

Rational Curves

CS 418

Interactive Computer Graphics

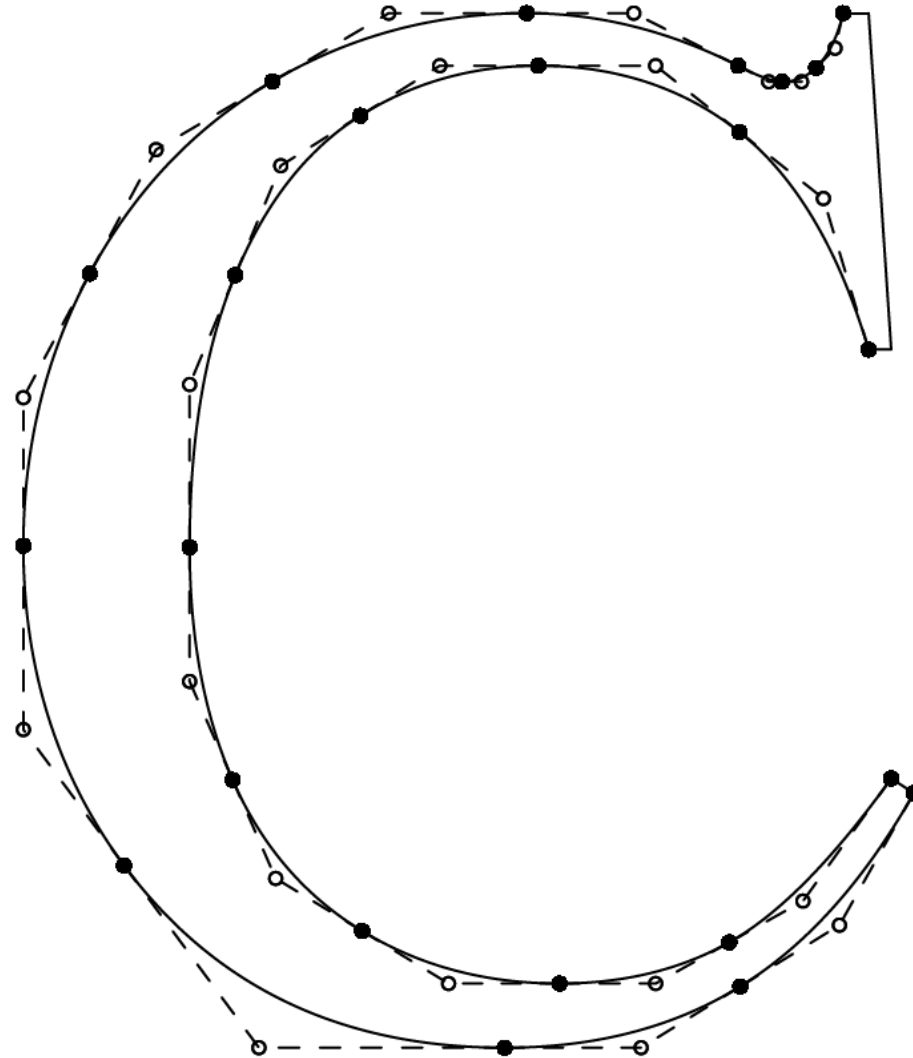
John C. Hart

2-D Quadratic Bezier Curves

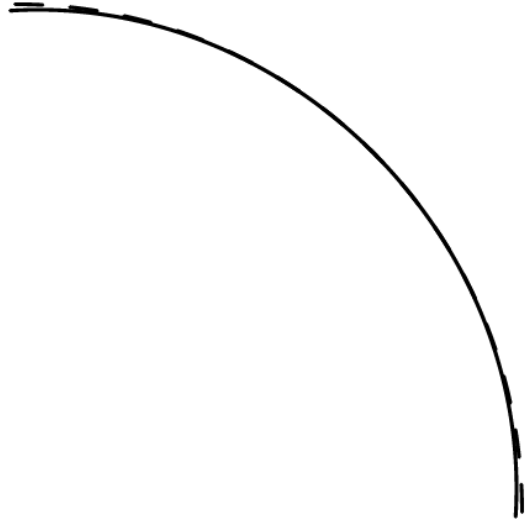
- Three control points

$$\mathbf{p}(t) = (1-t)^2 \mathbf{p}_0 + 2t(1-t) \mathbf{p}_1 + t^2 \mathbf{p}_2$$

- Always planar because of convex hull property and any three points always lie in some plane
- Used for True-Type fonts

