



Ready Player One

Video Games Tracking

CS 415: Game Development
(Virtual Reality Module)

Professor Luciano Soares



Tracking technologies



Mechanical

Electromagnetic

Acoustical

Inertial (accelerometers, gyroscopes)

Optical

Mechanical tracking from Sutherland HMD



The first ever HMD used a mechanical tracking solution to identify user's head pose

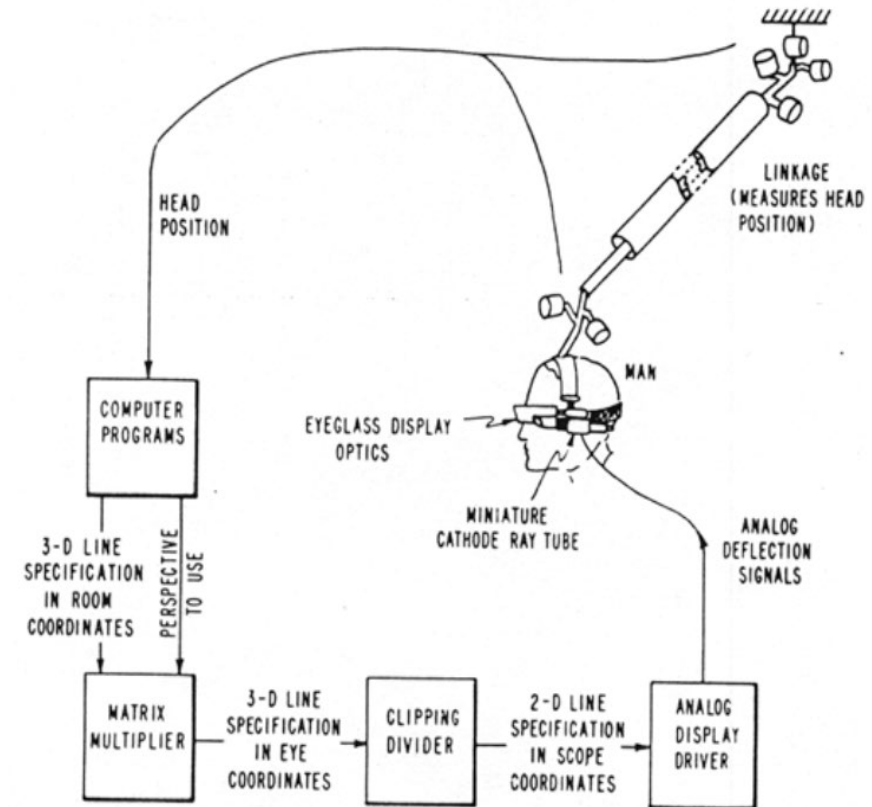


FIGURE 1—The parts of the three-dimensional display system



The Sword of Damocles



Reference: Ivan E. Sutherland. 1968. A head-mounted three dimensional display. In Proceedings of the December 9-11, 1968, fall joint computer conference, part I (AFIPS '68 (Fall, part I)). Association for Computing Machinery, New York, NY, USA, 757–764. <https://doi.org/10.1145/1476589.1476686>

Mechanical Tracking - Encoders



Encoders:

Absolute and Incremental Encoders

Types

- Linear Encoders
- Rotary Encoders
- Angle Encoders

Sensing

- Optical
- Magnetic
- Capacitive



Rotary Encoder



Mechanical



Articulated arm paradigm

Problems:

Limited by the size of the articulated arms

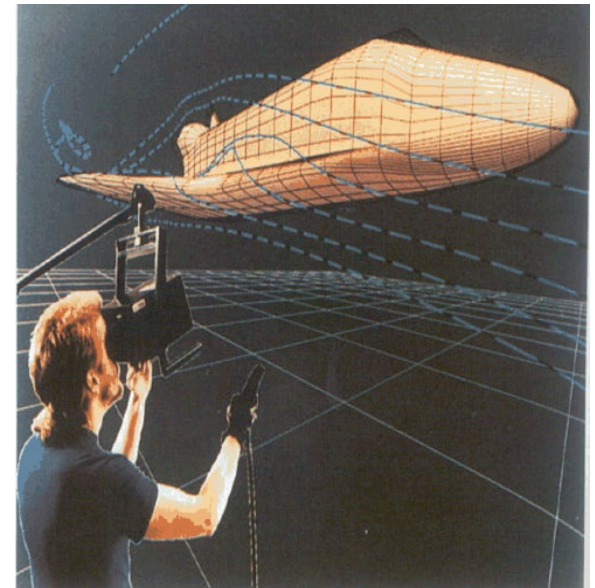
User stuck in the system

Example:

