

13. Stochastic and online algorithms

- stochastic gradient method
- online optimization and dual averaging method
- minimizing finite average

Stochastic optimization problem

$$\underset{x \in X}{\text{minimize}} \quad \left\{ F(x) \stackrel{\text{def}}{=} \mathbf{E}_{\xi} f(x, \xi) \right\}$$

- $X \subset \mathbf{R}^n$ is a (bounded) closed convex set
- ξ is a random vector whose distribution P is supported on set $\Xi \subset \mathbf{R}^d$
- $f : X \times \Xi \rightarrow \mathbf{R}$, and the expectation

$$\mathbf{E}_{\xi} f(x, \xi) = \int_{\Xi} f(x, \xi) dP(\xi)$$

is well defined and has finite value for every $x \in X$

- $F(\cdot)$ continuous and convex on X , and optimal value F^* attained at x^* (e.g., $F(\cdot)$ is convex if $f(\cdot, \xi)$ is convex for every $\xi \in \Xi$)

Sample average approximation

$$\underset{x \in X}{\text{minimize}} \quad \left\{ \hat{F}_N(x) \stackrel{\text{def}}{=} \frac{1}{N} \sum_{j=1}^N f(x, \xi_j) \right\}$$

- **assumption:** $\{\xi_j\}_{j=1}^N$ is a sequence of independent random outcomes
- reasonably efficient when solved by appropriate (deterministic) algorithm
- **sample complexity:** suppose f has bounded variation, and let

$$V = \max \{ f(x_1, \xi_1) - f(x_2, \xi_2) : x_1, x_2 \in X, \xi_1, \xi_2 \in \Xi \}$$

then for any $\epsilon > 0$ and $\rho \in (0, 1)$, sample size $N = \lceil \frac{V^2}{2\epsilon^2} \ln \frac{2}{\rho} \rceil$ guarantees

$$\mathbf{prob}(|\hat{F}_N(x) - F(x)| \leq \epsilon) \geq 1 - \rho, \quad \forall x \in X$$

(proved using Hoeffding inequality in probability theory)

Stochastic approximation

choose $x^{(1)} \in X$, and iterate for $k = 1, 2, \dots$

$$x^{(k+1)} = \pi_X \left(x^{(k)} - t_k g(x^{(k)}, \xi_k) \right)$$

- $g(x, \xi)$ is a *stochastic subgradient*, i.e., $g(x, \xi) \in \partial_x f(x, \xi)$ and

$$F'(x) \stackrel{\text{def}}{=} \mathbf{E}_\xi g(x, \xi) \in \partial F(x)$$

assumption: there exist a constant G such that

$$\mathbf{E}_\xi [\|g(x, \xi)\|_2^2] \leq G^2, \quad \forall x \in X$$

- $\pi_X(\cdot)$ denotes projection onto X :

$$\pi_X(x) = \operatorname{argmin}_{y \in X} \|y - x\|_2^2$$

Convergence analysis

consider squared distance to x^\star , and let $r_k = \mathbf{E}[\|x^{(k)} - x^\star\|_2^2]$

$$\begin{aligned}\|x^{(k+1)} - x^\star\|_2^2 &= \|\pi_X(x^{(k)} - t_k g(x^{(k)}, \xi_k)) - \pi_X(x^\star)\|_2^2 \\ &\leq \|x^{(k)} - t_k g(x^{(k)}, \xi_k) - x^\star\|_2^2 \\ &= \|x^{(k)} - x^\star\|_2^2 - 2t_k (x^{(k)} - x^\star)^T g(x^{(k)}, \xi_k) + t_k^2 \|g(x^{(k)}, \xi_k)\|_2^2\end{aligned}$$

since $x^{(k)}$ is a function of $\xi_{[k-1]} = (\xi_0, \dots, \xi_{k-1})$, it is independent of ξ_k

$$\begin{aligned}\mathbf{E}[(x^{(k)} - x^\star)^T g(x^{(k)}, \xi_k)] &= \mathbf{E}\{\mathbf{E}[(x^{(k)} - x^\star)^T g(x^{(k)}, \xi_k) \mid \xi_{[k-1]}]\} \\ &= \mathbf{E}\{(x^{(k)} - x^\star)^T \mathbf{E}[g(x^{(k)}, \xi_k) \mid \xi_{[k-1]}]\} \\ &= \mathbf{E}[(x^{(k)} - x^\star)^T F'(x^{(k)})]\end{aligned}$$

therefore

$$r_{k+1} \leq r_k - 2t_k \mathbf{E}[(x^{(k)} - x^\star)^T F'(x^{(k)})] + t_k^2 G^2 \quad (1)$$

by convexity of F , it holds $F(x^*) \geq F(x^{(k)}) + (x^* - x^{(k)})^T F'(x^{(k)})$, hence

$$\mathbf{E}[(x^{(k)} - x^*)^T F'(x^{(k)})] \geq \mathbf{E}[F(x^{(k)}) - F^*]$$

combining with (1) gives

$$t_k \mathbf{E}[F(x^{(k)}) - F^*] \leq \frac{1}{2}(r_k - r_{k+1} + t_k^2 G^2)$$

summing over $j = 1, \dots, k$ yields

$$\sum_{j=1}^k t_j \mathbf{E}[F(x^{(j)}) - F^*] \leq \frac{1}{2} \left(r_1 - r_{k+1} + G^2 \sum_{j=1}^k t_j^2 \right) \leq \frac{1}{2} \left(r_1 + G^2 \sum_{j=1}^k t_j^2 \right)$$

let $\nu_j^{(k)} = \frac{t_j}{\sum_{i=1}^k t_i}$ and $\tilde{x}^{(k)} = \sum_{j=1}^k \nu_j^{(k)} x^{(j)}$ (note $\sum_{j=1}^k \nu_j^{(k)} = 1$), then

$$\mathbf{E}[F(\tilde{x}^{(k)}) - F^*] \leq \mathbf{E} \left[\sum_{j=1}^k \nu_j^{(k)} F(x^{(j)}) - F^* \right] \leq \frac{r_1 + G^2 \sum_{j=1}^k t_j^2}{2 \sum_{j=1}^k t_j}$$

