Multinomial and Ordinal Regression Notes

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We now develop modeling for multinomial responses and ordinal categorical responses. These models arise as a natural extension of the generalized linear modeling framework that we have discussed throughout.

Multinomial Response Models

In these notes we will suppose that the response varible Y is categorical, with J possible categories. The response variable can be:

- nominal (for example: your favorite soft drink among Coke, Pepsi, other)
- ordinal (for example: customer rating of service among good, neutral, or bad)

Let categories be coded as 1, ..., J (in order, if ordinal). In these notes we model the distribution of Y in terms of explanatory variables $X_1, ..., X_p$. Let

$$\pi_j(x) = \mathbb{P}(Y \text{ in category } j \mid x), \qquad j = 1, ..., J,$$

where $x \in \mathbb{R}^p$, and note that the multinomial model has the constraint

$$\sum_{j=1}^{J} \pi_j(x) = 1, \quad \text{for any } x.$$

As usual, there are n observations of (Y, x). Assume that observations of Y are independent (conditional on x). Let x_i be the explanatory vector for observation i. The response variable Y may be represented in alternative formats. We could use **ungrouped codes** where $y_i = j, j \in \{1, ..., J\}$, but this is inconvenient for mathematical expressions. We can use **ungrouped indicator vectors**:

$$y_i = (y_{11}, ..., y_{iJ})$$

where

$$y_{ij} = \begin{cases} 1 & \text{if observation } i \text{ in category } j \\ 0 & \text{otherwise,} \end{cases}$$

where $\sum_{j=1}^{J} y_{ij} = 1$ for every i. In this ungrouped indicator vector formulation we have that

$$Y_i \sim \text{Multinomial}(1, \pi(x_i)),$$

where $\pi(x) = (\pi_1(x), \dots, \pi_J(x))$. We can also consider **grouped codes** where we assume observation *i* represents n_i independent responses having the same explanatory vector x_i (i.e., replicates). Let

$$y_i = (y_{11}, \dots, y_{iJ})$$

with y_{ij} defined as the number of responses in category j (for observation i) so that $\sum_{j=1}^{J} y_{ij} = n_i$. Then,

$$Y_i \sim \text{Multinomial}(n_i, \pi(x_i)).$$

Parametric models assume a form for each $\pi_j(x)$ in terms of (vector) parameter θ . The log likelihood for this model is given by

$$l(\theta) \propto \log \prod_{i=1}^{n} \prod_{j=1}^{J} \pi_{j}(x_{i}; \theta)^{y_{ij}}$$

$$= \sum_{i=1}^{n} \left\{ \sum_{j=1}^{J-1} y_{ij}(\alpha_{j} + x_{i}^{T} \beta_{j}) - \log \left[1 + \sum_{j=1}^{J-1} \exp(\alpha_{j} + x_{i}^{T} \beta_{j}) \right] \right\}$$

$$= \sum_{j=1}^{J-1} \left[\alpha_{j} \left(\sum_{i=1}^{n} y_{ij} \right) + \sum_{k=1}^{p} \beta_{jk} \left(\sum_{i=1}^{n} x_{ik} y_{ij} \right) \right]$$

$$- \sum_{i=1}^{n} \log \left[1 + \sum_{j=1}^{J-1} \exp(\alpha_{j} + x_{i}^{T} \beta_{j}) \right]$$

where y_{ij} is from the ungrouped indicator or grouped format, and β_J is a reference category level taken to be 0. From the above derivation we see that the multinomial response model has $\sum_{i=1}^{n} y_{ij}$ as the sufficient statistic for α_j ; this is the total number of outcomes in category j.

Many quantities are as they were for binary/binomial models: MLEs, saturated model, deviances, Wald and likelihood ratio tests and confidence intervals, AIC, G^2 , X^2 . Previously discussed optimization algorithms can be used for parameter estimation.

Nominal responses

We will now consider the baseline-category logistic model for multinomial response data:

$$\log\left(\frac{\pi_j(x)}{\pi_J(x)}\right) = x^T \beta_j, \qquad j = 1, \dots, J - 1.$$

These are the baseline (category) logits, with J as the baseline category. The J-1 values of vectors β_j are unrestricted parameters to be estimated (MLE), where we define $\beta_J = 0$. Logits for other pairs of categories can also be determined. For categories a and b we can write

$$\log\left(\frac{\pi_a(x)}{\pi_b(x)}\right) = \log\left(\frac{\pi_a(x)}{\pi_J(x)}\right) - \log\left(\frac{\pi_b(x)}{\pi_J(x)}\right)$$
$$= x^T \beta_a - x^T \beta_b$$
$$= x^T (\beta_a - \beta_b)$$

Note: Any choice of baseline category leads to a model of the same form (with linearly transformed parameters).

Interpretations

Let x_k be the kth component of x, and let x_{-k} be the vector x with the kth component removed. Also let β_{jk} be the kth component of β_j and let β_{j-k} be the vector β with the kth component removed. Then exponentiation gives

$$\frac{\pi_j(x)}{\pi_J(x)} = e^{x^T \beta_j}$$

as the odds of Y = j conditional on $\{Y = j \text{ or } Y = J\}$. We call it the odds of j relative to J. Then,

$$e^{\beta_{jk}x_k}$$

is the multiplicative change in odds when x_k increases by one with all other components x_{-k} held fixed. The response probabilities are given as

$$\pi_j(x) = \frac{e^{x^T \beta_j}}{\sum_{h=1}^J e^{x^T \beta_h}}$$

where we recall that $\beta_J = 0$. Remark: unlike in the binomial case, $\pi_j(x)$ is not necessarily a monotone function of each component x_k .

