

**HW2**



## § Problem 2

# 2(a)

\*  $u''(x) = f(x), u(0) = u(1) = 1, h = \frac{1}{3}$

$$A = 9 \begin{bmatrix} 1/9 & & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & & 1 & \\ & & & & 1/9 \end{bmatrix}$$


$$\vec{u} = \begin{bmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{bmatrix} \quad \hat{f} = \begin{bmatrix} 1 \\ f(x_1) \\ f(x_2) \\ 1 \end{bmatrix}$$

# 2(b)

# Let  $B$  be the inverse of  $A$ , then columns of  $B$  are  $hG(x_i, x_j)$ , the Greens function to  $h\delta(x-x_j)$ .

$$B_{i,j} = hG(x_i, x_j) = \begin{cases} h(x_j - 1)x_i & i = 1, 2, \dots, j \quad (i \leq j) \\ h(x_i - 1)x_j & i = j, j+1, \dots, m \quad (i \geq j) \\ 0 & i = m+1, 0 \end{cases}$$

for the interior points:

$$B_{i,0} = G_0(x_i) = 1 - x_i \quad B_{i,m+1} = G_1(x_i) = x_i$$

for the first

\*  $A^{-1}$  can be written out as:

$$A^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ \frac{2}{3} & \frac{1}{3}(-\frac{2}{3})(\frac{1}{3}) & \frac{1}{3}(-\frac{1}{3})\frac{1}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3}(\frac{-1}{3})(\frac{1}{3}) & \frac{1}{3}(\frac{-1}{3})\frac{2}{3} & \frac{2}{3} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ \frac{2}{3} & \frac{-2}{27} & \frac{-1}{27} & \frac{1}{3} \\ \frac{1}{3} & \frac{-1}{27} & \frac{-2}{27} & \frac{2}{3} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

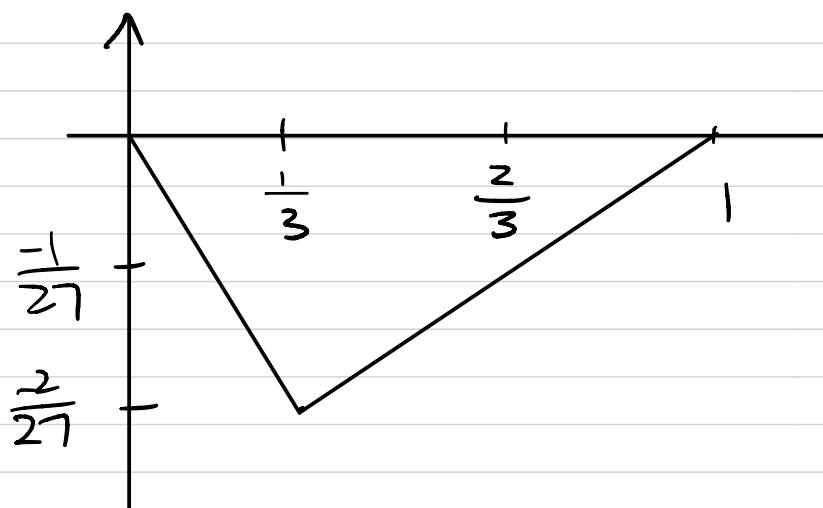
#2(c)

\* Let  $f(x) = x$ , determine discrete approx to this BVP problem.

