

★ Relation (or not) between R_0 & R_{0PR}

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R_{0PR} : write $\vec{u} = (u_x, u_\phi, u_z)$ (1)

$$(\vec{u} \cdot \nabla \vec{u})_r = u_x \frac{\partial u_x}{\partial r} + \frac{u_\phi}{r} \frac{\partial u_x}{\partial \phi} + u_z \frac{\partial u_x}{\partial z} - \frac{u_\phi^2}{r} \quad (2)$$

$$(\vec{u} \cdot \nabla \vec{u})_z = u_x \frac{\partial u_z}{\partial r} + \frac{u_\phi}{r} \frac{\partial u_z}{\partial \phi} + u_z \frac{\partial u_z}{\partial z} \quad (3)$$

write $\vec{u} = (\bar{u}_x + u'_x, \bar{u}_\phi + u'_\phi, \bar{u}_z + u'_z)$ (4)

with $\bar{u}_\phi = \lambda \Omega^*$ (5)

overbar \rightarrow zonal + temporal mean (6)

$$\Rightarrow \overline{(\vec{u} \cdot \nabla \vec{u})_r} = \bar{u}_x \frac{\partial \bar{u}_x}{\partial r} + \overline{u'_x \frac{\partial \bar{u}_x}{\partial r}} + \bar{\lambda \Omega^*} \frac{\partial \bar{u}_x}{\partial \phi} + \overline{\frac{u'_\phi}{r} \frac{\partial u'_x}{\partial \phi}} + \bar{u}_z \frac{\partial \bar{u}_x}{\partial z} + \overline{u'_z \frac{\partial \bar{u}_x}{\partial z}} - \bar{\lambda \Omega^{*2}} - \overline{\frac{u_\phi'^2}{r}} \quad (7)$$

$$\overline{(\vec{u} \cdot \nabla \vec{u})_z} = \bar{u}_x \frac{\partial \bar{u}_z}{\partial r} + \overline{u'_x \frac{\partial \bar{u}_z}{\partial r}} + \bar{\lambda \Omega^*} \frac{\partial \bar{u}_z}{\partial \phi} + \overline{\frac{u'_\phi}{r} \frac{\partial u'_z}{\partial \phi}} + \bar{u}_z \frac{\partial \bar{u}_z}{\partial z} + \overline{u'_z \frac{\partial \bar{u}_z}{\partial z}} \quad (8)$$

Now,

$\{ \dots \} = \text{"typical value of"}$

$(\bar{u}_x, \bar{u}_z) \Leftrightarrow$ meridional circulation (9)

$(u'_x, u'_\phi, u'_z) \Leftrightarrow$ convection + waves (10)

Might suspect

$$\{ |\bar{u}_x|, |\bar{u}_z| \} \ll \{ |u'_x|, |u'_\phi|, |u'_z| \} \quad (11)$$

(7), (8) $\Rightarrow \overline{(\vec{u} \cdot \nabla \vec{u})_r} \approx -\lambda \Omega^{*2} + \overline{u'_x \cdot \nabla u'_x} - \overline{u_\phi'^2 / r}$ (12)

$\overline{(\vec{u} \cdot \nabla \vec{u})_z} \approx \overline{u'_x \cdot \nabla u'_z}$ (13)

Derive

$$U \equiv \{ |u_r'|, |u_\phi'|, |u_z'| \} = \{ |\vec{u} - \Omega_* \hat{e}_\phi| \} \quad (14)$$

$H =$ "scale of variation in \vec{u}' "

Might suspect $H \gg \lambda$ (ignore $\overline{u_\phi'^2}/\lambda$ in (12)) (15)

$$\text{Then: } \overline{(\vec{u} \cdot \nabla \vec{u})}_m = \underbrace{-\lambda \Omega_*^2 \hat{e}_\lambda}_{\text{magnitudes: } \lambda \Omega_*^2} + \underbrace{(\overline{\vec{u}' \cdot \nabla u_r'}) \hat{e}_\lambda}_{V^2/H} + \underbrace{(\overline{\vec{u}' \cdot \nabla u_z'}) \hat{e}_z}_{V^2/H} \quad (16)$$

$$\text{"m"} = \text{"meridional part"}: \vec{A}_m \equiv A_\lambda \hat{e}_\lambda + A_z \hat{e}_z \quad (17)$$

so define

$$Ro_{6PR} \equiv \frac{V^2}{\lambda H \Omega_*^2} \quad \checkmark \quad (18)$$

Ro: pick rotating frame (Ω_0). Ignore centrifugal force
i.e., ignore $+\lambda \Omega_0^2 \hat{e}_\lambda$ on RHS of momentum equation.

$$\text{Then "all inertial terms"} = -\vec{V} \cdot \nabla \vec{V}^* + 2\Omega_0 \hat{e}_z \times \vec{V} \quad (19)$$

$$\text{where } \vec{V} \equiv \vec{u} - \lambda \Omega_0 \hat{e}_\phi \quad (20)$$

Note: $(\overline{V_\lambda}, \overline{V_z}) = (\overline{u_\lambda}, \overline{u_z}) =$ meridional circulation
is same in both frames (21)

$$\text{compute: } \left[-2\Omega_0 \hat{e}_z \times \vec{V} \right]_m = - \left[2\Omega_0 (\overline{V_\lambda} \hat{e}_\lambda + \overline{V_\phi} \hat{e}_\phi + \overline{V_z} \hat{e}_z) \times \hat{e}_z \right]_m$$