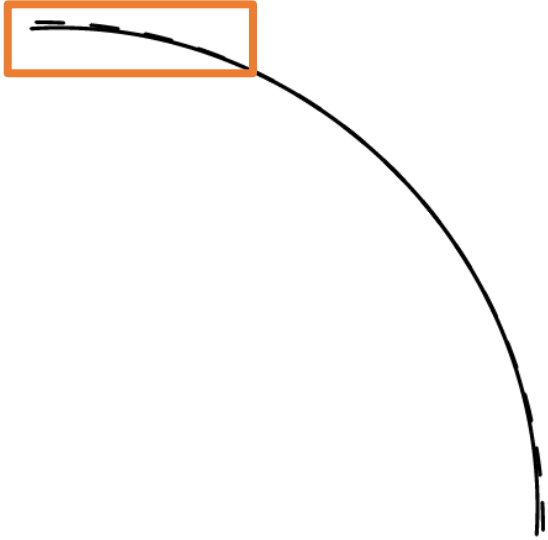


Cubic Arc Approximation

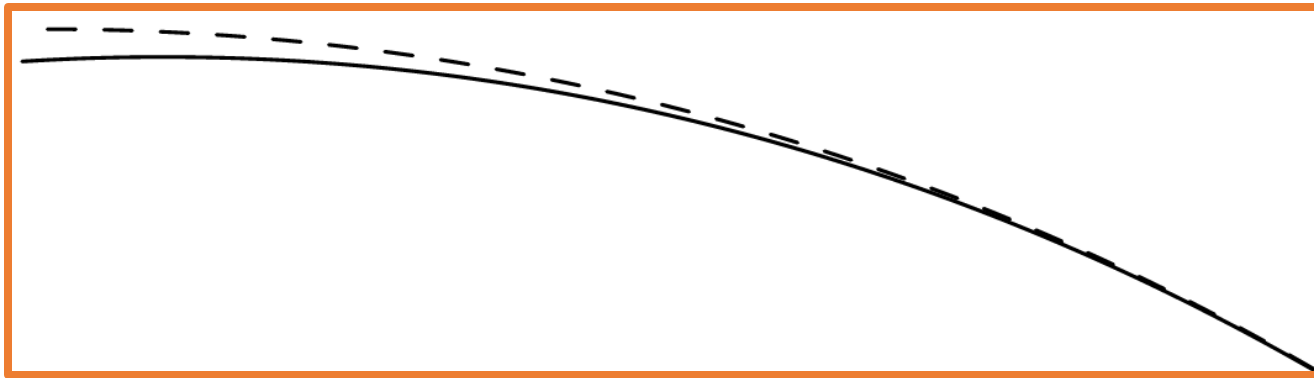


$$\begin{aligned}x(t) &= C - S \left(t - \frac{\pi}{4}\right) - C \frac{\left(t - \frac{\pi}{4}\right)^2}{2} + S \frac{\left(t - \frac{\pi}{4}\right)^3}{6}, \\y(t) &= S + C \left(t - \frac{\pi}{4}\right) - S \frac{\left(t - \frac{\pi}{4}\right)^2}{2} - C \frac{\left(t - \frac{\pi}{4}\right)^3}{6},\end{aligned}$$