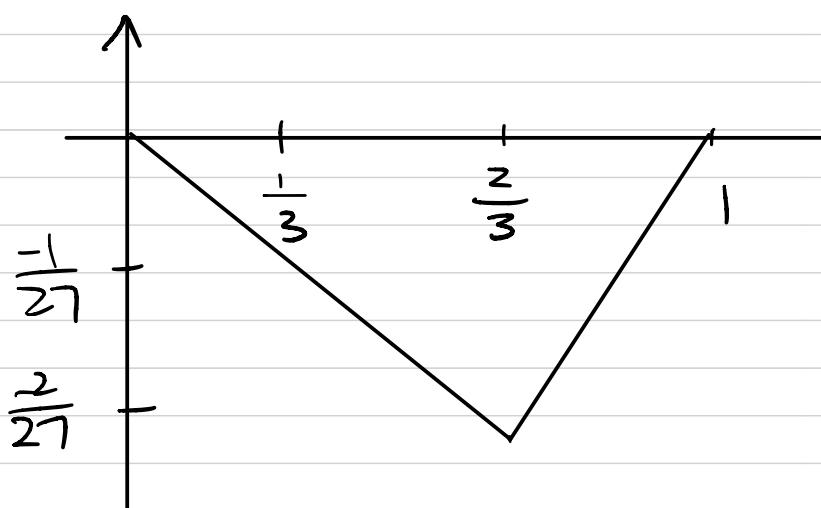
\* Sketch the solution

\* Sketch the 4 Green's function.

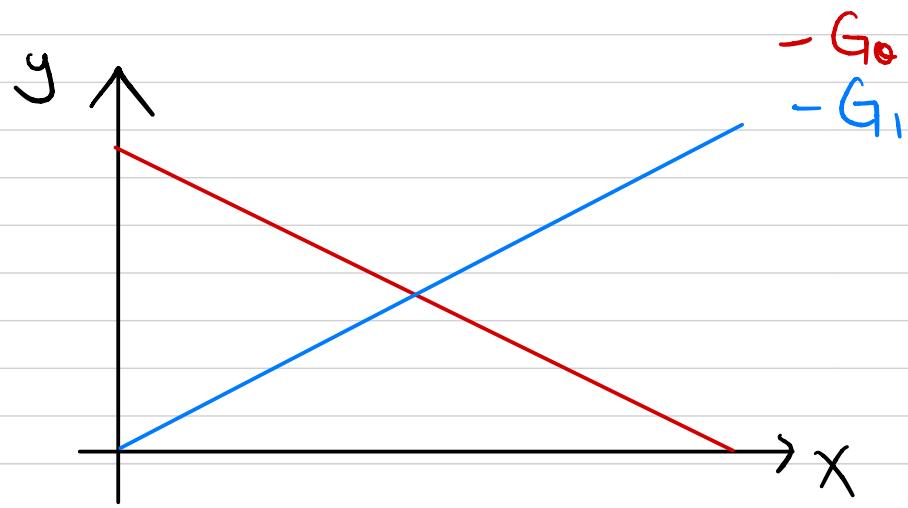
$G(x, \frac{1}{3})$ :



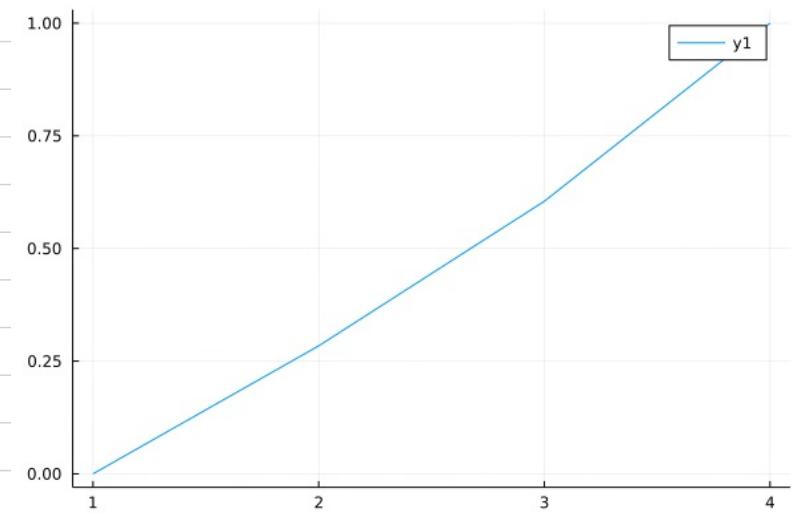
$G(x, \frac{2}{3})$



$G_0(x)$  and  $G_1(x)$



$U$  :: Approximated:



## § Problem 3

\* 3(a)

# Consider:

$$h \sum_{j=0}^m \frac{g(x_j) + g(x_{j+1})}{2} \approx \int_a^b g(x) dx$$

#  $g$  is smooth, then consider Taylor series:

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x) + \mathcal{O}(h^3)$$

# Consider each term in the sum using Taylor expansion:

$$\begin{aligned} & h \frac{g(x_j) + g(x_j + h)}{2} \\ &= \frac{h}{2} \left( 2g(x_j) + hg'(x_j) + \frac{h^2}{2}g''(x_j) + \mathcal{O}(h^3) \right) \\ &= hg(x_j) + \frac{h}{2} \left( hg'(x_j) + \frac{h^2}{2}g''(x_j) + \mathcal{O}(h^3) \right) \\ &= hg(x_j) + \frac{1}{2} \left( h^2g'(x_j) + \frac{h^3}{2}g''(x_j) + \mathcal{O}(h^4) \right) \end{aligned}$$

# which serves an approximation to  $\int_{x_j}^{x_j+h} g(x) dx$ .

# Compute this exact quantity:

$$\int_{x_j}^{x_j+h} g(x) dx = \int_0^h g(x_j + \xi) d\xi$$

sub:  $x = x_j + \xi$

$$= \int_0^h g(x_j) + \xi g'(x_j) + \frac{\xi^2}{2}g''(x_j) + \mathcal{O}(\xi^3) d\xi$$

$$= h g(x_j) + \frac{h^2}{2} g'(x_j) + \frac{h^3}{3!} g''(x_j) + O(h^4)$$

# We used Taylor series and its uniform convergence. What's the local error between integral and discrete sum?

$$\int_{x_j}^{x_j+h} g(x) dx - \frac{h}{2} (g(x_j) + g(x_j + h))$$

$$= h g(x_j) + \frac{h^2}{2} g'(x_j) + \frac{h^3}{3!} g''(x_j) + O(h^4) - \dots$$

$$hg(x_j) - \frac{1}{2} \left( h^2 g'(x_j) + \frac{h^3}{2} g''(x_j) + O(h^4) \right)$$

$$= \frac{h^3}{3!} g''(x_j) - \frac{h^3}{2} g''(x_j) + O(h^4)$$

$$\in O(h^3)$$

# Then the error Globally loses one degree of accuracy because:

$$\int_a^b g(x) dx - \sum_{j=0}^m h \frac{g(x_j) + g(x_{j+1})}{2}$$

$$= \sum_{j=0}^m \int_{x_j}^{x_j+h} g(x) dx - \frac{h}{2} (g(x_j) + g(x_j + h))$$

$$= \sum_{j=0}^m \frac{h^3}{3!} g''(x_j) - \frac{h^3}{2} g''(x_j) + O(h^4)$$

$$= \sum_{j=0}^m g''(x_j) h^3 \left( \frac{-1}{3} \right) + O(h^4)$$

\* Suppose  $\sup_{x \in [0,1]} |g''(x)| \leq M$ ,

$$\Rightarrow \left| \sum_{j=0}^m g''(x_j) h^3 \left( \frac{-1}{3} \right) + O(h^4) \right| \leq h^3 \left( \frac{1}{3} \right) m M + O(h^3)$$

observe:  $m = \frac{b-a}{h}$

$$\Rightarrow h^3 \left( \frac{1}{3} \right) m M + O(h^3) \in O(h^2)$$

# If the second derivative is bounded then the global error is  $O(h^2)$ .

\*3(b)

