CNN Models on MNIST

Imports

```
In [1]: # Credits: https://github.com/keras-team/keras/blob/master/examples/mnist_cnn.py
    from __future__ import print_function
    import keras
    from keras.datasets import mnist
    from keras.models import Sequential
    from keras.layers import Dense, Dropout, Flatten, BatchNormalization
    from keras.layers import Conv2D, MaxPooling2D
    from keras import backend as K
    import warnings
```

Using TensorFlow backend.

```
In [0]: from matplotlib import pyplot as plt
```

Defining epochs and batch size

```
In [0]: batch_size = 128
num_classes = 10
epochs = 13
```

Pre-processing of Image data

```
In [4]: # input image dimensions
        img rows, img cols = 28, 28
        # the data, split between train and test sets
        (x train, y train), (x test, y test) = mnist.load data()
        if K.image data format() == 'channels first':
            x train = x train.reshape(x train.shape[0], 1, img rows, img cols)
            x test = x test.reshape(x test.shape[0], 1, img rows, img cols)
            input shape = (1, img rows, img cols)
        else:
            x train = x train.reshape(x train.shape[0], img rows, img cols, 1)
            x test = x test.reshape(x test.shape[0], img rows, img cols, 1)
            input shape = (img rows, img cols, 1)
        x train = x train.astype('float32')
        x test = x test.astype('float32')
        x train /= 255
        x test /= 255
        print('x_train shape:', x_train.shape)
        print(x train.shape[0], 'train samples')
        print(x test.shape[0], 'test samples')
        # convert class vectors to binary class matrices
        y train = keras.utils.to categorical(y train, num classes)
        y test = keras.utils.to categorical(y test, num classes)
        print(x train.shape, y train.shape)
        print(x test.shape, y test.shape)
        Downloading data from https://s3.amazonaws.com/img-datasets/mnist.npz (https://s3.amazonaws.com/img-datasets/m
        nist.npz)
        x train shape: (60000, 28, 28, 1)
        60000 train samples
        10000 test samples
        (60000, 28, 28, 1) (60000, 10)
```

Model 1:

(10000, 28, 28, 1) (10000, 10)

Planning Architecture of the network. Want to use (5x5) kernels all over the network without any padding at any stage. So the size of layers changes as follows during the network.

(layer 28x28) --(5x5 kernel)--> (layer 24x24) --(2x2 pooling s-2)--> (layer 12x12) --(5x5 kernel)--> (layer 8x8) --(2x2 pooling s-2)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

(1x28x28) --> (32x24x24) --> (32x12x12) --> (64x8x8) --> (64x4x4) --(Flatten)--> 1024 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
## Building above model
In [5]:
        warnings.filterwarnings('ignore')
        model = Sequential()
        model.add(Conv2D(32, kernel size=(5, 5), activation='relu',
                         input shape=input shape, kernel initializer='he normal'))
        model.add(MaxPooling2D(pool size=(2, 2)))
        model.add(Conv2D(64, (5, 5), activation='relu', kernel initializer='he normal'))
        model.add(MaxPooling2D(pool size=(2, 2)))
        model.add(Dropout(0.25))
        model.add(Flatten())
        model.add(Dense(512, activation='relu', kernel initializer='he normal'))
        model.add(BatchNormalization())
        model.add(Dropout(0.5))
        model.add(Dense(128, activation='relu', kernel initializer='he normal'))
        model.add(BatchNormalization())
        model.add(Dropout(0.5))
        model.add(Dense(num classes, activation='softmax'))
        model.compile(loss=keras.losses.categorical crossentropy,
                      optimizer=keras.optimizers.Adadelta(),
                      metrics=['accuracy'])
        model1 = model
        history1 = model.fit(x train, y train,
                  batch size=batch size,
                  epochs=epochs,
                  verbose=1,
                  validation data=(x test, y test))
        score = model.evaluate(x test, y test, verbose=0)
        print('Test loss:', score[0])
        print('Test accuracy:', score[1])
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The nam e tf.get default graph is deprecated. Please use tf.compat.v1.get default graph instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:541: The na me tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4479: The name tf.truncated normal is deprecated. Please use tf.random.truncated_normal instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow backend.py:4267: The n

ame tf.nn.max pool is deprecated. Please use tf.nn.max pool2d instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:148: The na me tf.placeholder_with_default is deprecated. Please use tf.compat.v1.placeholder_with_default instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3733: calling dropout (from tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.

Instructions for updating:

Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4432: The n ame tf.random uniform is deprecated. Please use tf.random.uniform instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/math_grad.py:1250: add_dispatch_support.<locals>.wrapper (from tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

Train on 60000 samples, validate on 10000 samples

Epoch 1/13

Epoch 2/13

val acc: 0.9852

Epoch 3/13

val_acc: 0.9887

Epoch 4/13

val acc: 0.9894

Epoch 5/13

val acc: 0.9894

Epoch 6/13

val acc: 0.9925

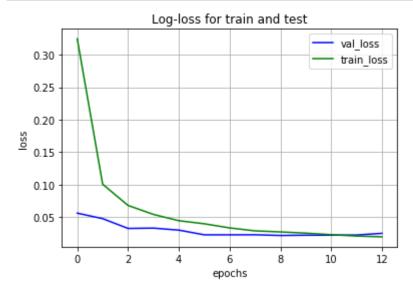
Epoch 7/13

val acc: 0.9931

```
Epoch 8/13
val acc: 0.9934
Epoch 9/13
val acc: 0.9929
Epoch 10/13
val acc: 0.9932
Epoch 11/13
val acc: 0.9932
Epoch 12/13
val_acc: 0.9934
Epoch 13/13
val acc: 0.9936
Test loss: 0.024945586624209228
Test accuracy: 0.9936
```

```
In [6]: val_loss = history1.history['val_loss']
    loss = history1.history['loss']

    plt.plot(val_loss, color='b', label='val_loss')
    plt.plot(loss, color='g', label='train_loss')
    plt.grid()
    plt.legend()
    plt.title('Log-loss for train and test')
    plt.xlabel('epochs')
    plt.ylabel('loss')
    plt.show()
```



This model did pretty good with loss = 0.02494 and accuracy = 99.36 %. And we can train for more epochs (current epochs = 10) as the model is not overfitting yet. Below is summary of the entire model with all layers included (batch normalization and dropouts)

In [7]: model1.summary()

Model: "sequential_1"

Layer (type)	ουτρυτ	Shape	Param #
======================================	(None,	24, 24, 32)	832
max_pooling2d_1 (MaxPooling2	2 (None,	12, 12, 32)	0
conv2d_2 (Conv2D)	(None,	8, 8, 64)	51264
max_pooling2d_2 (MaxPooling2	None,	4, 4, 64)	0
dropout_1 (Dropout)	(None,	4, 4, 64)	0
flatten_1 (Flatten)	(None,	1024)	0
dense_1 (Dense)	(None,	512)	524800
batch_normalization_1 (Batch	None,	512)	2048
dropout_2 (Dropout)	(None,	512)	0
dense_2 (Dense)	(None,	128)	65664
batch_normalization_2 (Batch	None,	128)	512
dropout_3 (Dropout)	(None,	128)	0
dense_3 (Dense)	(None,	10)	1290

Trainable params: 645,130 Non-trainable params: 1,280

Model 2:

Will use only (3x3) kernels in the network without any padding at any stage. The convolution part of the network will be deeper

than previous model. So the size of layers changes as follows during the network.