Fixed step size

suppose the number of iterations N is known in advance, then

$$\mathbf{E}[F(\tilde{x}^{(k)}) - F^*] \leq \frac{D^2 + G^2 N t^2}{2Nt}$$

where $D = \max_{x \in X} \|x - x^*\|_2$, so that $r_1 = \mathbf{E}\|x^{(1)} - x^*\|_2^2 \leq D^2$

- minimizing upper bound over $t > 0$ gives $t = \frac{D}{G\sqrt{N}}$ and

$$\mathbf{E}[F(\tilde{x}^{(k)}) - F^*] \leq \frac{DG}{\sqrt{N}}$$

- if $t = \frac{\theta D}{G\sqrt{N}}$ for some constant $\theta > 0$, then

$$\mathbf{E}[F(\tilde{x}^{(k)}) - F^*] \leq \max\{\theta, \theta^{-1}\} \frac{DG}{\sqrt{N}}$$

therefore, $O(1/\sqrt{N})$ convergence *robust* against step size choices

Diminishing step size

following the halving trick in deterministic subgradient method, redefine

$$\tilde{x}^{(k)} = \frac{\sum_{k/2 \leq j \leq k} t_j x^{(j)}}{\sum_{k/2 \leq j \leq k} t_j}$$

if the step sizes are chosen as

$$t_k = \frac{\theta D}{G\sqrt{k}}$$

then the following holds with a constant $C > 1$

$$\mathbf{E}[F(\tilde{x}^{(k)}) - F^*] \leq C \max\{\theta, \theta^{-1}\} \frac{DG}{\sqrt{k}}$$

$O(1/\sqrt{k})$ convergence rate is optimal for general convex functions

Analysis for strongly convex functions

assume $F = \mathbf{E}_\xi f(x, \xi)$ is differentiable and strongly convex

$$F(y) \geq F(x) + \nabla F(x)^T (y - x) + \frac{\mu}{2} \|y - x\|_2^2 \quad \forall x, y \in X$$

or equivalently

$$(x - y)^T (\nabla F(x) - \nabla F(y)) \geq \mu \|x - y\|_2^2, \quad \forall x, y \in X$$

by optimality of x^\star ,

$$(x - x^\star)^T \nabla F(x^\star) \geq 0, \quad \forall x \in X$$

therefore

$$(x - x^\star)^T \nabla F(x) \geq \mu \|x - x^\star\|_2^2, \quad \forall x \in X \quad (2)$$

combining (1) and (2) gives

$$r_{k+1} \leq (1 - 2\mu t_k)r_k + t_k^2 G^2$$

let's take step size $t_k = \theta/k$ for some constant $\theta > 1/(2\mu)$, then

$$r_{k+1} \leq (1 - 2\mu\theta/k)r_k + \theta^2 G^2/k^2$$

- it follows by induction that (Nemirovski et al. 2009)

$$\mathbf{E}[\|x^{(k)} - x^*\|_2^2] = r_k \leq \frac{Q(\theta)}{k}$$

where $Q(\theta) = \max\{\theta^2 G^2 (2\mu\theta - 1)^{-1}, \|x^{(1)} - x^*\|_2^2\}$

- if in addition ∇F is Lipschitz continuous with constant $L > 0$, then

$$\mathbf{E}[F(x^{(k)}) - F^*] \leq \frac{L}{2} \mathbf{E}[\|x^{(k)} - x^*\|_2^2] \leq \frac{LQ(\theta)}{2k}$$

Sensitivity to priori knowledge of μ

example: let $F(x) = x^2/10$, $X = [-1, 1]$, $\mu = 0.2$, and there is no noise

- if $\theta = 1$ (which violates the condition $\theta > 1/(2\mu)$), then

$$x^{(k+1)} = x^{(k)} - \frac{1}{k}F'(x^{(k)}) = \left(1 - \frac{1}{5k}\right) x^{(k)}$$

starting with $x^{(1)} = 1$ leads to

$$x^{(k)} > 0.8k^{-1/5}$$

error is larger than 0.015 even after 10^9 iterations!