Estimation

We consider MLEs $\hat{\beta}_1, \ldots, \hat{\beta}_{J-1}$ when they uniquely exist. When would the MLEs not uniquely exist? Note that the total number of (scalar) free parameters is (J-1)p where p is the number of explanatory variables $(\beta_i \in \mathbb{R}^p)$. Substituting the MLEs gives estimated response functions

$$\hat{\pi}_j(x)$$
, (for all j),

the "fitted values"

$$\hat{\pi}_{ij} = \hat{\pi}_j(x),$$
 (for all i and j),

and the estimated logits, such as

$$\log\left(\frac{\hat{\pi}_j(x)}{\hat{\pi}_J(x)}\right) = x^T \hat{\beta}_j.$$

Sabermetrics example

In the game of baseball it is important to understand how the characteristics of a player's swing translate to positive outcomes on the baseball field. We want to estimate the probabilities of different baseball outcomes given quality of swing and hitting tendency variables (obtained by STATCAST).

The outcomes of interest are: single (1 base), double (2 bases), triple (3 bases), home runs (4 bases), and outs. The more bases the better, 4 bases = 1 run. The team with the most runs wins the game. An out is a bad outcome for a batter, an out means the batter ended their time at the plate without reaching base.

The swing and batting tendency variables are: exit velocity (launch speed off the bat), launch angle (angle off the bat into the air), and spray angle (where on the field the ball is going).



```
library(VGAM) # has model-fitting functions
bball <- read.csv("bball.csv")
bball$events <- as.factor(bball$events)</pre>
```

We now fit two baseline category logistic models (nested), using a function from the VGAM package:

Why are we considering a quadratic term for launch angle?

```
llrts <- deviance(mod1) - deviance(mod2)
llrts.df <- df.residual(mod1) - df.residual(mod2)

llrts; llrts.df</pre>
```

```
## [1] 12213.38
```

```
## [1] 4
```

```
1 - pchisq(llrts, llrts.df)
```

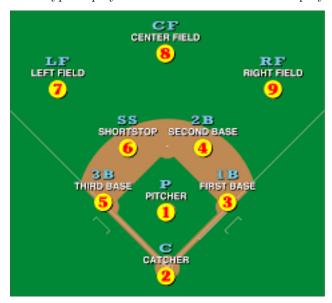
[1] 0

AIC(mod1); AIC(mod2)

[1] 83119.98

[1] 70914.6

What type of polynomial should we consider for spray angle?



```
## user system elapsed
## 8.731 0.722 9.457
```

The polynomial model called mod3 is suppressed in the .Rmd file (echo = FALSE). We see that AIC and the LRT both favor the polynomial model for spray angle.

```
llrts <- deviance(mod2) - deviance(mod3)
llrts.df <- df.residual(mod2) - df.residual(mod3)
1 - pchisq(llrts, llrts.df)</pre>
```

[1] 0

AIC(mod2); AIC(mod3)

