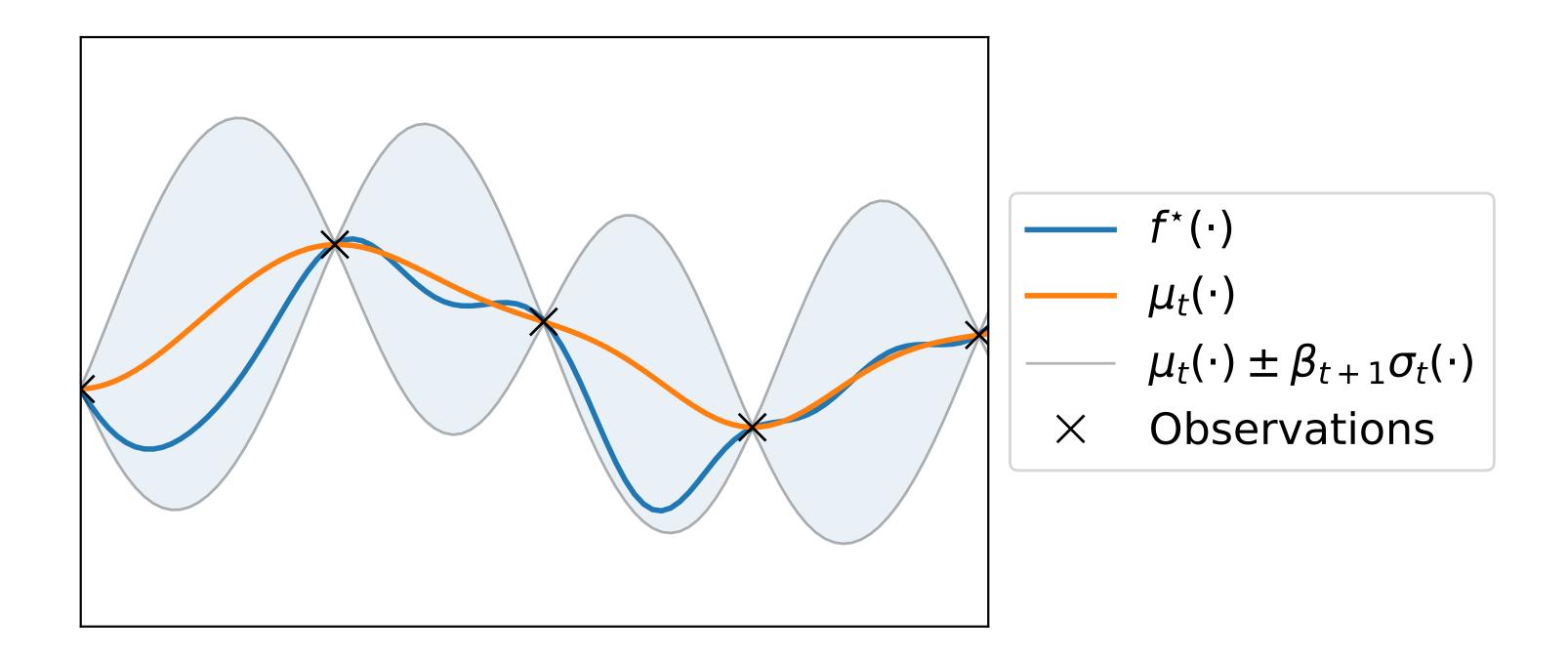
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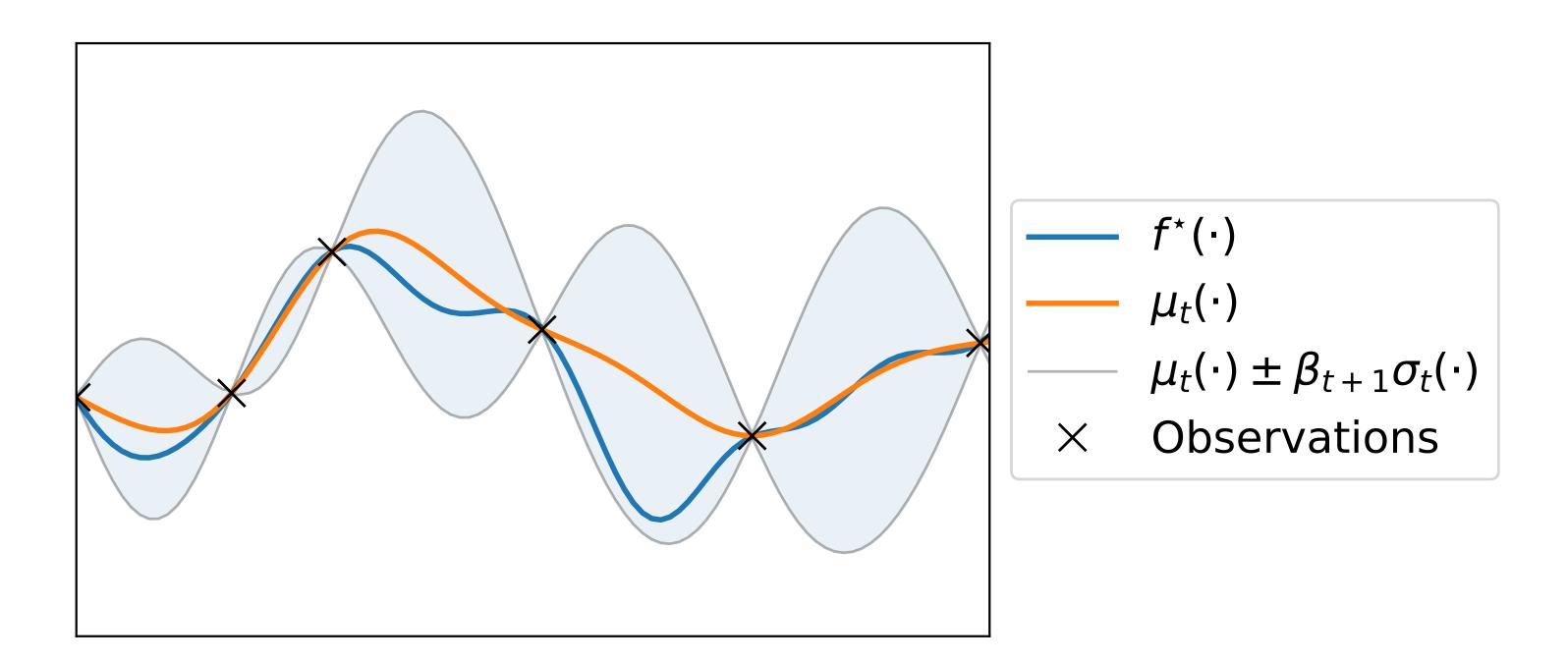
