

## 25. Future treatments as proxies for confounding

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University of Wisconsin, Madison

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Cornell Info 6751: Causal Inference in Observational Settings  
Fall 2022

17 Nov 2022

# Learning goals for today

At the end of class, you will be able to:

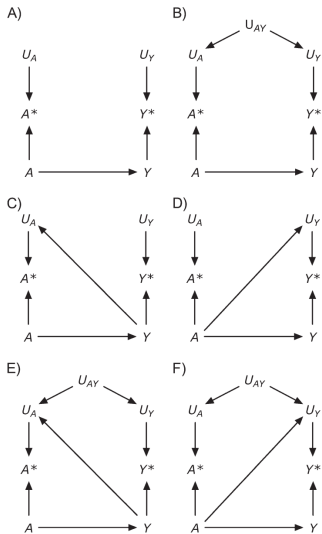
1. Reason about when future treatments can proxy for unmeasured confounding

Note that this class is based on:

Elwert, F., & Pfeffer, F. T. (2022). [The future strikes back: Using future treatments to detect and reduce hidden bias.](#) *Sociological Methods & Research*, 51(3), 1014-1051.

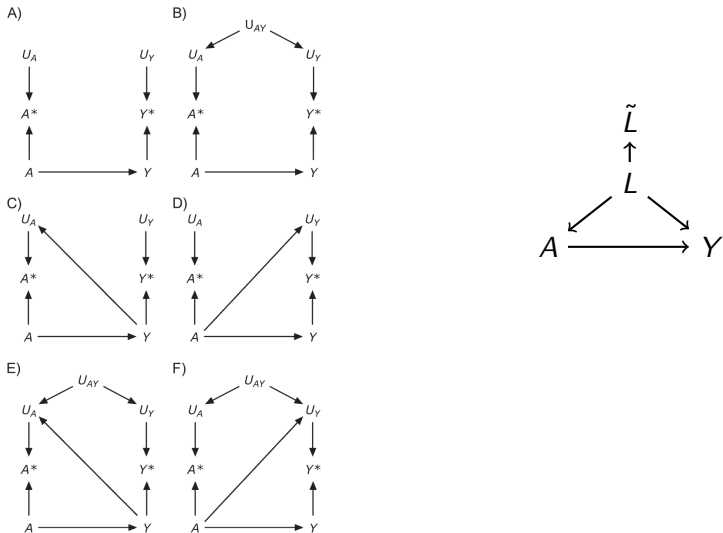
A few things we've recently covered

# Hernán & Cole 2009



**Figure 2.** A structural classification of measurement error.

# Hernán & Cole 2009



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# Hernán & Cole 2009

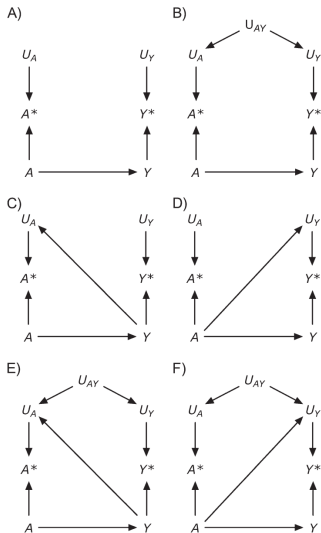
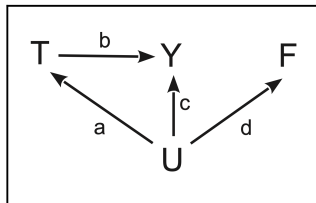


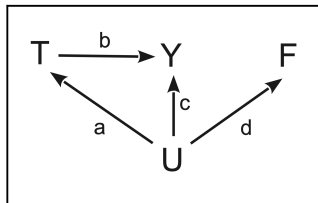
Figure 2. A structural classification of measurement error.