(layer 28x28) --(3x3 kernel)--> (layer 26x26) --(2x2 pooling s-2)--> (layer 13x13) --(3x3 kernel)--> (layer 11x11) --(2x2 pooling s-1)--> (layer 10x10) --(3x3 kernel)--> (layer 8x8) --(2x2 pooling s-2)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

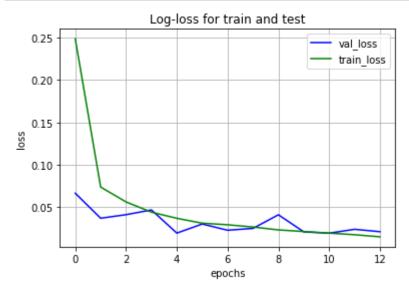
(1x28x28) --> (32x26x26) --> (32x13x13) --> (64x11x11) --> (64x10x10) --> (128x8x8) --> (128x4x4) --(Flatten)--> 2048 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [8]:
        ## Building above model
        warnings.filterwarnings('ignore')
        model = Sequential()
        model.add(Conv2D(32, kernel size=(3, 3), activation='relu',
                         input shape=input shape, kernel initializer='he normal'))
        model.add(MaxPooling2D(pool size=(2, 2)))
        model.add(Conv2D(64, (3, 3), activation='relu', kernel initializer='he normal'))
        model.add(MaxPooling2D(pool size=(2, 2), strides=(1, 1)))
        model.add(Conv2D(128, (3, 3), activation='relu', kernel initializer='he normal'))
        model.add(MaxPooling2D(pool size=(2, 2)))
        model.add(Dropout(0.25))
        model.add(Flatten())
        model.add(Dense(512, activation='relu', kernel initializer='he normal'))
        model.add(BatchNormalization())
        model.add(Dropout(0.5))
        model.add(Dense(128, activation='relu', kernel initializer='he normal'))
        model.add(BatchNormalization())
        model.add(Dropout(0.5))
        model.add(Dense(num classes, activation='softmax'))
        model.compile(loss=keras.losses.categorical crossentropy,
                      optimizer=keras.optimizers.Adadelta(),
                      metrics=['accuracy'])
        model2 = model
        history2 = model.fit(x train, y train,
                  batch size=batch size,
                  epochs=epochs,
                  verbose=1,
                  validation data=(x test, y test))
        score = model.evaluate(x test, y test, verbose=0)
        print('Test loss:', score[0])
        print('Test accuracy:', score[1])
        Train on 60000 samples, validate on 10000 samples
        Epoch 1/13
```

```
- val acc: 0.9885
Epoch 4/13
- val acc: 0.9840
Epoch 5/13
- val acc: 0.9933
Epoch 6/13
- val acc: 0.9902
Epoch 7/13
- val acc: 0.9929
Epoch 8/13
- val acc: 0.9924
Epoch 9/13
- val acc: 0.9903
Epoch 10/13
- val acc: 0.9935
Epoch 11/13
- val acc: 0.9937
Epoch 12/13
- val acc: 0.9929
Epoch 13/13
- val acc: 0.9940
Test loss: 0.021181408596438998
Test accuracy: 0.994
```

```
In [9]: val_loss = history2.history['val_loss']
    loss = history2.history['loss']

    plt.plot(val_loss, color='b', label='val_loss')
    plt.plot(loss, color='g', label='train_loss')
    plt.grid()
    plt.legend()
    plt.title('Log-loss for train and test')
    plt.xlabel('epochs')
    plt.ylabel('loss')
    plt.show()
```



Loss and accuracy are slightly good than the previous model (loss = 0.0212, accuracy = 99.4 %). Not sure we can go for more epochs as validation loss seems to be reducing but not steadily. Have to find out by training more epochs.

In [10]: model2.summary()

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 26, 26, 32)	320
max_pooling2d_3 (MaxPooling2	(None, 13, 13, 32)	0
conv2d_4 (Conv2D)	(None, 11, 11, 64)	18496
max_pooling2d_4 (MaxPooling2	(None, 10, 10, 64)	0
conv2d_5 (Conv2D)	(None, 8, 8, 128)	73856
max_pooling2d_5 (MaxPooling2	(None, 4, 4, 128)	0
dropout_4 (Dropout)	(None, 4, 4, 128)	0
flatten_2 (Flatten)	(None, 2048)	0
dense_4 (Dense)	(None, 512)	1049088
batch_normalization_3 (Batch	(None, 512)	2048
dropout_5 (Dropout)	(None, 512)	0
dense_5 (Dense)	(None, 128)	65664
batch_normalization_4 (Batch	(None, 128)	512
dropout_6 (Dropout)	(None, 128)	0
dense_6 (Dense)	(None, 10)	1290

Total params: 1,211,274
Trainable params: 1,209,994
Non-trainable params: 1,280

Model 3:

Will use only (7x7) kernels in the network without any padding at any stage. The convolution part of the network will be less deeper than previous model. So the size of layers changes as follows during the network.

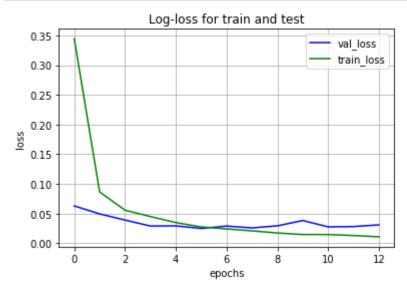
(layer 28x28) --(7x7 kernel)--> (layer 22x22) --(2x2 pooling s-2)--> (layer 11x11) --(7x7 kernel)--> (layer 5x5) --(2x2 pooling s-1)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

(1x28x28) --> (32x22x22) --> (32x11x11) --> (64x5x5) --> (64x4x4) --(Flatten)--> 1024 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [11]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel size=(7, 7), activation='relu',
                           input shape=input shape, kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(64, (7, 7), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2), strides=(1, 1)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(512, activation='relu', kernel_initializer='he_normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                        optimizer=keras.optimizers.Adadelta(),
                        metrics=['accuracy'])
         model3 = model
         history3 = model.fit(x_train, y_train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x test, y test))
         score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
         Train on 60000 samples, validate on 10000 samples
         Epoch 1/13
```

```
Epoch 4/13
val acc: 0.9918
Epoch 5/13
val acc: 0.9919
Epoch 6/13
val acc: 0.9923
Epoch 7/13
val acc: 0.9923
Epoch 8/13
val acc: 0.9930
Epoch 9/13
val acc: 0.9918
Epoch 10/13
val acc: 0.9894
Epoch 11/13
val acc: 0.9927
Epoch 12/13
val acc: 0.9921
Epoch 13/13
val acc: 0.9929
Test loss: 0.03089997356858553
Test accuracy: 0.9929
```