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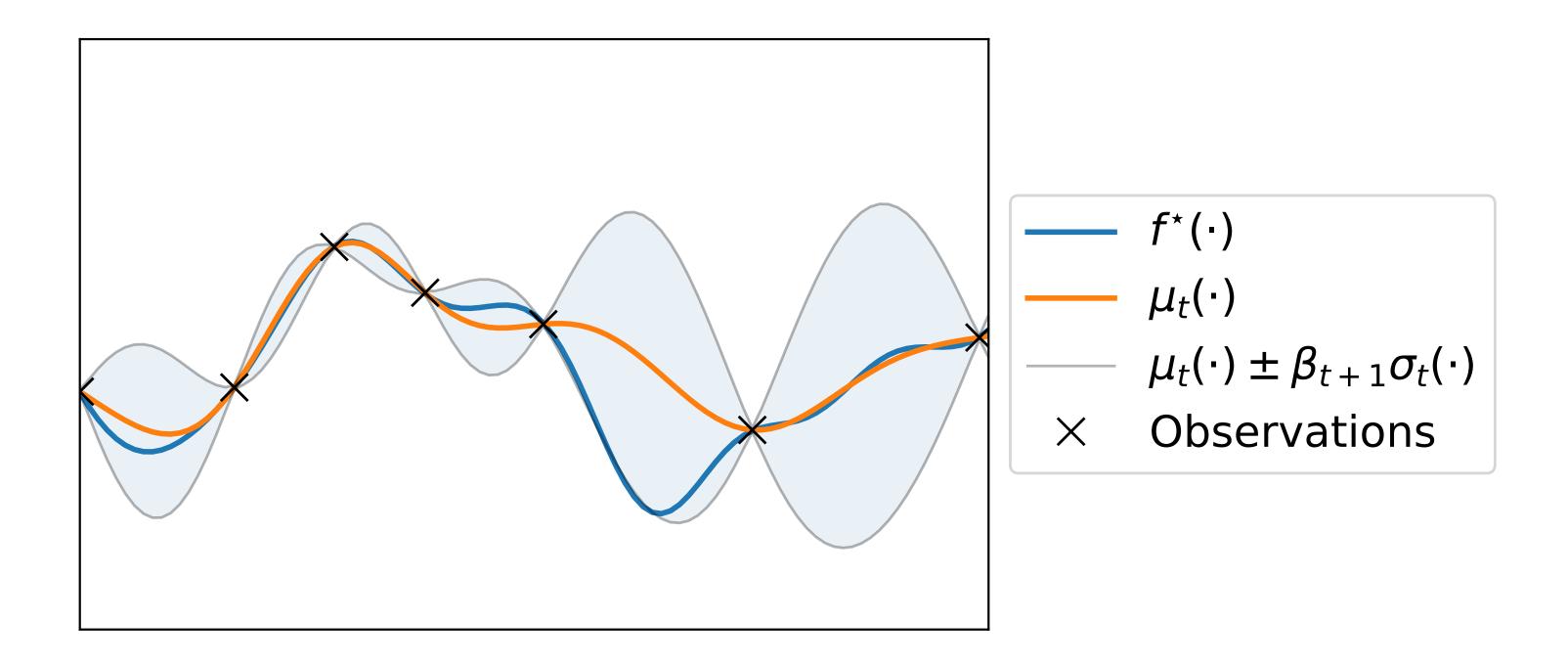
