

# Graph

# Graph

A *graph*  $G$  consists of two things:

- (i) A set  $V = V(G)$  whose elements are called *vertices*, *points*, or *nodes* of  $G$ .
- (ii) A set  $E = E(G)$  of unordered pairs of distinct vertices called *edges* of  $G$ .

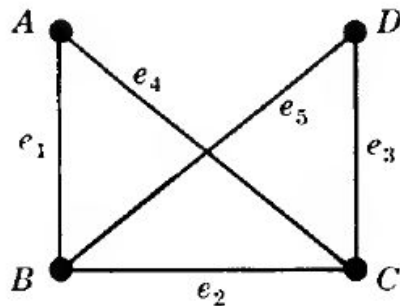
We denote such a graph by  $G(V, E)$  when we want to emphasize the two parts of  $G$ .

# Vertex and Edge

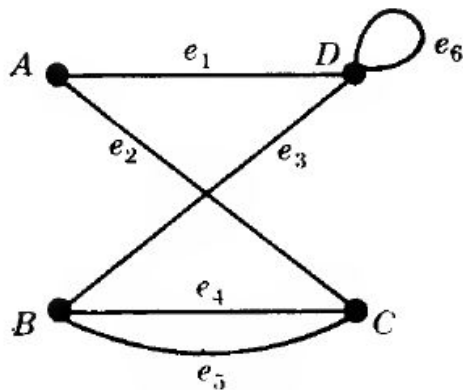
(i)  $V$  consists of vertices  $A, B, C, D$ .

(ii)  $E$  consists of edges  $e_1 = \{A, B\}$ ,  $e_2 = \{B, C\}$ ,  $e_3 = \{C, D\}$ ,  $e_4 = \{A, C\}$ ,  $e_5 = \{B, D\}$ .

In fact, we will usually denote a graph by drawing its diagram rather than explicitly listing its vertices and edges.



(a) Graph



(b) Multigraph

# Degree of vertex

## Degree of a Vertex

The *degree* of a vertex  $v$  in a graph  $G$ , written  $\deg(v)$ , is equal to the number of edges in  $G$  which contain  $v$ , that is, which are incident on  $v$ . Since each edge is counted twice in counting the degrees of the vertices of  $G$ , we have the following simple but important result.

**Theorem 8.1:** The sum of the degrees of the vertices of a graph  $G$  is equal to twice the number of edges in  $G$ .

Consider, for example, the graph in Fig. 8-5(a). We have

$$\deg(A) = 2, \quad \deg(B) = 3, \quad \deg(C) = 3, \quad \deg(D) = 2.$$

# Subgraph

## Subgraphs

Consider a graph  $G = G(V, E)$ . A graph  $H = H(V', E')$  is called a *subgraph* of  $G$  if the vertices and edges of  $H$  are contained in the vertices and edges of  $G$ , that is, if  $V' \subseteq V$  and  $E' \subseteq E$ . In particular:

- (i) A subgraph  $H(V', E')$  of  $G(V, E)$  is called the subgraph *induced* by its vertices  $V'$  if its edge set  $E'$  contains all edges in  $G$  whose endpoints belong to vertices in  $H$ .
- (ii) If  $v$  is a vertex in  $G$ , then  $G - v$  is the subgraph of  $G$  obtained by deleting  $v$  from  $G$  and deleting all edges in  $G$  which contain  $v$ .
- (iii) If  $e$  is an edge in  $G$ , then  $G - e$  is the subgraph of  $G$  obtained by simply deleting the edge  $e$  from  $G$ .

## Isomorphic Graphs

Graphs  $G(V, E)$  and  $G(V^*, E^*)$  are said to be *isomorphic* if there exists a one-to-one correspondence  $f: V \rightarrow V^*$  such that  $\{u, v\}$  is an edge of  $G$  if and only if  $\{f(u), f(v)\}$  is an edge of  $G^*$ . Normally, we do not distinguish between isomorphic graphs (even though their diagrams may “look different”). Figure 8-6 gives ten graphs pictured as letters. We note that  $A$  and  $R$  are isomorphic graphs. Also,  $F$  and  $T$  are isomorphic graphs,  $K$  and  $X$  are isomorphic graphs and  $M$ ,  $S$ ,  $V$ , and  $Z$  are isomorphic graphs.