- if $\theta = 1/\mu = 5$, then $x^* = 0$ is obtained in one iteration
- step size $t_k = \theta/k$ too small if F is not strongly convex

Outline

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- **online optimization and dual averaging method**
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Online convex optimization

- explained as online game: for $k = 1, 2, 3, \dots$,
 - player chooses $x^{(k)} \in X$ based on previous information
 - adversary reveals cost function f_k , and player incurs loss $f_k(x^{(k)})$
- assumptions: f_k convex; X bounded, closed and convex

- player wants to minimize *regret*:

$$R_N \triangleq \sum_{k=1}^N (f_k(x^{(k)})) - \min_{x \in X} \left\{ \sum_{k=1}^N f_k(x) \right\}$$

- online subgradient method

$$x^{(k+1)} = \pi_X(x^{(k)} - t_k g^{(k)}), \quad g^{(k)} \in \partial f_k(x^{(k)})$$

with appropriate step size, can show $R_N \leq O(\sqrt{N})$

Connection to stochastic approximation

- a more general framework without stochastic assumptions
- suppose $f_k(x) \stackrel{\text{def}}{=} f(x, \xi_k)$, and let $\bar{x}^{(N)} = \frac{1}{N} \sum_{k=1}^N x^{(k)}$, then

$$F(\bar{x}^{(N)}) - F^* \leq \frac{1}{N} \mathbf{E}[R_N]$$

proof:

$$\begin{aligned} F(\bar{x}^{(N)}) - F^* &\leq \frac{1}{N} \sum_{k=1}^N \left(F(x^{(k)}) - F^* \right) \\ &= \frac{1}{N} \sum_{k=1}^N \left(\mathbf{E}[f(x^{(k)}, \xi_k)] - \min_x \mathbf{E}[f(x, \xi_k)] \right) \\ &= \frac{1}{N} \mathbf{E} \left[\sum_{k=1}^N \left(f(x^{(k)}, \xi_k) - f(x^*, \xi_k) \right) \right] \end{aligned}$$

Dual averaging method (Nesterov)

initialize: choose $x^{(1)} \in \mathbf{R}^n$ and set $s^{(0)} = 0$

iterate for $k = 0, 1, 2, \dots$

1. compute $g^{(k)} \in \partial f_k(x^{(k)})$ and set

$$s^{(k)} = s^{(k-1)} + g^{(k)}$$

$$\begin{aligned} \text{2. update: } x^{(k+1)} &= \operatorname{argmin}_{x \in X} \left\{ \langle s^{(k)}, x \rangle + \frac{\beta_k}{2} \|x - x^{(0)}\|_2^2 \right\} \\ &= \pi_X \left(x^{(0)} - \frac{1}{\beta_k} s^{(k)} \right) \end{aligned}$$

- choice of $\{\beta_k\}$: e.g., $\beta_k = \gamma\sqrt{k}$ with $\gamma > 0$
- can also work with composite objectives: $\operatorname{minimize}_x f(x) + \Psi(x)$

A soft support function

for any $\beta \geq 0$ and any $x^{(0)} \in X$, define

$$V_\beta(s) = \max_{x \in X} \left\{ \langle s, x - x^{(0)} \rangle - \frac{\beta}{2} \|x - x^{(0)}\|_2^2 \right\}$$

- $V_\beta(s) \geq 0$ for any $\beta \geq 0$; if $\beta_2 \geq \beta_1 > 0$, then $V_{\beta_2}(s) \leq V_{\beta_1}(s)$
- $V_\beta(\cdot)$ is convex and differentiable
- ∇V_β is Lipschitz continuous with constant $1/\beta$

$$\|\nabla V_\beta(s_1) - \nabla V_\beta(s_2)\|_2 \leq \frac{1}{\beta} \|s_1 - s_2\|_2, \quad \forall s_1, s_2 \in \mathbf{R}^n$$

therefore

$$V_\beta(s + \delta) \leq V_\beta(s) + \langle \delta, \nabla V_\beta(s) \rangle + \frac{1}{2\beta} \|\delta\|_2^2$$

lemma: let $D = \max_{x \in X} \|x - x^{(0)}\|_2$, then

$$\max_{x \in X} \langle s, x - x^{(0)} \rangle \leq \frac{\beta D^2}{2} + V_\beta(s)$$

proof:

$$\begin{aligned} \max_{x \in X} \langle s, x - x^{(0)} \rangle &= \max_{x \in X} \left\{ \langle s, x - x^{(0)} \rangle : \frac{1}{2} \|x - x^{(0)}\|_2^2 \leq \frac{1}{2} D^2 \right\} \\ &= \max_{x \in X} \min_{\beta \geq 0} \left\{ \langle s, x - x^{(0)} \rangle + \frac{\beta}{2} (D^2 - \|x - x^{(0)}\|_2^2) \right\} \\ &\leq \min_{\beta \geq 0} \max_{x \in X} \left\{ \langle s, x - x^{(0)} \rangle + \frac{\beta}{2} (D^2 - \|x - x^{(0)}\|_2^2) \right\} \\ &\leq \max_{x \in X} \left\{ \langle s, x - x^{(0)} \rangle + \frac{\beta}{2} (D^2 - \|x - x^{(0)}\|_2^2) \right\} \\ &\leq \frac{\beta D^2}{2} + V_\beta(s) \end{aligned}$$