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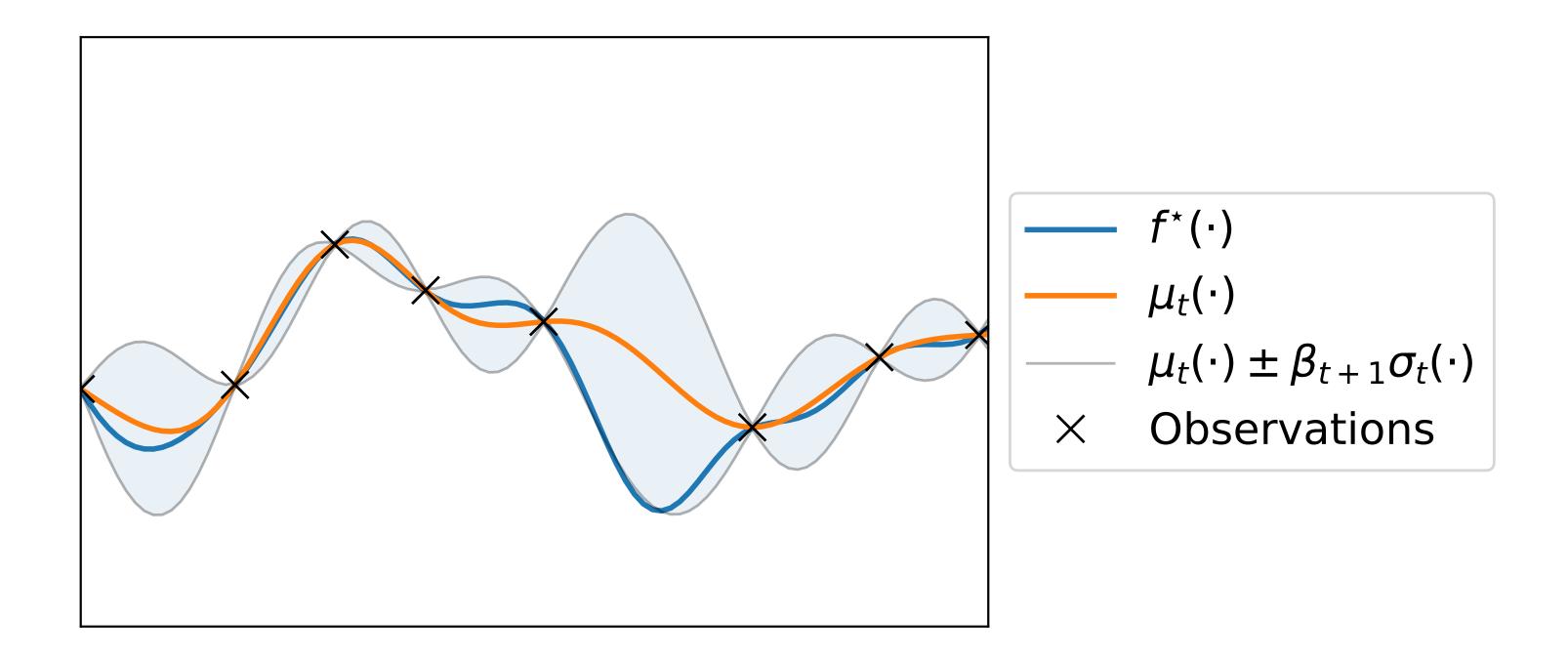
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