

Note to self: Each time you work on the project, you should enter the date, start time and end time. You should document the references you consult, the main points from your reading, important tables or circuits from your reading, the ideas you have, the circuits you design, the software you write, simulation and experimental test results, your successes and failures, etc. You will submit your current notebook each week along with your weekly report, see below.

Illa's 2804 Project Notebook

Click on the hyperlink to see the start of the notes taken during the referenced milestone

Table of contents

[P2](#) *Milestone 1 notes*

[P9.....](#) *Milestone 2 notes*

7/14/21
2:17pm – 3:00pm

To Do's milestone #1

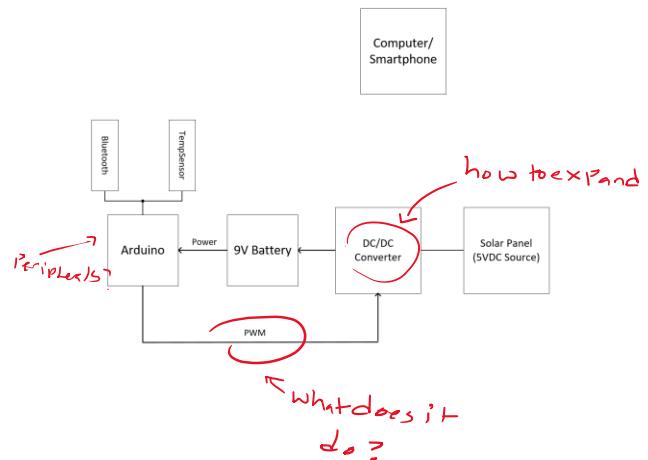
- Intro
 - background, proposed sol, significance

- overview
 - explain design + general plan

- Block diagram
 - key functions for hardware (blocks)
 - key functions for software + digital
 - analog to digital interface

- Break into milestones

- list goals for hardware + software
- specify deliverables
- specify testing (components + combined)



Software → only can use bluetooth lib

Preliminary Research (sites visited and articles read):

https://en.wikipedia.org/wiki/DC-to-DC_converter (Wikipedia page on DC/DC converter)

Converter_Steady_State_Analysis.pdf (Info for DC/DC converter circuit I think?)

<http://ww1.microchip.com/downloads/en/devicedoc/20001942g.pdf> (datasheet for temp sensor)

Converter chapter notes

Buck converter \rightarrow reducing DC voltage using only non-dissipative switches, inducts + caps

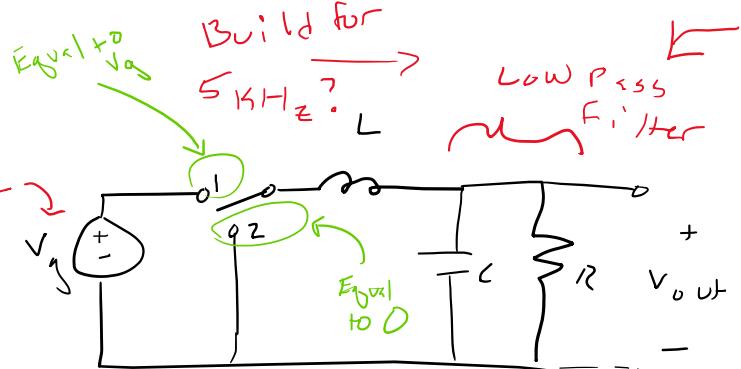
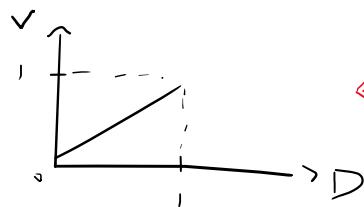
↓
rect wave form