# The BVP is :  $\begin{cases} u''(x) = f(x) \\ u(0) = u(1) = 0 \end{cases}$

# Solution can be written as:

$$u(x) = \int_0^1 f(\bar{x}) G(x; \bar{x}) d\bar{x} \quad (1)$$

# Using central diff, and solving it gives approximation:

$$u_i = h \sum_{j=1}^m f(x_j) G(x_i | x_j), \quad i=1 \dots m \quad (2)$$

\* Show (2) is the trapz approximation to (1)

$$u(x_i) = \int_0^1 f(\bar{x}) G(x_i | \bar{x}) d\bar{x}$$



$$\approx \sum_{j=0}^m \frac{h}{2} \left( f(x_j) G(x_i | x_j) + f(x_j + h) G(x_i | x_j + h) \right)$$

$$= \sum_{j=0}^m \frac{h}{2} \left( f(x_j) G(x_i | x_j) \right) + \sum_{j=1}^{m+1} \frac{h}{2} \left( f(x_j) G(x_i | x_j) \right)$$

$$= \frac{h}{2} \left( f(x_0) G(x_i | x_0) + f(x_{m+1}) G(x_i | x_{m+1}) \right) + \dots$$

$$\sum_{j=1}^m h f(x_j) G(x_i | x_j)$$

$$= 0 + \sum_{j=1}^m h \left( f(x_j) G(x_i | x_j) \right) = u_i$$

\*Therefore (2) is trapz for  $u(x_i)$

# Since trapz has  $\Theta(h^2)$ ; then  $u_i - u(x_i) \in \Theta(h^2)$  as well.

\* $G(x_i|\bar{x})$  has discontinuous derivative at  $x=x_j$ , why does this not degrade the accuracy of the composite trapezoidal rule?

# Short answer: Because Green's function is discontinuous on one of the grid points  $x_j$ .

# Long answer:

# There is  $\Theta(h^2)$  error when approximating the integral using trapezoid rule locally because:

$$\int_{x_j}^{x_{j+1}} f(\bar{x}) G(x_i|\bar{x}) d\bar{x} = \frac{h}{2} \left( f(x_j) G(x_i|x_j) + f(x_{j+1}) G(x_i|x_{j+1}) \right) + \Theta(h^2)$$

# This is true because  $G(x_i|x_j)$  is a linear function in the interval  $(x_j, x_{j+1})$ , and if  $f(\bar{x})$  has bounded second derivative, then using the analysis from 3(a), the error is  $\Theta(h^3)$  locally, and  $\Theta(h^2)$  globally.

## § Problem 4: Green's function With Neuman Boundary

# 4(a)

#  $u'' = f(x)$ , Neuman Boundary at  $x=0$ , Dirichlet B.C. at  $x=1$

$$\begin{cases} u''(x) = \delta(x - \bar{x}) \\ u'(0) = 0, u(1) = 0 \end{cases}$$

#  $G_0$  solves:

$$\begin{cases} u''(x) = 0 \\ u'(0) = 1, u(1) = 0 \end{cases}$$

$$\iint u(x) dx dx = \iint 0 dx dx$$

$$= \int c dx = Cx + D$$

$$\partial_x(Cx + D) \Big|_{x=0} = 1$$

$$C = 1$$

$$(Cx + D) \Big|_{x=1} = 0$$

$$C + D = 0$$

$$1 + D = 0$$

$$D = -1$$

$$\Rightarrow G_0(x) = x - 1$$

#  $G_1(x)$  solves :

$$\begin{cases} u''(x) = 0 \\ u'(0) = 0, u(1) = 1 \end{cases}$$

# Similar to previous case,  $G_1(x)$  takes the form:  $Cx + D$

$$\partial_x (Cx + D) \Big|_{x=0} = 0$$

$$C = 0$$

$$(Cx + D) \Big|_{x=1} = 1$$

$$D = 1$$

$$D = 1$$

$$\Rightarrow G_1(x) = 1$$

#  $G(x|\bar{x})$  ?

$$\Rightarrow$$

$$\begin{cases} u''(x) = \delta(x - \bar{x}) \\ u'(0) = 0, u(1) = 0 \end{cases}$$

