NEURAL NETWORK IMAGE STYLE TRANSFER METHODS

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ARTICLES

- Multimodal Transfer: A Hierarchical Deep Convolutional Neural Network for Fast Artistic Style Transfer 11.04.2017 Xin Wang, Geoffrey Oxholm, Da Zhang, Yuan-Fang Wang University of California, Santa Barbara, CA Adobe Research, San Francisco, CA
- Deformable Style Transfer 24.03.2020 Sunnie S. Y. Kim, Nicholas Kolkin, Jason Salavon, Gregory Shakhnarovich Toyota Technological Institute at Chicago University of Chicago

Problems of current style transfer methods









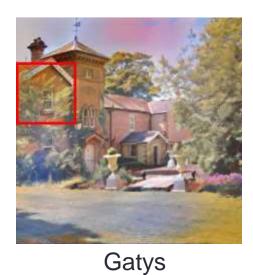


ethod Ulyanov



Johnson

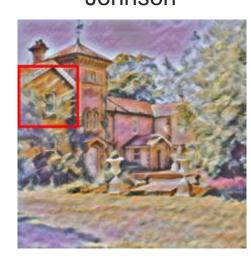












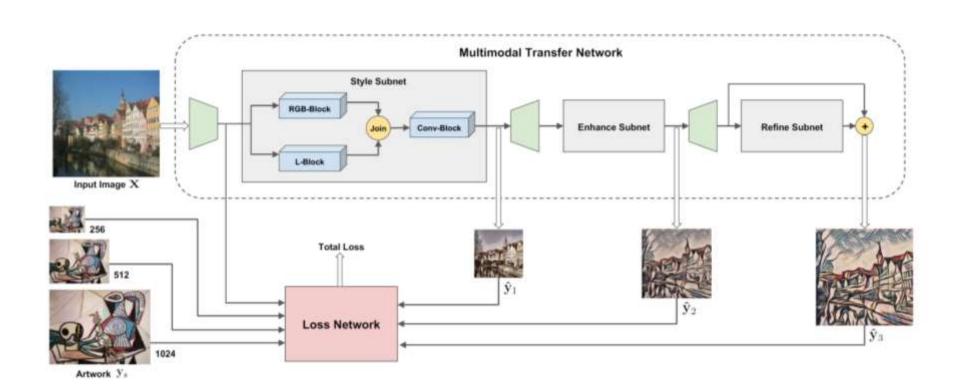
Ulyanov

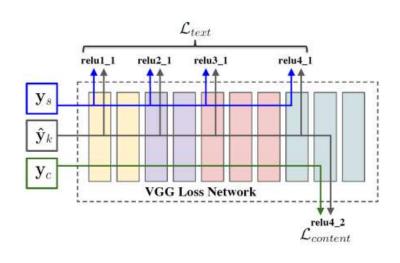
Our method

- The current feed-forward networks are trained on a specific resolution of the style image, so deviating from that resolution (bigger or smaller) results in a scale mismatch
- Current networks often fail to capture small, intricate textures, like brushwork, of many kinds of artworks on high-resolution images.

- Learn both coarse, large-scale texture distortion and fine, exquisite brushwork of an artistic style by utilizing multiple scales of a style image
- Our hierarchical training scheme and end-to-end CNN network architecture allow us to combine multiple models into one network to handle increasingly larger image sizes
- Instead of taking only RGB color channels into consideration, our network utilizes representations of both color and luminance channels for style transfer

- Johnson proposed a feed-forward network for both fast style transfer and super-resolution using the perceptual losses defined in Gatys
- Ulyanov shows that replacing spatial batch normalization in the feed-forward network with instance normalization can significantly improve the quality of generated images for fast style transfer





Content Loss

$$L_{content}(\hat{y}_k, y_c, l) = \sum_{i=1}^{N_l} ||F_i^l(\hat{y}_k) - F_i^l(y_c)||_2^2$$

Texture or Style Loss

$$G_{ij}^l(x) = \langle F_i^l(x), F_j^l(x) \rangle$$

$$L_{style}(\hat{y}_k, y_s) = \sum_{l \in L} \|G^l(\hat{y}_k) - G^l(y_s)\|_2^2$$

• Finally, the stylization loss for each output \hat{y}_k from the MT network is defined as a weighted sum of the content loss and the texture loss

$$L_S(\hat{y}_k, y_c, y_s) = \alpha L_{content}(\hat{y}_k, y_c) + \beta L_{style}(\hat{y}_k, y_s)$$