Loss and accuracy are not good compared to previous models (loss = 0.0309 and accuracy = 99.29 %). Validation loss seems to be stagnating compared to train loss which might indicate that furthur epochs may lead to overfitting.

In [13]: model3.summary()

Model: "sequential_3"

Layer (type)	Output	Shape	Param #
conv2d_6 (Conv2D)		22, 22, 32)	1600
max_pooling2d_6 (MaxPooling2	(None,	11, 11, 32)	0
conv2d_7 (Conv2D)	(None,	5, 5, 64)	100416
max_pooling2d_7 (MaxPooling2	(None,	4, 4, 64)	0
dropout_7 (Dropout)	(None,	4, 4, 64)	0
flatten_3 (Flatten)	(None,	1024)	0
dense_7 (Dense)	(None,	512)	524800
batch_normalization_5 (Batch	(None,	512)	2048
dropout_8 (Dropout)	(None,	512)	0
dense_8 (Dense)	(None,	128)	65664
batch_normalization_6 (Batch	(None,	128)	512
dropout_9 (Dropout)	(None,	128)	0
dense_9 (Dense)	(None,	10)	1290
Total params: 696,330	=====:	=========	=======

Total params: 696,330
Trainable params: 695,050
Non-trainable params: 1,280

Model 4:

Let us try models with padding now. (5x5) kernels used with padding (but not for all layers. some layers have (3x3) kernels

without padding). The size of layers changes as follows.

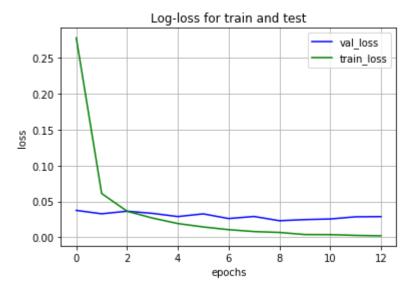
(layer 28x28) --(5x5 kernel)--> (layer 28x28) --(2x2 pooling s-2)--> (layer 14x14) --(5x5 kernel)--> (layer 14x14) --(2x2 pooling s-2)--> (layer 7x7) --(3x3 kernel No Pad)--> (layer 5x5) --(5x5 kernel No Pad)--> (layer 1x1) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

(1x28x28) --> (32x28x28) --> (32x14x14) --> (128x14x14) --> (128x7x7) --> (256x5x5) --> (512x1x1) --(Flatten)--> 512 --> 256 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [14]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel_size=(5, 5), activation='relu', padding='same',
                           input_shape=input_shape, kernel_initializer='he normal'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Conv2D(128, (5, 5), activation='relu', padding='same',
                           kernel initializer='he_normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(256, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(Conv2D(512, (5, 5), activation='relu', kernel initializer='he normal'))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(256, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                        optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model4 = model
         history4 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x_test, y_test))
          score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
```

```
Epoch 3/13
- val acc: 0.9901
Epoch 4/13
- val acc: 0.9904
Epoch 5/13
- val acc: 0.9913
Epoch 6/13
- val acc: 0.9914
Epoch 7/13
- val acc: 0.9937
Epoch 8/13
- val acc: 0.9923
Epoch 9/13
- val acc: 0.9940
Epoch 10/13
- val acc: 0.9937
Epoch 11/13
- val acc: 0.9945
Epoch 12/13
- val acc: 0.9943
Epoch 13/13
- val acc: 0.9937
Test loss: 0.028838168385518566
Test accuracy: 0.9937
```



This model seems to be doing good as accuracy values in some epochs is better than other models but there is some overfit in the model as train loss is lot less than validation loss (train at last epoch = 0.002 which is nearly zero)

In [16]: model4.summary()

Model: "sequential_4"

Layer (type)	Output	Shape	Param #
conv2d_8 (Conv2D)	(None,	28, 28, 32)	832
max_pooling2d_8 (MaxPooling2	(None,	14, 14, 32)	0
conv2d_9 (Conv2D)	(None,	14, 14, 128)	102528
max_pooling2d_9 (MaxPooling2	(None,	7, 7, 128)	0
conv2d_10 (Conv2D)	(None,	5, 5, 256)	295168
conv2d_11 (Conv2D)	(None,	1, 1, 512)	3277312
dropout_10 (Dropout)	(None,	1, 1, 512)	0
flatten_4 (Flatten)	(None,	512)	0
dense_10 (Dense)	(None,	256)	131328
batch_normalization_7 (Batch	(None,	256)	1024
dropout_11 (Dropout)	(None,	256)	0
dense_11 (Dense)	(None,	128)	32896
batch_normalization_8 (Batch	(None,	128)	512
dropout_12 (Dropout)	(None,	128)	0
dense_12 (Dense)	(None,	•	1290
T + 1			

Total params: 3,842,890 Trainable params: 3,842,122 Non-trainable params: 768

Model 5:

Let us try models with padding now. (3x3) kernels used with padding (but not for all layers. some layers dont have padding). The size of layers changes as follows.

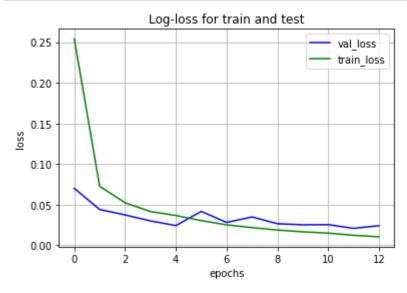
(layer 28x28) --(3x3 kernel)--> (layer 28x28) --(2x2 pooling s-2)--> (layer 14x14) --(3x3 kernel)--> (layer 14x14) --(2x2 pooling s-2)--> (layer 7x7) --(3x3 kernel No Pad)--> (layer 5x5) --(2x2 pooling s-1)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

(1x28x28) --> (32x28x28) --> (32x14x14) --> (64x14x14) --> (64x7x7) --> (128x5x5) --> (128x4x4) --(Flatten)--> 2048 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [17]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel size=(3, 3), activation='relu', padding='same',
                           input_shape=input_shape, kernel_initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(64, (3, 3), activation='relu', padding='same',
                           kernel_initializer='he_normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(128, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2), strides=(1, 1)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(512, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                        optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model5 = model
         history5 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x_test, y_test))
          score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
```

```
Epoch 3/13
- val acc: 0.9892
Epoch 4/13
- val acc: 0.9899
Epoch 5/13
- val acc: 0.9923
Epoch 6/13
- val acc: 0.9878
Epoch 7/13
- val acc: 0.9917
Epoch 8/13
- val acc: 0.9895
Epoch 9/13
- val acc: 0.9920
Epoch 10/13
- val acc: 0.9928
Epoch 11/13
- val acc: 0.9922
Epoch 12/13
- val acc: 0.9944
Epoch 13/13
- val acc: 0.9938
Test loss: 0.024092171756089693
Test accuracy: 0.9938
```



