

示例代码_双电机同步控制

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```
tank_driver = MoveTank(OUTPUT_A, OUTPUT_B)
```

控制左右电机按速度和角度运转

```
tank_driver.on_for_degrees(left_speed=SpeedPercent(50), right_speed=SpeedPercent(-50), degrees=720)
```

控制左右电机根据旋转数和速度运转

```
tank_driver.on_for_rotations(left_speed=SpeedPercent(50), right_speed=SpeedPercent(-50), rotations=2)
```

控制左右电机根据速度、持续时间旋转

```
tank_driver.on_for_seconds(left_speed=SpeedPercent(50), right_speed=SpeedPercent(-50), seconds=5)
```

电机组控制

将一对电机视作统一的整体

```
steering_driver = MoveSteering(OUTPUT_A, OUTPUT_B)
```

steering参数区间[-100, 100]， 0 表示直走， 负值代表逆时针行驶、正值代表顺时针行驶，数值越大角度越大

控制电机组按速度和旋转数运转

```
steering_driver.on_for_rotations(-80, speed=SpeedPercent(50), rotations=10)
```

控制电机组根据角度和速度运转

```
steering_driver.on_for_degrees(100, SpeedPercent(50), 720)
```

控制电机组根据速度、持续时间旋转

```
steering_driver.on_for_seconds(-100, SpeedPercent(50), 3)
```

获取左右电机的速度值

```
steering_driver.get_speed_steering(70, SpeedPercent(50))
```