Total Points: / 30 Name: Jeremiah Webb

- Late Day Policy:
 You have 2 late days policy with cost of 20% of the assignment grade. Past that
 the submissions are not accepted
- Turn in an **electronic copy** in PDF format on Canvas
- Show all the calculations and steps
- 1. **Stored Program Computer.** What is a stored program computer? (1 points) A stored program computer stores specific program instructions in a binary number format in a memory device, most likely RAM on the motherboard or registers & cache on the CPU. The idea of a stored program computer was initially introduced by John Von Neumann.
- 2. Processor Performance. What are the two ways that can be used by the processor designers to increase the performance of the microprocessor? (2 points) Physically put memory and processor cache close to the processor. Ensure that memory access is optimized in programs, unnecessary access to memory can cause the processor to slow down. Integrating processor pipelining where the processor can effectively implement instruction level parallelism. A designer can also increase the clock cycle rate or decrease the clock cycle time to increase performance of the microprocessor.
- 3. **Processor Performance.** What are the obstacles that become more significant with the increase in clock and logic density of microprocessor? *Please elaborate each point inorder to get the full credit*. (3 points)

A major obstacle would be power consumption and heat. The power density increases with logic density and the increasing clock speed can increase the amount of heat generation. This can be especially difficult to implement on mobile phones and laptops, for example. Another potential obstacle could be the limitation of memory, if memory does not have speed or storage, the microprocessor may throttle its computations and waste clocks as a result. In addition, the RC delay, the speed at which the physical electrons flow between resistors, and the capacitance of the wires connecting them can cause slowdowns for the CPU. The more wires that interconnect, the increased resistance. The closer the wires are together, the increased capacitance.

4. Moore's Law. Explain Moore's law? (2 points)

HW 1

Gordon Moore predicted that the number of transistors that can be integrated into a single chip would double every two years.

5. **Computer Architecture.** What is Instruction Set Architecture (ISA)? (1 point)

The instruction set architecture is the abstract model that defines how a CPU can be controlled by software. The ISA acts as an interface between the hardware of the computer and the software. It defines the supported data types in programs, the registers that users can program with, how the hardware manages main memory and how the CPU does I/O operations.

6. **Clock time.** If clock frequency is 900MHz, calculate the <u>cycle time</u> (1 point).

$$\frac{1}{frequency \cdot 10^6} = Clock Time$$

$$\left(\frac{1}{900 \cdot 10^6}\right) = 1.111 \text{ nanoseconds}$$

7. **Clock Speed.** A program runs in 15 seconds on Computer A, which has a clock frequency of 600 MHz. We are trying to help a computer designer build a new machine B, that will run this program in 6 seconds. One thing the designer can do is increase the clock frequency which will affect the CPU design causing machine B to require 1.5 times as many clock cycles as machine A for the same program. What clock rate should we tell the computer designer to target?

(4 points)

Computer A:

Program Time: 15 seconds Clock Frequency: 600 MHz

Computer B:

Program Time: 6 seconds

1.5 times as many clock cycles than A

$$\frac{15 \, seconds}{6 \, seconds} = \frac{x}{600 \, MHz + 1.5}$$

 $x = 2250 \, MHz$

The clock rate should be at least 2250 MHz.

- 8. **Performance and CPI.** Assume a typical program has the following instruction type breakdown:
 - a. 30% loads
 - b. 10% stores
 - c. 50% adds
 - d. 8% multiplies
 - e. 2% divides

Assume the current-generation processor has the following instruction latencies:

f. loads: 4 cyclesg. stores: 4 cyclesh. adds: 2 cycles

i. multiplies: 16 cyclesj. divides: 50 cycles

If for the next-generation design you could pick one type of instruction to make twice as fast (half the latency), which instruction type would you pick? Why? (4 points)

Initial instruction latencies:

30 * 4 = 120 cycles Loads

with 2 clock cycles

30 * 2 = 60 cycles Loads (Upgraded)

10 * 4 = 40 cycles Stores

50 * 2 = 100 cycles Adds

8 * 2 = 16 cycles Multiplies

2 * 50 = 100 cycles Divides

The program has a 30% "loads" instruction type and has a latency of 4 clock cycles, the best decision would be to make the loads instruction twice as fast, and reduce it to 2 clock cycles. Using weighted math above we can see that reducing the loads instruction type to 2 cycles, instead of 120 cycles being used, only 60 cycles would be used. This is proportionally greater than any other reduction for other instructions.