$$\langle v_s \rangle = \frac{1}{T_s} \int_0^{T_s} v_s(t) dt$$

$$\langle v_s \rangle = \frac{1}{T_s} (D T_s v_s) = D v_s$$

DC INPUT VOLT

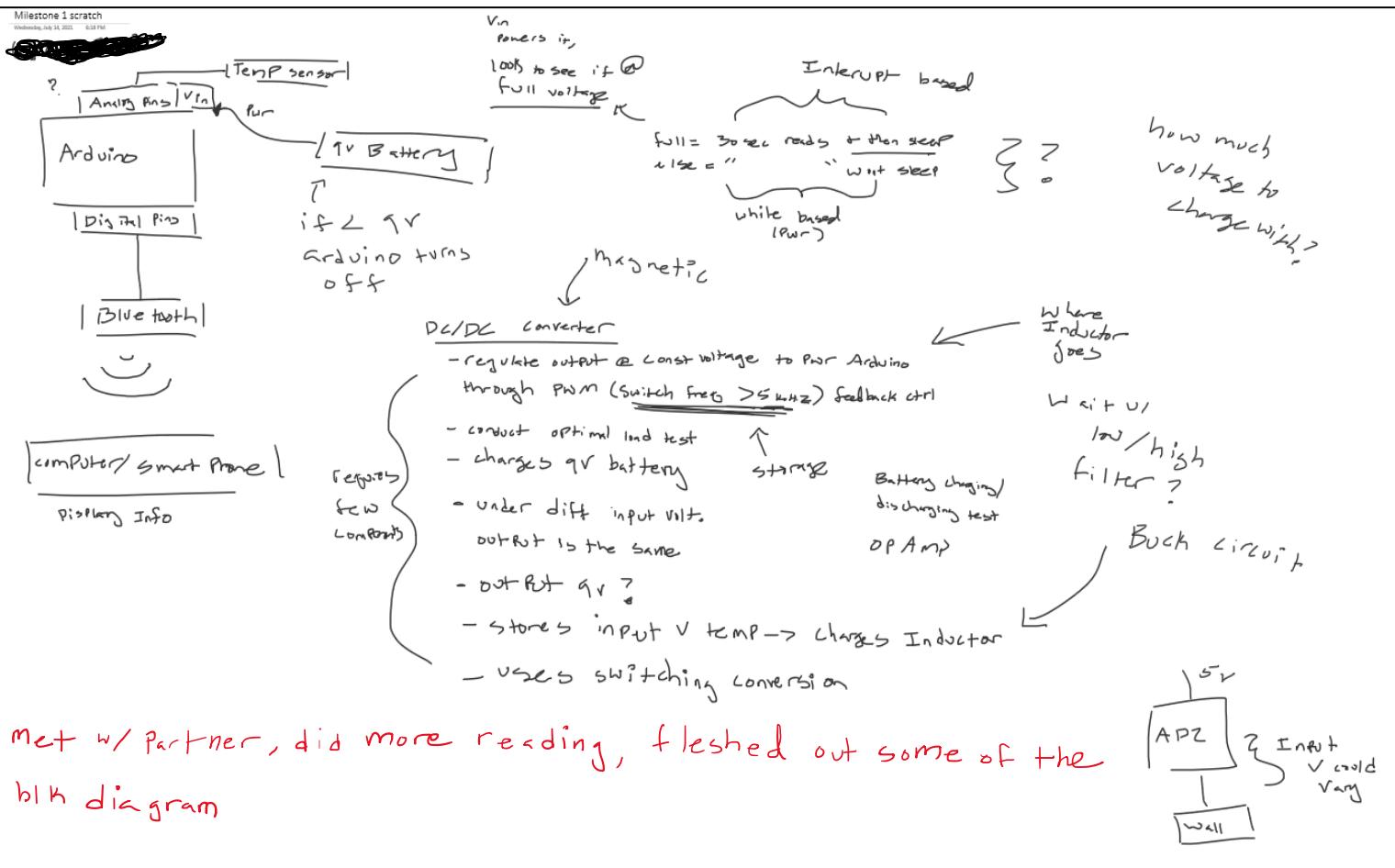
Duty cycle



Buck converter
DC out V_o vs
Duty cycle

7/14/21

6:21pm – 7:40pm



Peripherals of Arduino?

- Clock: for 30 sec intervals
- Monitor/display: to show value
- Bluetooth: to communicate data
- Temp sensor: to read temp
- Input volt val: to PWR + to analyze

Something for PWM?

needed Programming

Pwr {
 Setting }

- clock module
- Interrupt based code
- While based code
- Read + interrupt + temp
- Display module
- Bluetooth module

Arduino Research notes

uses simplified C++

major Arduino components

- USB Connector → used to load code ("on PWR")
 - PWR port → PWR port (ops @ 5V)? ? might need to reconsider PWR idea from earlier
 - Analog Pins → (6 pins) temp sensor, only measure volt.
 - Digital Pins → In or out (read comp. sig)
 - Reset switch → run from start
 - Crystal oscillator → ticks, math stuff
 - TX RX Leds → Transmit, receive data
 - micro controller → Brain (has flash mem, ram)
32 kB 2 kB
 - USB Interface chip → signal translator
- can be reconfig as dig
- ~(Tilde)
- pins can be used for PWM (simulate analog out)

Arduino References (Read or watched to refresh memory / find info)

<https://www.arduino.cc/en/Guide/ArduinoUno>

https://www.youtube.com/watch?v=_ItSHuIJAJ8

7/15/21

11:42am - 2:00pm

Converter reading notes cont.

Converter options

- Buck \rightarrow dec V ; $v \leq v_s$
- boost \rightarrow inc V ; $v \geq v_s$
- buck-boost \rightarrow inc or dec
but Polarity reverses

How to make switch?

Is switch related to PWM?
Buck

Impossible for filter to remove all stuff, so there is small V ripple

$$|V_{\text{ripple}}| \ll V; V(+) \approx V$$

$$V_L = V_s - V(+)$$

$$V_L(+) = L \frac{di_L(t)}{dt}$$

$$\frac{di_L(t)}{dt} \approx \frac{V}{L}$$

Knowing peak $i(t)$ is important for specifying ratings

use to
select
buck 2

$$\left. \begin{array}{l} L = \frac{V_s - V}{2 \pi f_i L} D T_s \\ \uparrow \\ \text{current ripple} \end{array} \right\}$$

10% - 20% full load

Val of DC component I

stored on pg 9

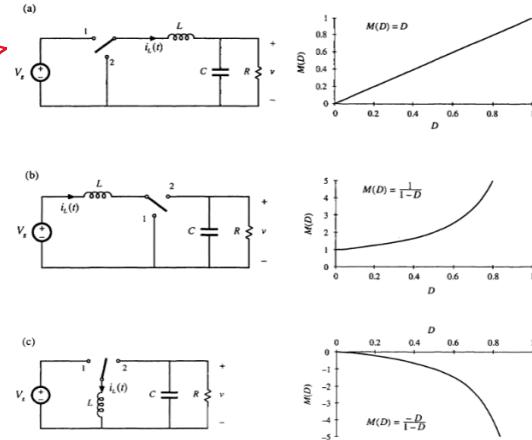


Fig. 2.5 Three basic converters and their dc conversion ratios $M(D) = V/V_s$: (a) buck, (b) boost, (c) buck-boost.

IP.S of P.D.F

Research on PWM

- Is the switch for converter, releasing + stopping the charge?

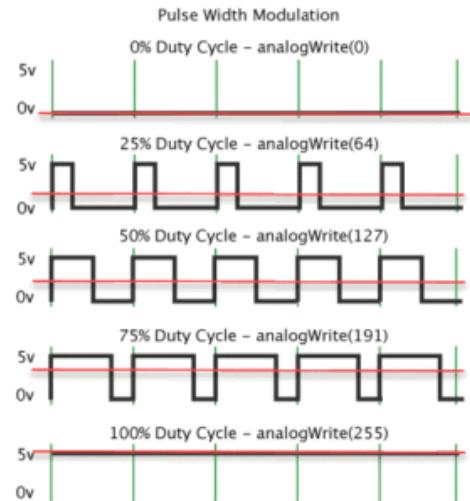


Figure 1: An example of a PWM signal shown at several duty cycles and a high voltage level of 5 volts. The red line is the average voltage that the driven device (e.g., a motor) is experiencing.