Hierarchical Stylization Loss Function

$$L_S^k(\hat{y}_k, y_c^k, y_s^k) = \alpha L_{content}(\hat{y}_k, y_c^k) + \beta L_{style}(\hat{y}_k, y_s^k)$$

Total Loss Function

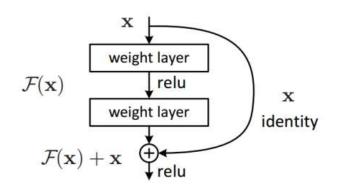
$$L_H = \sum_{k=1}^K \lambda_k L_S^k(\hat{y}_k, y_C^k, y_S^k)$$

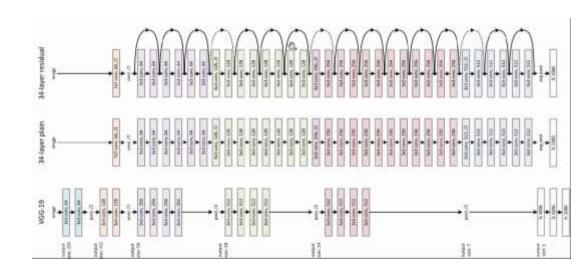
Each subnet denoted by Θ_k is trained to minimize the parallel weighted stylization losses that are computed from the latter outputs \hat{y}_i (i \geq k)

$$\Theta_{k} = \underset{\Theta_{k}}{\operatorname{argmin}} E_{x \sim \chi} \left[\sum_{i \geq k}^{K} \lambda_{i} L_{S}^{i}(f\left(\bigcup_{j=1}^{i} \Theta_{j}, x\right), y_{c}^{i}, y_{S}^{i}) \right]$$

Even though all those subnets are designed for different purposes, they are not totally independent!

- RGB-Block and L-Block
 - 1. three convolutional layers (9×9, 3×3, 3×3)
 - three residual blocks
- Conv-Block
 - 1. three residual blocks
 - 2. two resize-convolution layers for upsampling
 - 3. 3x3 convolutional layer to obtain the output image
- All non-residual convolutional layers are followed by instance normalization and ReLU

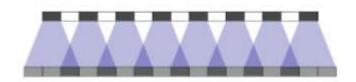


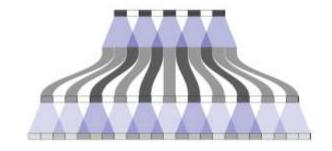


Single Residual Block

ResNet architectures

Deconvolution and Checkerboard Artifacts





 Using nearest-neighbor interpolation or bilinear interpolation and then do a convolutional layer (resize-convolution)







Using deconvolution.

Heavy checkerboard artifacts.

Using resize-convolution.

No checkerboard artifacts.

Enhance Subnet

- 1. convolutional layer for downsampling
- 2. the same structure as the style subnet
- 3. resize-convolution layer for upsampling

Refine Subnet

- 1. three convolutional layers
- three residual blocks
- 3. two resize-convolution layers
- 4. one last convolutional layer to obtain the final output









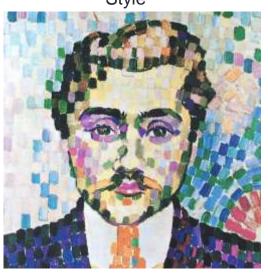








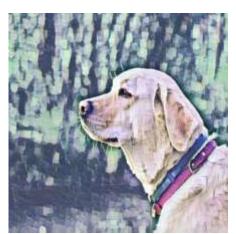
Style



Singular Transfer (style size 256)



Singular Transfer (style size 1024)



Multimodal Transfer



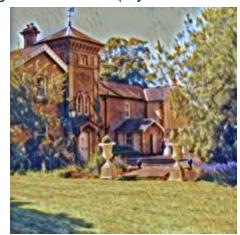
Style



Singular Transfer (style size 256)



Singular Transfer (style size 1024)



Multimodal Transfer



Style



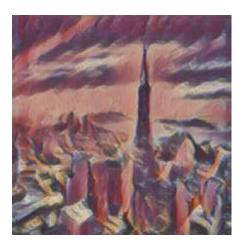
Singular Transfer (style size 256)



Singular Transfer (style size 1024)



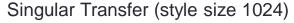
Multimodal Transfer

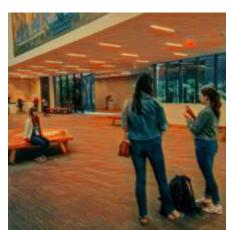


Style



Singular Transfer (style size 256)