This model is doing good with loss = 0.0241 and accuracy = 99.38 %. And there is not a big overfit problem like previous model. but further epochs may lead to overfitting.

In [19]: model5.summary()

Model: "sequential_5"

Layer (type)	Output Shape	Param #
conv2d_12 (Conv2D)	(None, 28, 28, 32)	320
max_pooling2d_10 (MaxPooling	(None, 14, 14, 32)	0
conv2d_13 (Conv2D)	(None, 14, 14, 64)	18496
max_pooling2d_11 (MaxPooling	(None, 7, 7, 64)	0
conv2d_14 (Conv2D)	(None, 5, 5, 128)	73856
max_pooling2d_12 (MaxPooling	(None, 4, 4, 128)	0
dropout_13 (Dropout)	(None, 4, 4, 128)	0
flatten_5 (Flatten)	(None, 2048)	0
dense_13 (Dense)	(None, 512)	1049088
batch_normalization_9 (Batch	(None, 512)	2048
dropout_14 (Dropout)	(None, 512)	0
dense_14 (Dense)	(None, 128)	65664
batch_normalization_10 (Batc	(None, 128)	512
dropout_15 (Dropout)	(None, 128)	0
dense_15 (Dense)	(None, 10)	1290
Total params: 1,211,274		

Total params: 1,211,274
Trainable params: 1,209,994
Non-trainable params: 1,280

Model 6:

Let us try models with padding now. (7x7) kernels used with padding (but not for all layers. some layers have (3x3) kernels without padding). The size of layers changes as follows.

(layer 28x28) --(7x7 kernel)--> (layer 28x28) --(2x2 pooling s-2)--> (layer 14x14) --(7x7 kernel)--> (layer 14x14) --(2x2 pooling s-2)--> (layer 7x7) --(7x7 kernel No Pad)--> (layer 1x1) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

Channels of CNN and number of hidden layer units changes as follows.

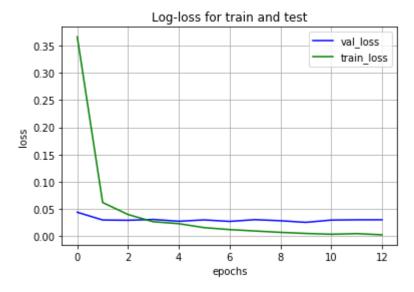
(1x28x28) --> (64x28x28) --> (64x14x14) --> (256x14x14) --> (256x7x7) --> (512x1x1) --(Flatten)--> 512 --> 256 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [20]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(64, kernel_size=(7, 7), activation='relu', padding='same',
                           input_shape=input_shape, kernel_initializer='he normal'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Conv2D(256, (7, 7), activation='relu', padding='same',
                           kernel initializer='he_normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(512, (7, 7), activation='relu', kernel initializer='he normal'))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(256, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                        optimizer=keras.optimizers.Adadelta(),
                        metrics=['accuracy'])
         model6 = model
         history6 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x test, y test))
         score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
         Train on 60000 samples, validate on 10000 samples
         Epoch 1/13
```

```
- val acc: 0.9916
Epoch 4/13
- val acc: 0.9896
Epoch 5/13
- val acc: 0.9925
Epoch 6/13
val acc: 0.9907
Epoch 7/13
- val acc: 0.9925
Epoch 8/13
- val acc: 0.9928
Epoch 9/13
val acc: 0.9938
Epoch 10/13
- val acc: 0.9942
Epoch 11/13
- val acc: 0.9937
Epoch 12/13
- val acc: 0.9933
Epoch 13/13
- val acc: 0.9938
Test loss: 0.029870165106981584
Test accuracy: 0.9938
```

```
In [21]: val_loss = history6.history['val_loss']
    loss = history6.history['loss']

    plt.plot(val_loss, color='b', label='val_loss')
    plt.plot(loss, color='g', label='train_loss')
    plt.grid()
    plt.legend()
    plt.title('Log-loss for train and test')
    plt.xlabel('epochs')
    plt.ylabel('loss')
    plt.show()
```



Accuracy of model is good but the loss is not reducing further. This model is good with fewer epochs which can be used to classify. Further epochs may overfit the model

In [22]: model6.summary()

Model: "sequential_6"

Layer (type)	Output	Shape	Param #
conv2d_15 (Conv2D)		28, 28, 64)	3200
max_pooling2d_13 (MaxPooling	(None,	14, 14, 64)	0
conv2d_16 (Conv2D)	(None,	14, 14, 256)	803072
max_pooling2d_14 (MaxPooling	(None,	7, 7, 256)	0
conv2d_17 (Conv2D)	(None,	1, 1, 512)	6423040
dropout_16 (Dropout)	(None,	1, 1, 512)	0
flatten_6 (Flatten)	(None,	512)	0
dense_16 (Dense)	(None,	256)	131328
batch_normalization_11 (Batc	(None,	256)	1024
dropout_17 (Dropout)	(None,	256)	0
dense_17 (Dense)	(None,	128)	32896
batch_normalization_12 (Batc	(None,	128)	512
dropout_18 (Dropout)	(None,	128)	0
dense_18 (Dense)	(None,	10)	1290
_			

Total params: 7,396,362 Trainable params: 7,395,594 Non-trainable params: 768

Model 7:

Let us try models with less frequent pooling (for every 2 convolution layer 1 maxpool layer). Not using padding as it gives lot of parameters which seems to be reducing performance of the model. kernels of all sizes are used. The size of layers changes as follows.

(layer 28x28) --(5x5 kernel)--> (layer 24x24) --(3x3 kernel)--> (layer 22x22) --(2x2 pooling s-2)--> (layer 11x11) --(5x5 kernel)--> (layer 7x7) --(3x3 kernel)--> (layer 5x5) --(2x2 pooling s-1)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y pred

Channels of CNN and number of hidden layer units changes as follows.

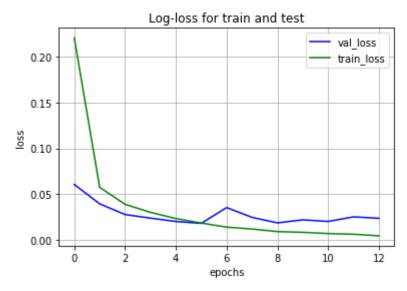
(1x28x28) --> (32x24x24) --> (64x22x22) --> (64x11x11) --> (128x7x7) --> (256x5x5) --> (256x4x4) --(Flatten)--> 4096 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

