

### **Game Art**

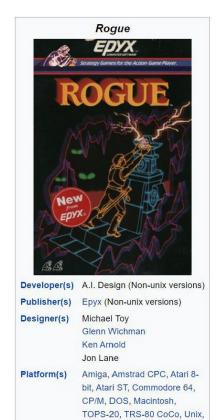
**Simple Maze Generation** 

CS 415: Game Development

**Professor Eric Shaffer** 



# A Very Brief History of Maze Generation in Games



ZX Spectrum

Roquelike

Single-player

Release Genre(s)

Mode(s)

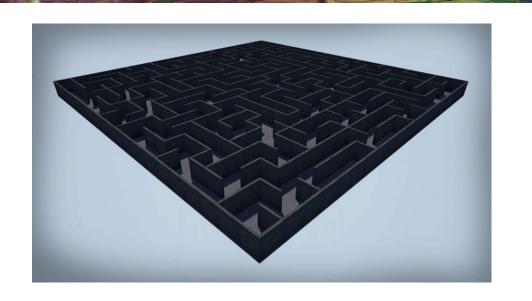
Rogue (also known as Rogue: Exploring the Dungeons of Doom) is a dungeon crawling video game by Michael Toy and Glenn Wichman with later contributions by Ken Arnold. Rogue was originally developed around 1980 for Unix-based mainframe systems as a freely distributed executable. ... Moreover, no game is the same as any previous one, as the dungeon levels, monster encounters, and treasures are procedurally generated for each playthrough.

pieces of gold

-Wikipedia



### Maze Generation in Unreal









- Lots of visual variety is possible...be creative
- 2D that looks 3D would be interesting choice



# Vocabulary

#### A *dungeon* is corridors and rooms

#### A *maze* is set of corridors with no rooms

- Formally, it's a maze only if it includes loops and/or dead ends
- A complicated path that zigzags without branching is *labyrinth*
- In practice...this distinction is usually ignored

https://www.imdb.com > title

Labyrinth (1986) - IMDb

Sixteen-year-old Sarah is given thirteen hours to solve a labyrinth and rescue her baby brother Toby when her wish for him to be taken away is granted by ...

Directors: Jim Henson

\*\*\*\* Rating: 7.3/10 · 137,527 votes



# Depth First Backtracking

Start with a grid of cells; all of them initially unused.

Initially the entrance cell is excavated and this becomes the current cell.

At each iteration a random unused neighbor of the current cell is chosen.

- The current cell is connected to that neighbor
- The neighbor becomes the new current cell.
- If there is no unused neighbor, we return to the previous current cell.



# Depth First Backtracking

When we return to the starting cell, if it has no unused neighbors, then the algorithm is complete

The cells are stored on a stack.

When a neighbor becomes current cell, it is pushed to the top of the stack. If the current cell has no unused neighbors, it is popped from the stack.



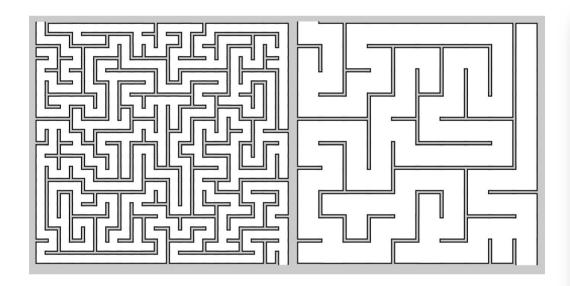
### Exits!

Usually mazes have an exit as well as an entrance

- You pick the exit cell
- The exit appears as a normal unused cell while the algorithm is running
- Algorithm is guaranteed to spread the maze to all reachable locations in the grid
  - Including the exit.



