# CMPS 102 — Spring 2020 – Homework 2

Four problems, 10 points each, due Monday April 27 (11:59 PM) on Gradescope.

Before you begin the assignment, please read the following carefully.

- Read the Homework Guidelines.
- The assignment consists of four problems worth ten points each. Unless otherwise stated, algorithms and their proofs of correctness are weighted equally.
- Due to class size, it is likely that only a subset of the problems will be graded. We will announce the problem(s) which will be graded after the due date of the assignment.
- Every part of each question begins on a new page. Do not change this.
- This does not mean that you should write a full page for every question. Your answers should be short and precise. Lengthy and wordy answers will lose points.
- Do not change the format of this document. Simply type your answers as directed.
- You are **not** allowed to work in teams.

I have read and agree to the collaboration policy. – Isai Lopez Rodas, ilopezro@ucsc.edu Collaborators: None

# **Recommended exercises (not to be turned in)**

1. The solved exercises in 5 (Divide and Conquer).

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#### Problems to be turned in

1. You are interested in building a coffeeshop and charging station beside a freeway running between two cities. Let n be the number of interchanges between the cities, and number them consecutively so that interchange 0 is at the first city, 1 is the next interchange, and so on, with n-1 being the interchange at the other city. We say each interchange i is adjacent to interchanges i-1 and i+1 (only).

Each interchange i has a cost c(i) to construct a coffee shop/charging station. Call an interchange i a local minimum if (and only if) the cost of building there is less than the costs of building at the adjacent interchanges, i.e. both c(i) < c(i+1) and c(i) < c(i-1). You want to ensure that you build at a local minimum so that no one can build a coffeeshop/charging station more cheaply at an adjacent interchange.

You can assume that:

- $n \ge 3$ , so there is at least one interchange between the cities.
- The costs at the cities c(0) and c(n-1) are both known to be the same large number (say 100n).
- The other costs are all different and are all strictly less than c(0) (and thus also less than c(n-1)).

The difficulty is that the c(i) values are not known ahead of time (except for c(0) and c(n-1)) and it is expensive to determine the cost of building at any interchange.

The goal is to create a divide and conquer algorithm that finds any interchange k that is a local minimum while examining relatively few of the c(i) values. Although there may be many local minimums, your algorithm need only find one of them.

(a) (2 points) First, prove that a local minimum exists.

#### Solution.

I will use proof by contradiction to show that a local minumum exists.

**Base Case:** When n=3, we know that c(0) and c(2) are both equal to each other in terms of costs. Additionally, we also know that c(1) is strictly less than c(0) and c(2). This means that there is a local minimum at n=2 since c(1)< c(0) **AND** c(1)< c(2).

For the sake of contradiction, I will assume that no local minimum exists. By the definition of local maxima and minima, this means that c(0) will have to be the largest cost and every interchange thereafter is either strictly lower or strictly higher than the cost of building that first interchange. So if c(0) is the largest cost, that still satisfies the  $3^{rd}$  requirement of being able to build an interchange. According to the  $2^{nd}$  requirement, c(0) is the largest cost. So I will say that interchange city c(1) will be strictly less than c(0). c(2) will be strictly less than c(1) and every city until c(n-1) will all be strictly less than their previous interchange city. This creates the inequality  $c(0) > c(1) > c(2) \cdots > c(n-1)$ ; however, we've got a contradiction here because this breaks the  $2^{nd}$  requirement in that c(0) = c(n-1).

(b) (3 points) Clearly describe a divide and conquer algorithm for the problem

## Algorithm.

I will design a Binary Search algorithm that returns the first local minumum that it finds. It will contain two recursive calls on the first  $\frac{n}{2}$  and the last  $\frac{n+1}{2}$  elements.

```
1: procedure BINARY SEARCH(\mathcal{A}, \mathcal{L}, \mathcal{R})
                                                                    \triangleright \mathcal{A} is array, \mathcal{L} is left index, \mathcal{R} is right index
          len \leftarrow length of A
          if len = 3 then
 3:
               return 1
 4:
                                                                                                                   \triangleright len > 3
 5:
          else
              mid \leftarrow \frac{\mathcal{L} + \mathcal{R}}{2}midElement \leftarrow \mathcal{A}[mid]
 6:
 7:
               leftElement \leftarrow \mathcal{A}[mid-1]
 8:
               rightElement \leftarrow \mathcal{A}[mid+1]
 9:
               if midElement < leftElement and midElement < rightElement then
10:
                    return \ mid
11:
               else if leftElement > rightElement then
12:
13:
                    BINARY SEARCH(\mathcal{A}, mid + 1, \mathcal{R})
14:
               else
                    BINARY SEARCH(\mathcal{A}, \mathcal{L}, mid)
15:
               end if
16:
17:
          end if
18: end procedure
```

I have a base case on line 3 when the length of the array = 3. Since we proved that a local minimum must exists, I start off by saying that if our array is of size 3, then return the middle value. I then compare the middle element of the array to its adjacent elements and if they middle element is less than its adjacent elements, we have found a local minimum. I return the index of the minima. If the local minimum does not exists within the initial  $\mathcal{L}$  and  $\mathcal{R}$  indeces, I recursively call on  $\mathcal{L}$  to mid and mid + 1 to  $\mathcal{R}$  until a minumum is found.