Multimodal Transfer





First style



Second style



Content



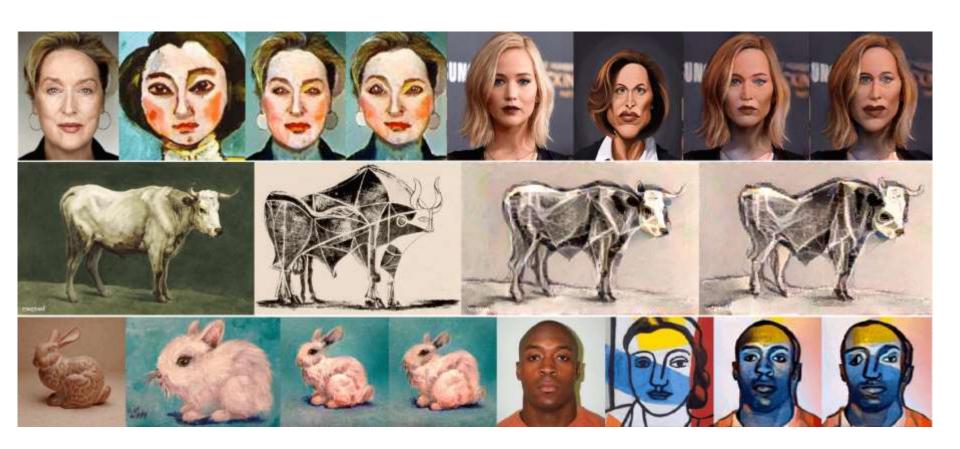




Deformable Style Transfer 24.03.2020

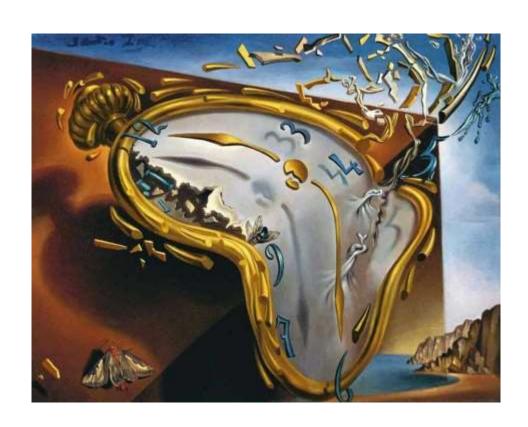
Sunnie S. Y. Kim, Nicholas Kolkin, Jason Salavon, Gregory Shakhnarovich Toyota Technological Institute at Chicago University of Chicago

Here proposed deformable style transfer (DST), an optimization-based approach that integrates texture and geometry style transfer.



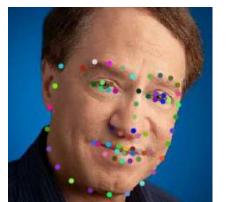


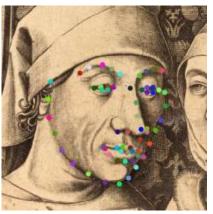
Pablo Picasso



Salvador Dali

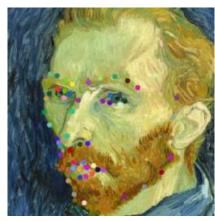
• The key idea in our approach is to consider a spatial deformation of the content image that would bring it into a spatial alignment with the style image. This deformation is guided by a set of matching keypoints, chosen to maximize the feature similarity between paired keypoints across the two images





Correspondences







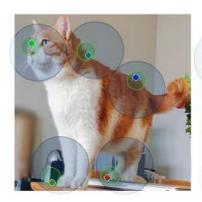


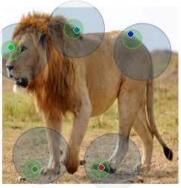




Neural Best-Buddies (NBB)

NBB finds a sparse set of correspondences between two images that could be from different domains or semantic categories. It utilizes the hierarchies of deep features of a pre-trained CNN, that is, the characteristic that deeper layers extract high-level semantically meaningful and spatially invariant features and shallow layers encode low-level features such as edge and color features. Starting from the deepest layer, NBB searches for pairs of correspondences that are mutual nearest neighbors, filters them based on activation values, and percolates them through the hierarchy to narrow down the search region at each level. At the end of the algorithm, it clusters the set of pixel-level correspondences into k spatial clusters and returns k keypoint pairs.





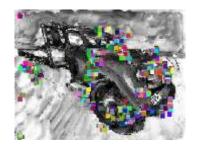




 A thin-plate spline interpolation can extend set of displacements to a full displacement field specifying how to deform every pixel in the output image.

There is a modified NBB in DST.

