Convergence analysis

$$\begin{aligned} V_{\beta_k}(-s^{(k)}) &\leq V_{\beta_{k-1}}(-s^{(k)}) \\ &\leq V_{\beta_{k-1}}(-s^{(k-1)}) + \langle -g^{(k)}, \nabla V_{\beta_{k-1}}(-s^{(k-1)}) \rangle + \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2 \\ &= V_{\beta_{k-1}}(-s^{(k-1)}) - \langle g^{(k)}, x^{(k)} - x^{(0)} \rangle + \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2 \end{aligned}$$

therefore

$$\langle g^{(k)}, x^{(k)} - x^{(0)} \rangle \leq V_{\beta_{k-1}}(-s^{(k-1)}) - V_{\beta_k}(-s^{(k)}) + \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2$$

summing over $k = 2, \dots, N$ and choose $x^{(0)} = x^{(1)}$ results in

$$\sum_{k=1}^N \langle g^{(k)}, x^{(k)} - x^{(0)} \rangle \leq V_{\beta_1}(-s^{(1)}) - V_{\beta_N}(-s^{(N)}) + \sum_{k=2}^N \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2$$

$$\begin{aligned}
\delta_N &\stackrel{\text{def}}{=} \max_{x \in X} \sum_{k=1}^N \langle g^{(k)}, x^{(k)} - x \rangle \\
&= \sum_{k=1}^N \langle g^{(k)}, x^{(k)} - x^{(0)} \rangle + \max_{x \in X} \sum_{k=1}^N \langle g^{(k)}, x^{(0)} - x \rangle \\
&= \sum_{k=1}^N \langle g^{(k)}, x^{(k)} - x^{(0)} \rangle + \max_{x \in X} \langle -s^{(N)}, x - x^{(0)} \rangle \\
&\leq V_{\beta_1}(-s^{(1)}) - V_{\beta_N}(-s^{(N)}) + \sum_{k=2}^N \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2 + \frac{\beta_N D^2}{2} + V_{\beta_N}(-s^{(N)}) \\
&\leq \frac{1}{2\beta_1} \|g^{(1)}\|_2^2 + \sum_{k=2}^N \frac{1}{2\beta_{k-1}} \|g^{(k)}\|_2^2 + \frac{\beta_N D^2}{2} \\
&\leq \frac{\beta_N D^2}{2} + \sum_{k=0}^{N-1} \frac{G^2}{2\beta_k} \quad (\text{for convenience, define } \beta_0 = \beta_1)
\end{aligned}$$

by convexity,

$$\begin{aligned}\delta_N &\stackrel{\text{def}}{=} \max_{x \in X} \sum_{k=1}^N \langle g^{(k)}, x^{(k)} - x \rangle \\ &\geq \max_{x \in X} \sum_{k=1}^N (f_k(x^{(k)}) - f_k(x)) \\ &= \sum_{k=1}^N f_k(x^{(k)}) - \min_{x \in X} \sum_{k=1}^N f_k(x)\end{aligned}$$

therefore, $R_N \leq \delta_N$, so

$$R_N \stackrel{\text{def}}{=} \sum_{k=1}^N f_k(x^{(k)}) - \min_{x \in X} \sum_{k=1}^N f_k(x) \leq \frac{\beta_N D^2}{2} + \sum_{k=0}^{N-1} \frac{G^2}{2\beta_k}$$

choose parameters

$$\beta_k = \gamma\sqrt{k}, \quad k \geq 1$$

and let $\beta_0 = \beta_1$, then

$$\sum_{k=0}^{N-1} \frac{G^2}{2\beta_k} = \frac{G^2}{2\gamma} \left(1 + \sum_{k=1}^{N-1} \frac{1}{\sqrt{k}} \right) \leq \frac{G^2}{2\gamma} \left(2 + \int_1^N \frac{1}{\sqrt{t}} dt \right) = \frac{G^2\sqrt{N}}{\gamma}$$

finally,

$$R_N \leq \left(\gamma \frac{D^2}{2} + \frac{G^2}{\gamma} \right) \sqrt{N}$$

upper bound is minimized by choosing

$$\gamma^* = \sqrt{2} \frac{G}{D}$$

which yields

$$R_N \leq \sqrt{2} G D \sqrt{N}$$

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- **minimizing finite average**

Minimizing finite average of convex functions

problem

$$\text{minimize} \quad F(x) \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n f_i(x)$$

stochastic gradient method: pick $i_k \in \{1, \dots, n\}$ randomly and update

$$x_{k+1} = x_k - \eta_k \nabla f_{i_k}(x_k)$$

two perspectives:

- *stochastic optimization*: viewed as trying to minimize $\mathbf{E}_\xi f(x, \xi)$
- *deterministic optimization*: a randomized incremental gradient method for a structured convex problem

Note the problem structure

stochastic optimization perspective:

- complexity theory: $O(\frac{1}{\epsilon^2})$, or $O(\frac{1}{\epsilon})$ with strong convexity

deterministic optimization perspective:

- sanity check: should at least beat full gradient methods:
complexity $O(n \frac{L}{\mu} \log \frac{1}{\epsilon})$ or $O(n \sqrt{\frac{L}{\mu}} \log \frac{1}{\epsilon})$
- recent progress: SAG and SVRG by exploiting finite average structure

Stochastic average gradient (SAG)

- SAG method (Le Roux, Schmidt, Bach 2012)

$$x_{k+1} = x_k - \frac{\alpha_k}{n} \sum_{i=1}^n g_k^{(i)}$$

where

$$g_k^{(i)} = \begin{cases} \nabla f_i(x_k) & \text{if } i = i_k \\ g_{k-1}^{(i)} & \text{otherwise} \end{cases}$$

- a randomized variant of incremental aggregated gradient (IAG) of Blatt, Hero, & Gauchman (2007)
- complexity (# component gradient evaluations): $O(\max\{n, \frac{L}{\mu}\} \log \frac{1}{\epsilon})$
cf. full gradient method: $O(n \frac{L}{\mu} \log \frac{1}{\epsilon})$, and stochastic gradient: $O(\frac{1}{\epsilon})$
- need to store most recent gradient of each component, but can be avoided for some structured problems