Fake Space Labs BOOM



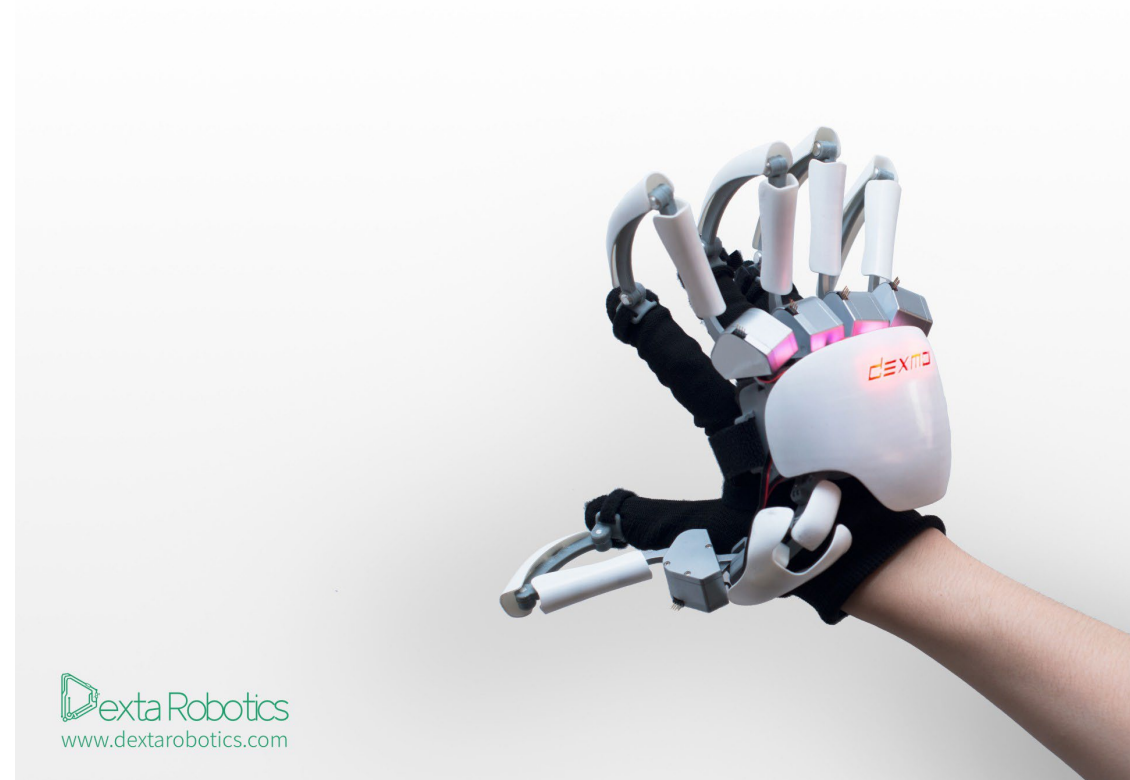
Fakespace Boom



Kind of Mechanical Tracking



Phantom Omni





Electromagnetic



Measures a magnetic field

Problems:

Interference of metallic materials

Example:

Ascension Flock of Birds

Magic Leap

Premo



Magic Leap 1 6DoF
electromagnetic tracking

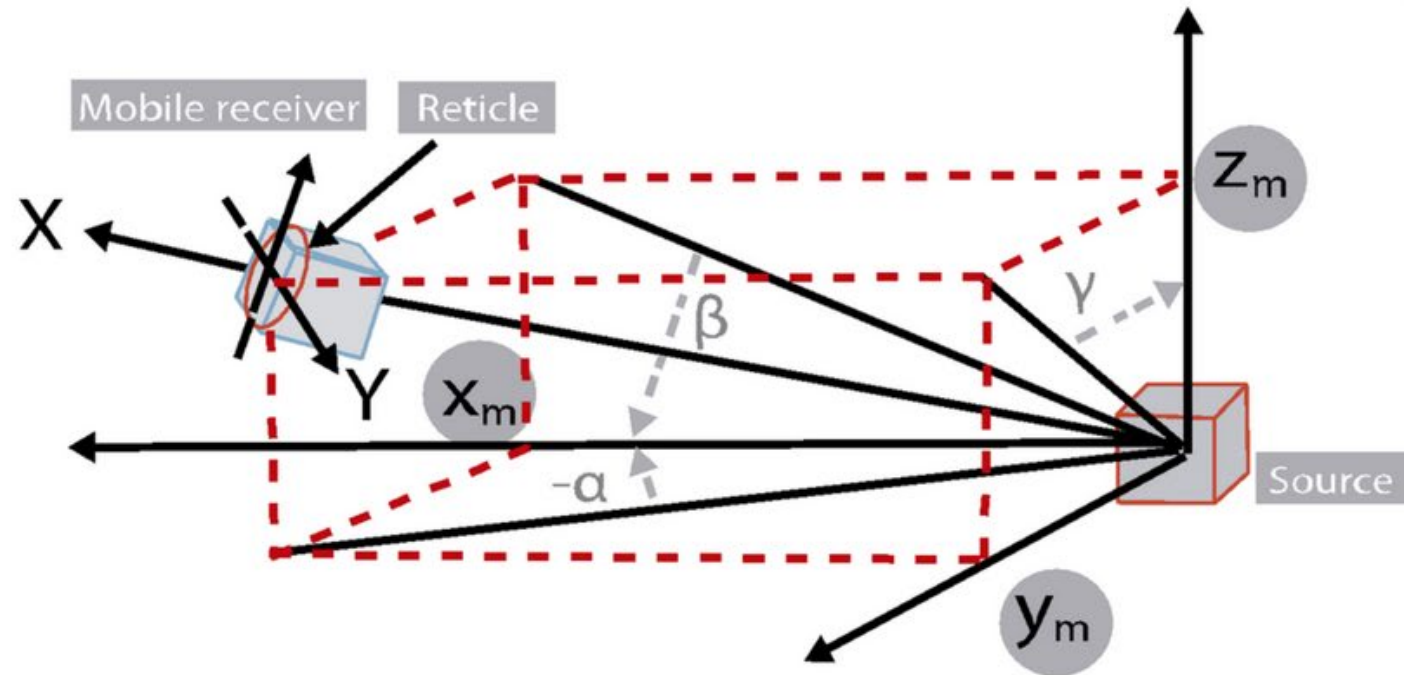


Premo



Ascension Flock of Birds

How Electromagnetic Trackers work



Acoustic



Time-of-flight or wave coherence

Problems:

Accumulation of errors

Low refresh rate and occlusions

Example:

TDK SonicTrack Chip CH-101

Intersense I-900





Inertial



uses gyroscopes and accelerometers
(eventually magnetometers)

Problems:

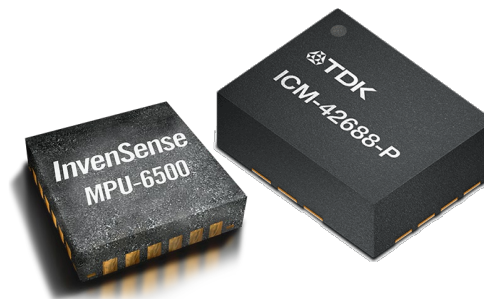
can accumulate errors

Examples:

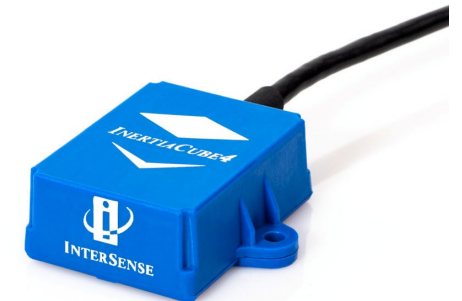
Perception Neuron

MotionNode

Intersense InertiaCube



Inertial Measurement Units
(IMU)



Optic (Outside-in)



Currently most used solution

Problems:

Line of sight, ambient light and infrared radiation problem

Example:

Vicon

ARTrack by A.R.T

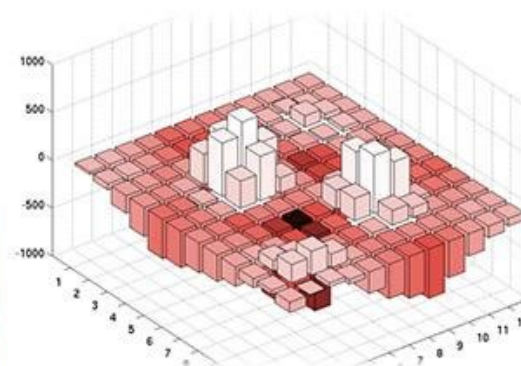
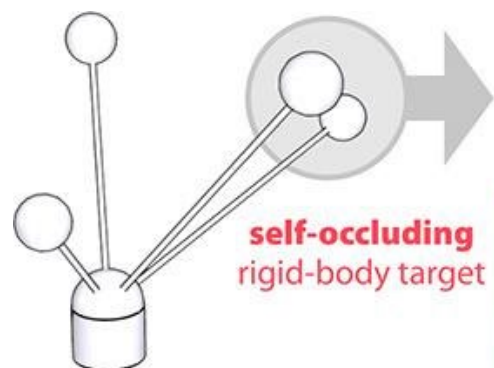
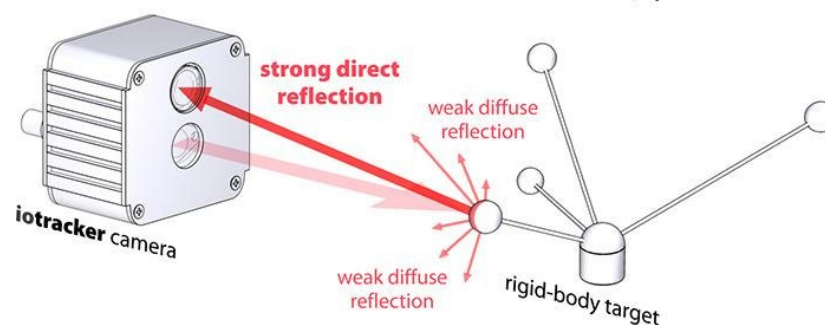
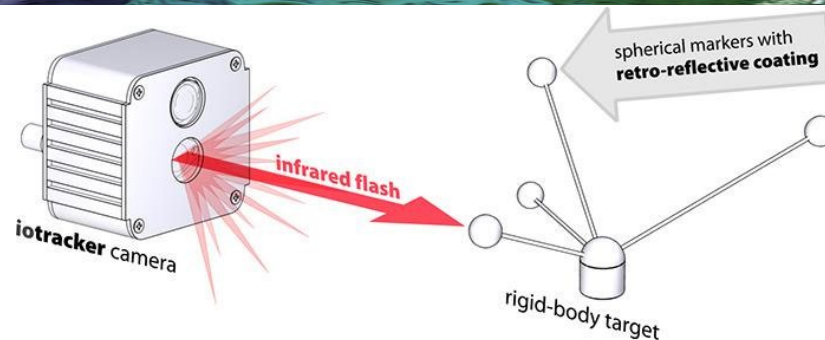