- We specify an image deformation by a set of source keypoints $P = \{p_1, \ldots, p_k\}$ and the associated 2D displacement vectors $\theta = \{\theta_1, \ldots, \theta_k\}$. The θ_i specify for each source keypoint p_i the destination coordinates $p_i + \theta_i$.
- The input to DST consists of a style image I_s , a content image I_c , and aligned keypoint pairs P (source) and P' (target).
- DST optimizes the stylization parameters (usually the pixels of the output image) X and the deformation parameters θ . The final output is the warped stylized image $W(X, \theta)$.

- DST framework can be used with any optimization-based style transfer method with a content loss and a style loss.
 In this work DST demonstrated with two such methods: Gatys and Kolkin.
- The style loss of DST is composed of two terms:

$$L_{style}(I_s, X) + L_{style}(I_s, W(X, \theta))$$

Deformation Loss Term

Given the set of k source keypoints P and the matching target points P', we define the deformation loss as

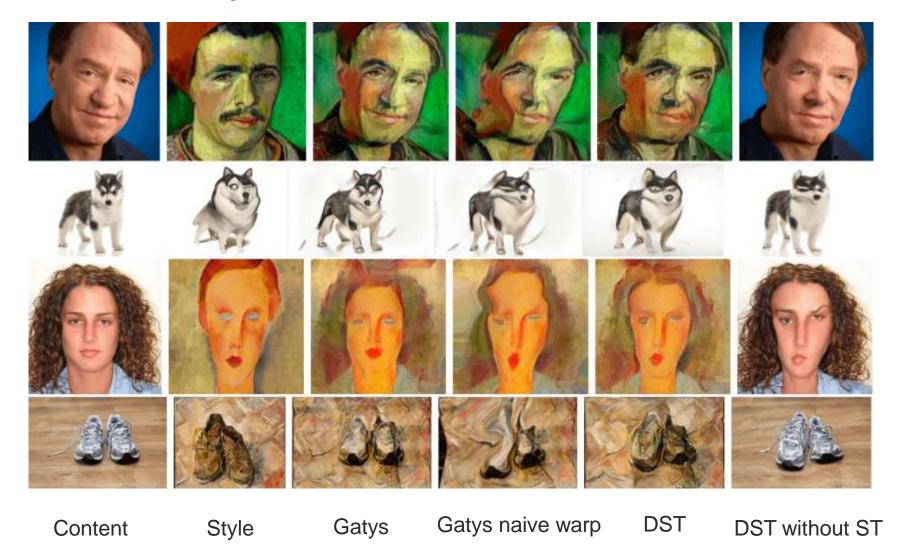
$$L_{warp}(P, P', \theta) = \frac{1}{k} \sum_{i=1}^{k} \|(p_i + \theta_i) - p_i'\|_2$$

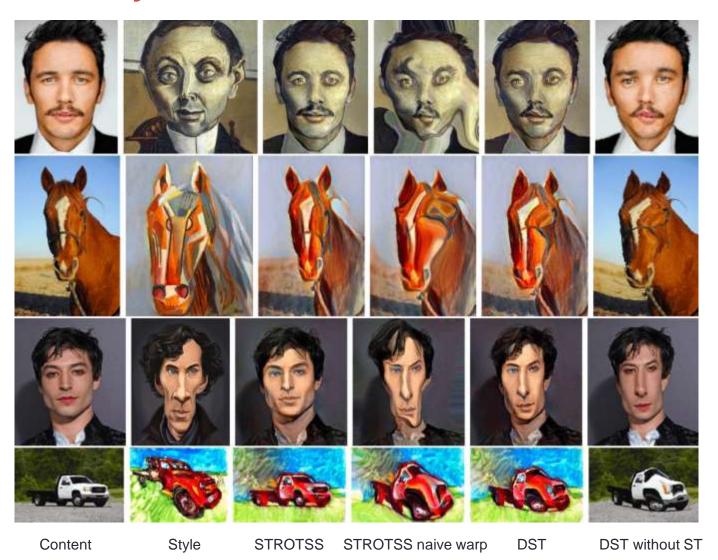
Total variation norm of the 2D warp field f normalized by its size:

$$R_{TV}(f) = \frac{1}{W \times H} \sum_{i=1}^{W} \sum_{j=1}^{H} \|f_{i+1,j} - f_{i,j}\|_{1} + \|f_{i,j+1} - f_{i,j}\|_{1}$$

Joint optimization:

$$L(X, \theta, I_c, I_s, P) = \alpha L_{content}(I_c, X) + L_{style}(I_s, X) + L_{style}(I_s, W(X, \theta)) + \beta L_{warp}(P, P', \theta) + \gamma R_{TV}(f_{\theta})$$









Style





Content

DST output

WarpGAN output