[1] 70914.6

[1] 66678.96

We now consider some interaction terms.

```
##
      user
            system elapsed
##
     9.383
             0.647 10.040
llrts <- deviance(mod3) - deviance(mod4)</pre>
llrts.df <- df.residual(mod3) - df.residual(mod4)</pre>
1 - pchisq(llrts, llrts.df)
## [1] 0
AIC(mod3); AIC(mod4)
## [1] 66678.96
## [1] 66325.19
We now obtain summary information for our final model.
system.time(print(summary(mod4)))
##
## Call:
## vglm(formula = events ~ launch_speed + launch_angle + spray_angle +
       I(launch_angle^2) + I(spray_angle^2) + I(spray_angle^3) +
##
##
       I(spray_angle^4) + I(spray_angle^5) + I(spray_angle^6) +
##
       I(spray_angle * launch_angle) + I(spray_angle * launch_speed) +
##
       I(launch_angle * launch_speed), family = multinomial, data = bball)
##
## Coefficients:
##
                                      Estimate Std. Error z value Pr(>|z|)
                                    -1.021e+00 9.570e-02 -10.664 < 2e-16 ***
## (Intercept):1
## (Intercept):2
                                    -8.758e+00 3.668e-01 -23.876 < 2e-16 ***
                                    -9.472e+00 1.349e+00 -7.022 2.19e-12 ***
## (Intercept):3
## (Intercept):4
                                    -8.201e+01 4.605e+00 -17.807 < 2e-16 ***
## launch_speed:1
                                     7.482e-03 1.010e-03
                                                            7.407 1.29e-13 ***
## launch_speed:2
                                     5.941e-02 3.752e-03 15.834
                                                                  < 2e-16 ***
                                                                   0.00243 **
## launch speed:3
                                     4.155e-02 1.370e-02
                                                           3.032
## launch speed:4
                                     4.737e-01 3.957e-02 11.970
                                                                   < 2e-16 ***
## launch_angle:1
                                     4.413e-02 4.475e-03
                                                           9.862
                                                                   < 2e-16 ***
## launch_angle:2
                                    -3.720e-02 1.970e-02 -1.888
                                                                   0.05898
                                    -1.407e-01 6.302e-02
## launch_angle:3
                                                               NA
                                                                        NA
## launch_angle:4
                                     2.102e+00 1.734e-01 12.124
                                                                   < 2e-16 ***
                                    -1.719e-02 3.477e-03 -4.946 7.59e-07 ***
## spray_angle:1
## spray_angle:2
                                    -1.983e-02 8.191e-03 -2.421 0.01549 *
## spray_angle:3
                                     2.235e-02
                                                2.845e-02
                                                            0.786
                                                                   0.43200
                                                            0.439
## spray_angle:4
                                     1.610e-02 3.667e-02
                                                                   0.66069
## I(launch_angle^2):1
                                    -1.432e-03 2.963e-05 -48.335
                                                                   < 2e-16 ***
## I(launch_angle^2):2
                                    -4.206e-03 1.143e-04 -36.779
                                                                   < 2e-16 ***
## I(launch angle^2):3
                                    -4.513e-03 3.618e-04 -12.474
                                                                   < 2e-16 ***
                                    -3.649e-02 1.096e-03 -33.296
## I(launch_angle^2):4
                                                                  < 2e-16 ***
## I(spray_angle^2):1
                                    -1.615e-04 6.331e-05 -2.551 0.01075 *
## I(spray_angle^2):2
                                    -2.376e-03 1.571e-04 -15.121 < 2e-16 ***
## I(spray_angle^2):3
                                    -3.395e-03 4.625e-04 -7.341 2.11e-13 ***
## I(spray_angle^2):4
                                     2.587e-03 2.677e-04
                                                            9.666
                                                                  < 2e-16 ***
## I(spray_angle^3):1
                                    -5.570e-06 1.138e-06 -4.895 9.83e-07 ***
## I(spray_angle^3):2
                                    -4.860e-07
                                                3.545e-06 -0.137
                                                                   0.89096
## I(spray_angle^3):3
                                     1.243e-06 1.438e-05
                                                            0.086
                                                                  0.93112
## I(spray_angle^3):4
                                     5.779e-06 7.238e-06 0.798 0.42460
```

```
## I(spray_angle^4):1
                                     1.736e-08 3.992e-08
                                                             0.435
                                                                    0.66367
                                     2.810e-06
## I(spray_angle^4):2
                                                1.302e-07 21.586
                                                                   < 2e-16 ***
## I(spray_angle^4):3
                                     3.142e-06
                                                4.417e-07
                                                            7.113 1.13e-12 ***
## I(spray_angle^4):4
                                    -1.555e-07
                                                2.189e-07
                                                           -0.710
                                                                    0.47759
## I(spray_angle^5):1
                                     5.978e-10
                                                1.939e-10
                                                            3.083
                                                                    0.00205
                                                          -1.391
## I(spray_angle^5):2
                                    -1.497e-09
                                               1.076e-09
                                                                    0.16429
## I(spray_angle^5):3
                                    -3.256e-10
                                                5.290e-09
                                                           -0.062
                                                                    0.95092
                                                           -0.733
## I(spray_angle^5):4
                                    -1.949e-09
                                                2.659e-09
                                                                    0.46360
## I(spray_angle^6):1
                                     2.375e-12
                                                4.872e-12
                                                             0.488
                                                                    0.62590
## I(spray_angle^6):2
                                    -5.001e-10
                                                2.937e-11 -17.028
                                                                    < 2e-16 ***
## I(spray_angle^6):3
                                    -5.583e-10
                                                1.215e-10
                                                           -4.594 4.34e-06
## I(spray_angle^6):4
                                    -5.527e-11
                                                5.019e-11
                                                           -1.101
                                                                   0.27081
## I(spray_angle * launch_angle):1
                                     2.590e-04
                                                2.559e-05
                                                           10.122
                                                                   < 2e-16 ***
## I(spray_angle * launch_angle):2
                                     3.545e-04
                                                5.329e-05
                                                             6.652 2.88e-11 ***
## I(spray_angle * launch_angle):3
                                    -1.617e-04
                                                1.974e-04
                                                           -0.819
                                                                    0.41287
## I(spray_angle * launch_angle):4
                                    -1.786e-04
                                                2.428e-04
                                                           -0.736
                                                                    0.46198
## I(spray_angle * launch_speed):1
                                     2.205e-04
                                                3.502e-05
                                                             6.296 3.06e-10 ***
## I(spray_angle * launch_speed):2
                                     1.172e-04
                                                7.382e-05
                                                             1.587
                                                                    0.11241
## I(spray_angle * launch_speed):3
                                    -6.553e-05
                                                2.623e-04
                                                           -0.250
                                                                    0.80272
## I(spray_angle * launch_speed):4
                                    -2.098e-04
                                                3.153e-04
                                                           -0.665
                                                                    0.50584
## I(launch_angle * launch_speed):1 -3.362e-04
                                                5.187e-05
                                                           -6.482 9.05e-11 ***
## I(launch_angle * launch_speed):2
                                     2.225e-03
                                                2.048e-04
                                                           10.866 < 2e-16 ***
## I(launch_angle * launch_speed):3
                                     3.709e-03
                                                6.498e-04
                                                             5.708 1.15e-08 ***
## I(launch angle * launch speed):4 1.310e-03
                                                1.360e-03
                                                             0.963
                                                                   0.33551
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Names of linear predictors: log(mu[,1]/mu[,5]), log(mu[,2]/mu[,5]),
  log(mu[,3]/mu[,5]), log(mu[,4]/mu[,5])
##
## Residual deviance: 66221.19 on 199948 degrees of freedom
##
  Log-likelihood: -33110.59 on 199948 degrees of freedom
##
## Number of Fisher scoring iterations: 14
##
## Warning: Hauck-Donner effect detected in the following estimate(s):
  '(Intercept):2', '(Intercept):3', '(Intercept):4', 'launch_angle:3', 'I(launch_angle^2):2', 'I(launch_angle
##
##
##
## Reference group is level 5 of the response
##
      user
            system elapsed
   81.019
            4.268 85.353
```

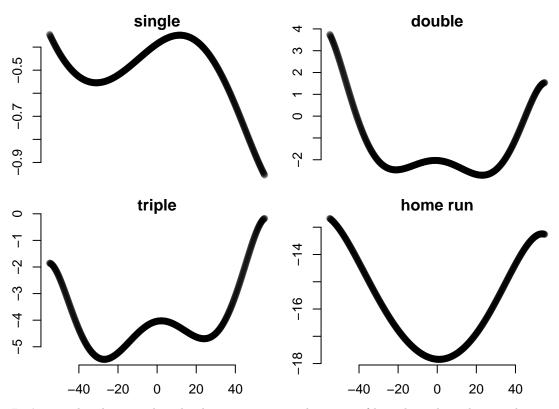
Notice that several terms are dropped from consideration, and the summary table refers to this as a Hauck-Donner effect which is another name for "near-separation" in the multinomial model. Current glmdr software does not yet address separation in the multinomial response model.