```
In [23]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel size=(5, 5), activation='relu',
                           input shape=input shape, kernel initializer='he normal'))
         model.add(Conv2D(64, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(128, (5, 5), activation='relu', kernel initializer='he normal'))
         model.add(Conv2D(256, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2), strides=(1, 1)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(512, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                       optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model7 = model
         history7 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x test, y test))
         score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
         Train on 60000 samples, validate on 10000 samples
```

```
- val acc: 0.9925
Epoch 4/13
- val acc: 0.9934
Epoch 5/13
- val acc: 0.9940
Epoch 6/13
- val acc: 0.9945
Epoch 7/13
- val acc: 0.9907
Epoch 8/13
- val acc: 0.9940
Epoch 9/13
val acc: 0.9947
Epoch 10/13
- val acc: 0.9945
Epoch 11/13
- val acc: 0.9954
Epoch 12/13
- val acc: 0.9941
Epoch 13/13
- val acc: 0.9948
Test loss: 0.023324923777469486
Test accuracy: 0.9948
```

```
In [24]: val_loss = history7.history['val_loss']
loss = history7.history['loss']

plt.plot(val_loss, color='b', label='val_loss')
plt.plot(loss, color='g', label='train_loss')
plt.grid()
plt.legend()
plt.title('Log-loss for train and test')
plt.xlabel('epochs')
plt.ylabel('loss')
plt.ylabel('loss')
```



Best model seen so far. the accuracy is very good and its not randomly good for only one epoch i.e. last few epochs have good accuracy scores which are above 99.4 %. But there seems to be slight overfit problem. further training may harm the performance

In [25]: model7.summary()

Model: "sequential_7"

Layer (type)	Output	Shape	Param #
conv2d_18 (Conv2D)	 (None,		======= 832
conv2d_19 (Conv2D)	(None,	22, 22, 64)	18496
max_pooling2d_15 (MaxPooling	(None,	11, 11, 64)	0
conv2d_20 (Conv2D)	(None,	7, 7, 128)	204928
conv2d_21 (Conv2D)	(None,	5, 5, 256)	295168
max_pooling2d_16 (MaxPooling	(None,	4, 4, 256)	0
dropout_19 (Dropout)	(None,	4, 4, 256)	0
flatten_7 (Flatten)	(None,	4096)	0
dense_19 (Dense)	(None,	512)	2097664
batch_normalization_13 (Batc	(None,	512)	2048
dropout_20 (Dropout)	(None,	512)	0
dense_20 (Dense)	(None,	128)	65664
batch_normalization_14 (Batc	(None,	128)	512
dropout_21 (Dropout)	(None,	128)	0
dense_21 (Dense)	(None,	10)	1290
Total params: 2,686,602	======	:========:	=======

Total params: 2,686,602 Trainable params: 2,685,322 Non-trainable params: 1,280

Model 8:

Let us try models with less frequent pooling (for every 2 convolution layer 1 maxpool layer). Not using padding much as it gives lot of parameters which seems to be reducing performance of the model. kernels of different sizes are used. The size of layers changes as follows.

(layer 28x28) --(5x5 kernel padding)--> (layer 28x28) --(5x5 kernel)--> (layer 24x24) --(2x2 pooling s-2)--> (layer 12x12) --(3x3 kernel)--> (layer 8x8) --(2x2 pooling s-2)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

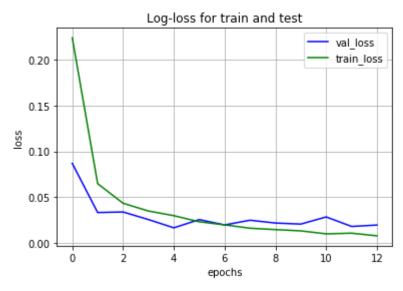
Channels of CNN and number of hidden layer units changes as follows.

```
(1x28x28) --> (32x28x28) --> (64x24x24) --> (64x12x12) --> (128x10x10) --> (256x8x8) --> (256x4x4) --(Flatten)--> 4096 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)
```

I will add dropouts and batch normalization in between so that our model doesnt overfit.

```
In [26]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel size=(5, 5), activation='relu', padding='same',
                           input shape=input shape, kernel initializer='he normal'))
         model.add(Conv2D(64, (5, 5), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(128, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(Conv2D(256, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(512, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                       optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model8 = model
         history8 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x test, y test))
         score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
         print('Test accuracy:', score[1])
         Train on 60000 samples, validate on 10000 samples
```