(Source: [Timothy Hirzel](#),)

how to implement?

Pulse is on 50% of the time

calculating duty cycle could help w/ building converter

"we use duty cycle + frequency to describe PWM"

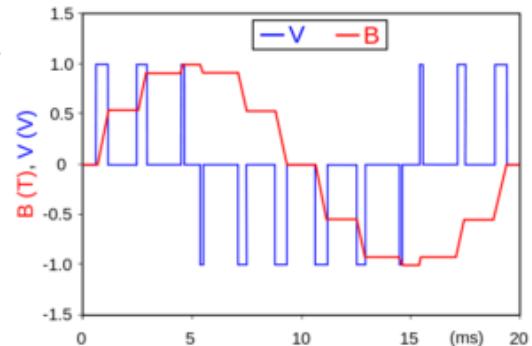


Figure 2: The blue lines are PWM output from an MCU, and the red line is the average voltage. In this case, the pulse width (and corresponding duty cycle) change so that the average voltage looks more like an analog output that is not in a steady state such as shown in Figure 1. (Source: [Zureks - Own work, CC BY-SA 3.0,](#))

$$V_{\text{Avg}} = V_{\text{high}} \times D$$

← Instantaneous D
↑ Instantaneous V

ECE Embedded syst notes

$$D = \frac{\text{on Time}}{\text{Period}}$$

$T = \frac{1}{f}$

Interrupts
Set so when timer exp, triggers?

Proj 3 had PWM I think

Toggle / reset or Toggle set?

need timer for PWM

Prescaler P
Loadval N

$$N \times P = \frac{f_s}{f_{\text{PWM}}} \leftarrow \begin{array}{l} \text{Syst} \\ \text{is @ Vref} \\ \text{when index} \\ \text{counts switches} \\ \text{Pwm counts till} \\ \text{discharge} \end{array}$$

Pwm for syst counts to when index is @ Vref

then counts switches till discharge

Inductors Review

$$L = \frac{\phi_B}{I}$$

magnetic flux

of turns

$$L = \frac{N^2 \mu_r \mu_0 A}{l}$$

Avg length of coil

Area of coil in m^2 (πr^2)

$$L \approx \frac{\mu N^2 A}{2\pi r}$$

A = cross-sectional area
 r = toroid radius to centerline

491 x 94

$$V(t) = L \frac{di(t)}{dt}$$

We are making a Toroidal Inductor I think?

$$L = 0.01595 N^2 \left(D - \sqrt{D^2 - d^2} \right)$$

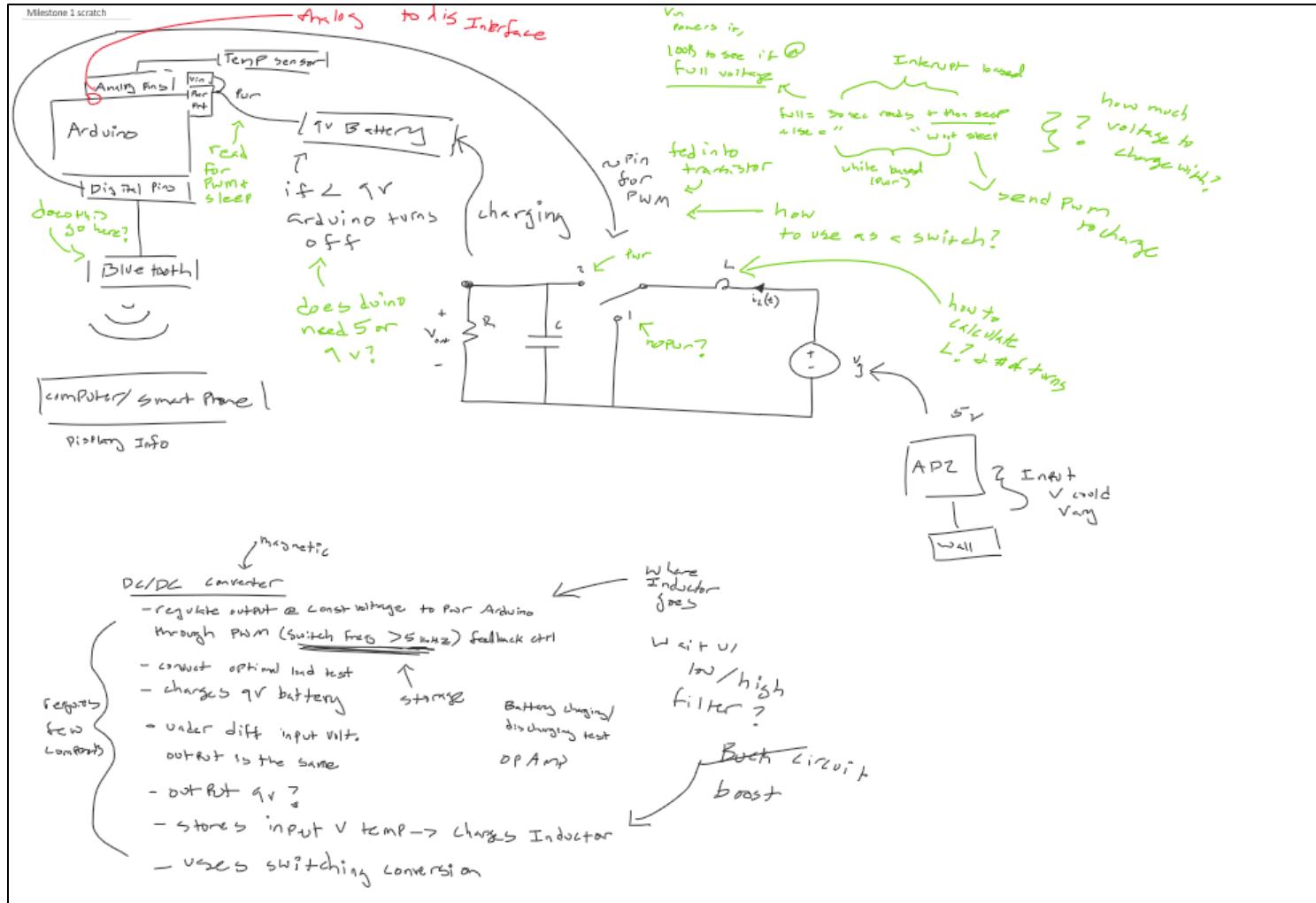
- L = inductance (μH)
- d = diameter of coil winding (in)
- N = number of turns
- D = $2 * \text{radius of revolution}$ (in)