# Elwert & Pfeffer 2022



If you measure  $U$

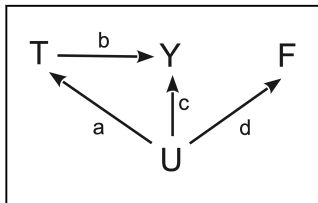
$$E(Y \mid A, U) = \alpha + \beta A + \gamma U$$



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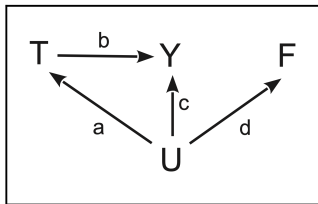
$$E(Y \mid A, U) = \alpha + \beta A + \gamma U$$

$$\begin{aligned}\beta &= \frac{\text{Cov}(T, Y) - \text{Cov}(U, Y)\text{Cov}(U, A)}{1 - [\text{Cov}(U, A)]^2} \\ &= \frac{(b + ac) - ((c + ab)a)}{1 - a^2} \\ &= \frac{b + ac - ac - a^2b}{1 - a^2} \\ &= \frac{b(1 - a^2)}{1 - a^2} \\ &= b\end{aligned}$$



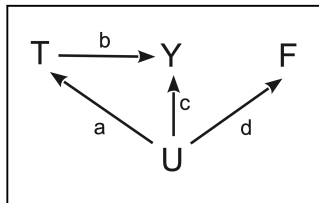


If you don't measure  $U$



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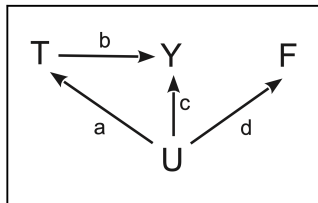
$$\beta = \frac{\text{Cov}(A, Y) - \text{Cov}(\tilde{L}, Y)\text{Cov}(\tilde{L}, A)}{1 - [\text{Cov}(\tilde{L}, A)]^2}$$

$$= \frac{(b + ac) - ((cd + abd)ad)}{1 - a^2d^2}$$

$$= \frac{b + ac - acd^2 - a^2bd^2}{1 - a^2d^2}$$

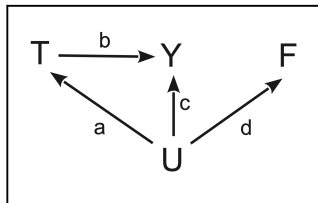
$$= \frac{b(1 - a^2d^2) + ac(1 - d^2)}{1 - a^2d^2}$$

$$= b + \underbrace{ac}_{\text{Bias without control}} \underbrace{\frac{1 - d^2}{1 - a^2d^2}}_{\substack{\text{Bias Multiplier} \\ |M| < 1}}$$



If you don't measure  $U$

$$E(Y \mid A, F) = \alpha + \beta A + \gamma F$$

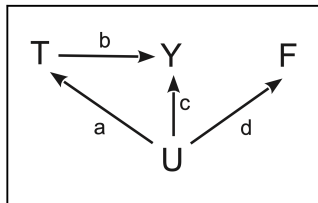


Control Estimator

$$\beta = b + \underbrace{ac}_{\substack{\text{Bias} \\ \text{without} \\ \text{control}}} \underbrace{\frac{1 - d^2}{1 - a^2 d^2}}_{\substack{\text{Bias} \\ \text{Multiplier} \\ |M| < 1}}$$

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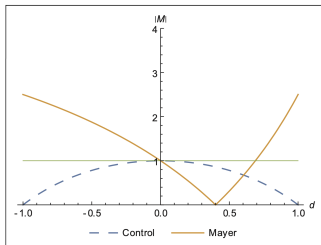
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Difference (Mayer) Estimator

$$\beta - \gamma = b + \underbrace{ac}_{\text{Bias without control}} \underbrace{\frac{a - d}{a - a^2 d}}_{\substack{\text{Bias Multiplier} \\ |M| < 1}}$$

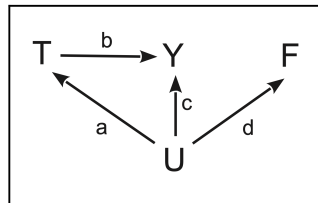
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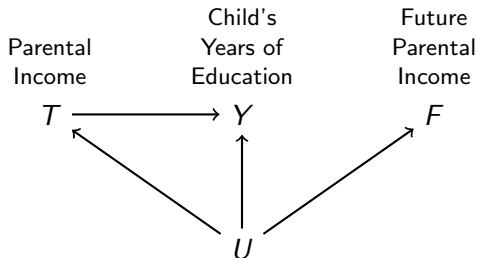
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Parts of the paper we have not yet covered

# Empirical example

What is the effect of log parental income on years of education?