# Examples and Pseudo-Code



```
function maze(level: Level, start: Location):
       # A stack of locations we can branch from.
      locations = [start]
       level.startAt(start)
       while locations:
           current = locations.top()
           # Try to connect to a neighboring location.
           next = level.makeConnection(current)
10
           if next:
11
               # If successful, it will be our next iteration.
12
               locations.push(next)
13
           else:
14
               locations.pop()
15
```



### More Pseudo-Code

```
class Level:
function startAt(location: Location)
function makeConnection(location: Location) -> Location
```

```
class Location:
   x: int
   y: int
class Connections:
   inMaze: bool = false
   directions: bool[4] = [false, false, false, false]
class GridLevel:
   # dx, dy, and index into the Connections.directions array.
   NEIGHBORS = [(1, 0, 0), (0, 1, 1), (0, -1, 2), (-1, 0, 3)]
   width: int
   height: int
   cells: Connections[width][height]
   function startAt(location: Location):
       cells[location.x][location.y].inMaze = true
   function canPlaceCorridor(x: int, y: int, dirn :int) -> bool:
       # Must be in-bounds and not already part of the maze.
       0 \le y \le height and
              not cells[x][y].inMaze
```

```
function makeConnection(location: Location) -> Location:

# Consider neighbors in a random order.
neighbors = shuffle(NEIGHBORS)

x = location.x
y = location.y
for (dx, dy, dirn) in neighbors:

# Check if that location is valid.
nx = x + dx
ny = y + dy
fromDirn = 3 - dirn
if canPlaceCorridor(nx, ny, fromDirn):
```

```
# Perform the connection.

cells[x][y].directions[dirn] = true

cells[nx][ny].inMaze = true

cells[nx][ny].directions[fromDirn] = true

return Location(nx, ny)

# null of the neighbors were valid.

return null
```



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```



### Performance

#### O(n) in execution time

n is the number of cells in the grid

#### O(k) in space

- k is the longest path in the maze
  - usually this is not the route from the goal to the endpoint
  - it is possible that  $k \propto n$ , if the grid is almost a line, it is
  - more common that  $k \propto \log n$ , and performance may be given as  $O(\log n)$  in space.

What data structure determines k? Why is this structure typically not O(n) in size?

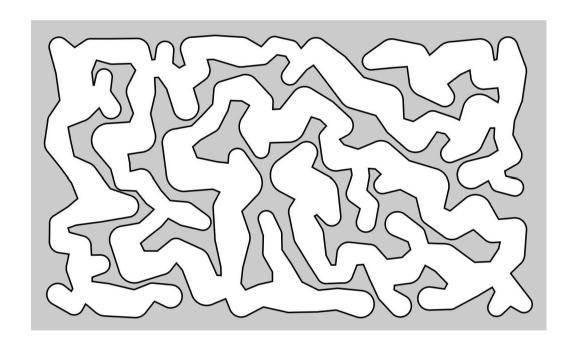


#### Caves

What if we didn't use a grid?

Algorithm still works!

Can move in a random direction in space instead...to generate something like this:





### Pseudo-Code

```
class Location:
    x: float
    y: float
    r: float
    passageFrom: Location = null

class CavesLevel:
    locations: Location[]
    collisionDetector # Checks whether a cave is blocked.

function startAt(location: Location):
    locations.push(location)
    collisionDetector.add(location)

function makeConnection(location: Location) -> Location:
    # Sstart checking in a random direction.
```

Need to handle entrance and exit somehow...maybe find closest caves to randomly picked corners...

```
initialAngle = random() * 2 * pi
17
18
           # The next cave will have a random size.
           nextRadius = randomRange(MIN_RADIUS, MAX_RADIUS)
           offset = r + nextRadius
21
22
           x = location.x
           y = location.y
24
           r = location.r
25
           for i in 0...ITERATIONS:
               # Try to place the next cave.
               theta = 2 * pi * i / ITERATIONS + initialAngle
               tx = x + offset * cos(theta)
               ty = y + offset * sin(theta)
31
32
               # If there is space in the collision detector, add
33
               # it to the list of cave locations.
               candidate = new Location(tx, ty, nextRadius, location)
               if collisionDetector.valid(candidate):
                    collisionDetector.add(candidate)
                   locations.push(candidate)
                    return candidate
           return null
```