(c) (3 points) Prove that your algorithm is correct

#### **Proof of correctness.**

**Base Case:** n = 3.

My algorithm will correctly return the local minima at index 1 because we are given the rule that the first and last elements/cities are the largest and all other interchanging stops are strictly lower than the first and last element.

**Inductive Step:** I will assume that my algorithm correctly sorts elements up until n. I will prove that my algorithm correctly sorts n+1 elements.

Since we are only looking for first lowest element we can find, will initially compare our median value to its neighboring elements. If the median value is not a local minima, we will recurse on the side where the smallest of the three elements was, which reduces the number of elements we are looking at by half. Because we recurse on the side that has the smallest element, we are guaranteed to find the smallest value because we are following the smallest element all the way through until we find a local minima.

(d) (2 points) Analyze the (worst case) number of interchange costs (i.e. c(i) values) examined by your algorithm as a function of n.

#### Solution.

If we have n number of cities, I can deduce that in the worst case, the algorithm will compare  $\frac{n}{2}$  every time it is called. Within each recursive call, we can have up to three comparisons made. We compare median value to its adjacent element values and if no minima is found, we go on to compare if the left and right elements are less than or greater than each other. These comaprisons are made in constant time so our recurrance relation is  $T(n) = T(\frac{n}{2}) + \mathcal{O}(1)$ . Using Master's Theorem, we can say that:

$$a = 1, b = 2, d = 0$$

Using case #2, I get  $f(n) = \mathcal{O}(n^{\log_b a})$ . We can then say that  $T(n) = \mathcal{O}(n^{\log_b a} \log n)$ . Plugging in the above values, I get:

$$T(n) = \mathcal{O}(n^{\log_2 1} \log n)$$
$$= \mathcal{O}(n^0 \log n)$$
$$= \mathcal{O}(\log n)$$

Therefore, we can conclude, through the Master's Theorem, that the worst case runtime of my algorithm is  $\mathcal{O}(\log n)$ .

2. We all know how to search a sorted 1-dimensional array. This problem involves searching two dimensional arrays that are partially sorted.

Call a two-dimensional square  $(n \times n)$  array A line-sorted if

- the entries of A are all distinct numbers,
- the entries in each row are sorted in ascending order (left to right), and
- the entries in each column are sorted in ascending order (top to bottom).

If A is line-sorted then both A[i-1,j] < A[i,j] < A[i+1,j] and A[i,j-1] < A[i,j] < A[i,j+1] (assuming the indices are inside the array).

Devise a two-dimensional divide and conquer algorithm which takes a line-sorted array A and number k to search for, and returns either indices i and j such that A[i,j]=k or an indicator that k is not in the array. Describe your algorithm (in pseudo-code), argue that your algorithm is correct, give and and analyze its (worst-case) running time through a recurrence. You may assume that n is a power of two.

The goal is for your algorithm to take asymptotically less time than the number of elements in the array, but it will probably not be as efficient as simply performing binary search on each row.

Continued on the next page.

# Algorithm.

```
1: procedure TWODSEARCH(A, k)

ightarrow \mathcal{A} - array, k - element to find
        row \leftarrow 0
 2:
        column \leftarrow len(\mathcal{A}) - 1
 3:
        while row \leq len(A) or column \geq 0 do
 4:
            if A[row][column] = k then
 5:
                return True
 6:
            else if \mathcal{A}[row][column] < k then
 7:
                row ++
 8:
 9:
            else
10:
                column ++
            end if
11:
12:
        end while
        return False
13:
14: end procedure
```

## **Proof of correctness.**

**Loop Invariant:** Element k is contained within the submatrix whose top right corner is (row, column) only if k can be found within the matrix.

## **Base Case:** n = 1

If we have a  $1 \times 1$  matrix that contains the element 1 and we try and find element 1 in that matrix, our loop invariant holds true because the top right corner of our  $1 \times 1$  matrix holds the element we are looking for.

# Inductive Step:

Assume that our loop invariant holds true from  $1 \to n$ . We want to prove that it also holds true for n+1.

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3. Problem 3 in Chapter 5 (Divide and Conquer). This is the equivalent back card problem: determine if *more than* half the *n* possible fraudulent bank cards are from the same account using a machine that detects if two cards are from the same account or not. If this doesn't sound like Problem 3 in Chapter 5 of your version of the text, then let us know.

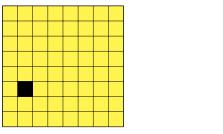
Clearly describe your algorithm, prove that it is correct, and analyze its running time. For full credit, the running time should be  $O(n \lg n)$ .

Algorithm.

**Proof of correctness.** 

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4. Tiling a Room. You have a square room that is  $2^k$  feet on a side (for some  $k \ge 1$ ), so you can think of the room as a grid of  $2^k \times 2^k$  cells. One of these cells is used for a floor vent. You are to find a way to fill in the  $(2^k \times 2^k) - 1$  other cells perfectly with L-shaped tiles, like the one shown. The L-shaped tiles can be rotated in four different ways, but cannot be cut or extend outside the room. Give a divide and conquer algorithm that finds a tiling and argue that it is correct.





For full credit, your algorithms should take O(n) time where  $n=2^{2k}=(2^k)^2$  is the number of cells in the room. The intent of the problem is to show that rooms of this kind can be tiled, do not worry about the book-keeping needed to record the particular solution found by your divide and conquer algorithm.

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Algorithm.

**Proof of correctness.**