Panel Study of Income Dynamics. Born 1956–1968. ( $n = 1,513$ )

- ▶  $T$  log family income averaged at child age 13–17
- ▶  $Y$  years of education by age 24
- ▶  $F$  log family income at child age 25–29

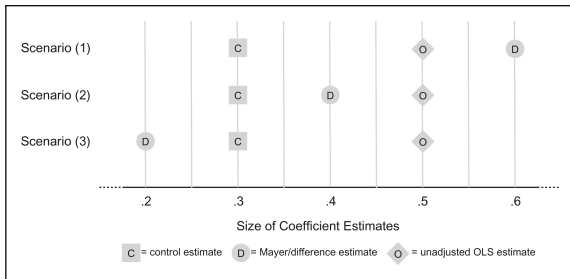


**Table 3.** Estimating the Causal Effect of Parental Income on Children's Years of Education With and Without Future Treatments.

|  | (1)              | (2)              | (3)              | (4)              |
|--|------------------|------------------|------------------|------------------|
| <b>Coefficients</b>  |                  |                  |                  |                  |
| <i>T</i> : Parental income   | .448<br>(.039)** | .319<br>(.049)** | .185<br>(.039)** | .118<br>(.041)** |
| <i>F</i> : Future parental income                                    |                  | .274<br>(.088)** |                  | .202<br>(.076)** |
| <i>X</i> : Controls  |                  |                  | Yes              | Yes              |
| <b>Difference in coefficients</b>                                    |                  |                  |                  |                  |
| <i>T</i> – <i>F</i>  |                  | .045<br>(.126)   |                  | –.084<br>(.098)  |
| <b>Test of equality of coefficients on <i>T</i>: <i>p</i> values</b> |                  |                  |                  |                  |
| Model (1) versus (2):  | .0006            |                  |                  |                  |
| Model (1) versus (3):  | .0000            |                  |                  |                  |
| Model (3) versus (4):  | .0006            |                  |                  |                  |
| Model (1) versus (4):  | .0000            |                  |                  |                  |
| <i>N</i>   | 1,513            | 1,513            | 1,513            | 1,513            |

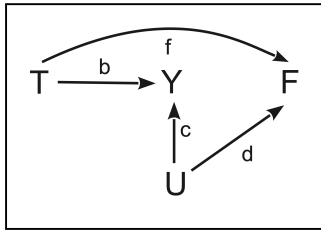
*Note.* Standardized OLS regression coefficients (standard errors in parentheses); weighted. Significance tests for the difference between coefficients across models are using seemingly unrelated regression.

Statistical significance at <sup>†</sup> $p < .10$ . \* $p < .05$ . \*\* $p < .01$ . \*\*\* $p < .001$  (two-tailed test).

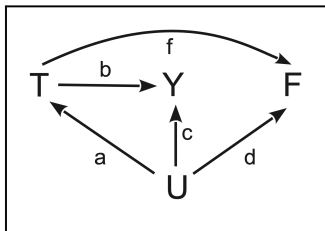


**Figure 4.** Illustration of the heuristic for choosing between estimates. The relative position of the control (C), difference (D), and unadjusted OLS (O) estimates can help the analyst decide between alternative estimates. In data generated by Figure 2, the location of the control estimate indicates the direction of unadjusted OLS bias (in this example, upward bias). In scenarios (1) and (2), the control estimate is preferred. In scenario (3), additional assumptions are needed to decide between the control and difference estimates.