Let's now examine what we can do with this flexible final model. We plot the $\log\left(\frac{\hat{\pi}_j(x)}{\hat{\pi}_J(x)}\right)$ as a function of spray angle for each hit outcome where J corresponds to an out. We will set launch angle and exit velocity to their median values.

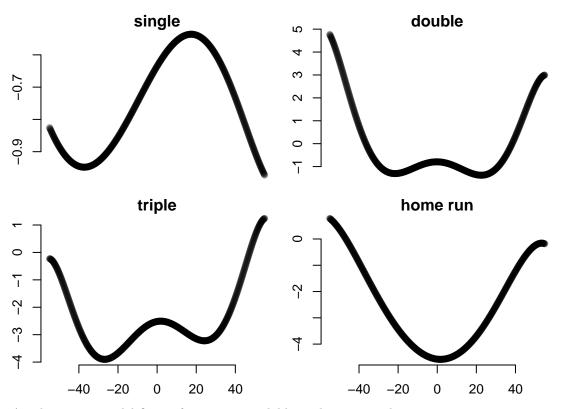
```
summary(bball$spray_angle)
```

```
## Min. 1st Qu. Median Mean 3rd Qu. Max.
```

```
## -89.9156 -23.5685 -0.6636
                                0.2956 24.7655 90.0000
summary(bball$launch_angle)
##
      Min. 1st Qu. Median
                              Mean 3rd Qu.
                                              Max.
            -6.00
                                             89.00
## -89.00
                    12.00
                             12.29
                                     30.00
summary(bball$launch_speed)
##
      Min. 1st Qu. Median
                              Mean 3rd Qu.
                                              Max.
##
      9.40
           80.00
                     90.30
                             88.07
                                     98.80 121.30
## obtain predictions
new_data = data.frame(spray_angle = seq(-55,55, by = 0.1),
           launch_speed = 90.30,
           launch_angle = 12)
pred <- predict(mod4, newdata = new_data)</pre>
par(mfrow = c(2,2), oma = c(4,4,0,0), mar = c(1,2,1,1))
plot.new()
title("single")
plot.window(xlim = c(-55,55), ylim = c(min(pred[, 1]), max(pred[, 1])))
points(new_data$spray_angle, pred[, 1], pch = 19, col = rgb(0,0,0,alpha=0.2))
axis(2)
plot.new()
title("double")
plot.window(xlim = c(-55,55), ylim = c(min(pred[, 2]), max(pred[, 2])))
points(new_data$spray_angle, pred[, 2], pch = 19, col = rgb(0,0,0,alpha=0.2))
axis(2)
plot.new()
title("triple")
plot.window(xlim = c(-55,55), ylim = c(min(pred[, 3]), max(pred[, 3])))
points(new_data$spray_angle, pred[, 3], pch = 19, col = rgb(0,0,0,alpha=0.2))
axis(1)
axis(2)
plot.new()
title("home run")
plot.window(xlim = c(-55,55), ylim = c(min(pred[, 4]), max(pred[, 4])))
points(new_data$spray_angle, pred[, 4], pch = 19, col = rgb(0,0,0,alpha=0.2))
axis(1)
axis(2)
```



Let's consider these predicted values at a new combination of launch angle and exit velocity.



An alternative model fitting function is available in the nnet package:

```
## # weights: 70 (52 variable)
## initial value 80471.895622
## iter 10 value 71115.175486
## iter 20 value 65694.311578
## iter 30 value 58754.075454
## iter 40 value 55973.366379
## iter 40 value 55973.366379
## iter 50 value 52903.873054
## iter 60 value 48282.900567
## iter 70 value 47041.990949
## iter 70 value 47041.990949
## iter 80 value 46612.356353
## iter 90 value 42350.893366
## iter 100 value 41161.169449
## iter 110 value 39638.418181
## iter 120 value 39035.829021
## iter 130 value 38485.011435
## iter 140 value 37740.808989
## iter 150 value 37463.917203
```

```
## iter 160 value 36840.650567
## iter 170 value 36493.551763
## iter 180 value 35782.149057
## iter 190 value 35530.791473
## iter 200 value 35370.728874
## iter 210 value 35226.571426
## iter 220 value 35121.421843
## iter 230 value 35081.384809
## iter 240 value 35020.726417
## iter 250 value 34972.501435
## iter 260 value 34945.988675
## iter 270 value 34926.375444
## iter 280 value 34919.280452
## iter 290 value 34917.335314
## iter 300 value 34908.771298
## iter 310 value 34891.101750
## iter 320 value 34890.065619
## iter 330 value 34885.742128
## iter 340 value 34883.971480
## iter 350 value 34883.333647
## iter 360 value 34867.268410
## iter 370 value 34857.764695
## iter 380 value 34856.510809
## iter 390 value 34853.943645
## iter 390 value 34853.943645
## iter 400 value 34851.416597
## iter 410 value 34850.155614
## iter 420 value 34835.960756
## iter 430 value 34647.082237
## iter 440 value 34631.274175
## iter 450 value 34583.920032
## iter 460 value 34537.209507
## iter 470 value 34525.313146
## iter 480 value 34510.846518
## iter 490 value 34502.484661
## iter 500 value 34470.171829
## iter 510 value 34465.324366
## iter 520 value 34455.917650
## iter 530 value 34454.726360
## iter 540 value 34451.287707
## iter 550 value 34450.967108
## iter 560 value 34449.403679
## iter 570 value 34448.851783
## iter 570 value 34448.851612
## final value 34448.798620
## converged
##
            system elapsed
      user
             0.345
                   49.275
```

Question: Fit the nnet model and comment on the similarities and differences between the nnet and VGAM fits. Report interesting conclusions using either implementation.