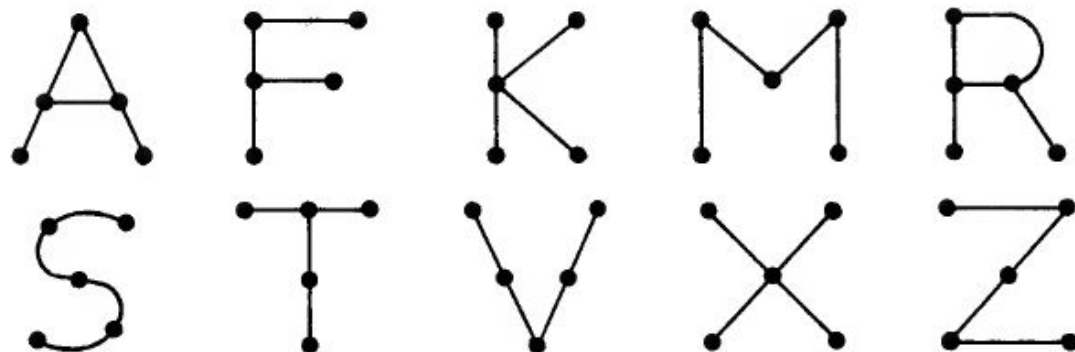


Fig. 8-6

## Homeomorphic Graphs

Given any graph  $G$ , we can obtain a new graph by dividing an edge of  $G$  with additional vertices. Two graphs  $G$  and  $G^*$  are said to be *homeomorphic* if they can be obtained from the same graph or isomorphic graphs by this method. The graphs (a) and (b) in Fig. 8-7 are not isomorphic, but they are homeomorphic since they can be obtained from the graph (c) by adding appropriate vertices.

# Homomorphic graph

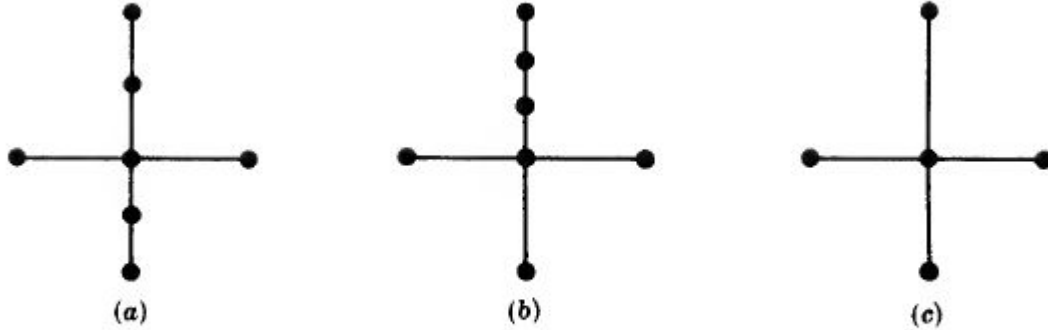
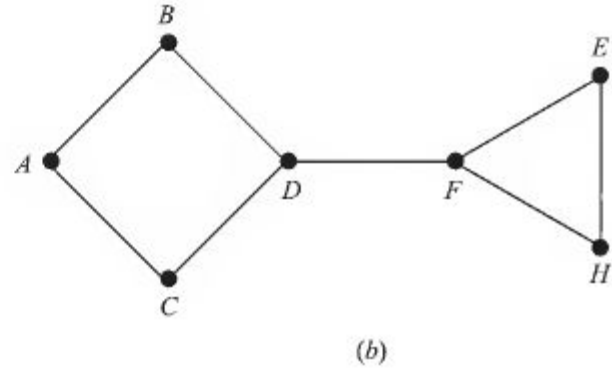
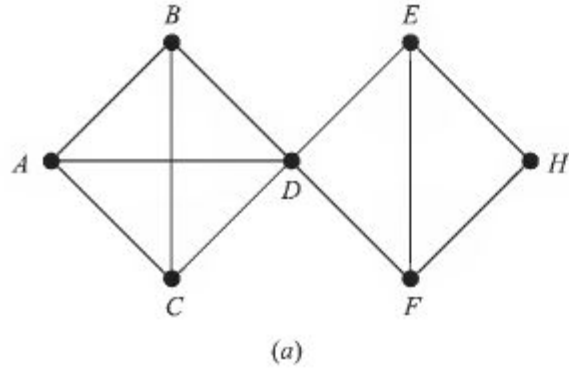