$$\partial_x G(x|\bar{x}) \Big|_{x=0} = 0$$

$$G(1|\bar{x}) = 0$$

$$\forall \varepsilon > 0 : \int_{\bar{x}-\varepsilon}^{\bar{x}+\varepsilon} G''(x|\bar{x}) dx = 1$$

$$= G'(\bar{x}+\varepsilon|\bar{x}) - G'(\bar{x}-\varepsilon|\bar{x}) = 1$$

$$* \int_0^{\bar{x}-\varepsilon} \int_0^{\bar{x}-\varepsilon} G(x|\bar{x}) dx dx \quad \forall x \in [0, \bar{x}-\varepsilon]$$

$$= C_1 x + C_2$$

$$\int_{\bar{x}+\varepsilon}^1 \int_{\bar{x}+\varepsilon}^1 G(x|\bar{x}) dx dx = C_3 x + C_4$$

as  $\varepsilon \rightarrow 0$

$$\Rightarrow G(x|\bar{x}) = \begin{cases} C_1 x + C_2 & x \in [0, \bar{x}] \\ C_3 x + C_4 & x \in [\bar{x}, 1] \end{cases}$$

# Solving for the Coefficients!

# Consider the Boundary Conditions first:

$$* G'(0) = 0 \Rightarrow \partial_x [C_1 x + C_2] \Big|_{x=0} = 0$$

$$C_1 = 0$$

$$* G(1) = 0 \Rightarrow C_3 + C_4 = 0 \Rightarrow$$

$$\Rightarrow G(x|\bar{x}) = \begin{cases} C_2 & x \in [0, \bar{x}] \\ C_3 x - C_3 & x \in [\bar{x}, 1] \end{cases}$$

$$G'(\bar{x}+\varepsilon|\bar{x}) - G'(\bar{x}-\varepsilon|\bar{x}) = 1$$

$$= C_3 - 0 = 1 \Rightarrow C_3 = 1$$

$$\Rightarrow G(x|\bar{x}) = \begin{cases} c_2 & x \in [0, \bar{x}] \\ x-1 & x \in [\bar{x}, 1] \end{cases}$$

#  $G(x|\bar{x})$  continuous!

$$\Rightarrow c_2 = \bar{x} - 1$$

$$\text{Then } G(x|\bar{x}) = \begin{cases} \bar{x} - 1 & x \in [0, \bar{x}] \\ x-1 & x \in [\bar{x}, 1] \end{cases}$$

# Combining the Green's function to get the solutions.

$$G_0(x) \text{ is like } \begin{cases} G''_0(x) = 0 \\ G'_0(0) = 1, G_0(1) = 0 \end{cases}$$

$$G_1(x) \text{ is like: } \begin{cases} G''_1(x) = 0 \\ u'(0) = 0, u(1) = 1 \end{cases}$$

$$G(x|\bar{x}) \text{ is like: } \begin{cases} G''(x|\bar{x}) = \delta(x - \bar{x}) \\ u'(0) = 0, u(1) = 0 \end{cases}$$

# In general Neumann at  $x=0$  and Dirichlet at  $x=1$   
is the system:

$$\begin{cases} u''(x) = f(x) \\ u'(0) = \alpha, u(1) = \beta \end{cases}$$

# Then the solution expressed using Green's function  
will be:

$$u(x) = \alpha G_0(x) + \int_0^1 f(\bar{x}) G(x|\bar{x}) d\bar{x} + \beta G_1(x)$$

# Discretizing it at grid points:  $x_0, x_1, \dots, x_m, x_{m+1}$ , width:  $h$

$$u_i = \alpha G_0(x_i) + \sum_{j=1}^m h f(x_j) G(x_i|x_j) + \beta G_1(x_i)$$

$$\vec{u} = \underbrace{\alpha G_0(\vec{x})}_{\text{first column of } A^{-1}} + \underbrace{\sum_{j=1}^m h f(x_j) G(\vec{x}|x_j)}_{\text{columns in the middle of } A^{-1}} + \underbrace{\beta G_1(\vec{x})}_{\text{last column of } A^{-1}}$$

\* 4(b)

# The inverse for (2.54) should follow the same rule as the inverse for (2.43) in the text which we derived in the lecture.