Stochastic variance reduced gradient (SVRG)

- SVRG (Johnson & Zhang 2013, Mahdavi, Zhang & Jin 2013)

$$x_{k+1} = x_k - \eta(\nabla f_{i_k}(x_k) - \nabla f_{i_k}(\tilde{x}) + \nabla F(\tilde{x}))$$

and update \tilde{x} periodically (every few passes)

- still a stochastic gradient method

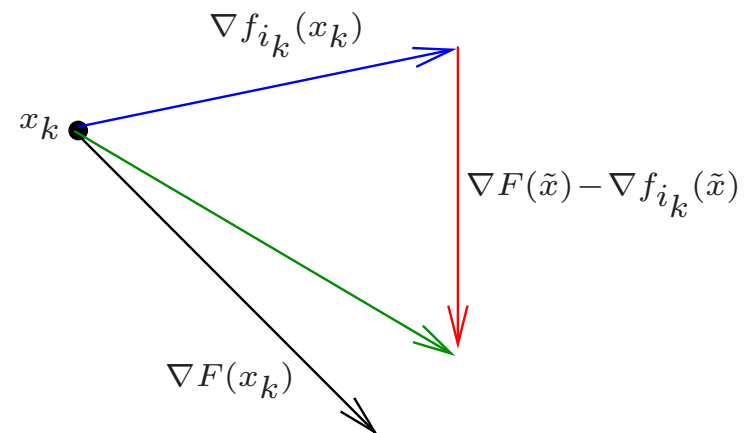
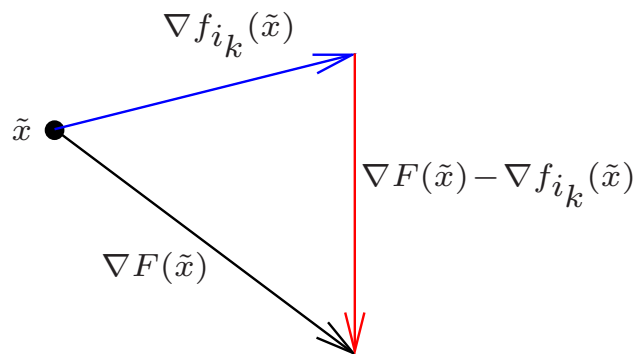
$$\begin{aligned} & \mathbf{E}[\nabla f_{i_k}(x_k) - \nabla f_{i_k}(\tilde{x}) + \nabla F(\tilde{x})] \\ &= \nabla F(x_k) - \nabla F(\tilde{x}) + \nabla F(\tilde{x}) \\ &= \nabla F(x_k) \end{aligned}$$

- expected update direction is the same as $\mathbf{E} f_{i_k}(x_k)$
- variance can be diminishing if \tilde{x} updated periodically

- complexity: $O\left((n + \frac{L}{\mu}) \log \frac{1}{\epsilon}\right)$, cf. SAG: $O\left(\max\{n, \frac{L}{\mu}\} \log \frac{1}{\epsilon}\right)$

Stochastic variance reduced gradient (SVRG)

- computational cost per iteration:
 - unlike SAG, no need to store gradients for each component
 - need to compute two gradients at each iteration, and also full gradient periodically
 - for many structured problems, two gradients at each iteration can be reduced to only one
- intuition of variance reduction



Problem statement and assumptions

$$\underset{x \in \mathbf{R}^d}{\text{minimize}} \quad F(x) = \frac{1}{n} \sum_{i=1}^n f_i(x)$$

assumptions:

- each $f_i(x)$, for $i = 1, \dots, n$, is convex
- each $f_i(x)$ is smooth with Lipschitz constant L

$$\|\nabla f_i(x) - \nabla f_i(y)\| \leq L\|x - y\|$$

(which implies that $\nabla F(x)$ also has Lipschitz constant L)

- $F(x)$ strongly convex: for all $x, y \in \mathbf{R}^d$,

$$F(y) \geq F(x) + \nabla F(x)^T(y - x) + \frac{\mu}{2}\|y - x\|^2$$

SVRG method

input: \tilde{x}_0, η, m

iterate: for $s = 1, 2, \dots$

$$\tilde{x} = \tilde{x}_{s-1}$$

$$\tilde{v} = \nabla F(\tilde{x})$$

$$x_0 = \tilde{x}$$

iterate: for $k = 1, 2, \dots, m$

pick $i_k \in \{1, \dots, n\}$ uniformly at random

$$x_k = x_{k-1} - \eta(\nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(\tilde{x}) + \tilde{v})$$

end

$$\text{set } \tilde{x}_s = \frac{1}{m} \sum_{k=1}^m x_{k-1}$$

end

Convergence analysis of SVRG

- **theorem:** suppose $0 < \eta \leq 1/2L$ and m sufficiently large so that

$$\rho = \frac{1}{\mu\eta(1 - 2L\eta)m} + \frac{2L\eta}{1 - 2L\eta} < 1$$

then we have geometric convergence in expectation:

$$\mathbf{E}F(\tilde{x}_s) - F(x_\star) \leq \rho^s[F(\tilde{x}_0) - F(x_\star)]$$