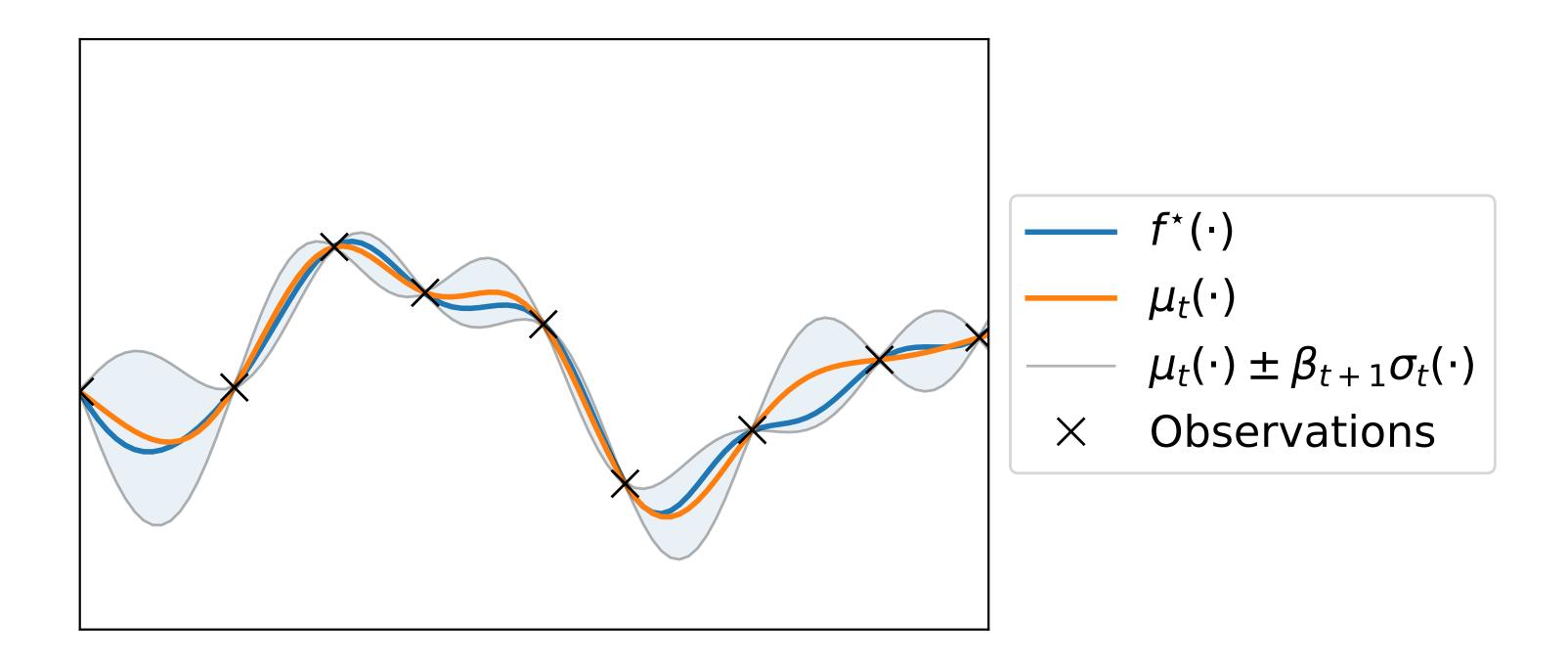
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