Remarks:

1. This multivariate response model can be represented as a multivariate response GLM, see Section 8.1.5

- in Agresti [2013]. A probit-type model is also possible, see Section 8.1.6 in Agresti [2013]. The (residual) degrees of freedom depends on the data format grouped data with n multinomial observations generally have (J-1)(n-p) degrees of freedom where p is the number of elements in x.
- 2. Note that Gerber and Craig (2020) develop a mixed effects multinomial logistic-normal model for baseball applications. This model accounts for positive and negative correlations between outcomes that the standard multinomial model is not flexible enough to handle. The idea is that a player who hits a lot of home runs tends to hit a lot of doubles. Thus these outcomes are expected to exhibit positive correlation, and the standard multinomial model specifies these correlations as negative.
- 3. The baseball example could also be fit using ordinal responses, see below.
- 4. One may be interested in taking this analysis further and investigating where the ball is likely to go when a specific batter faces a specific pitcher. People at UIUC have done work on this project (note that one student author works at the Houston Astros and the other student author is an intern at the Baltimore Orioles). Fitting a multinomial regression model to estimate outcomes of individual matchups is likely impossible (too many parameters). The SEAM approach instead uses distance based weighting to pool outcomes from similar players in order to perform its estimation. SEAM has its roots in PECOTA and it borrows aesthetics from nonparametric density estimation, model averaging, and synthetic control methodology. One can see that PECOTA performs well when compared to other more refined statistical approaches. A discussion of the reasons for this is beyond the scope of this course, we are already off track as it is.

Ordinal Responses

Let response Y be ordinal, ungrouped, and represented with codes $1, \ldots, J$ in that order. As before $x \in \mathbb{R}^p$. We will now consider conditional probabilities of the form

$$\mathbb{P}(Y \le j \mid x) = \pi_1(x) + \dots + \pi_j(x), \qquad j = 1, \dots, J.$$

The cumulative logits are

$$\operatorname{logit}\left(\mathbb{P}(Y \leq j \mid x)\right) = \operatorname{log}\left(\frac{\mathbb{P}\left(Y \leq j \mid x\right)}{\mathbb{P}\left(Y > j \mid x\right)}\right)$$

for j = 1, ..., J - 1.

We now motivate the **proportional odds model**. Let $x \in \mathbb{R}^p$ that does not include an intercept. Then the model is given by

$$logit (\mathbb{P}(Y \le j \mid x)) = \alpha_j + x^T \beta, \qquad j = 1, \dots, J - 1,$$

where $\alpha_1 \leq \alpha_2 \leq \cdots \leq \alpha_{J-1}$. For each j, this is a logistic regression model, with binary outcome indicating subset $\{1,\ldots,j\}$ versus $\{j+1,\ldots,J\}$. Also, β does not depend on j. Why are there order restriction on the α_j values? For $1 \leq j < J-1$,

$$0 < \mathbb{P}\left(Y \leq j \mid x\right) \leq \mathbb{P}\left(Y \leq j + 1 \mid x\right) < 1,$$

so, since the logit function is an increasing function, we have that

$$0 \le \operatorname{logit} (\mathbb{P}(Y \le j + 1 \mid x)) - \operatorname{logit} (\mathbb{P}(Y \le j \mid x))$$
$$= (\alpha_{j+1} + x^T \beta) - (\alpha_j + x^T \beta)$$
$$= \alpha_{j+1} - \alpha_j,$$

which is true if and only if $\alpha_{j+1} \ge \alpha_j$. The same β is assumed across j indices, otherwise there would exist x for which the probabilities would be in the wrong order. The probabilities $\pi_j(x)$ can be recovered from the cumulative probabilities:

• for
$$j = 1$$
,
$$\pi_1(x) = \mathbb{P}(Y < 1 \mid x),$$

• for 1 < j < J,

$$\pi_{j}(x) = \mathbb{P}\left(Y \leq j \mid x\right) - \mathbb{P}\left(Y \leq j - 1 \mid x\right),\,$$

• for j = J,

$$\pi_J(x) = 1 - \mathbb{P}\left(Y \le J - 1 \mid x\right).$$

We now develop interpretations for the proportional odds models. For some j < J, consider the **cumulative** odds ratio

$$\frac{\operatorname{odds}(Y \le j \mid x_1)}{\operatorname{odds}(Y \le j \mid x_2)},$$

which is the odds ratio for $Y \leq j$ at x_1 versus x_2 . The natural logarithm of the above is

$$\begin{aligned} \operatorname{logit} \left(\mathbb{P}(Y \leq j \mid x_1) \right) - \operatorname{logit} \left(\mathbb{P}(Y \leq j \mid x_2) \right) \\ &= (\alpha_j + x_1^T \beta) - (\alpha_j + x_2^T \beta) \\ &= (x_1 - x_2)^T \beta, \end{aligned}$$

which does not depend on j. When p=1, the log cumulative odds ratio becomes $\beta(x_1-x_2)$ which is proportional to x_1-x_2 , with the same proportionality constant for all j. If $x_1-x_2=1$, the cumulative odds ratio (for any j < J) is e^{β} . Consider the implications when X is binary and J=3:

$$\begin{array}{c|cccc} & & & Y & \\ & 1 & 2 & 3 & \\ X = 1 & \pi_1(1) & \pi_2(1) & \pi_3(1) \\ X = 0 & \pi_1(0) & \pi_2(0) & \pi_3(0) \end{array}$$

where the rows sum to 1. Under the proportional odds model, we must have

$$\frac{\pi_1(1)(\pi_2(0) + \pi_3(0))}{(\pi_2(1) + \pi_3(1))\pi_1(0)} = \frac{(\pi_1(1) + \pi_2(1))\pi_3(0)}{\pi_3(1)(\pi_1(0) + \pi_2(0))}$$

with the common value being e^{β} .