- *more concretely*, if $\eta = \theta/L$, then

$$\rho = \frac{L/\mu}{\theta(1 - 2\theta)m} + \frac{2\theta}{1 - 2\theta}$$

choosing $\theta = 0.1$ and $m = 50(L/\mu)$ results in $\rho = 1/2$

- overall complexity: $O\left(\left(\frac{L}{\mu} + n\right) \log\left(\frac{1}{\epsilon}\right)\right)$

Proof

- let $g_k = \nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(\tilde{x}) + \nabla F(\tilde{x})$, then

$$x_k = x_{k-1} - \eta g_k, \quad \text{and} \quad \mathbf{E}_{i_k}[g_k] = \nabla F(x_{k-1})$$

- similar as in classical analysis of stochastic gradient methods

$$\begin{aligned} \mathbf{E}\|x_k - x_\star\|^2 &= \mathbf{E}\|x_{k-1} - \eta g_k - x_\star\|^2 \\ &= \|x_{k-1} - x_\star\|^2 - 2\eta(x_{k-1} - x_\star)^T \mathbf{E}[g_k] + \eta^2 \mathbf{E}[\|g_k\|^2] \\ &= \|x_{k-1} - x_\star\|^2 - 2\eta(x_{k-1} - x_\star)^T \nabla F(x_{k-1}) + \eta^2 \mathbf{E}[\|g_k\|^2] \\ &\leq \|x_{k-1} - x_\star\|^2 - 2\eta(F(x_{k-1}) - F(x_\star)) + \eta^2 \mathbf{E}[\|g_k\|^2] \end{aligned}$$

then need to bound $\mathbf{E}[\|g_k\|^2]$ carefully using the finite average structure

- by smoothness of $f_i(x)$,

$$\|\nabla f_i(x) - \nabla f_i(x_\star)\|^2 \leq 2L[f_i(x) - f_i(x_\star) - \nabla f_i(x_\star)^T(x - x_\star)]$$

- summing above inequalities over $i = 1, \dots, n$ and using $\nabla F(x_\star) = 0$,

$$\frac{1}{n} \sum_{i=1}^n \|\nabla f_i(x) - \nabla f_i(x_\star)\|^2 \leq 2L[F(x) - F(x_\star)]$$

$$\begin{aligned} \mathbf{E}\|g_k\|^2 &= \mathbf{E}\|\nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(x_\star) + \nabla f_{i_k}(x_\star) - \nabla f_{i_k}(\tilde{x}) + \nabla F(\tilde{x})\|^2 \\ &\leq 2\mathbf{E}\|\nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(x_\star)\|^2 + 2\mathbf{E}\|\nabla f_{i_k}(\tilde{x}) - \nabla f_{i_k}(x_\star) - \nabla F(\tilde{x})\|^2 \\ &= 2\mathbf{E}\|\nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(x_\star)\|^2 \\ &\quad + 2\mathbf{E}\|\nabla f_{i_k}(\tilde{x}) - \nabla f_{i_k}(x_\star) - \mathbf{E}[\nabla f_{i_k}(\tilde{x}) - \nabla f_{i_k}(x_\star)]\|^2 \\ &\leq 2\mathbf{E}\|\nabla f_{i_k}(x_{k-1}) - \nabla f_{i_k}(x_\star)\|^2 + 2\mathbf{E}\|\nabla f_{i_k}(\tilde{x}) - \nabla f_{i_k}(x_\star)\|^2 \\ &\leq 4L[F(x_{k-1}) - F(x_\star) + F(\tilde{x}) - F(x_\star)] \end{aligned}$$

continue derivation on page 13–29

$$\mathbf{E}\|x_k - x_\star\|^2 \leq \|x_{k-1} - x_\star\|^2 - 2\eta(1 - 2L\eta)[F(x_{k-1}) - F(x_\star)] + 4L\eta^2[F(\tilde{x}) - F(x_\star)]$$

summing over $k = 1, \dots, m$, and take expectation w.r.t. whole history

$$\begin{aligned} & \mathbf{E}\|x_m - x_\star\|^2 + 2\eta(1 - 2L\eta) \sum_{k=0}^{m-1} \mathbf{E}[F(x_k) - F(x_\star)] \\ & \leq \mathbf{E}\|x_0 - x_\star\|^2 + 4Lm\eta^2 \mathbf{E}[F(x_0) - F(x_\star)] \\ & \leq \frac{2}{\mu} \mathbf{E}[F(x_0) - F(x_\star)] + 4Lm\eta^2 \mathbf{E}[F(x_0) - F(x_\star)] \end{aligned}$$

therefore, for each stage s

$$\begin{aligned} \mathbf{E}[F(\tilde{x}_s) - F(x_\star)] & \leq \frac{1}{m} \sum_{k=0}^{m-1} \mathbf{E}[F(x_k) - F(x_\star)] \\ & \leq \frac{1}{2\eta(1 - 2L\eta)m} \left(\frac{2}{\mu} + 4Lm\eta^2 \right) \mathbf{E}[F(x_0) - F(x_\star)] \end{aligned}$$

Numerical experiments

- binary classification: $(a_1, b_1), \dots, (a_n, b_n)$ with $a_i \in \mathbf{R}^d$, $b_i \in \{+1, -1\}$
- regularized logistic regression