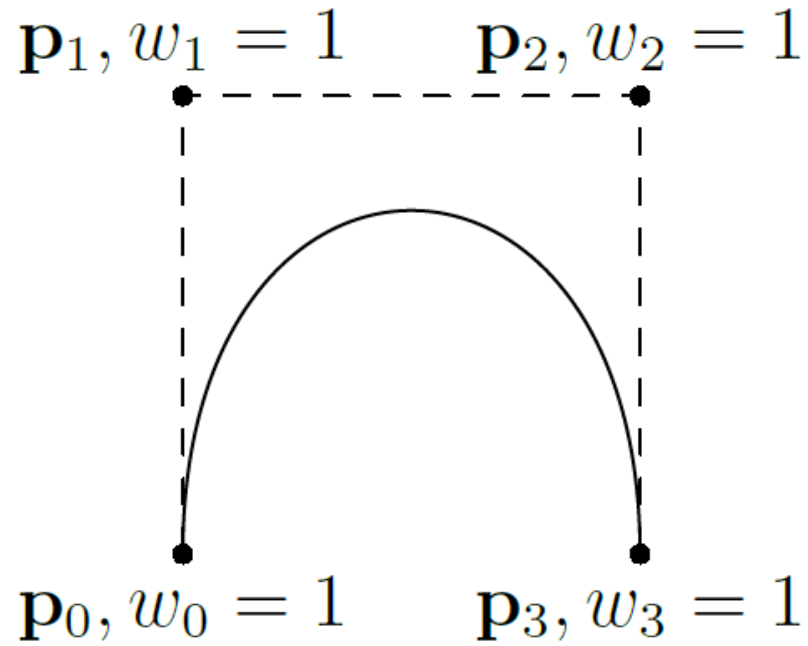
Cubic Arc Approximation



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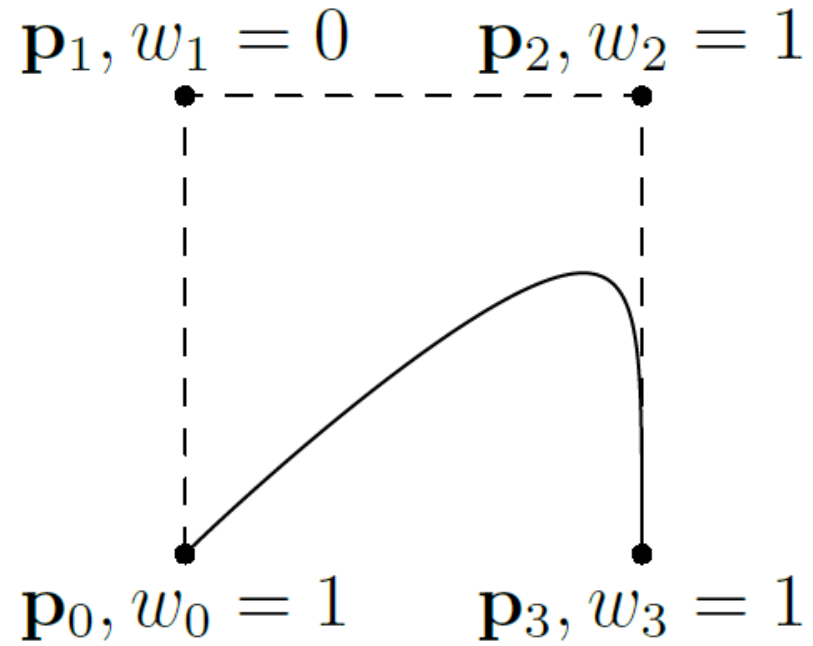


Rational Bezier Curves



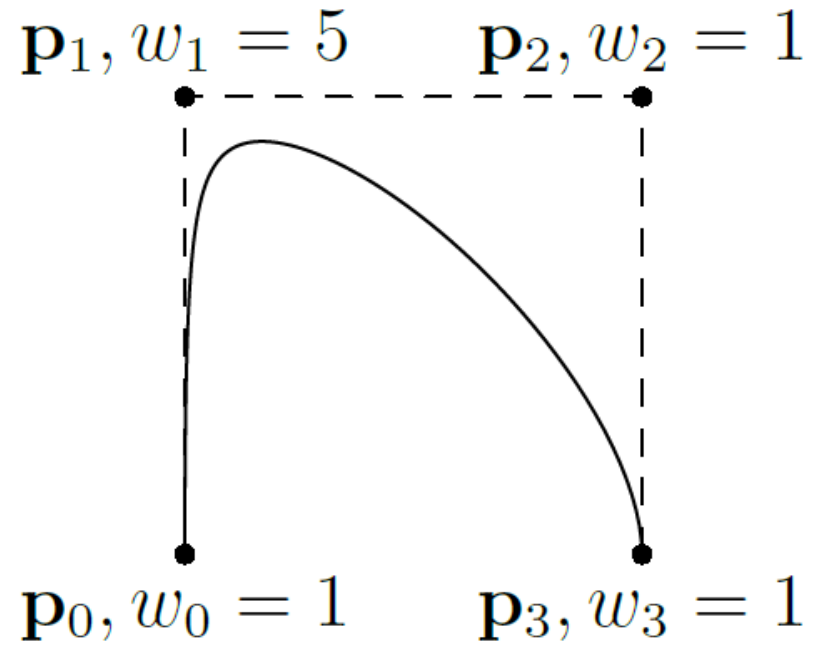
$$\mathbf{p}(t) = \frac{\sum_{i=0}^n w_i B_i^n(t) \mathbf{p}_i}{\sum_{i=0}^n w_i B_i^n(t)},$$