```
- val acc: 0.9905
Epoch 4/13
- val acc: 0.9918
Epoch 5/13
- val acc: 0.9945
Epoch 6/13
- val acc: 0.9926
Epoch 7/13
- val acc: 0.9944
Epoch 8/13
- val acc: 0.9927
Epoch 9/13
- val acc: 0.9935
Epoch 10/13
- val acc: 0.9940
Epoch 11/13
- val acc: 0.9930
Epoch 12/13
- val acc: 0.9953
Epoch 13/13
- val acc: 0.9951
Test loss: 0.019591454985709335
Test accuracy: 0.9951
```



This model is also pretty good. The test loss of model is very low. Accuracy reached 99.5 %. but further training may give good accuracy or overfit problems

In [28]: model8.summary()

Model: "sequential_8"

Layer (type)	Output Shape	Param #
conv2d_22 (Conv2D)	(None, 28, 28, 32)	832
conv2d_23 (Conv2D)	(None, 24, 24, 64)	51264
max_pooling2d_17 (MaxPooling	(None, 12, 12, 64)	0
conv2d_24 (Conv2D)	(None, 10, 10, 128)	73856
conv2d_25 (Conv2D)	(None, 8, 8, 256)	295168
max_pooling2d_18 (MaxPooling	(None, 4, 4, 256)	0
dropout_22 (Dropout)	(None, 4, 4, 256)	0
flatten_8 (Flatten)	(None, 4096)	0
dense_22 (Dense)	(None, 512)	2097664
batch_normalization_15 (Batc	(None, 512)	2048
dropout_23 (Dropout)	(None, 512)	0
dense_23 (Dense)	(None, 128)	65664
batch_normalization_16 (Batc	(None, 128)	512
dropout_24 (Dropout)	(None, 128)	0
dense_24 (Dense)	(None, 10)	1290
Total params: 2,588,298		

Total params: 2,588,298
Trainable params: 2,587,018
Non-trainable params: 1,280

Model 9:

Let us try one another model with less frequent pooling (for every 2 convolution layer 1 maxpool layer). In previous model we used 5x5 in early layers and 3x3 in later layers. Now we reverse this

(layer 28x28) --(3x3 kernel padding)--> (layer 28x28) --(3x3 kernel)--> (layer 26x26) --(2x2 pooling s-2)--> (layer 13x13) --(5x5 kernel)--> (layer 9x9) --(5x5 kernel)--> (layer 5x5) --(2x2 pooling s-1)--> (layer 4x4) --(Flatten)--> Dense --> Dense --> Softmax --> y_pred

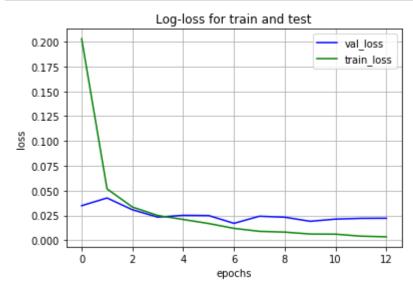
Channels of CNN and number of hidden layer units changes as follows.

(1x28x28) --> (32x28x28) --> (64x26x26) --> (64x13x13) --> (128x9x9) --> (256x5x5) --> (256x4x4) --(Flatten)--> 4096 --> 512 (Dense 1) --> 128 (Dense 2) --> 10 (Softmax)

I will add dropouts and batch normalization in between so that our model doesnt overfit.

```
In [29]:
         ## Building above model
         warnings.filterwarnings('ignore')
         model = Sequential()
         model.add(Conv2D(32, kernel size=(3, 3), activation='relu', padding='same',
                           input shape=input shape, kernel initializer='he normal'))
         model.add(Conv2D(64, (3, 3), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Conv2D(128, (5, 5), activation='relu', kernel initializer='he normal'))
         model.add(Conv2D(256, (5, 5), activation='relu', kernel initializer='he normal'))
         model.add(MaxPooling2D(pool size=(2, 2), strides=(1, 1)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(512, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(128, activation='relu', kernel initializer='he normal'))
         model.add(BatchNormalization())
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                       optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model9 = model
         history9 = model.fit(x train, y train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation data=(x test, y test))
         score = model.evaluate(x test, y test, verbose=0)
         print('Test loss:', score[0])
          print('Test accuracy:', score[1])
         Train on 60000 samples, validate on 10000 samples
         Epoch 1/13
```

```
- val acc: 0.9913
Epoch 4/13
- val acc: 0.9937
Epoch 5/13
- val acc: 0.9928
Epoch 6/13
- val acc: 0.9928
Epoch 7/13
- val acc: 0.9953
Epoch 8/13
- val acc: 0.9937
Epoch 9/13
val acc: 0.9942
Epoch 10/13
- val acc: 0.9949
Epoch 11/13
- val acc: 0.9945
Epoch 12/13
- val acc: 0.9939
Epoch 13/13
- val acc: 0.9954
Test loss: 0.022201177267580988
Test accuracy: 0.9954
```



This model gave good accuracy and loss but the model is overfitting. So further training may give bad results.

In [31]: model9.summary()

Model: "sequential_9"

Layer (type)	Output Shape	Param #
conv2d_26 (Conv2D)	(None, 28, 28, 32)	320
conv2d_27 (Conv2D)	(None, 26, 26, 64)	18496
max_pooling2d_19 (MaxPooling	(None, 13, 13, 64)	0
conv2d_28 (Conv2D)	(None, 9, 9, 128)	204928
conv2d_29 (Conv2D)	(None, 5, 5, 256)	819456
max_pooling2d_20 (MaxPooling	(None, 4, 4, 256)	0
dropout_25 (Dropout)	(None, 4, 4, 256)	0
flatten_9 (Flatten)	(None, 4096)	0
dense_25 (Dense)	(None, 512)	2097664
batch_normalization_17 (Batc	(None, 512)	2048
dropout_26 (Dropout)	(None, 512)	0
dense_26 (Dense)	(None, 128)	65664
batch_normalization_18 (Batc	(None, 128)	512
dropout_27 (Dropout)	(None, 128)	0
dense_27 (Dense)	(None, 10)	1290
Total params: 3,210,378		

Total params: 3,210,378
Trainable params: 3,209,098
Non-trainable params: 1,280

Model 10:

Trying to build a model similar to inception (not exactly similar) to see the effect on the model's performance. Architecture looks as below.

First we form 4 individual layers as follows from input.

```
(1x28x28 input) --(1x1 kernel)--> (32x28x28) - layer1
(1x28x28 input) --(3x3 kernel pad)--> (32x28x28) - layer2
(1x28x28 input) --(5x5 kernel pad)--> (32x28x28) - layer3
(1x28x28 input) --(1x1 kernel)--> (32x28x28) --(3x3 pooling s-1 pad)--> (32x28x28) - layer4
```

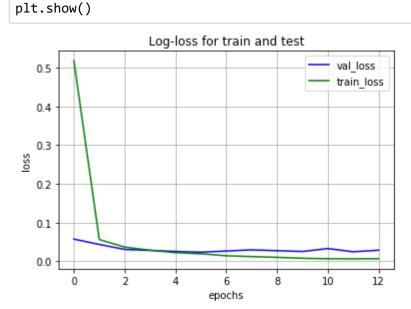
Now above layers will be merged to form single layer and this will be fed for next layers which are as follows. (below kernels have no padding)

```
4 layers merged --> (128x28x28) --(7x7 kernel)--> (256x22x22) --(2x2 pooling s-2)--> (256x11x11) --(5x5 kernel)--> (512x7x7) --(5x5 kernel)--> (1024x3x3) --(3x3 kernel)--> (2048x1x1) --(Flatten)--> 2048 --> 512 (Dense) --> 128 (Dense) --> 10 (Softmax)
```