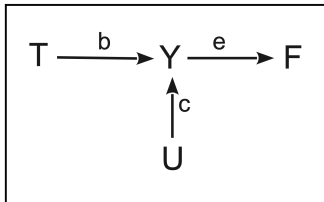
## Challenge 1: True State Dependence



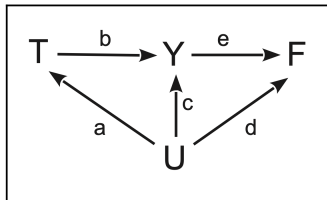
## Challenge 2: Confounded True State Dependence



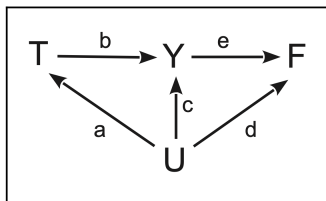
### Challenge 3: Unconfounded Study with Selection



## Challenge 4: Confounded Study with Selection



## Challenge 4: Confounded Study with Selection



**Table 2.** Performance of the Control Estimator and the Mayer/Difference Estimator in the Presence of Selection and Weak to Moderate Path Parameters,  $|p| < .5$ .

| Selection (e)                     | Bias With  |                            |
|-----------------------------------|--|----------------------------|
|                                   | Control Estimator                                  | Mayer/Difference Estimator |
| Selection ( $e \neq 0$ )          | Negligibly amplified or weakly reduced (see below) | Mostly amplified           |
| Mild selection ( $ e  \leq 0.3$ ) | Weakly reduced                                     | Mostly amplified           |

# Nonparametric results

Previous results relied on a linear path model.

Next results rely only on a DAG (nonparametric).



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If and only if  $Y$  is conditionally related to  $F$ ,

then  $T \rightarrow Y$  is confounded.

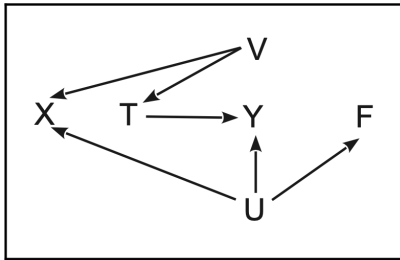
(this will require additional assumptions)

# Nonparametric Example 1.

Want to say: If and only if  $Y$  is conditionally related to  $F$ , then  $T \rightarrow Y$  is confounded

Is  $F$  related to  $Y$ ?

Is  $T \rightarrow Y$  confounded given  $X$ ?



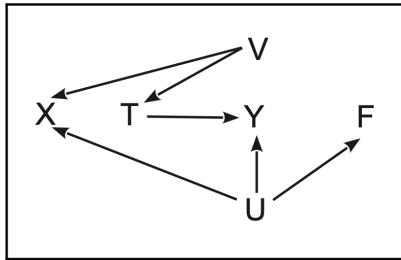
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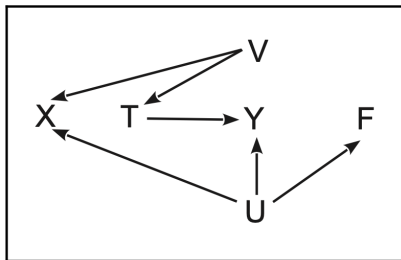
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Yes.  $T \leftarrow V \rightarrow \boxed{X} \leftarrow U \rightarrow Y$



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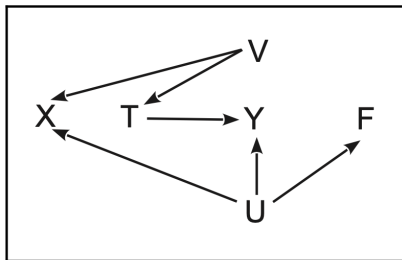
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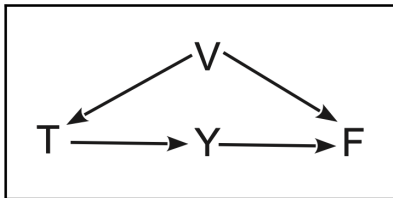
✓ Consistent with what we want to say