Fig. 8-7

# Cut point and Bridge



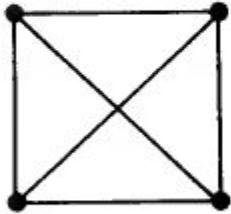


# Complete Graph

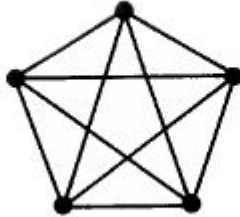
$K_1$  = isolated vertex: ●

$K_2$  = line segment: ●—●

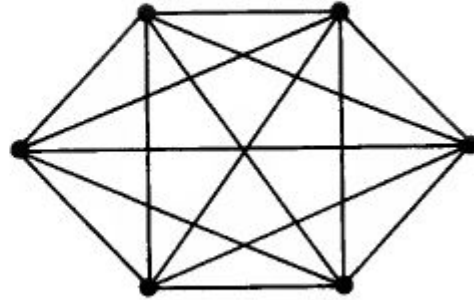
$K_3$  = triangle: 



$K_4$



$K_5$



$K_6$

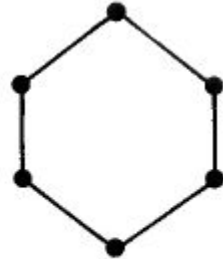
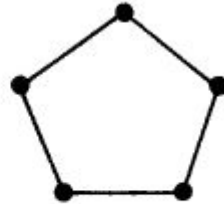
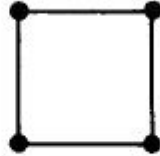
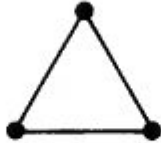
# Regular graph



(i) 0-regular



(ii) 1-regular



(iii) 2-regular

# Bipartite graph

A graph  $G$  is said to be bipartite if its vertices  $V$  can be partitioned into two subsets  $M$  and  $N$  such that each

edge of  $G$  connects a vertex of  $M$  to a vertex of  $N$ . By a complete bipartite graph, we mean that each vertex of

$M$  is connected to each vertex of  $N$ ; this graph is denoted by  $K_{m,n}$  where  $m$  is the number of vertices in  $M$  and

$n$  is the number of vertices in  $N$ , and, for standardization, we will assume  $m < n$ .

Figure 8-16 shows the graphs

$K_{2,3}$ ,  $K_{3,3}$ , and  $K_{2,4}$ . Clearly the graph  $K_{m,n}$  has  $mn$  edges.

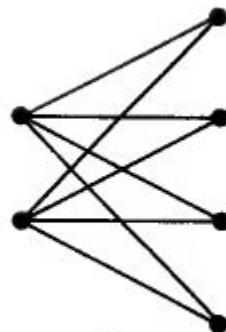
# Bipartite graph



$K_{2,3}$



$K_{3,3}$



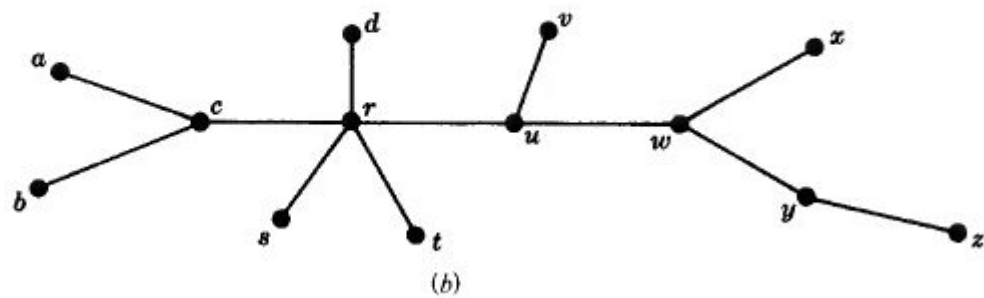
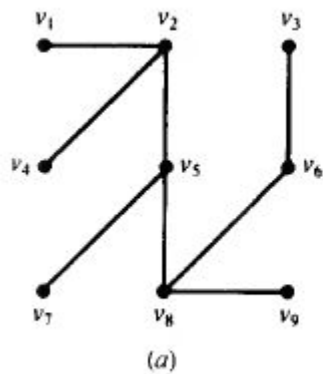
$K_{2,4}$