Checking the proportional odds assumptions

One can use a test (eg LRT) of the fitted model versus a more general model that allows a separate β_j for each cumulative logit (j = 1, ..., J - 1). The more general model does not rigidly specify the proportional structure and therefore, allows for non-parallel curves. This leads to possible invalid probabilities. However, it might still fit adequately within the range of the data. See Section 8.2.5 in Agresti [2013].

We can fit the proportional odds model using maximum likelihood estimation via Newton-Raphson or Fisher scoring. The log likelihood for this model is

$$\sum_{i=1}^{n} \sum_{j=1}^{J} y_{ij} \log \left[\frac{\exp(\alpha_j + x_i^T \beta)}{1 + \exp(\alpha_j + x_i^T \beta)} - \frac{\exp(\alpha_{j-1} + x_i^T \beta)}{1 + \exp(\alpha_{j-1} + x_i^T \beta)} \right].$$

Notice that observed and expected information is not the same in this model since it is a noncanonical link model.

R Example: Happiness and Traumatic Events

The following is modified from a social survey:

We first display the first six rows of the data

head(happiness)

```
##
      control trauma happy
## 1
             0
                     0
## 2
             0
                     0
                             1
## 3
             0
                     0
                             1
## 4
             0
                     0
                             1
             0
## 5
                     0
                             1
## 6
             0
                     0
                             1
```

In our notation, the estimates are

Here trauma is a count of the number of traumatic events that the individual faced in the previous year. The variable happiness is an ordinal categorical variable indicating the current happiness level of the individual (1 if very happy, 2 if pretty happy, and 3 if not too happy). The control variable is a binary categorical variable that was deemed important by the researchers who conducted the study (0 if in category A, 1 if in category B). We now fit a proportional odds model (cumulative logit):

```
##
## Call:
## vglm(formula = happy ~ trauma + control, family = propodds(reverse = FALSE),
       data = happiness)
##
##
##
  Coefficients:
##
                 Estimate Std. Error z value Pr(>|z|)
                              0.3382 -1.532 0.12552
## (Intercept):1
                 -0.5181
## (Intercept):2
                   3.4006
                              0.5648
                                       6.021 1.74e-09 ***
## trauma
                  -0.4056
                              0.1809
                                      -2.242 0.02493 *
                  -2.0361
                              0.6911
                                     -2.946 0.00322 **
## control
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Names of linear predictors: logitlink(P[Y<=1]), logitlink(P[Y<=2])
## Residual deviance: 148.407 on 190 degrees of freedom
##
## Log-likelihood: -74.2035 on 190 degrees of freedom
##
  Number of Fisher scoring iterations: 5
##
##
## No Hauck-Donner effect found in any of the estimates
##
##
## Exponentiated coefficients:
##
      trauma
               control
## 0.6665934 0.1305338
```

$$\begin{array}{ll} \hat{\alpha}_1 \approx -0.518 \\ \hat{\alpha}_2 \approx 3.401 \end{array} \qquad \hat{\beta} \approx \left(\begin{array}{c} -0.406 \\ -2.036 \end{array} \right)$$

where

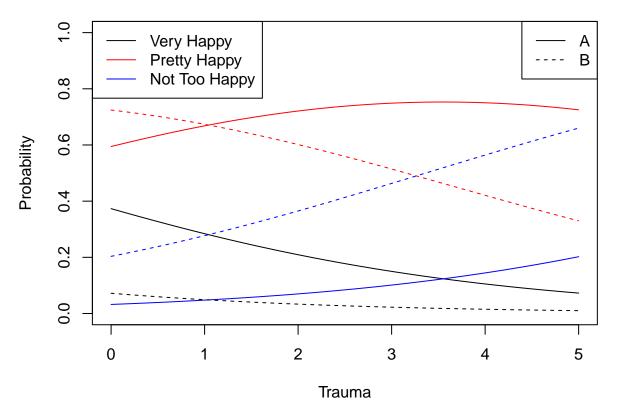
$$x = \begin{pmatrix} \text{trauma} \\ \text{control} \end{pmatrix}$$
.

So happiness is estimated lower (Y is estimated to be larger) as trauma increases. We can estimate the odds of "very happy" for control category A relative to control category B (trauma held fixed), and a Wald 95% confidence interval for these estimates:

[1] 0.002379297

We can also graph probability curves (versus trauma) by happiness category and control:

```
curve(predict(mod, data.frame(trauma=x,control=0), type="response")[,1],
      xlab="Trauma", ylab="Probability",
      xlim=range(happiness$trauma), ylim=c(0,1))
curve(predict(mod, data.frame(trauma=x,control=0), type="response")[,2],
      add=TRUE, col="red")
curve(predict(mod, data.frame(trauma=x,control=0), type="response")[,3],
      add=TRUE, col="blue")
curve(predict(mod, data.frame(trauma=x,control=1), type="response")[,1],
      add=TRUE, lty=2)
curve(predict(mod, data.frame(trauma=x,control=1), type="response")[,2],
      add=TRUE, col="red", lty=2)
curve(predict(mod, data.frame(trauma=x,control=1), type="response")[,3],
      add=TRUE, col="blue", lty=2)
legend("topright", c("A", "B"), lty=1:2)
legend("topleft", c("Very Happy","Pretty Happy","Not Too Happy"), lty=1,
      col=c("black","red","blue"))
```



```
##
## Call:
## vglm(formula = happy ~ trauma + control, family = cumulative(parallel = FALSE),
##
       data = happiness)
##
##
  Coefficients:
##
                  Estimate Std. Error z value Pr(>|z|)
## (Intercept):1
                   -0.5661
                               0.3662 -1.546
                                                 0.1221
                                        4.587 4.5e-06 ***
## (Intercept):2
                    3.4837
                               0.7595
## trauma:1
                   -0.3409
                               0.2124 - 1.605
                                                 0.1086
## trauma:2
                   -0.4836
                               0.2752
                                       -1.757
                                                 0.0789 .
## control:1
                  -16.8922
                            1358.1457
                                            NA
                                                     NA
## control:2
                   -1.8467
                               0.7628
                                       -2.421
                                                 0.0155 *
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Names of linear predictors: logitlink(P[Y<=1]), logitlink(P[Y<=2])</pre>
##
## Residual deviance: 146.9951 on 188 degrees of freedom
##
## Log-likelihood: -73.4976 on 188 degrees of freedom
##
## Number of Fisher scoring iterations: 17
##
```

```
## Warning: Hauck-Donner effect detected in the following estimate(s):
  '(Intercept):2', 'control:1'
##
##
## Exponentiated coefficients:
##
       trauma:1
                     trauma:2
                                 control:1
                                               control:2
## 7.111256e-01 6.165865e-01 4.611204e-08 1.577527e-01
Now perform the LRT:
llrts <- deviance(mod) - deviance(modnotprop)</pre>
llrts.df <- df.residual(mod) - df.residual(modnotprop)</pre>
## [1] 1.411892
llrts.df
## [1] 2
1 - pchisq(llrts, llrts.df)
## [1] 0.4936413
Here is an alternative function for fitting proportional odds models:
library(MASS)
mod2 <- polr(factor(happy) ~ trauma + control, data=happiness)</pre>
summary(mod2)
##
## Re-fitting to get Hessian
## polr(formula = factor(happy) ~ trauma + control, data = happiness)
##
## Coefficients:
##
            Value Std. Error t value
## trauma 0.4056
                       0.1830
                                2.216
## control 2.0361
                       0.6859
                                2.968
##
## Intercepts:
##
       Value
               Std. Error t value
## 1|2 -0.5181 0.3400
                           -1.5238
## 2|3 3.4006 0.5680
                            5.9872
##
## Residual Deviance: 148.407
## AIC: 156.407
```

Note: Signs of coefficients (but not intercepts) are different from what was obtained using vglm, because polr uses a different parameterization (See Section 8.2.3 in Agresti [2013]). Comment on the differences between the vglm and polr implementations.

Remark: If you change the direction of the Y ordering (i.e., label in the reverse order), this will change the signs of the α_i values and of β , and rearrange the α_i values (to keep them ordered least to greatest). Other than that, the model will be equivalent: the direction of the Y ordering doesn't fundamentally change the class of models being fit.

More about ordinal responses

Let ungrouped response Y be ordinal, with ordered codes $1, \ldots, J$ and let $x \in \mathbb{R}^p$ be an explanatory variable without an intercept element. Besides proportional odds, what other models are available?

Latent variable formulation

Suppose that Y derives from a latent continuous variable Y^* . The real line is divided into J successive segments (with unknown boundaries), and Y indicates which one contains Y^* . With this formulation we have that

$$Y = j$$
 if $\alpha_{j-1} < Y^* \le \alpha_j$,

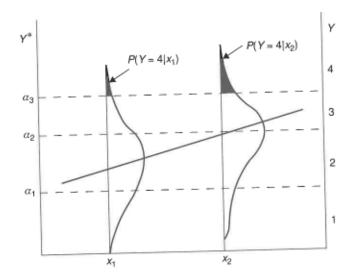
where the cutpoints (or thresholds) are

$$-\infty = \alpha_0 < \alpha_1 \le \dots \le \alpha_{J-1} < \alpha_J = \infty.$$

The interior cutpoints $\alpha_1, \ldots, \alpha_{J-1}$ are unknown. Suppose that Y^* satisfies a no-intercept linear regression

$$Y^* = x^T \beta + \varepsilon,$$

where the error term ε has known cumulative density function G (usually with mean zero), assumed to be continuous and invertible. (Alternatively, we could add an intercept, but then fix one of the cutpoints, e.g., set $\alpha_1 = 0$). See the figure below for intuition for a single variable X, and $\beta > 0$,



Note:

• In this parameterization, if an element of β is positive, its X variable is positively related to Y (all else held constant):

 $\beta_k > 0$: X_k larger $\Longrightarrow Y$ tends larger $\beta_k < 0$: X_k larger $\Longrightarrow Y$ tends smaller

• Assuming the latent variables Y^* are independent (conditionally on the given X values), the observations Y are independent.

For j < J,

$$\mathbb{P}(Y \le j \mid x) = \mathbb{P}(Y^* \le \alpha_j \mid x)$$

$$= \mathbb{P}(Y^* - x^T \beta \le \alpha_j - x^T \beta \mid x)$$
$$= \mathbb{P}(\varepsilon \le \alpha_j - x^T \beta)$$
$$= G(\alpha_j - x^T \beta).$$

Thus,

$$G^{-1}\left(\mathbb{P}(Y \le j \mid x)\right) = \alpha_j - x^T \beta$$

If G^{-1} is the logit function, the latent model is equivalent to the proportional odds model, except with a different sign for β . The choice $G = \log i t^{-1}$ is the cumulative distribution function of the standard **logistic distribution**. In general, this kind of model may be called a **cumulative link model**. Estimation uses maximum likelihood, and the usual concepts apply: deviances, residuals, Wald, LRT, etc. Other link choices exist such as the cumulative probit model ($G = \Phi = \text{c.d.f.}$ of N(0,1)) and the proportional hazards model with the complementary log-log link $G^{-1}(p) = \log(-\log(1-p))$.