- 9. **Amdahl's Law.** A program has 10% divide instructions. All non-divide instructions take one cycle. All divide instructions take 20 cycles. (6 points)
 - a. What is the CPI of this program on this processor?
 - b. What percent of time is spent just doing divides?
 - c. What would the speedup be if we sped up divide by 2x?
 - d. What would the speedup be if we sped up divide by 5x?
 - e. What would the speedup be if we sped up divide by 20x?
 - f. What would the speedup be if divide instructions were infinitely fast (zero cycles)?

a.
$$\frac{(20+90*1)}{100}$$
=1.1 *CPI*

b. If we assume 100 instruction program, it means that 90 instructions are non divide and 10 instructions are divide. The 90 non divide insutrctions take 90 cycles whereas the 10 divide instruction takes 20 cycles. Therefore the percent time is

$$\left(\frac{20 \, amount \, of \, divide \, cycles}{110 \, total \, cycles}\right) * 100=18.18 \%$$

c. If we speed up divide by 2 it means it would only take 10 cycles to complete the divide instructions. So the new cycle would be 100 cycles.

$$\frac{(110\ previous\ cycle)}{100\ new\ cycle} = 110\ \%\ faster\ \text{or}\ \textbf{1.1}\ \text{times}\ \text{faster}$$

d. If we speed up divide by 5, it then means it would only take 4 cycles to complete the divide instructions. So the new amount of cycles would be 94.

$$\frac{(110\ previous\ cycle)}{94\ new\ cycle} = 117\ \%\ faster\ \text{or}\ 1.17\ \text{times}\ \text{faster}$$

e. If we speed up divide by 20, it means that it would only take 1 cycle to complete the divide instructions. So the new amount of cycles would be 91.

$$\frac{(110\ previous\ cycle)}{91\ new\ cycle} = 121\ \%\ faster\ \text{or}\ 1.21\ \text{times}\ \text{faster}.$$

f. If all divide instructions take zero cycles, the new amount of cycles would be 90.

$$\frac{(110\ previous\ cycle)}{90\ new\ cycle} = 122\ \%\ faster\ \text{or}\ 1.22\ \text{times}\ \text{faster}.$$

- 10. **Performance and ISA.** Chip A executes the ARM ISA and has a 2.5Ghz clock frequency. Chip B executes the x86 and has a 3Ghz clock frequency. Assume that on average, programs execute 1.5 times as many ARM instructions than x86 instructions. (6 points)
 - a. For Program P1, Chip A has a CPI of 2 and Chip B has a CPI of 3. Which chip is faster for P1? What is the speedup for Program P1?
 - b. For Program P2, Chip A has a CPI of 1 and Chip B has a CPI of 2. Which chip is faster for P2? What is the speedup for Program P2?
 - c. Assuming that Programs P1 and P2 are equally important workloads for the target market of this chip, which chip is "faster"? Calculate the average speedup.
- a. CPIa = 2 CPIb = 3 Assuming 100 x86 Instructions => 150 ARM

A seconds =
$$\left(\frac{(2 * 150 * 1)}{2.5}\right) * 10^{-9} = 120 * 10^{-9} seconds$$

B seconds =
$$\left(\frac{(2 * 100 * 1)}{3}\right) * 10^{-9} = 100 * 10^{-9} seconds$$

B is faster in this case.

Speed up = 120/100 = 1.2 times

b. CPIa = 1 CPIb = 2

A seconds =
$$\left(\frac{(1 * 150 * 1)}{2.5}\right) * 10^{-9} = 60 * 10^{-9} seconds$$

B seconds =
$$\left(\frac{(2 * 100 * 1)}{3}\right) * 10^{-9} = 66.67 * 10^{-9} seconds$$

A is faster in this case.