$$L \approx 0.007975 \frac{d^2 N^2}{D}$$

- L = inductance (μH)
- d = diameter of coil winding (in)
- N = number of turns
- D = $2 * \text{radius of revolution}$ (in)

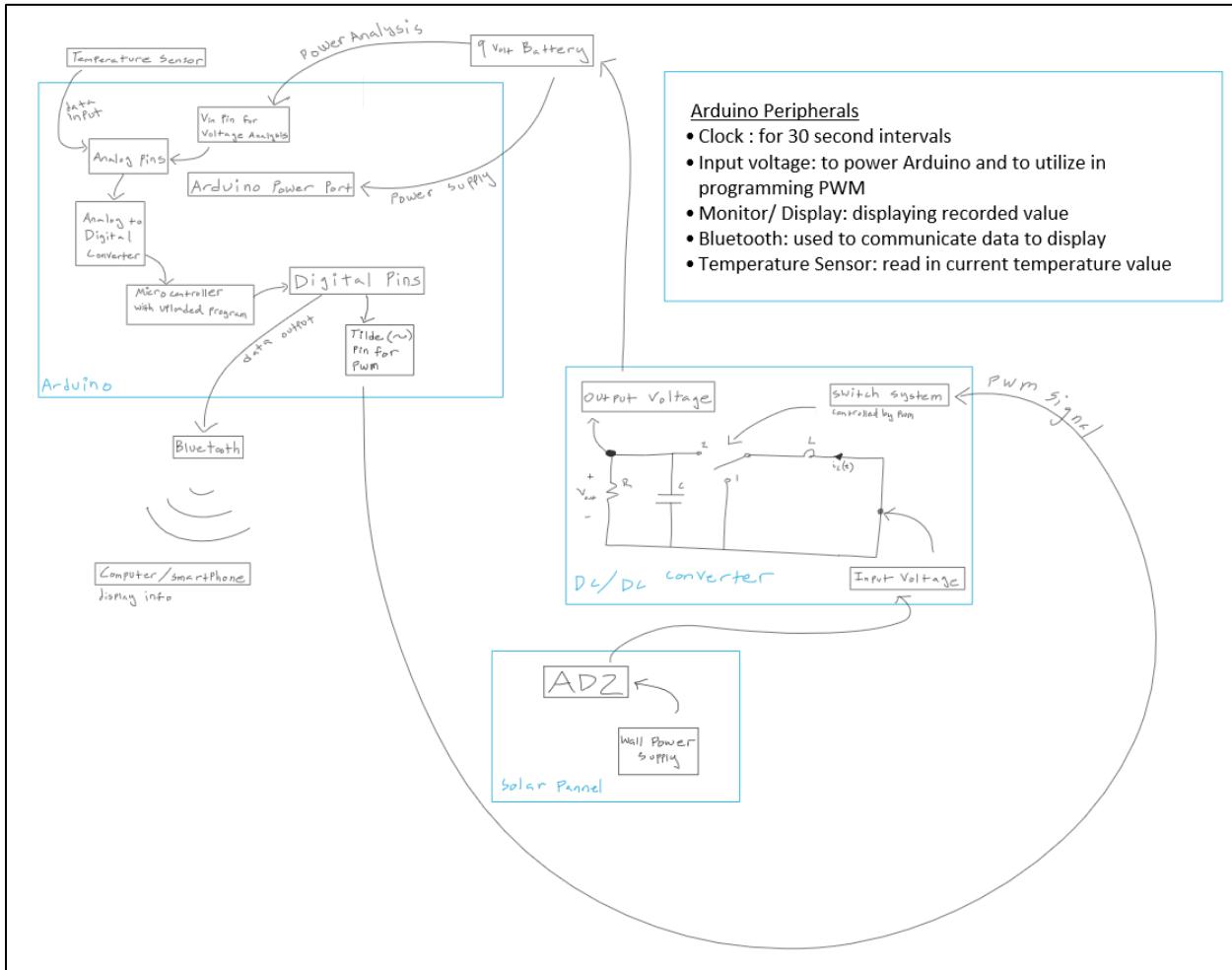
Img from wikipedia

\approx Prox when
 $d < 0.1 D$



Useful for programming Bluetooth: <https://www.geeksforgeeks.org/all-about-hc-05-bluetooth-module-connection-with-android/>

Talked with partner and finalized report. Made clean version of block diagram and wrote part of the outline



Today's Goals

- Calculate Values for DC/DC converter

- Inductor specifics

- Resistor + cap values

- Figure out switch

$$V_L = V_S - V$$

shouldn't
be -?

$$V_L = 5 - 1 = -4$$

- Simulate in LT spice

- Test behavior

- optimal Load + test

duty cycle

$$L_{\min} = \frac{D(1-D)R}{2f_L}$$

↑
mH

freq

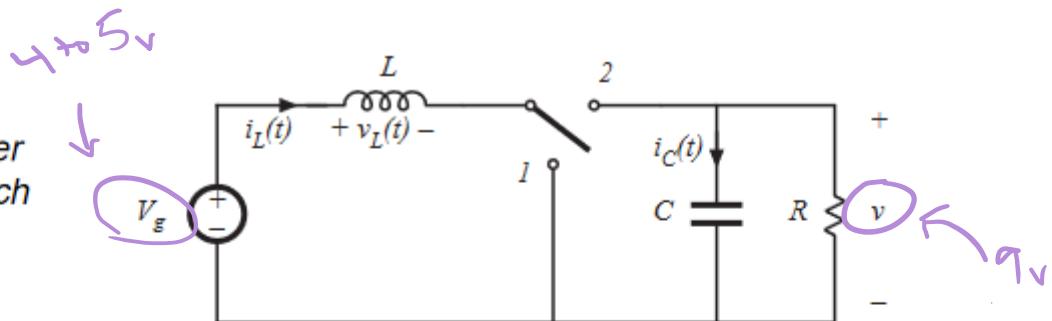
$$V = \frac{V_S}{D}$$

duty cycle?