(2.54) the  $O(h)$  one

$$A = \frac{1}{h^2} \begin{bmatrix} -h & h & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & \ddots & \\ & & \ddots & 1 & -2 & 1 \\ & & & & 0 & h^2 \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ \vdots \\ u_{m-1} \\ u_m \\ u_{m+1} \end{bmatrix} = \begin{bmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{m+1}) \\ f(x_m) \\ B \end{bmatrix}$$

# Similar to (2.43), index starts with zero:

$$(A^{-1})_{:,1} = G_0(\vec{x}) \quad (A^{-1})_{:,m+1} = G_1(\vec{x})$$

$$(A^{-1})_{:,j} = h G(\vec{x}|x_j)$$

# When  $h = \frac{1}{3}$ ,  $x_0, x_1, x_2, x_3 = 0, \frac{1}{3}, \frac{2}{3}, 1$

$$A = 9 \begin{bmatrix} -\frac{1}{3} & \frac{1}{3} & & \\ 1 & -2 & 1 & \\ & 1 & -2 & 1 \\ & & 0 & \frac{1}{9} \end{bmatrix}$$

#Let  $h = \frac{1}{3}$ , then:  $X_0, X_1, X_2, X_3 = 0, \frac{1}{3}, \frac{2}{3}, 1$

$$(A^{-1})_{:,0} = \begin{bmatrix} 0 \\ \frac{1}{3} \\ \frac{2}{3} \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ -\frac{2}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix}$$

$$(A^{-1})_{:,3} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

#Recall:  $G(x|\bar{x}) = \begin{cases} \bar{x} - 1 & x \in [0, \bar{x}] \\ x - 1 & x \in [\bar{x}, 1] \end{cases}$

$$(A^{-1})_{:,1} = \frac{1}{3} G(\bar{x} | \frac{1}{3}) \quad (A^{-1})_{:,2} = \frac{1}{3} G(\bar{x} | \frac{2}{3})$$

$$= \frac{1}{3} \begin{bmatrix} -\frac{2}{3} \\ -\frac{2}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix} \quad = \frac{1}{3} \begin{bmatrix} -\frac{1}{3} \\ -\frac{1}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -1 & \frac{-2}{9} & \frac{-1}{9} & 1 \\ -\frac{2}{3} & \frac{-2}{9} & \frac{-1}{9} & 1 \\ -\frac{1}{3} & \frac{-1}{9} & \frac{-1}{9} & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

## § Problem 5 :

$$A = \frac{1}{h^2} \begin{bmatrix} -h & h & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & \ddots & & \\ & & & 1 & -2 & 1 \\ & & & & h & -h \end{bmatrix}$$

$$A = \frac{1}{h^2} \begin{bmatrix} -h & h(\vec{e}_1^{(m)})^T & 0 & & \\ \vec{e}_1^{(m)} & \tilde{A} & \vec{e}_m^{(m)} & & \\ 0 & h(\vec{e}_m^{(m)})^T & -h & & \end{bmatrix} \quad \tilde{A} = \begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & 1 & \\ & & \ddots & & \\ & & & 1 & -2 \end{bmatrix}$$

$\tilde{A}$  is invertible

$$\tilde{A} = A^T A^{-1} \text{ D.N.E}$$

$$A^T = \frac{1}{h^2} \begin{bmatrix} -h & (\vec{e}_1^{(m)})^T & 0 & & \\ h(\vec{e}_1^{(m)}) & \tilde{A} & h\vec{e}_m^{(m)} & & \\ 0 & (\vec{e}_m^{(m)})^T & -h & & \end{bmatrix}$$