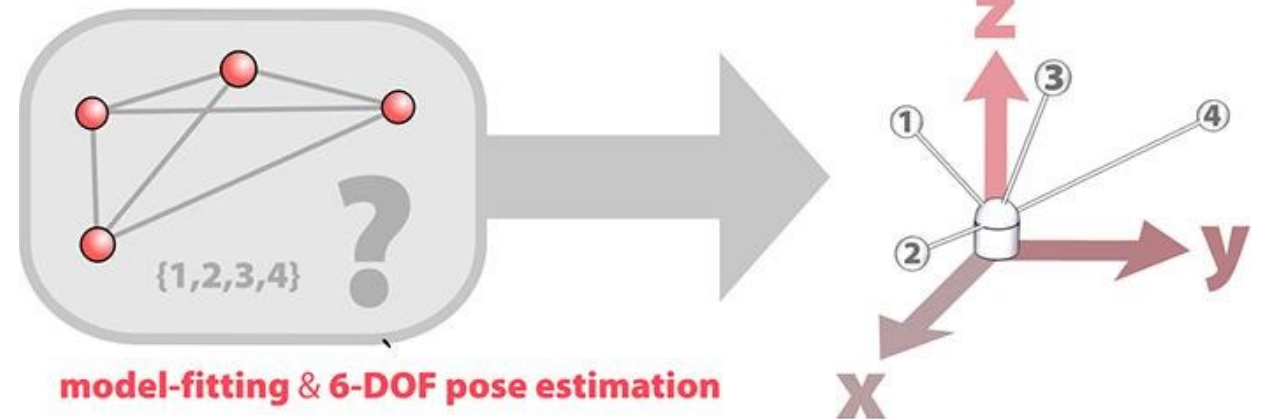
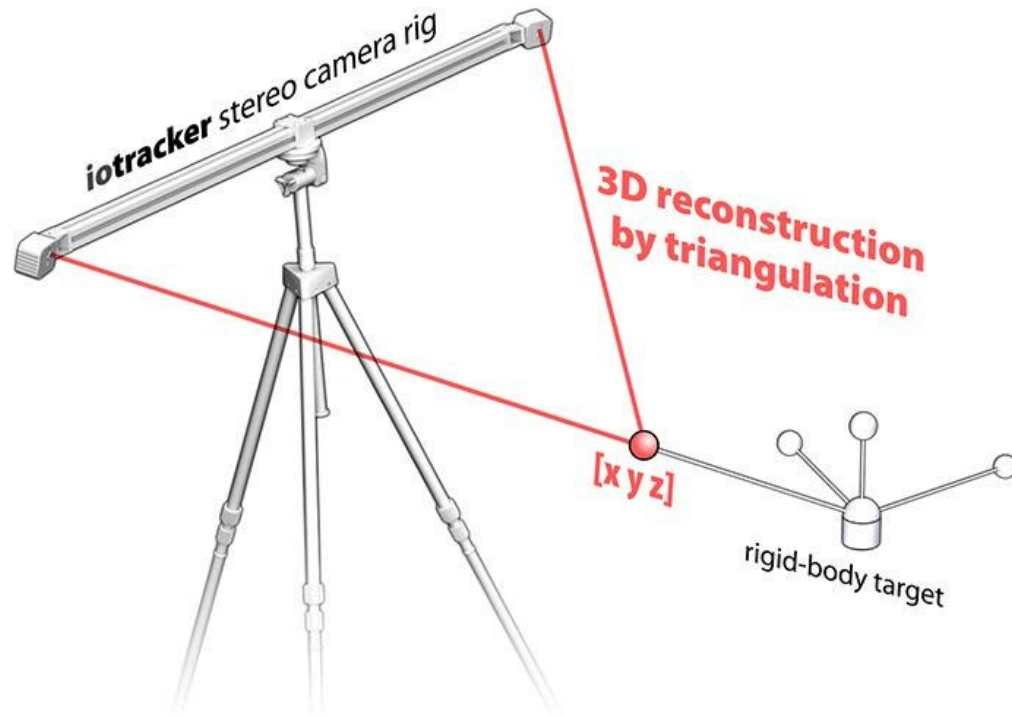
Motion picture industry application