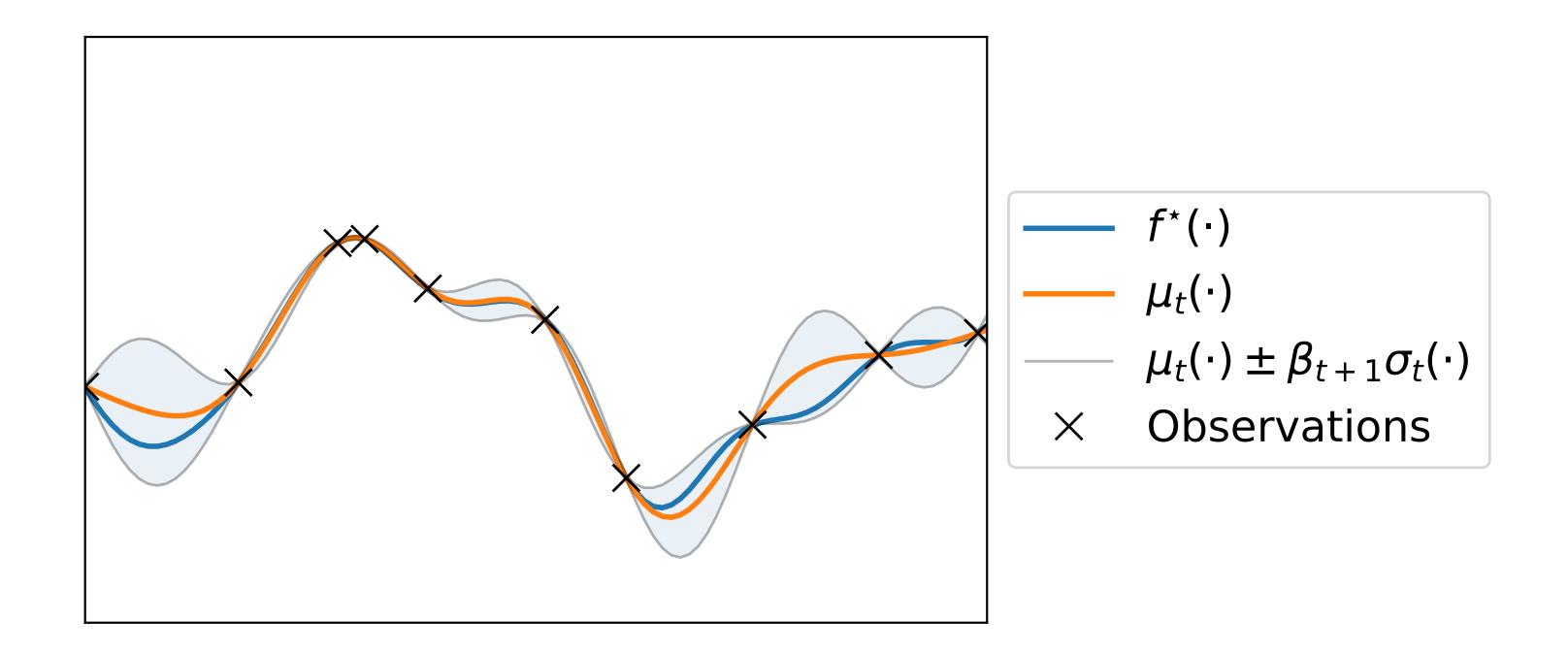
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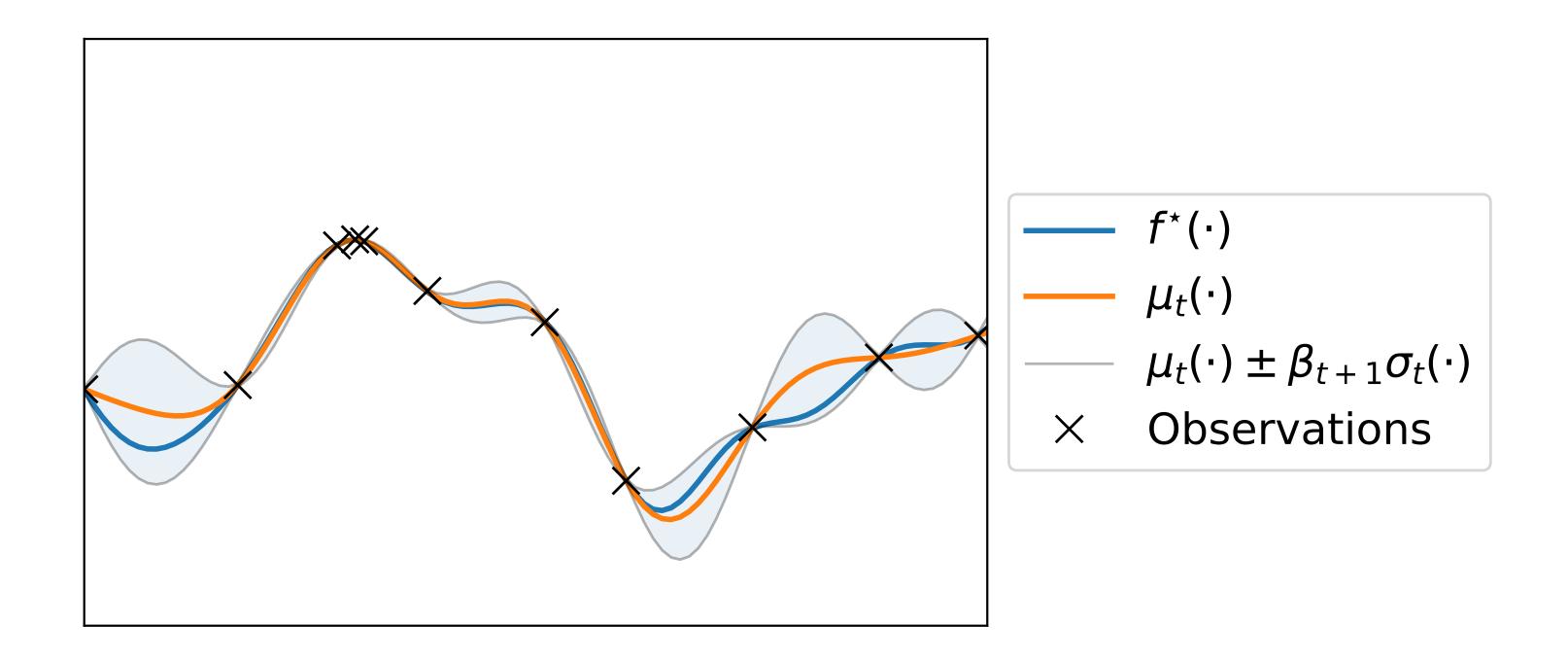
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- Our first algorithm: Enlarged Confidence UCB algorithm (EC-UCB)