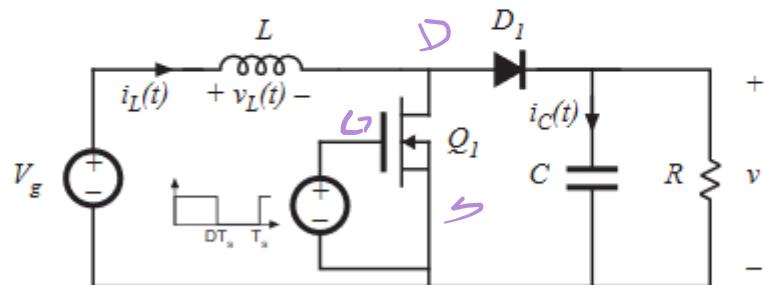
do we need a filter?

switching ≤ 5 kHz

Boost converter
with ideal switch



Realization using
power MOSFET
and diode



Average Current in the Boost Inductor

$$L \approx \frac{\mu N^2 A}{2\pi r}$$

491 x 94

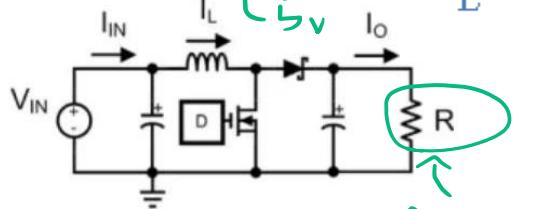
A = cross-sectional area
 r = toroid radius to centerline

- Average input current and average inductor current are equal
- Two basic ways to calculate I_{IN} and I_L :

$$I_L = I_{IN} = \frac{I_o}{(1-D) \times \eta_{EST}}$$

- Use 85-90% for η_{EST}
 - Non-sync
- Use 85-95% for η_{EST}
 - Synchronous

$$I_L = I_{IN} = \frac{I_o \times V_o}{V_{IN} \times \eta_{EST}}$$



$$V_L = N \frac{d\Phi}{dt} = \frac{\mu N^2 A}{l} \frac{di}{dt}$$

$$\Phi = BA \cos \theta$$

$$V(t) = L \frac{di(t)}{dt}$$

$$L = \frac{\phi_B}{I}$$

magnetic flux

current

size?

ask later

↓

↓ $V_{max} L$?

assume $V_L = -4$

$$I_L = \frac{V}{X_L} = \frac{V}{2\pi f L} = \frac{V}{2\pi (\frac{\mu N^2 A}{2\pi r})} = \frac{I_o \times V_o}{V_{IN} \times \eta_{EST}}$$

Inductance

?

How do we calculate $L, C, + R$?

$$T_{Dn} = \omega T$$

$$\omega_{max} = 1 - \sqrt{\frac{r}{R}}$$

$$1 - \alpha = \sqrt{\frac{r}{R}}$$

Self Inductance –the Maths

- When self inductance occurs the flux is proportional to the current in the inductor

$$\Phi = L \times I$$

where:

Φ = magnetic flux (Wb)
 L = self-inductance (H)
 I = current (A)

- Substituted into Faraday's law;

$$V = \frac{-L \Delta I}{\Delta t}$$

- Units for self-inductance is the Henry (symbol H)

$$I = \frac{V}{X_L}$$

where V is the rms voltage ac

$$X_L = 2\pi f L$$

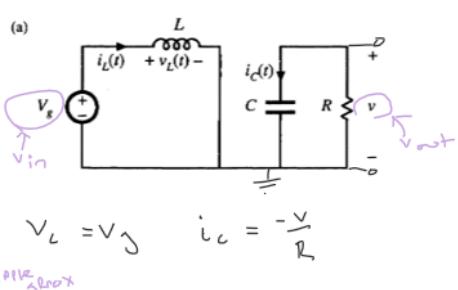
7/21/21
2:00pm – 3:06pm

Reading PDF so I can try a bit more to figure out converter.

QP 1:

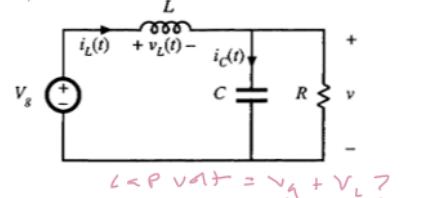
Switch in pos 1:

Charges Inductor, cap discharges



Switch in pos 2:

Releases Inductor charge, cap charges



$$\text{Cap v at } = V_g + V_L ?$$

$$V_L = V_g - V$$

$$i_C = i_L - \frac{V}{R}$$

$$V \approx V \quad \sum_{i_L \approx I} V_L = V_g - V$$

$$i_C = I - \frac{V}{R}$$

Eqn used to sketch

Inductor + cap wave forms

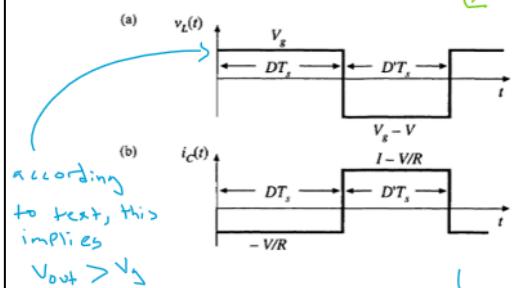
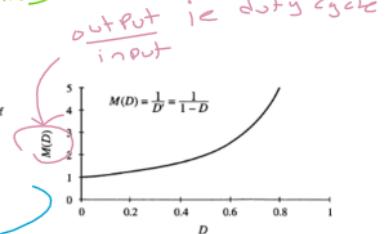


Fig. 2.16 Dc conversion ratio $M(D)$ of the boost converter.