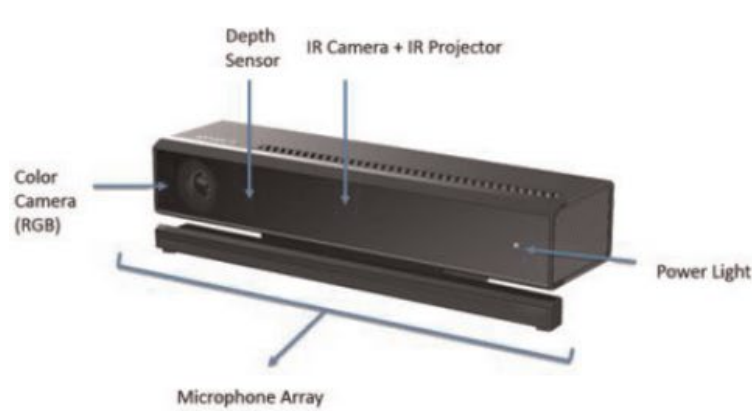
Optical tracking



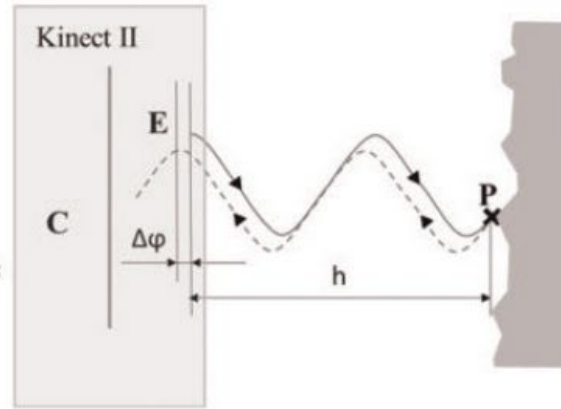
Needs many cameras and spheres



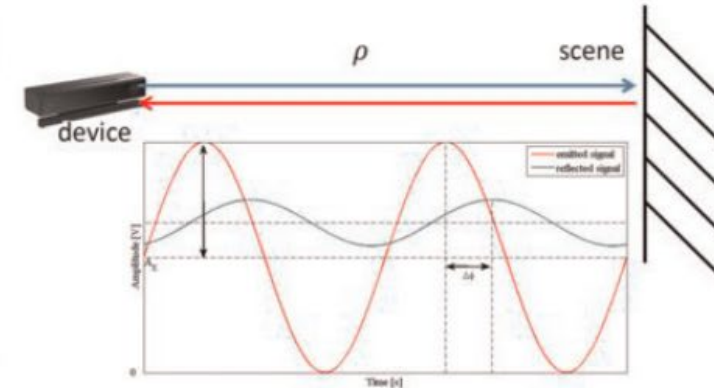
Kinect v2



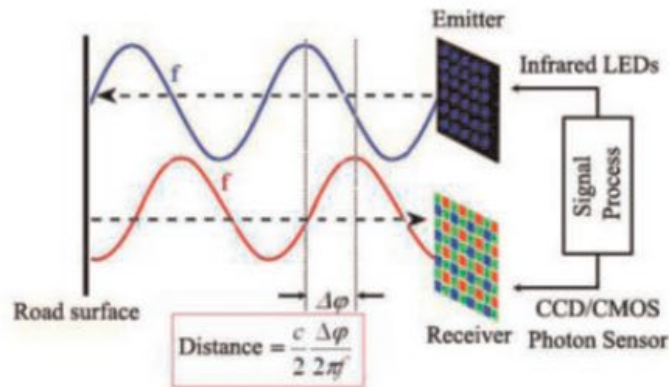
(a)



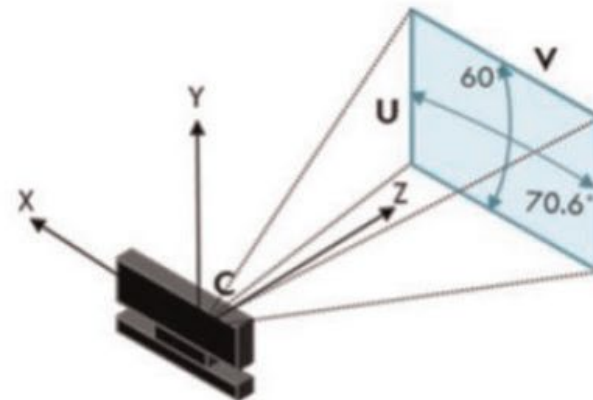
(b)



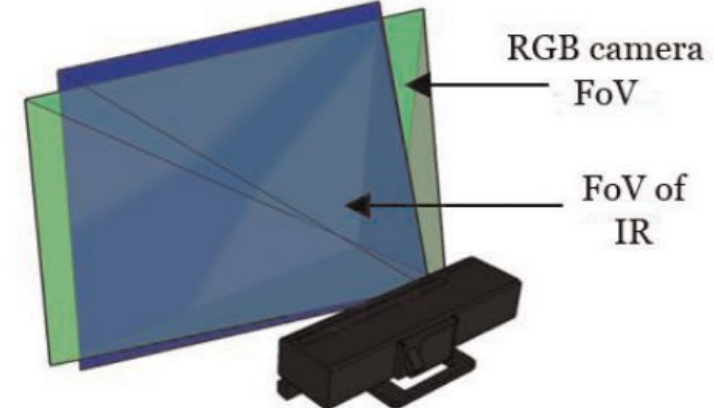
(c)