$\hat{e}_\lambda \times \hat{e}_z \perp m$

$$= -2\Omega_0 \overline{V_\phi} \hat{e}_\lambda = -2\lambda \Omega_0 (\Omega_* - \Omega_0) \hat{e}_\lambda \quad (22)$$

$$(\text{since } \overline{V_\phi} = \underbrace{\overline{u_\phi}}_{\lambda \Omega_*} - \lambda \Omega_0 = \lambda (\Omega_* - \Omega_0)) \quad (23)$$

* This term must be evaluated in co-rotating frame. i.e. the $\partial/\partial \phi$ in $\vec{V} \cdot \nabla \vec{V}$ is w.r.t. ϕ in rotating frame.

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Ignoring [meridional circulation]² terms at outset: (3)

$$\begin{aligned} \overline{(\vec{V} \cdot \nabla \vec{V})}_H &= \overline{V_H \frac{\partial V_H}{\partial H} + \frac{V_\phi}{H} \frac{\partial V_H}{\partial \phi} + V_z \frac{\partial V_H}{\partial z} - \frac{V_\phi^2}{H}} \\ &= \overline{V_H' \frac{\partial V_H'}{\partial H}} + \overline{(V_* - \Omega_0) \frac{\partial V_H'}{\partial \phi}} + \overline{V_\phi' \frac{\partial V_H'}{\partial \phi}} + \overline{V_z' \frac{\partial V_H'}{\partial z}} \\ &\quad - \overline{H (\Omega_* - \Omega_0)^2} - \overline{\frac{(V_\phi')^2}{H}} \\ &= -\overline{H (\Omega_* - \Omega_0)^2} + \overline{\vec{V}' \cdot \nabla V_H'} - \overline{V_\phi'^2 / H} \quad (24) \end{aligned}$$

$$\overline{(\vec{V} \cdot \nabla \vec{V})}_z = \overline{\vec{V}' \cdot \nabla V_z'} \quad (\text{convince yourself!}) \quad (25)$$

I can convince myself:

$$\overline{\vec{V}' \cdot \nabla \vec{V}'} = \overline{\vec{u}' \cdot \nabla \vec{u}'} \quad (26)$$

Thus, in rotating frame, (also assume $H \ll d$)

$$[\text{all inertial terms}]_m \approx \underbrace{\left[-2H\Omega_0(\Omega_* - \Omega_0) \right]}_{\text{coriolis}} \hat{e}_H + \underbrace{\left[-H(\Omega_* - \Omega_0)^2 \right]}_{\text{"extra" centrifugal}} \hat{e}_H$$

magnitudes: $2H\Omega_0|\Omega_* - \Omega_0|$ $H|\Omega_* - \Omega_0|^2$

$$+ \overline{(\vec{u}' \cdot \nabla u_H')} \hat{e}_H + \overline{\vec{u}' \cdot \nabla u_z'} \hat{e}_z \quad (27)$$

magnitudes: V^2/H V^2/H

If coriolis force dominates, everything (w/out DR), define:

$$\widetilde{R}_{0DR} \equiv \frac{|\Omega_* - \Omega_0|}{2\Omega_0} = \frac{1}{2} R_{0DR}^* \ll 1 \quad (28)$$

$$R_0 \equiv \frac{V^2}{2H\Omega_0|\Omega_* - \Omega_0|} \ll 1 \quad (29)$$

* As defined in the paper: $R_{0DR} \equiv |\Omega_* - \Omega_0|/\Omega_0$

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It furthermore

(4)

$$V \approx |\overline{V\phi}| = d |\Omega_* - \Omega_0| \quad (30)$$

(technically a separate assumption), then

$$\tilde{R}_{0DR} \approx \frac{V}{2d\Omega_0} \quad (31)$$

$$R_0 \approx \frac{V}{2\Omega_0 H} \quad \checkmark \quad (32)$$

If ω_{DR} is comparable to "extra" centrifugal, then:
(i.e., the Sun, strong DR)

$$\begin{aligned} & -2d\Omega_0(\Omega_* - \Omega_0) - d(\Omega_* - \Omega_0)^2 \\ &= -d[2\Omega_0\Omega_* - 2\Omega_0^2 + \Omega_*^2 - 2\Omega_0\Omega_* + \Omega_0^2] \\ &= -d(\Omega_*^2 - \Omega_0^2) \end{aligned} \quad (33)$$

This is obvious: we must get back everything we had in the inertial frame, except the ignored "frame" centrifugal force. But should we now define

$$\tilde{R}_{0GPR} \equiv \frac{V^2}{dH|\Omega_*^2 - \Omega_0^2|} \quad (34) \quad ???$$

seems weird. Shouldn't have ignored frame centrifugal force to begin with.

Note: in limiting case (weak DR + $V \approx d|\Omega_* - \Omega_0|$):

$$R_{0GPR} \approx \frac{V^2}{dH\Omega_0^2} = \left(\frac{4H}{d}\right) R_0^2 \quad (35)$$

So under no circumstances does $R_{0GPR} = R_0$.

$R_0 \ll 1$ (geostroph) $\Rightarrow R_{0GPR} \ll 1$ (GPR balance)
but not vice versa.