R Example: Happiness and Trauma (Again)

Recall the happiness and traumatic events data:

head(happiness)

```
##
      control trauma happy
## 1
             0
                      0
## 2
             0
                      0
                              1
## 3
             0
                      0
             0
                      0
## 4
                              1
## 5
             0
                      0
                              1
             0
                      0
## 6
                              1
```

Here trauma is a count of the number of traumatic events that the individual faced in the previous year. The variable happiness is an ordinal categorical variable indicating the current happiness level of the individual (1 if very happy, 2 if pretty happy, and 3 if not too happy). The control variable is a binary categorical variable that was deemed important by the researchers who conducted the study (0 if in category A, 1 if in category B). Another way to fit the proportional odds model, as a cumulative link model:

The logit link is the default cumulative link. Without parallel=TRUE, the β vector would be free to vary with j. It is important to note that the cumulative link model will use $\alpha_j + x^T \beta$ instead of $\alpha_j - x^T \beta$.

summary(mod.logit)

```
##
##
  Call:
   vglm(formula = happy ~ trauma + control, family = cumulative(parallel = TRUE),
##
       data = happiness)
##
##
  Coefficients:
##
                 Estimate Std. Error z value Pr(>|z|)
                                       -1.532 0.12552
   (Intercept):1
                  -0.5181
                               0.3382
   (Intercept):2
                   3.4006
                               0.5648
                                        6.021 1.74e-09 ***
##
                               0.1809
                                               0.02493 *
##
  trauma
                  -0.4056
                                       -2.242
##
  control
                  -2.0361
                               0.6911
                                       -2.946 0.00322 **
##
## Signif. codes:
                   0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
```

```
## Names of linear predictors: logitlink(P[Y<=1]), logitlink(P[Y<=2])
##
## Residual deviance: 148.407 on 190 degrees of freedom
## Log-likelihood: -74.2035 on 190 degrees of freedom
##
## Number of Fisher scoring iterations: 5
##
## No Hauck-Donner effect found in any of the estimates
##
##
## Exponentiated coefficients:
               control
      trauma
## 0.6665934 0.1305338
To fit a cumulative probit model instead, just change the link function. For example:
mod.probit <- vglm(happy ~ trauma + control,</pre>
                    family=cumulative(link="probitlink",parallel=TRUE),
                    data=happiness)
Again, this model will use the form \alpha_i + x^T \beta instead of \alpha_i - x^T \beta.
summary(mod.probit)
##
## Call:
## vglm(formula = happy ~ trauma + control, family = cumulative(link = "probitlink",
       parallel = TRUE), data = happiness)
##
## Coefficients:
                 Estimate Std. Error z value Pr(>|z|)
##
## (Intercept):1 -0.34808
                           0.20015 -1.739 0.08201 .
## (Intercept):2 1.91607
                                        6.774 1.26e-11 ***
                              0.28287
                 -0.22131
                              0.09897 -2.236 0.02535 *
## trauma
                 -1.15712
                              0.37872 -3.055 0.00225 **
## control
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Names of linear predictors: probitlink(P[Y<=1]), probitlink(P[Y<=2])</pre>
##
## Residual deviance: 148.1066 on 190 degrees of freedom
## Log-likelihood: -74.0533 on 190 degrees of freedom
##
## Number of Fisher scoring iterations: 5
## No Hauck-Donner effect found in any of the estimates
##
##
## Exponentiated coefficients:
```

Recall the alternative analysis function polr from the MASS package

trauma

0.8014668 0.3143908

control

```
library(MASS)
mod.logit2 <- polr(factor(happy) ~ trauma + control, data=happiness)</pre>
This implementation uses the logit cumulative link by default. Also, it does use \alpha_i - x^T \beta and not \alpha_i + x^T \beta.
summary(mod.logit2)
##
## Re-fitting to get Hessian
## polr(formula = factor(happy) ~ trauma + control, data = happiness)
##
## Coefficients:
            Value Std. Error t value
## trauma 0.4056
                      0.1830
                                 2.216
## control 2.0361
                      0.6859
                                 2.968
##
## Intercepts:
##
       Value
               Std. Error t value
## 1|2 -0.5181 0.3400
                           -1.5238
## 2|3 3.4006 0.5680
                            5.9872
## Residual Deviance: 148.407
## AIC: 156.407
To use probit cumulative link instead:
mod.probit2 <- polr(factor(happy) ~ trauma + control, data=happiness,</pre>
                     method="probit")
Again, this implementation uses the formulation \alpha_j - x^T \beta.
summary(mod.probit2)
## Re-fitting to get Hessian
## Call:
## polr(formula = factor(happy) ~ trauma + control, data = happiness,
##
       method = "probit")
##
## Coefficients:
            Value Std. Error t value
## trauma 0.2213 0.09816
                               2.255
## control 1.1571
                      0.38205
                               3.029
##
## Intercepts:
       Value
               Std. Error t value
## 1|2 -0.3481 0.1994
                           -1.7456
## 2|3 1.9161 0.2830
                            6.7713
## Residual Deviance: 148.1066
## AIC: 156.1066
```

Acknowledgments

These notes closely follow Trevor Park's slides. We also borrow materials from Agresti [2013].

References

A. Agresti. Categorical Data Analysis. John Wiley & Sons, 2013.