The total volt-seconds applied to the inductor over one switching period are:

$$\int_0^{T_s} v_L(t) dt = (V_g)DT_s + (V_g - V)DT_s$$

T_s is the period, ie $\frac{1}{f_s}$

How to use?
are important?

Instructor Yu Conversation

(0.1)(70mA)

$$\Delta i_L = \frac{V_g}{Z(L)} D T_s$$

Inductor current ripple

see text for details
but basically
pick a value smaller
than that

If input voltage varies $\rightarrow D$ varies
so the output voltage is constant

$$T_s = \frac{1}{f_s}$$

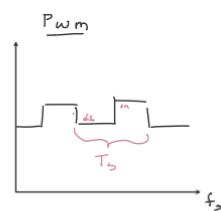
Proj description:
 $f_s > 5\text{kHz}$

$$\frac{T_{on}}{T_s} = D$$

duty cycle varies

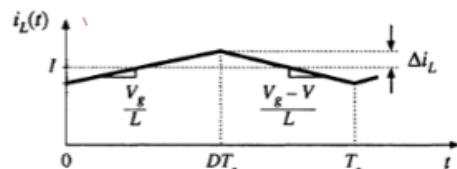
$$b/c \quad V = \frac{V_g}{D} = \frac{V_g}{1-D} \quad D = 1 - D$$

Proj description: $4V \leq V_g \leq 5V$



If we assume V_g
is constant then
 D doesn't vary

Fig. 2.18 Boost converter inductor current waveform $i_L(t)$



$$\Delta V = \frac{V}{2RL} DT_s$$

↑
Voltage
ripple peak
magnitude

↑ Capacitor
 R_{bias}

<https://ridleyengineering.com/design-center-ridley-engineering/39-magnetics/66-031-choosing-the-inductor-for-a-buck-converter.html>

<https://www.instructables.com/Using-the-Power-Supplies-With-the-Analog-Discovery/>

$\Delta i_L \%$ range from 2.5% to $50\% \rightarrow 10\%$ pretty commonly used

ADZ has

no more than 3%

current max of $700mA$

Pick a decent duty cycle

Voltage max of $5V$

found in
waveforms

current max of $700mA$

Voltage max of $5V$

found in
waveforms

Calculations

Inductor

$$\Delta i_L = \frac{V_{in}}{2L} DT_s$$

$$L = \frac{V_{in}}{2 \Delta i_L} DT_s$$

$$L = \frac{(5V)}{2(0.03)(700mA)} (0.5) \left(\frac{1}{5.5kHz} \right)$$

$$L = 1.0108H$$

make
sure
 ΔDZ
can handle

capacitor
close to 0Ω

$$\Delta V = \frac{V_{out}}{2RL} DT_s$$

$$C = \frac{V_{out}}{2\pi \Delta V} DT_s$$

$$C = \frac{(9V)}{2(1.5k\Omega)(0.03)(5)} (0.5) \left(\frac{1}{5.5kHz} \right)$$

$$C = 1.8 \times 10^{-6} = 1.8 \mu F$$

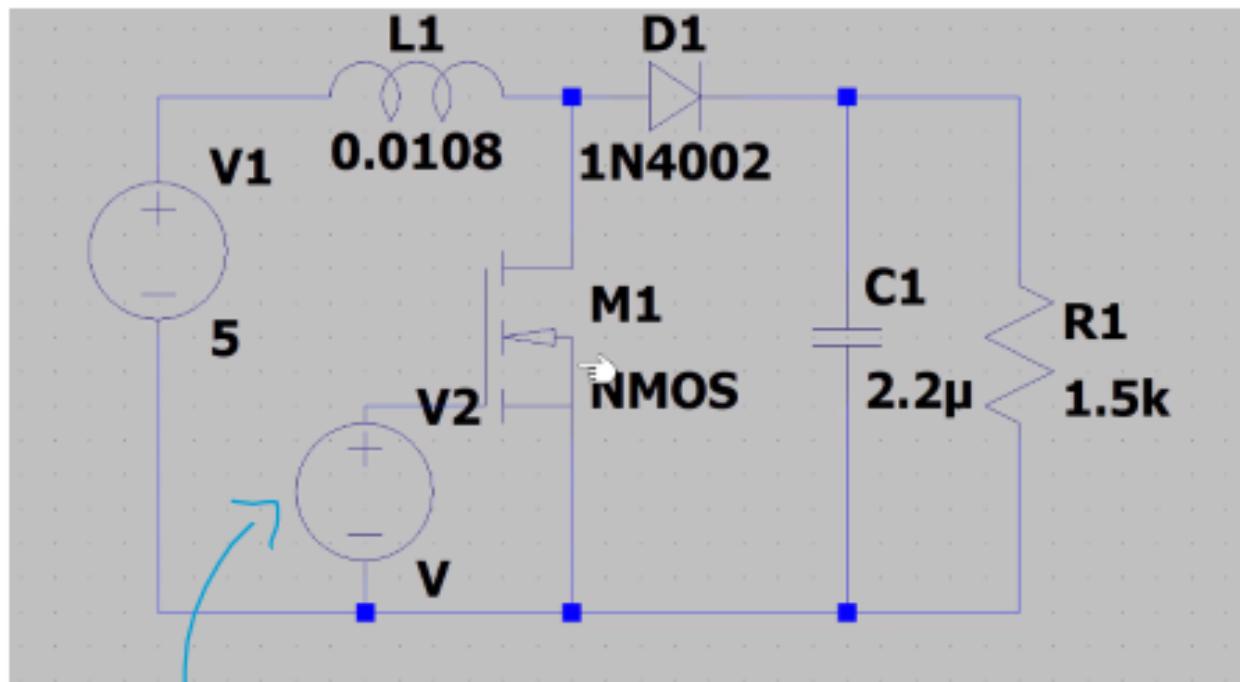
choosing $2.2\mu F$ from kit
choosing $R = 1.5k\Omega$

LTspice

IN 4001 ← diode

How to
make
work

ZN7000A ← N-mosfet



is Pwm

7/23/21

3:30pm – 11:00pm (some breaks taken)

Worked by self to make changes to LT Spice recommended. Also worked on refining block diagram for report and creating the Optimal Load Test graph. Uncertain if calculations are correct. Will check later.