```
## Building above model
In [37]:
         warnings.filterwarnings('ignore')
         ## Layer 1
         input layer = keras.layers.Input(shape=input shape)
         layer 1 = Conv2D(32, (1, 1), padding='same', activation='relu',
                           kernel initializer='he normal')(input layer)
         # Laver 2
         layer 2 = Conv2D(32, (3, 3), padding='same', activation='relu',
                           kernel initializer='he normal')(input layer)
         # Laver 3
         layer 3 = Conv2D(32, (5, 5), padding='same', activation='relu',
                           kernel initializer='he normal')(input layer)
         # Laver 4
         layer 4 = Conv2D(32, (1, 1), padding='same', activation='relu',
                           kernel initializer='he normal')(input layer)
         layer 4 = MaxPooling2D(pool size=(3, 3), padding='same', strides=(1, 1))(layer 4)
         # final CNN
         merged layers = keras.layers.Concatenate(axis=-1)([layer 1, layer 2, layer 3, layer 4])
         cl1 = Conv2D(256, (7, 7), activation='relu', kernel initializer='he normal')(merged layers)
         cl2 = MaxPooling2D(pool size=(2, 2))(cl1)
         cl3 = Conv2D(512, (5, 5), activation='relu', kernel initializer='he normal')(cl2)
         cl4 = Conv2D(1024, (5, 5), activation='relu', kernel_initializer='he_normal')(cl3)
         cl5 = Conv2D(2048, (3, 3), activation='relu', kernel initializer='he normal')(cl4)
         c16 = Dropout(0.25)(c15)
         l1 = Flatten()(cl6)
         12 = Dense(512, activation='relu', kernel initializer='he normal')(11)
         13 = BatchNormalization()(12)
         14 = Dropout(0.5)(13)
         15 = Dense(128, activation='relu', kernel initializer='he normal')(14)
         16 = BatchNormalization()(15)
         17 = Dropout(0.5)(16)
         output layer = Dense(num classes, activation='softmax')(17)
         model = keras.models.Model(inputs = input layer, outputs = output layer)
         model.compile(loss=keras.losses.categorical crossentropy,
                       optimizer=keras.optimizers.Adadelta(),
```

```
Epoch 1/13
val acc: 0.9828
Epoch 2/13
val acc: 0.9874
Epoch 3/13
val acc: 0.9913
Epoch 4/13
val acc: 0.9919
Epoch 5/13
val acc: 0.9928
Epoch 6/13
val acc: 0.9936
Epoch 7/13
val acc: 0.9929
Epoch 8/13
val acc: 0.9926
Epoch 9/13
val acc: 0.9934
Epoch 10/13
```

```
val acc: 0.9941
    Epoch 11/13
    val acc: 0.9928
    Epoch 12/13
    val acc: 0.9933
    Epoch 13/13
    val acc: 0.9944
    Test loss: 0.02869936848818943
    Test accuracy: 0.9944
In [38]: val loss = history10.history['val loss']
    loss = history10.history['loss']
    plt.plot(val loss, color='b', label='val loss')
    plt.plot(loss, color='g', label='train loss')
    plt.grid()
```



plt.title('Log-loss for train and test')

plt.legend()

plt.xlabel('epochs')
plt.ylabel('loss')

Even when we built complex model this didnt do as good as last 3 models (models 7, 8, 9). And results can be comparable to first 6 models. Overfitting is not as bad as other models which is good

In [39]: model10.summary()

Model: "model_3"

Layer (type)	Output	Shape	Param #	Connected to
<pre>input_3 (InputLayer)</pre>	(None,	 28, 28, 1)	 0	
conv2d_49 (Conv2D)	(None,	28, 28, 32)	64	input_3[0][0]
conv2d_46 (Conv2D)	(None,	28, 28, 32)	64	input_3[0][0]
conv2d_47 (Conv2D)	(None,	28, 28, 32)	320	input_3[0][0]
conv2d_48 (Conv2D)	(None,	28, 28, 32)	832	input_3[0][0]
<pre>max_pooling2d_25 (MaxPooling2D)</pre>	(None,	28, 28, 32)	0	conv2d_49[0][0]
concatenate_3 (Concatenate)	(None,	28, 28, 128)	0	conv2d_46[0][0] conv2d_47[0][0] conv2d_48[0][0] max_pooling2d_25[0][0]
conv2d_50 (Conv2D)	(None,	22, 22, 256)	1605888	concatenate_3[0][0]
<pre>max_pooling2d_26 (MaxPooling2D)</pre>	(None,	11, 11, 256)	0	conv2d_50[0][0]
conv2d_51 (Conv2D)	(None,	7, 7, 512)	3277312	max_pooling2d_26[0][0]
conv2d_52 (Conv2D)	(None,	3, 3, 1024)	13108224	conv2d_51[0][0]
conv2d_53 (Conv2D)	(None,	1, 1, 2048)	18876416	conv2d_52[0][0]
dropout_32 (Dropout)	(None,	1, 1, 2048)	0	conv2d_53[0][0]
flatten_12 (Flatten)	(None,	2048)	0	dropout_32[0][0]
dense_34 (Dense)	(None,	512)	1049088	flatten_12[0][0]
batch_normalization_21 (BatchNo	(None,	512)	2048	dense_34[0][0]
dropout_33 (Dropout)	(None,	512)	0	batch_normalization_21[0][0]

dense_35 (Dense)	(None,	128)	65664	dropout_33[0][0]
batch_normalization_22 (BatchNo	(None,	128)	512	dense_35[0][0]
dropout_34 (Dropout)	(None,	128)	0	batch_normalization_22[0][0]
dense_36 (Dense)	(None,	10)	1290	dropout_34[0][0]

Total params: 37,987,722 Trainable params: 37,986,442 Non-trainable params: 1,280

Conclusion:

```
In [7]: from prettytable import PrettyTable

table = PrettyTable()
table.field_names = ['Model number', 'Model Description', 'Train loss', 'Validation loss', 'Train accuracy', 'Te table.add_row(['Model 1', '5x5 no padding', 0.0196, 0.0249, '99.41 %', '99.36 %'])
table.add_row(['Model 2', '3x3 no padding', 0.0151, 0.0212, '99.52 %', '99.40 %'])
table.add_row(['Model 3', '7x7 no padding', 0.0108, 0.0309, '99.69 %', '99.29 %'])
table.add_row(['Model 4', '5x5 with padding', 0.0020, 0.0288, '99.94 %', '99.37 %'])
table.add_row(['Model 5', '3x3 with padding', 0.0104, 0.0241, '99.68 %', '99.38 %'])
table.add_row(['Model 6', '7x7 with padding', 0.0022, 0.0299, '99.94 %', '99.38 %'])
table.add_row(['Model 7', 'Maxpool less freq', 0.0042, 0.0233, '99.88 %', '99.48 %'])
table.add_row(['Model 8', 'Maxpool less freq', 0.0078, 0.0196, '99.79 %', '99.51 %'])
table.add_row(['Model 9', 'Maxpool less freq', 0.0035, 0.0222, '99.88 %', '99.54 %'])
table.add_row(['Model 10', 'Inception type model', 0.0067, 0.0287, '99.80 %', '99.44 %'])
print(table)
```

+		+	+		
Model number	Model Description	Train loss	Validation loss	Train accuracy	Test accuracy
+		+	+		++
Model 1	5x5 no padding	0.0196	0.0249	99.41 %	99.36 %
Model 2	3x3 no padding	0.0151	0.0212	99.52 %	99.40 %
Model 3	7x7 no padding	0.0108	0.0309	99.69 %	99.29 %
Model 4	5x5 with padding	0.002	0.0288	99.94 %	99.37 %
Model 5	3x3 with padding	0.0104	0.0241	99.68 %	99.38 %
Model 6	7x7 with padding	0.0022	0.0299	99.94 %	99.38 %
Model 7	Maxpool less freq	0.0042	0.0233	99.88 %	99.48 %
Model 8	Maxpool less freq	0.0078	0.0196	99.79 %	99.51 %
Model 9	Maxpool less freq	0.0035	0.0222	99.88 %	99.54 %
Model 10	Inception type model	0.0067	0.0287	99.80 %	99.44 %
+		+	+		

Conclusion:

- Accuracy wise models 7, 8, 9 are doing good. These models have less frequent Maxpooling layers than previous ones i.e.
 for every 2 Convolution layers there is a Maxpool layer. These models are overfitting slightly
- Models 1, 2 have less overfitting and good for futher training for few more epochs. These models accuracy and losses are
 not that good but can be improved by further training. These models have 5x5 and 3x3 kernel layers respectively with no
 padding in any layers
- Models with high padding layers (models 4, 5, 6) are not performing well as they are overfitting very easily and train accuracy is very high for two of these models. Accuracy is good but will not improve for further training

- Model 10 has slightly complex architecture (little bit similar to inception model). This model did good but not as good as 7, 8, 9 models. So its better to prefer one of 7, 8, 9 models as model 10 has lot of parameters (around ~37.9 Million) which gives low latency.
- Some models accuracy and losses are fluctuating a lot so final loss and accuracy are not best way to analyse the model.

 Above analysis done by seeing previous epoch scores.

Architectures of all 10 models are again printed below:

- 1. (1x28x28) --(5x5 kernel)--> (32x24x24) --(2x2 pooling s-2)--> (32x12x12) --(5x5 kernel)--> (64x8x8) --(2x2 pooling s-2)--> (64x4x4) --(Flatten)--> 1024 --> 512 --> 128 --> 10
- 2. (1x28x28) --(3x3 kernel)--> (32x26x26) --(2x2 pooling s-2)--> (32x13x13) --(3x3 kernel)--> (64x11x11) --(2x2 pooling s-1)--> (64x10x10) --(3x3 kernel)--> (128x8x8) --(2x2 pooling s-2)--> (128x4x4) --(Flatten)--> 2048 --> 512 --> 128 --> 10
- 3. (1x28x28) --(7x7 kernel)--> (32x22x22) --(2x2 pooling s-2)--> (32x11x11) --(7x7 kernel)--> (64x5x5) --(2x2 pooling s-1)--> (64x4x4) --(Flatten)--> 1024 --> 512 --> 128 --> 10
- 4. (1x28x28) --(5x5 kernel)--> (32x28x28) --(2x2 pooling s-2)--> (32x14x14) --(5x5 kernel)--> (128x14x14) --(2x2 pooling s-2)--> (128x7x7) --(3x3 kernel)--> (256x5x5) --(5x5 kernel)--> (512x1x1) --(Flatten)--> 512 --> 256 --> 128 --> 10
- 5. (1x28x28) --(3x3 kernel)--> (32x28x28) --(2x2 pooling s-2)--> (32x14x14) --(3x3 kernel)--> (64x14x14) --(2x2 pooling s-2)--> (64x7x7) --(3x3 kernel)--> (128x5x5) --(2x2 pooling s-1)--> (128x4x4) --(Flatten)--> 2048 --> 512 --> 128 --> 10
- 6. (1x28x28) --(7x7 kernel)--> (64x28x28) --(2x2 pooling s-2)--> (64x14x14) --(7x7 kernel)--> (256x14x14) --(2x2 pooling s-2)--> (256x7x7) --(7x7 kernel)--> (512x1x1) --(Flatten)--> 512 --> 256 --> 128 --> 10
- 7. (1x28x28) --(5x5 kernel)--> (32x24x24) --(3x3 kernel)--> (64x22x22) --(2x2 pooling s-2)--> (64x11x11) --(5x5 kernel)--> (128x7x7) --(3x3 kernel)--> (256x5x5) --(2x2 pooling s-1)--> (256x4x4) --(Flatten)--> 4096 --> 512 --> 128 --> 10
- 8. (1x28x28) --(5x5 kernel)--> (32x28x28) --(5x5 kernel)--> (64x24x24) --(2x2 pooling s-2)--> (64x12x12) --(3x3 kernel)--> (128x10x10) --(3x3 kernel)--> (256x8x8) --(2x2 pooling s-2)--> (256x4x4) --(Flatten)--> 4096 --> 512 --> 128 --> 10
- 9. (1x28x28) --(3x3 kernel)--> (32x28x28) --(3x3 kernel)--> (64x26x26) --(2x2 pooling s-2)--> (64x13x13) --(5x5 kernel)--> (128x9x9) --(5x5 kernel)--> (256x5x5) --(2x2 pooling s-1)--> (256x4x4) --(Flatten)--> 4096 --> 512 --> 128 --> 10

Model 10:

```
(1x28x28 input) --(1x1 kernel)--> (32x28x28) - layer1
(1x28x28 input) --(3x3 kernel pad)--> (32x28x28) - layer2
(1x28x28 input) --(5x5 kernel pad)--> (32x28x28) - layer3
(1x28x28 input) --(1x1 kernel)--> (32x28x28) --(3x3 pooling s-1 pad)--> (32x28x28) - layer4
```

Now above layers will be merged to form single layer and this will be fed for next layers which are as follows. (below kernels have no padding)

```
4 layers merged --> (128x28x28) --(7x7 kernel)--> (256x22x22) --(2x2 pooling s-2)--> (256x11x11) --(5x5 kernel)--> (512x7x7) --(5x5 kernel)--> (1024x3x3) --(3x3 kernel)--> (2048x1x1) --(Flatten)--> 2048 --> 512 (Dense) --> 128 (Dense) --> 10 (Softmax)
```

Batch Normalization layers and dropout layers are not mentioned in above architectures.