(d)



(e)



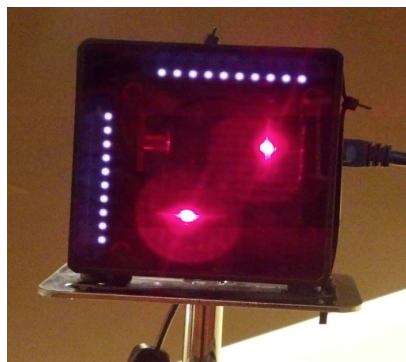
(f)

Ouma, Yashon. (2019). On the Use of Low-Cost RGB-D Sensors for Autonomous Pothole Detection with Spatial Fuzzy c-Means Segmentation. 10.5772/intechopen.88877.

Vive Tracking Sensors

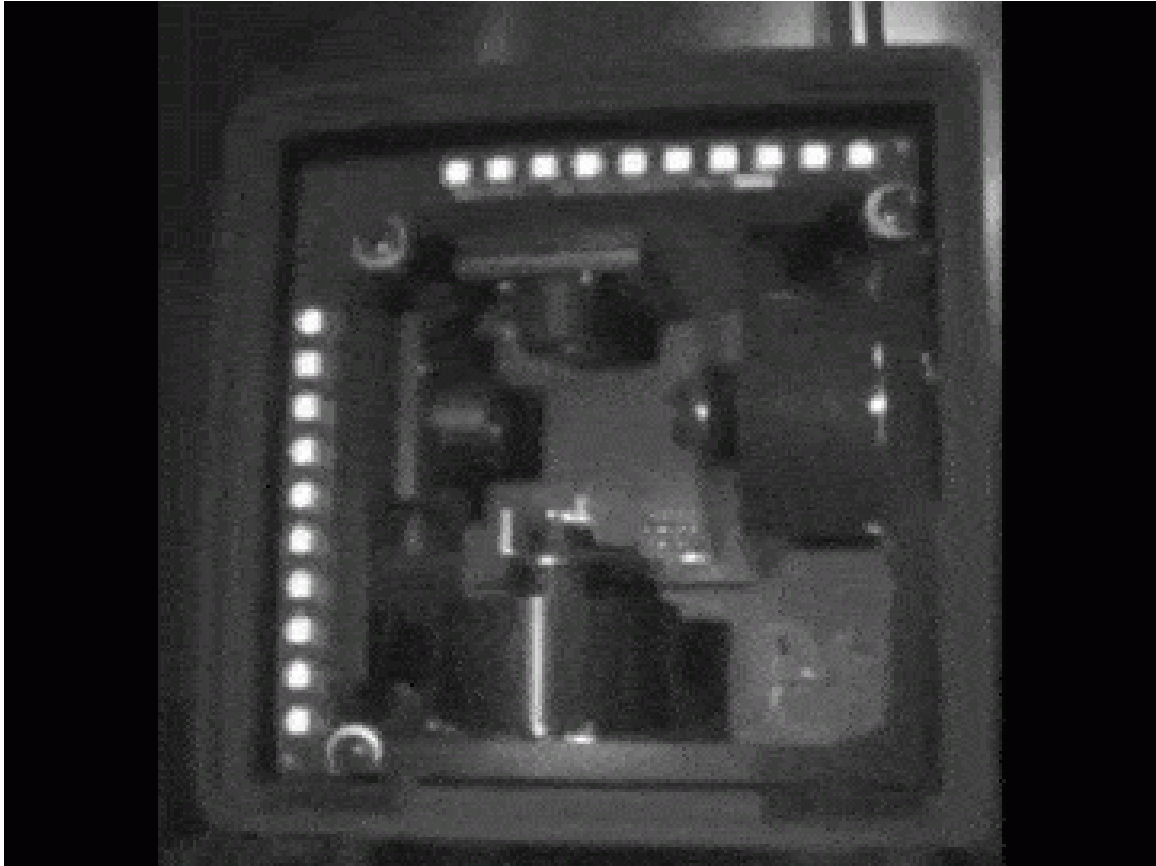
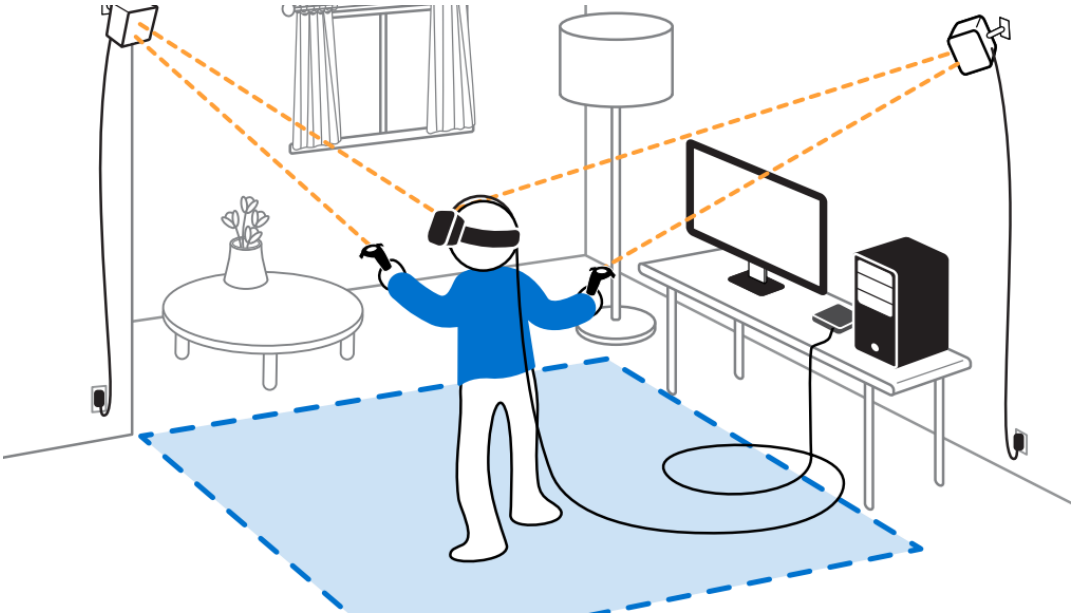