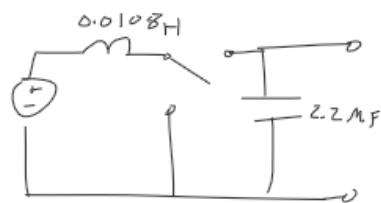
Efficiency curve based on load ($R_{L\text{md}}$)

"Sweep" across different R_L

Plot η_L vs. Pwr

$R_L = R_s$ is where max Power transfer is usually

need to find R_s for our circuit



$$X_c = \frac{1}{j\omega C}$$

$$X_L = j\omega L$$

$$\omega = 2\pi f$$

$$f = 5.5 \text{ kHz}$$

$$\omega = 2\pi(5.5 \times 10^3) = 34557.5$$

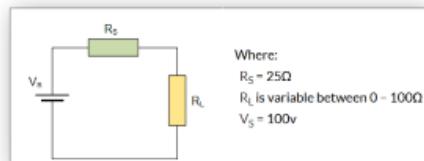
$$X_c = \frac{1}{j(34557.5)(2.2 \text{ MF})} = -13.153j \quad \text{note } \frac{1}{j} = -i$$

$$X_L = j(34557.5)(0.0108H) = 374.00j$$

$$R_s = 374.00j + 13.153j = 387.15j$$

$$|R_s| = \sqrt{(0)^2 + (387.15)^2} = \boxed{387.15}$$

Maximum Power Transfer Example No1



Where:
 $R_s = 25\Omega$
 R_L is variable between 0 – 100Ω
 $V_s = 100V$

$$I = \frac{V_s}{R_s + R_L} \quad \text{and} \quad P = I^2 R_L$$

https://www.electronics-tutorials.ws/dc/circuits/dcp_9.html

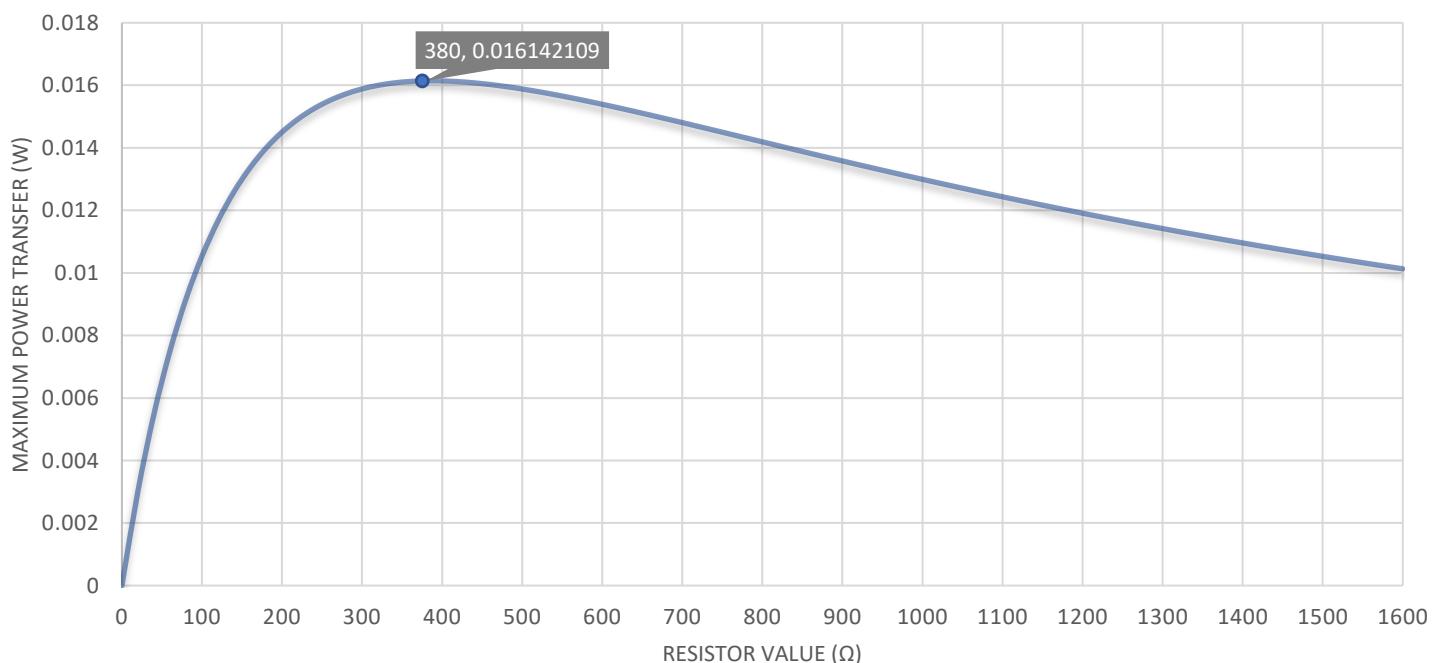
For better understanding

APZ has max bandwidth of
 12 MHz so 5.5 kHz is fine

$$|Z_e|^2 = R^2 + X^2$$

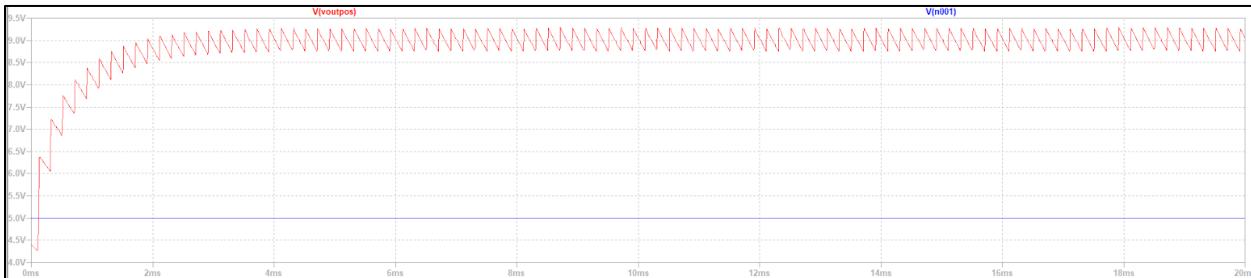
real \hookrightarrow Z_{real}
 imp. magnitude \hookrightarrow Z_{imp}

Optimal Load Test

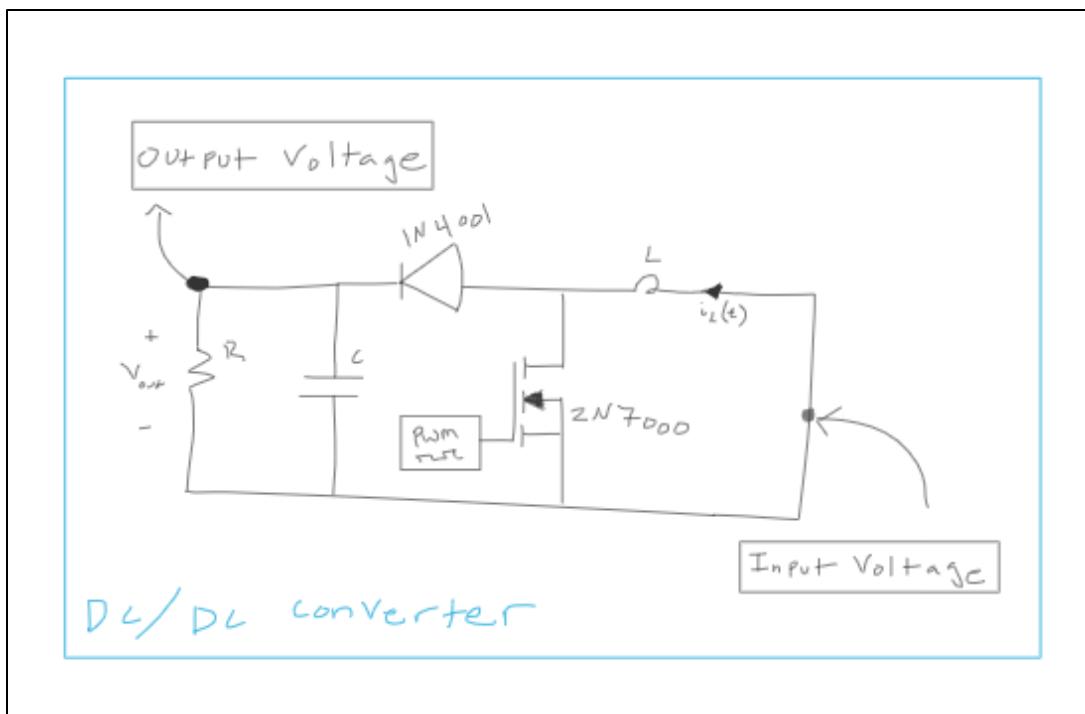


7/24/21
3:00pm – 7:00pm

Just refined math, redid calculations and wrote final report