$$= \frac{1}{h^2} \begin{bmatrix} -h & (\vec{e}_1^{(m)})^T & 0 & & \\ h(\vec{e}_1^{(m)}) & \tilde{A} & h\vec{e}_m^{(m)} & & \\ 0 & (\vec{e}_m^{(m)})^T & -h & & \end{bmatrix} \begin{bmatrix} x_1 \\ \vec{y} \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ \vec{0} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -hx_1 + y_1 \\ hxe_1^{(m)} + \tilde{A}\vec{y} + hx_2\vec{e}_m^{(m)} \\ y_m - x_2h \end{bmatrix} = \begin{bmatrix} 0 \\ \vec{0} \\ 0 \end{bmatrix}$$

$$(y_1) = h x_1 \quad x_1 = (y_1)/h$$

$$(y_m) = h x_2 \quad x_2 = (y_m)/h$$

$$h x_1 e_1^{(m)} + \tilde{A} \vec{y} + h x_2 e_m^{(m)}$$

$$= y_1 e_1^{(m)} + \tilde{A} \vec{y} + y_m e_m^{(m)} = \vec{0}$$

$$\tilde{A} \vec{y} = - (y_1) e_1^{(m)} - (y_m) e_m^{(m)}$$

$$(\tilde{A} + e_1 e_1^\top + e_m e_m^\top) \vec{y} = \vec{0}$$

$$\tilde{A} = \begin{bmatrix} -2 & 1 & & & & \\ 1 & -2 & 1 & & & \\ & 1 & -2 & \ddots & & \\ & & & \ddots & 1 & \\ & & & & 1 & \\ & & & & & -2 \end{bmatrix}$$

$$\Rightarrow \tilde{A} + e_1 e_1^\top + e_m e_m^\top = \begin{bmatrix} -1 & 1 & & & \\ 1 & -2 & 1 & & \\ & 1 & -2 & \ddots & \\ & & \ddots & 1 & \\ & & & 1 & -1 \end{bmatrix}$$

# The null space of above system is:

$$\vec{y} = c \vec{1}$$

let  $\vec{y} = c \vec{1}$ , then

$$x_1 = y_1 = x_2 = y_m$$

$$\# N(A^\top) = \text{Span} \left\{ \begin{bmatrix} h \\ -1 \\ \vdots \\ -1 \end{bmatrix} \right\}$$

# § Problem 6

# 6(a)

$$A = \frac{1}{h^2} \begin{bmatrix} -h & h \\ 1 & -2 & 1 \\ & 1 & -2 & 1 \\ & & \ddots & \ddots & 1 \\ & & & 1 & -2 \end{bmatrix}$$

$$DAD^{-1} = D \frac{1}{h^2} \begin{bmatrix} -\frac{h}{d_1} & \frac{h}{d_2} \\ \frac{1}{d_1} & \frac{-2}{d_2} & \frac{1}{d_3} \\ & \frac{1}{d_2} & \frac{-2}{d_3} & \ddots \\ & & \ddots & \frac{1}{d_m} \\ & & & \frac{1}{d_{m-1}} & \frac{-2}{d_m} \end{bmatrix}$$

$$= \frac{1}{h^2} \begin{bmatrix} -\frac{hd_1}{d_1} & \frac{hd_1}{d_2} \\ \frac{d_2}{d_1} & \frac{-2d_2}{d_2} & \frac{d_2}{d_3} \\ & \frac{d_3}{d_2} & \frac{-2d_3}{d_3} & \ddots \\ & & \ddots & \frac{d_{m-1}}{d_m} \\ & & & \frac{dm}{d_{m-1}} & \frac{-2dm}{dm} \end{bmatrix}$$

$$= \frac{1}{h^2} \begin{bmatrix} -h & \frac{hd_1}{d_2} & & & & \\ d_2 & -2 & \frac{d_2}{d_3} & & & \\ & \ddots & \ddots & \ddots & & \\ & & \frac{d_3}{d_2} & -2 & \ddots & \frac{d_{m-1}}{d_m} \\ & & & \ddots & \ddots & \\ & & & & \frac{d_m}{d_{m-1}} & -2 \end{bmatrix}$$