- Position and Orientation
- Good precision
- Depends on Base Stations





Lighthouse in Slowmotion



<https://www.youtube.com/watch?v=5yuUZV7cgd8>



Lighthouse Sweep



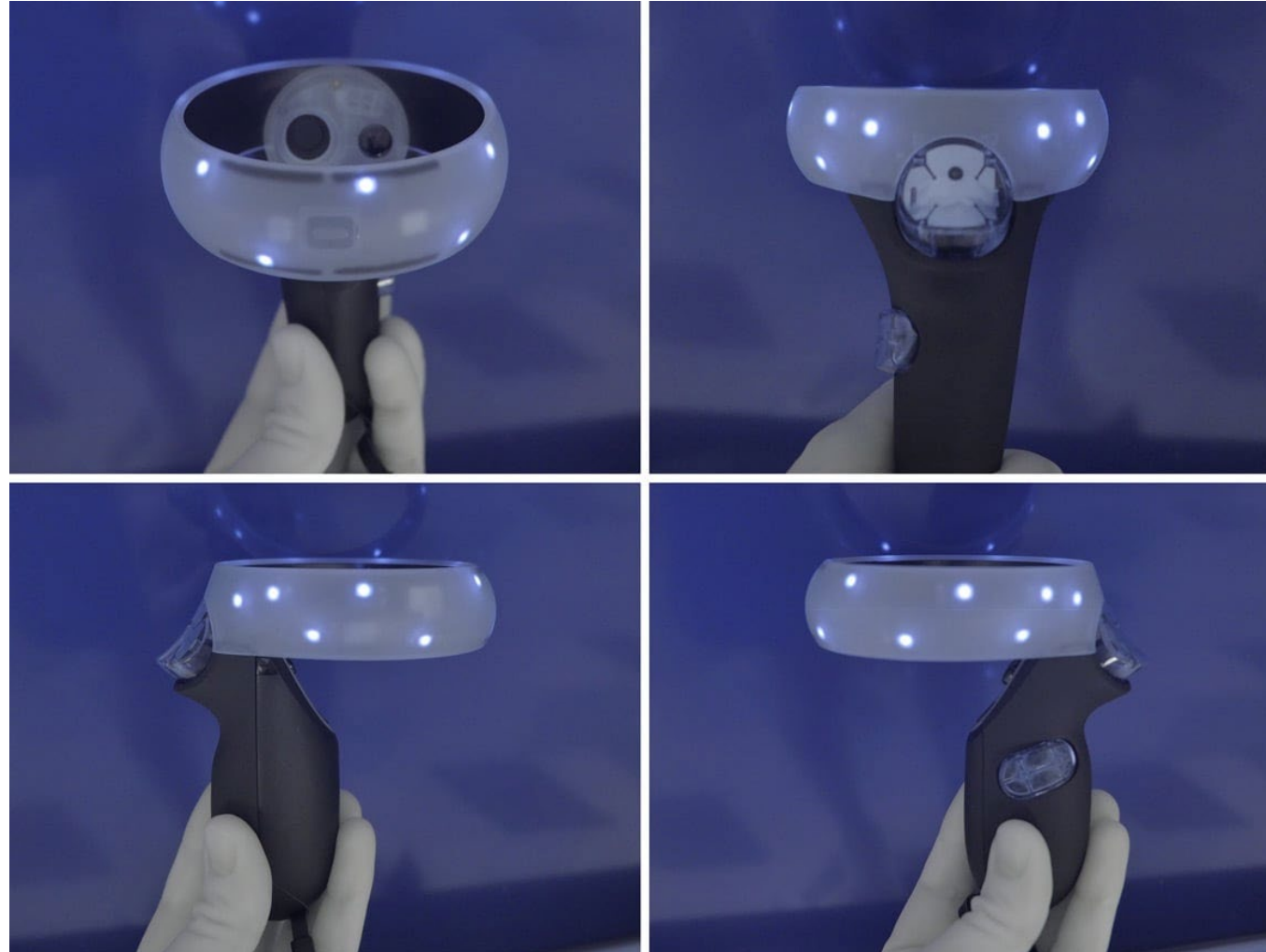
<https://www.youtube.com/watch?v=J54dotTt7k0>