Rational Bezier Curves



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Rational Bezier Curves



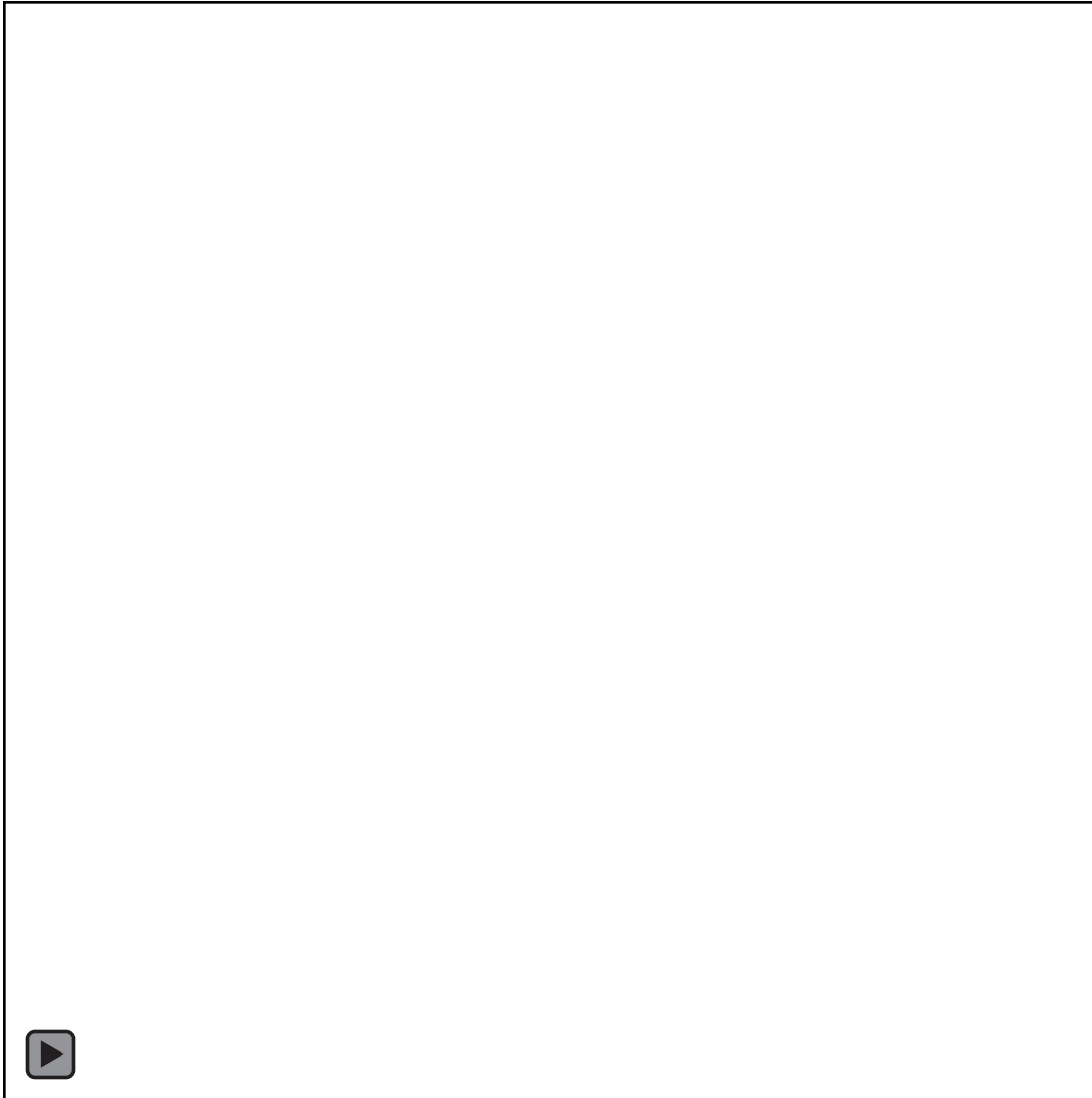
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Homogeneous Control Points

- Think of the control point $\mathbf{p}_i = (x_i, y_i)$ with weight w_i as a homogeneous control point $\mathbf{P}_i = (w_i x_i, w_i y_i, w_i)$
- Then $\mathbf{P}(t) = (w x, w y, w)$ and $\mathbf{p}(t) = \mathbf{P}(t)/w(t)$
- $\mathbf{P}(t)$ is an ordinary 3-D B-spline
- $w(t)$ is the denominator

$$\mathbf{p}(t) = \frac{\sum_{i=0}^n w_i B_i^n(t) \mathbf{p}_i}{\sum_{i=0}^n w_i B_i^n(t)},$$

Homogeneous Control Points



Rational Bezier Arc