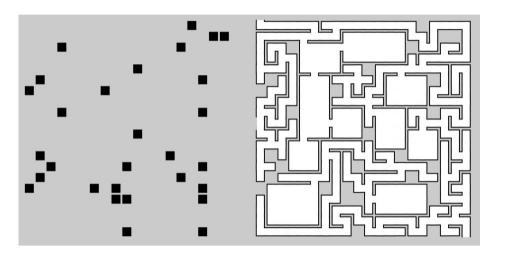


#### Rooms

The algorithm is flexible...initial state can be different

Can start out with areas that

- are unreachable
- contain resources
- add interest to the maze structure



What do the black dots represent?



#### Rooms

Nothing restricts locations to representing sections of corridor.

As long as the level data structure can treat them as a single location

- rooms can be placed
- the maze generated to connect them

The level data structure generalizes to graph instead of a grid...



### Room Pseudo-Code

```
class Room:
width: int
height: int

class GridLevelWithRooms extends GridLevel:
unplacedRooms: Room[]

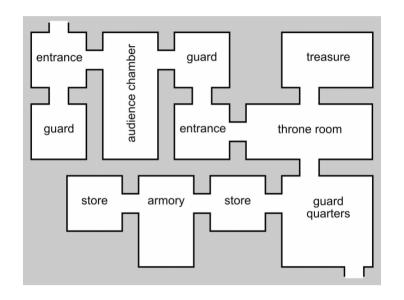
function canPlaceRoom(room: Room, x: int, y: int) -> bool:
inBounds = (
```

```
0 \le x \le (width - room.width) and
               0 <= y < (height - room.height))</pre>
           if not inBounds:
               return false
           for rx in x..(x + room.width):
               for ry in y..(y + room.height):
                   if cells[rx][ry].inMaze:
                       return false
           return true
       function addRoom(room: Room, location: Location):
           for x in location.x..(location.x + room.width):
               for y in location.y..(location.y + room.height):
                   cells[x][y].inMaze = true
                   # If you're using connections to determine where walls
                   # are drawn, then set all connections in the room.
       function makeConnection(location: Location) -> Location:
           # Try to fit a room.
30
           if unplacedRooms and random() < CHANCE_OF_ROOM:
```

```
x = location.x
   y = location.y
   # Choose a room and work out its origin.
   room = unplacedRooms.pop()
   (dx, dy, dirn) = randomChoice(NEIGHBORS)
   nx = x + dx
   ny = y + dy
   if dx < 0: nx -= room.width
   if dy < 0: ny -= room.height
   if canPlaceRoom(room, nx, ny):
       # Fill the room.
       addRoom(room)
       # Perform the connection.
       cells[x][y].directions[dirn] = true
       cells[x + dx][y + dy].directions[3 - dirn] = true
       # Return nothing if rooms aren't part of the main
       # maze. Otherwise you might return the room exit.
       return null
# Otherwise go through the neighbors as before.
return super.makeConnection(location)
```



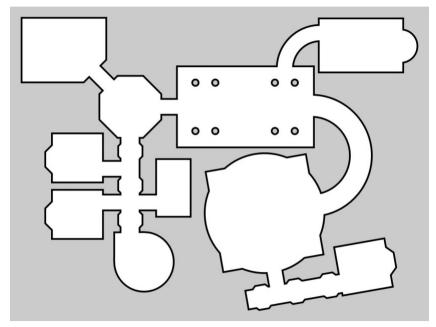
# Only Rooms



Instead of the grid representing square sections of corridor, each location may be a room. The maze then consists of rooms with adjoining doors. This is similar to the dungeons in a game such as the original Zelda



## Pre-fabricated Rooms



There is nothing that requires rooms to be placed on a grid.

If we have a set of prefabricated rooms or corridor sections, each with a list of possible exits, an implementation of the level interface can simply check, for each exit of the current location, whether a room can fit.