SLAM (Simultaneous Localization and Mapping)



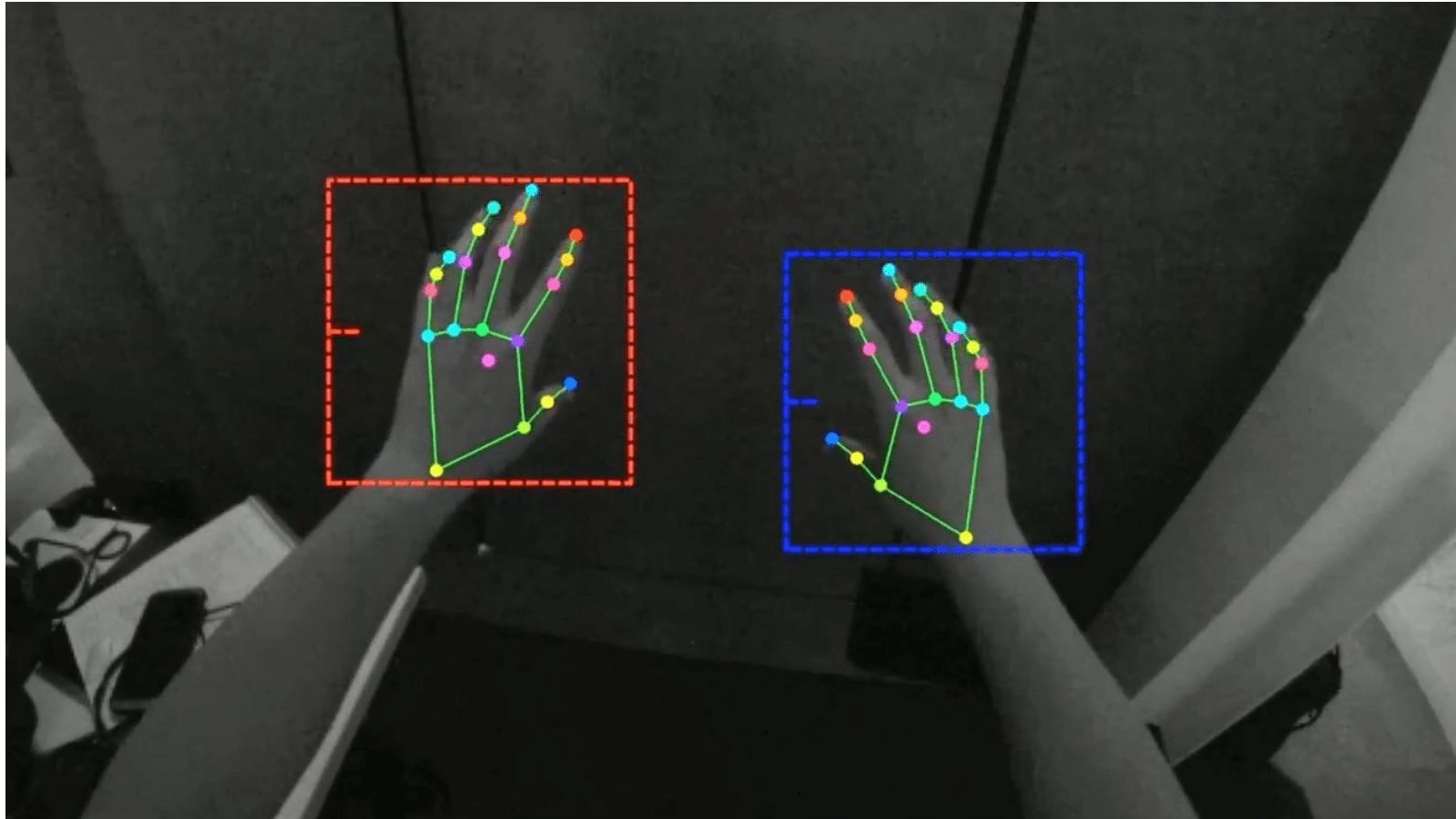
Meta Quest 2

Quest Touch Controllers



https://www.reddit.com/r/OculusQuest/comments/ca28kn/15_tracking_dots_per_touch_controller_seen/

Hand Tracking



<https://www.uploadvr.com/quest-hand-tracking-2-1-fast-movements/>

Other Tracking Systems



There are several technologies for tracking, let's see some of them here.



KatVR



GPS satellite