$$x_{t} \in \arg\max_{x \in D} \mu_{t}^{\star}(x) + \left(\beta_{t+1} + \frac{\epsilon \sqrt{t}}{\sqrt{\lambda}}\right) \sigma_{t}(x)$$
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• Enlargement is due to model misspecification: For all x, t it holds

$$|\mu_t(\,\cdot\,) - \mu_t^{\star}(\,\cdot\,)| \leq \frac{\epsilon\sqrt{t}}{\sqrt{\lambda}}\sigma_t(\,\cdot\,)$$

- $\mu_t(\cdot)$: Hypothetical mean estimator that corresponds to the (noisy) observations of the best in-class function, i.e., $f \in \underset{f \in \mathcal{F}_k(\mathcal{D};B)}{\min} \|f f^*\|_{\infty}$
- Intuition: Correlations among observations captured in the model increase the bias

Enlarged confidence UCB algorithm

- Recall assumptions:
 - Learner's hypothesis class $\mathscr{F}_k(\mathscr{D};B)$; True reward function satisfies $\min_{f\in\mathscr{F}_k(\mathscr{D};B)}\|f-f^\star\|_\infty\leq \epsilon$

Theorem: EC-UCB achieves the following regret bound w.p. $1 - \delta$

$$R_T = \tilde{O}\Big(\underbrace{\left(B + \sqrt{\ln(1/\delta)}\right)\sqrt{\gamma_T T} + \gamma_T \sqrt{T}}_{\text{standard regret}} + \underbrace{T\epsilon\sqrt{\gamma_T}}_{\text{due to misspecification}}\Big).$$

- ightharpoonup T: time horizon / number of samples
- ightharpoonup: misspecification parameter
- $ightharpoonup \gamma_T$: kernel dependent mutual information quantity (measure of function class complexity)

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• EC-UCB drawback: Requires knowing ϵ !!

Recall:
$$x_t = \underset{x \in D}{\operatorname{arg max}} \ \mu_t^*(x) + \left(\beta_{t+1} + \frac{\epsilon \sqrt{t}}{\sqrt{\lambda}}\right) \sigma_t(x)$$

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 - Set $\mathcal{D}_{e+1} \leftarrow \left\{ x \in \mathcal{D}_e : \mu_{m_e}^{\star}(x) + \beta_{m_e+1} \sigma_{m_e}(x) \geq \max_{x \in \mathcal{D}_e} \left(\mu_{m_e}^{\star}(x) \beta_{m_e+1} \sigma_{m_e}(x) \right) \right\}$

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- Note: \mathscr{D}_e might not contain the global maximizer since the confidence bounds are invalid
- Phased elimination in the misspecified linear bandit (Lattimore et al.'20)

Phased kernel uncertainty sampling

Theorem: Phased uncertainty sampling achieves the following regret bound w.h.p.

$$R_T = \tilde{O}\Big(B\sqrt{\gamma_TT} \quad + \quad T\epsilon\sqrt{\gamma_T}\Big) \,.$$
 standard regret — due to misspecification

Adapts to unknown misspecification parameter

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- Misspecified kernelized contextual setting (in the paper)
 - ► Based on the regret bound balancing strategy of Pacchiano et al. '20

Summary

Goal:

- Protect against model misspecification
 - ► Bandits (Ghosh et al.'17, Zanette et al.'20, Lattimore et al.'20, Neu et al.'20, Foster et al.'20), Contextual bandits (Foster et al.'20, Pacchiano et al.'20), RL (Jin et al.'20, Du et al.'19)
- Strong model assumptions are restrictive in practice

Our contributions:

- Complete treatment of the misspecified GP bandit optimization problem
- Practical algorithms inspired by the classical Bayesian optimization and ED acquisition functions
- Theoretical regret bounds in multiple settings

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