## Nonparametric results: Example 2.

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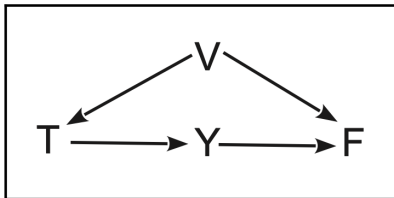
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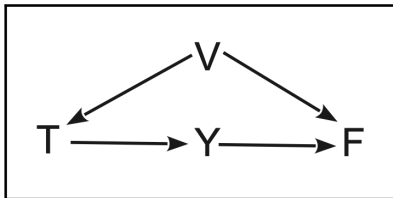
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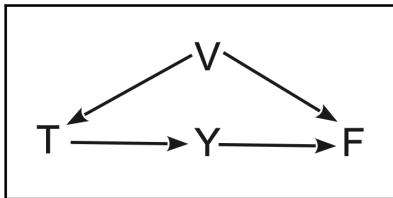
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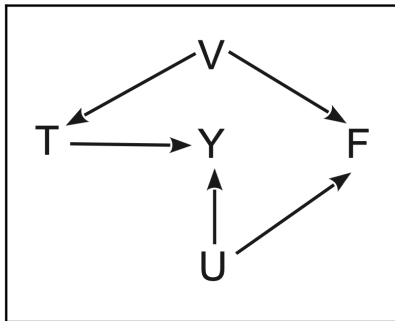
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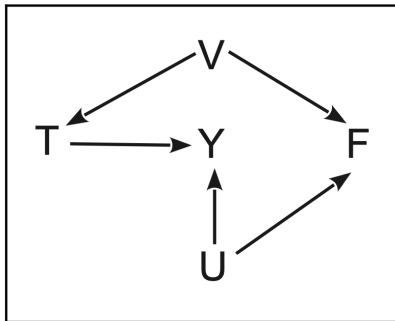
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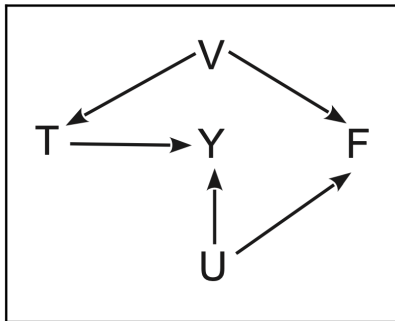
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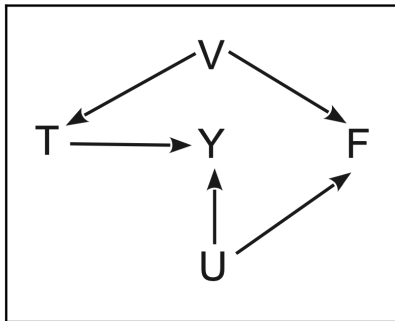
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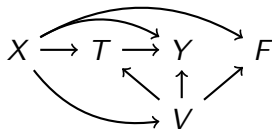
## Two nonparametric results: A formal answer

What does the relationship between  $F$  and  $Y$  tell us about confounding?



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What does the relationship between  $F$  and  $Y$  tell us about confounding?



Result 11. (Requires Assumption 1)

$$F \perp\!\!\!\perp Y \mid \{T, X\} \quad \rightarrow \quad \{Y^0, Y^1\} \perp\!\!\!\perp T \mid X$$

Result 12. (Requires Assumptions 2–3)

$$F \not\perp\!\!\!\perp Y \mid \{T, X\} \quad \rightarrow \quad \{Y^0, Y^1\} \not\perp\!\!\!\perp T \mid X$$

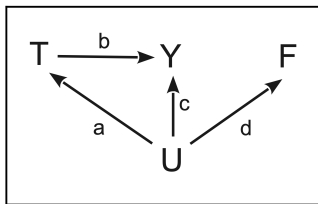
Assumption 1. There exists some unobserved  $V$  such that  
 $V \rightarrow T$  and  $V \not\perp\!\!\!\perp F \mid \{T, X\}$