<p><u>Calculations</u></p> <p><u>Inductor</u></p> $\Delta i_L = \frac{V_{in}}{ZL} DT_s$ $L = \frac{V_{in}}{Z \Delta i_L} DT_s$ $= \frac{(5V)}{(2)(100mA)} (0.5) \left(\frac{1}{70 \text{ kHz}} \right)$ $L = 1.79 \times 10^{-4} \text{ H}_z = 1.79 \mu\text{H}$ <p>Choosing 162uH based on LTspice</p>	<p><u>Circuit</u></p> $\Delta V = \frac{V_{out}}{ZRL} DT_s$ $L = \frac{V_{out}}{ZR \Delta V} DT_s$ $= \frac{(9V)}{2(1.5\text{mH})(0.03)(5)} (0.5) \left(\frac{1}{70 \text{ kHz}} \right)$ $L = 1.8 \times 10^{-6} = 1.8 \mu\text{F}$ <p>Choosing 2.2uH from kit Choosing R = 1.5kΩ</p>
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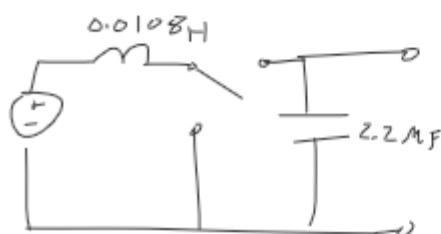


Efficiency curve based on load (R_{load})

"Sweep" across different R_L

Plot η vs. P_{out}

$R_L = R_s$ is where max power transfer is usually
need to find R_s for our circuit



$$X_C = \frac{1}{j\omega C}$$

$$X_L = j\omega L$$

$$\omega = 2\pi f$$

$$f = 5.5 \text{ Hz}$$

$$\omega = 2\pi(5.5 \times 10^3) = 34557.5$$

$$X_C = \frac{1}{j(34557.5)(2.2 \text{ MF})} = -13.153j \quad \text{note } \frac{1}{t} = -i$$

$$X_L = j(34557.5)(162\text{nH}) = 5.5j$$

$$R_s = 5.5j + 13.153j = 18.75j$$

$$|R_s| = \sqrt{(0)^2 + (18.75)^2} = \boxed{18.75} \quad |$$