Speed up = 66.66/60 = 1.11

c. The average instruction time of Chip B is less than the average time of Chip A, so Chip B will be faster, on average.

Average Instruction Time for A =
$$\frac{1.2 \, ns + .6 \, ns}{2}$$
 = .9 ns

Average Instruction Time for B =
$$\frac{1 \text{ ns} + .66 \text{ ns}}{2}$$
 = .83 ns

Average Speedup =
$$\frac{.9 \, ns}{.83}$$
 = 1.08

11. Bonus Question. Compiler Activity (Bonus: 4 points)

In this exercise, you will compile a couple small pieces of code and compare the assembly code generated. You can use an online tool named "gcc explorer" by Matt Godbolt, to look at the generated assembly code and compare the output with several different configurations. To use this tool, navigate to: http://gcc.godbolt.org.

11.1 Select x86-64 gcc 12.2 for the compiler, clear out compiler options, and copy the following code into the code editor:

```
int testFunction(int* input, int length) {
  int sum = 0;
  for (int i = 0; i < length; ++i) {
    sum += input[i];
  }
  return sum;
}</pre>
```

Copy/paste the assembly output into your solution.

11.2 **x86 vs. ARM Assembly:** Using the same code as the last problem, change the compiler option to ARM gcc 10.3.1 (2021.10 none). Compare the number of instructions with previous x86 compiler output in 11.1. Notice how x86 uses fewer instructions than ARM. What do you think is the reason, explain (Google to learn more about x86 and ARM).

```
x86 Assembly:
testFunction(int*, int):
    push rbp
    mov
          rbp, rsp
          QWORD PTR [rbp-24], rdi
    mov
          DWORD PTR [rbp-28], esi
    mov
          DWORD PTR [rbp-4], 0
    mov
          DWORD PTR [rbp-8], 0
    mov
          .L2
    jmp
.L3:
          eax, DWORD PTR [rbp-8]
    mov
    cdge
         rdx, [0+rax*4]
    lea
         rax, QWORD PTR [rbp-24]
    mov
         rax, rdx
    add
    mov eax, DWORD PTR [rax]
    add
          DWORD PTR [rbp-4], eax
```

```
DWORD PTR [rbp-8], 1
    add
.L2:
    mov
          eax, DWORD PTR [rbp-8]
    cmp eax, DWORD PTR [rbp-28]
    jl .L3
          eax, DWORD PTR [rbp-4]
    mov
    pop
          rbp
    ret
ARM Assembly:
      testFunction(int*, int):
    str fp, [sp, #-4]!
    add fp, sp, #0
    sub sp, sp, #20
    str r0, [fp, #-16]
    str r1, [fp, #-20]
    mov r3, #0
    str r3, [fp, #-8]
    mov r3, #0
    str
         r3, [fp, #-12]
.L3:
    ldr
        r2, [fp, #-12]
    ldr r3, [fp, #-20]
    cmp r2, r3
    bge
          .L2
    ldr r3, [fp, #-12]
    lsl r3, r3, #2
    ldr r2, [fp, #-16]
    add r3, r2, r3
    ldr r3, [r3]
    ldr r2, [fp, #-8]
    add r3, r2, r3
    str r3, [fp, #-8]
    ldr r3, [fp, #-12]
    add r3, r3, #1
    str
        r3, [fp, #-12]
    b
         .L3
.L2:
    ldr r3, [fp, #-8]
    mov r0, r3
          sp, fp, #0
    add
```

Because ARM processors belong to the "Reduced Instruction Set Computing" (RISC) architecture, this specific instruction set architecture splits activities into simple instructions, where a single instruction is executed in one clock cycle. This is in contrast to x86 where those processors follow the "Complex Instruction Set Computing" (CISC) architecture. This architecture follows an instruction set where complex instructions are processed in a single step in multiple clock cycles, this allows the computer to focus more on process efficiency. Furthermore, ARM uses fewer registers to do its processing, while x86 uses more registers to achieve it. ARM, however, takes advantage of this less consumption of registers to achieve very low power consumption and generate less heat. Thus, the instructions will be different amongst the different architectures, even for the same function.