$$\begin{aligned} \frac{hd_1}{d_2} &= \frac{d_2}{d_1} & hd_1^2 &= d_2^2 & \text{let } d_1 = 1 \\ \frac{d_2}{d_3} &= \frac{d_3}{d_2} & d_2^2 &= d_3^2 & \Rightarrow h = d_2^2 \\ \frac{d_3}{d_4} &= \frac{d_4}{d_3} & \vdots & & h^2 = d_3^2 \\ \frac{d_{j-1}}{d_j} &= \frac{d_j}{d_{j-1}} & d_{j-1}^2 &= d_j^2 & h^4 = d_4^2 \\ \vdots & & \vdots & & h^8 = d_4^2 \\ \frac{d_{m-1}}{d_m} &= \frac{d_m}{d_{m-1}} & d_{m-1}^2 &= d_m^2 & \vdots \\ & & & & h^{2^{j-1}} = d_j^2 \\ & & & & \vdots \\ & & & & h^{2^{m-1}} = d_m^2 \end{aligned}$$

$$d_j = h^{\frac{2^{j-1}}{2}} \quad 2 \leq j \leq m-1$$

$$d_1 = 1$$

## §6(b)

# Consider the first 2 rows.

$$\left\{ \begin{array}{l} \frac{1}{h} \left( \frac{3}{2}u_0 - 2u_1 + \frac{1}{2}u_2 \right) = \sigma \\ \frac{1}{h^2} (u_0 - 2u_1 + u_2) = h^2 f(x_1) \end{array} \right.$$

$$\left\{ \begin{array}{l} 3u_0 - 4u_1 + u_2 = 2h\sigma \\ u_0 - 2u_1 + u_2 = h^2 f(x_1) \end{array} \right.$$

$$\rightarrow 3u_0 - 4u_1 + u_2 = 2h\sigma$$

$$u_0 = \frac{1}{3} (2h\sigma + 4u_1 - u_2)$$

$$u_0 - 2u_1 + u_2 = h^2 f(x_1)$$



$$\frac{1}{3} (2h\sigma + 4u_1 - u_2) - 2u_1 + u_2 = h^2 f(x_1)$$

$$2h\sigma + 4u_1 - u_2 - 6u_1 + 3u_2 = 3h^2 f(x_1)$$

$$2h\sigma - 2u_1 + 2u_2 = 3h^2 f(x_1)$$

$$-2u_1 + 2u_2 = 3h^2 f(x_1) - 2h\sigma$$

$$u_2 - u_1 = \frac{3}{2} h^2 f(x_1) - h\sigma$$

$$\Rightarrow \frac{1}{h^2} (u_2 - u_1) = \frac{3}{2} f(x_1) - \frac{\sigma}{h}$$

$$\frac{1}{h^2} (hu_2 - hu_1) = \frac{3h}{2} f(x_1) - \sigma$$

#last 2 Rows of the matrix

$$\left\{ \begin{array}{l} u_{m-1} - 2u_m + u_{m+1} = h^2 f(x_m) \\ u_{m+1} = \beta \\ \hookrightarrow u_{m+1} = \beta \end{array} \right.$$

$$u_{m-1} - 2u_m = h^2 f(x_m) - \beta$$

$$\frac{1}{h^2} (u_{m-1} - 2u_m) = f(x_m) - \frac{\beta}{h^2}$$

#The System now is:

$$A = \frac{1}{h^2} \begin{bmatrix} -h & h & & & & \\ 1 & -2 & 1 & & & \\ & 1 & -2 & 1 & & \\ & & & \ddots & \ddots & \\ & & & & -1 & \\ & & & & & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix} = \begin{bmatrix} \frac{3h}{2} f(x_1) - \sigma \\ f(x_2) \\ \vdots \\ f(x_{m-1}) \\ f(x_m) - \frac{\beta}{h^2} \end{bmatrix}$$

## Yes it's diagonally similar to a symmetric matrix from the last part (a).