Assumption 2. All unobserved causes of  $F$  also cause  $T$

Assumption 3.  $Y$  does not directly or indirectly cause  $F$

## Discussion: Applied examples

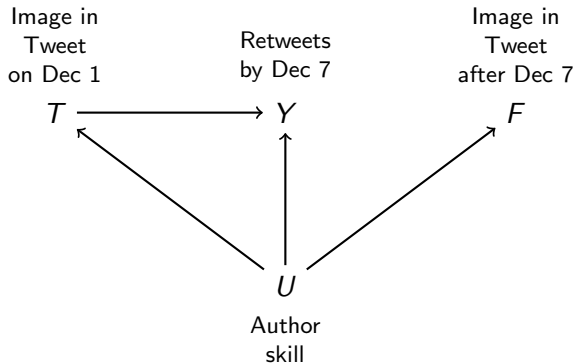
The usefulness of future treatments relies heavily on this DAG.



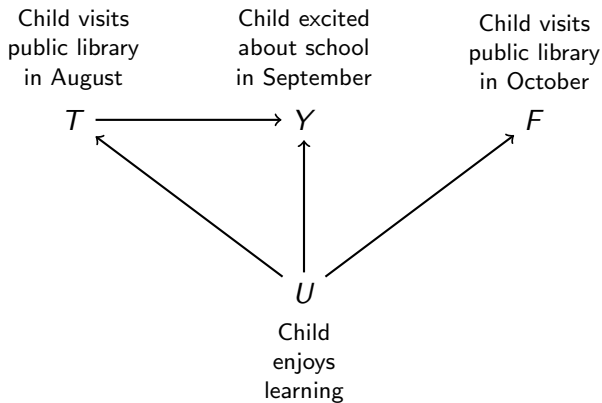
**Exercise.** Discuss the plausibility of this DAG in applied cases.

[tinyurl.com/FutureTreatmentsExamples](http://tinyurl.com/FutureTreatmentsExamples)

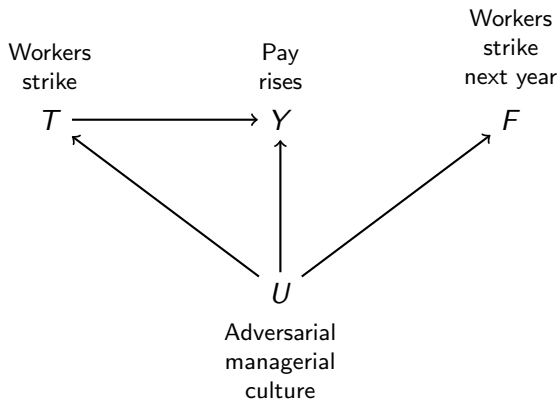
# Group 1



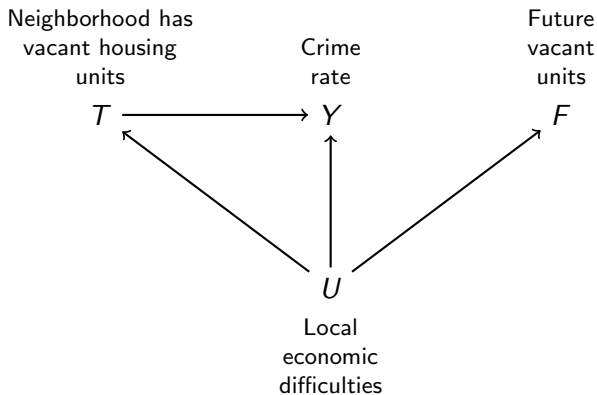
## Group 2



## Group 3



## Group 4



# Learning goals for today

At the end of class, you will be able to:

1. Reason about when future treatments can proxy for unmeasured confounding

Note that this class is based on:

Elwert, F., & Pfeffer, F. T. (2022). [The future strikes back: Using future treatments to detect and reduce hidden bias.](#) *Sociological Methods & Research*, 51(3), 1014-1051.

Feedback from class: [tinyurl.com/CausalQuestions](https://tinyurl.com/CausalQuestions)

No office hours today

**Invitation:** Cornell Sociology Department Colloquium

Friday, 3-4:15pm, Uris G08

Felix Elwert, University of Wisconsin, Madison

Rearranging the Desk Chairs: A Large Randomized  
Field Experiment on the Effects of Close Contact on Interethnic  
Relations