# Tree

Let  $G$  be a graph with  $n > 1$  vertices. Then the following are equivalent:

- (i)  $G$  is a tree.
- (ii)  $G$  is a cycle-free and has  $n - 1$  edges.
- (iii)  $G$  is connected and has  $n - 1$  edges.

# Tree



# Spanning tree

A subgraph  $T$  of a connected graph  $G$  is called a spanning tree of  $G$  if  $T$  is a tree and  $T$  includes all the

vertices of  $G$ . Figure 8-18 shows a connected graph  $G$  and spanning trees  $T_1$ ,  $T_2$ , and  $T_3$  of  $G$ .

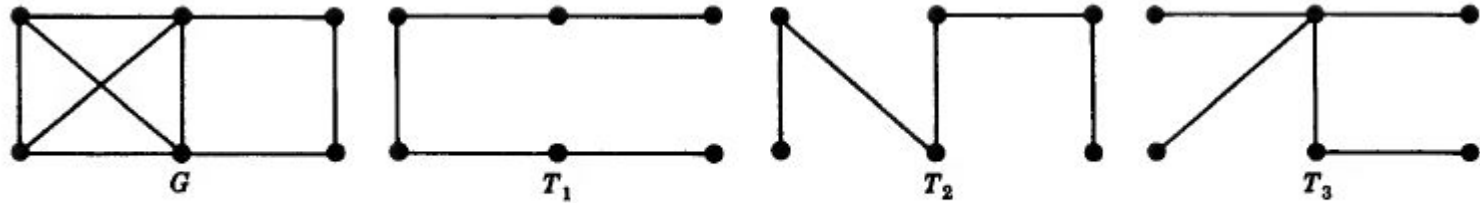


Fig. 8-18

# Minimum spanning tree algorithm

**Algorithm 8.2:** The input is a connected weighted graph  $G$  with  $n$  vertices.

*Step 1.* Arrange the edges of  $G$  in the order of decreasing weights.

*Step 2.* Proceeding sequentially, delete each edge that does not disconnect the graph until  $n - 1$  edges remain.

*Step 3.* Exit.

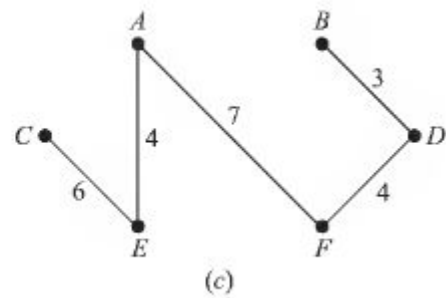
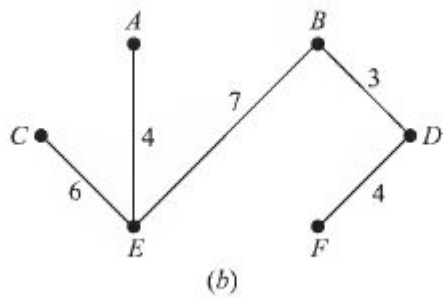
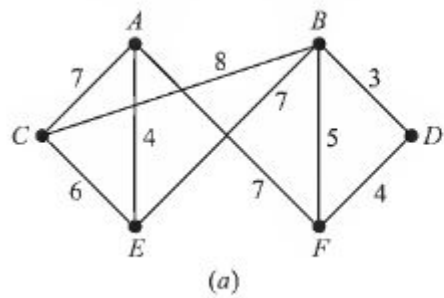
**Algorithm 8.3 (Kruskal):** The input is a connected weighted graph  $G$  with  $n$  vertices.

*Step 1.* Arrange the edges of  $G$  in order of increasing weights.

*Step 2.* Starting only with the vertices of  $G$  and proceeding sequentially, add each edge which does not result in a cycle until  $n - 1$  edges are added.

*Step 3.* Exit.





# Planar graph