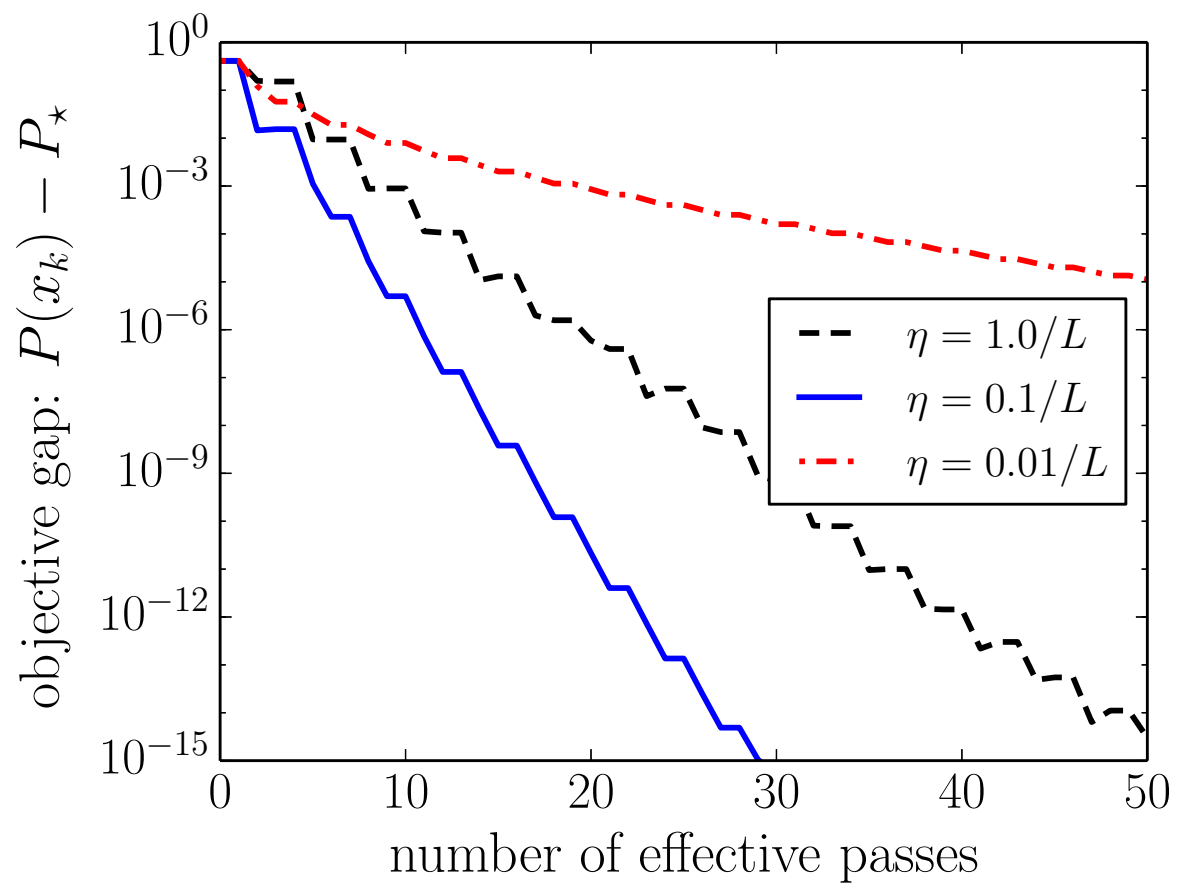
$$\underset{x \in \mathbf{R}^d}{\text{minimize}} \quad \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-b_i a_i^T x)) + \frac{\lambda_2}{2} \|x\|_2^2 + \lambda_1 \|x\|_1$$

nonsmooth term $\|x\|_1$ handled by proximal gradient methods

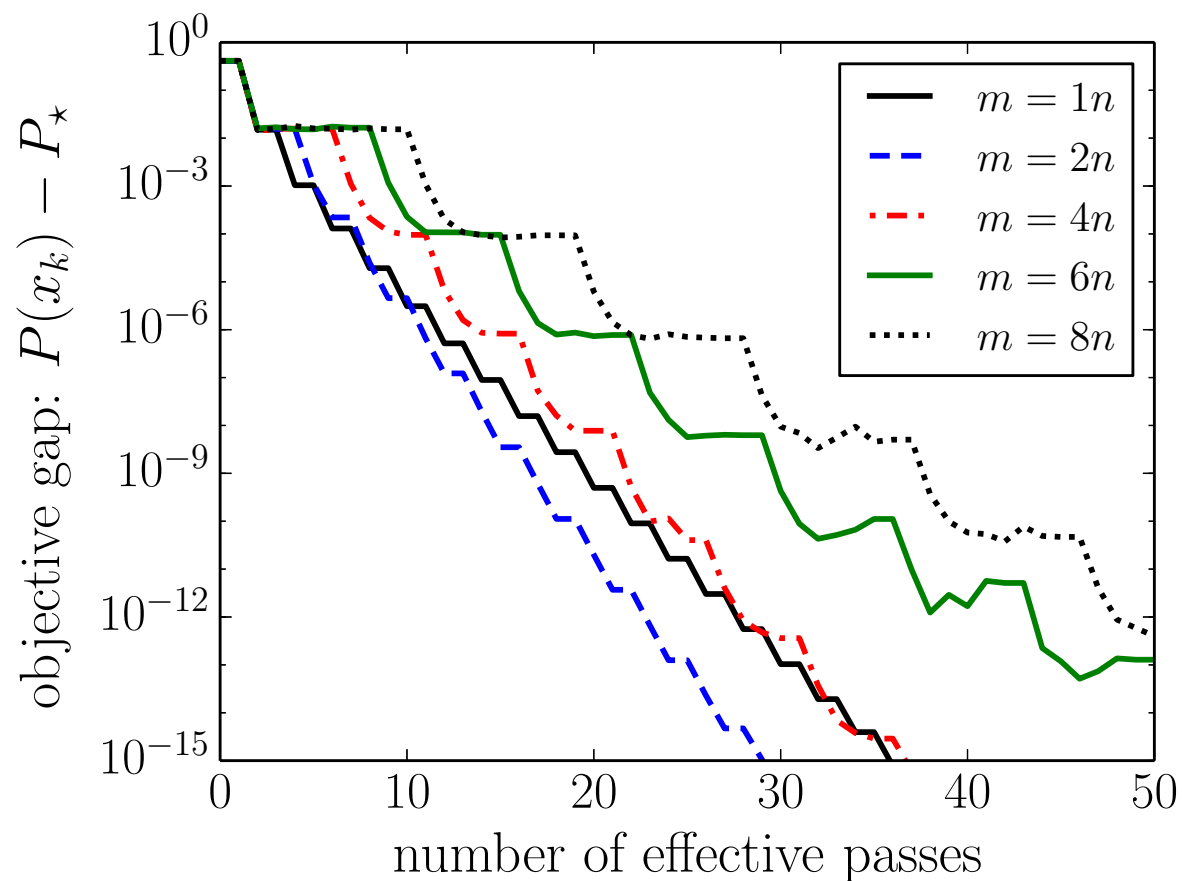
- data sets and characteristics:

data sets	n	d	λ_2	λ_1
rcv1	20,242	47,236	10^{-4}	10^{-5}
coverttype	581,012	54	10^{-5}	10^{-4}
sido0	12,678	4,932	10^{-4}	10^{-4}

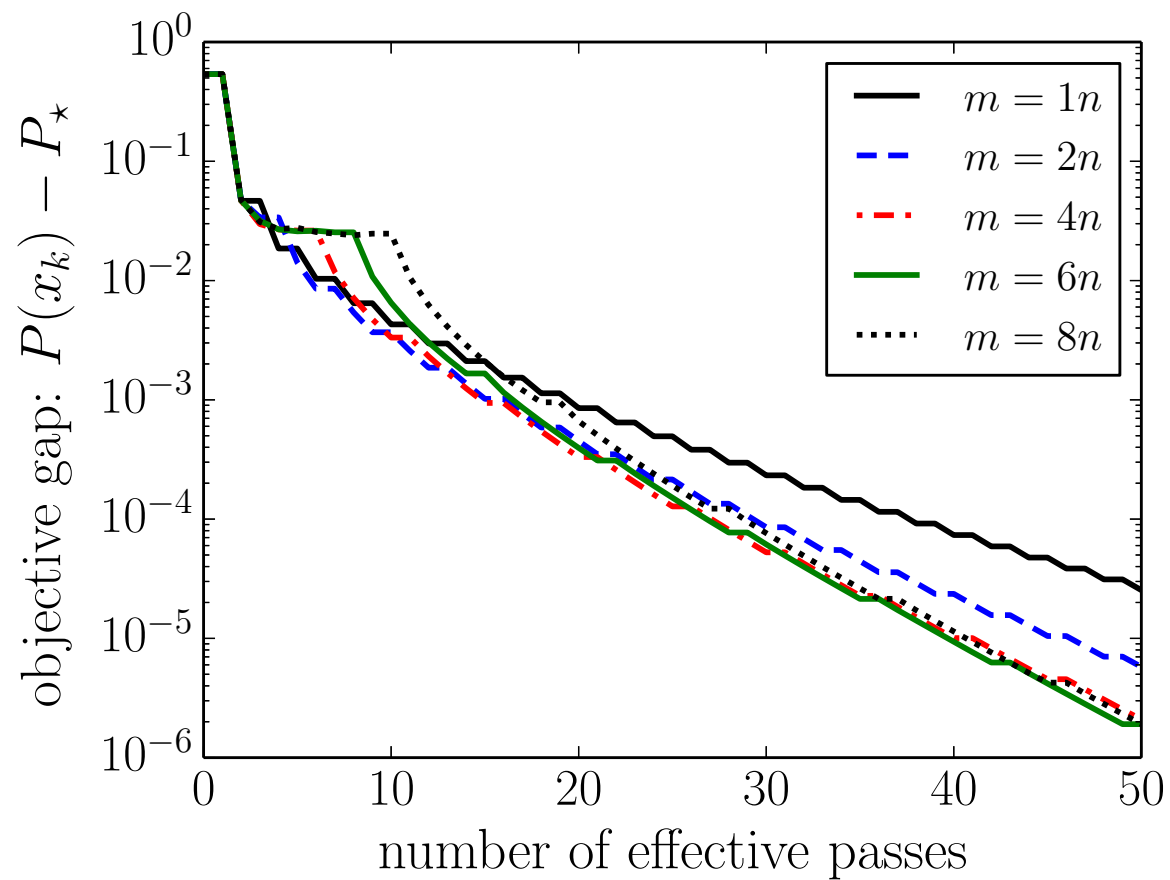
(thanks to Lin Xiao for the experiments)



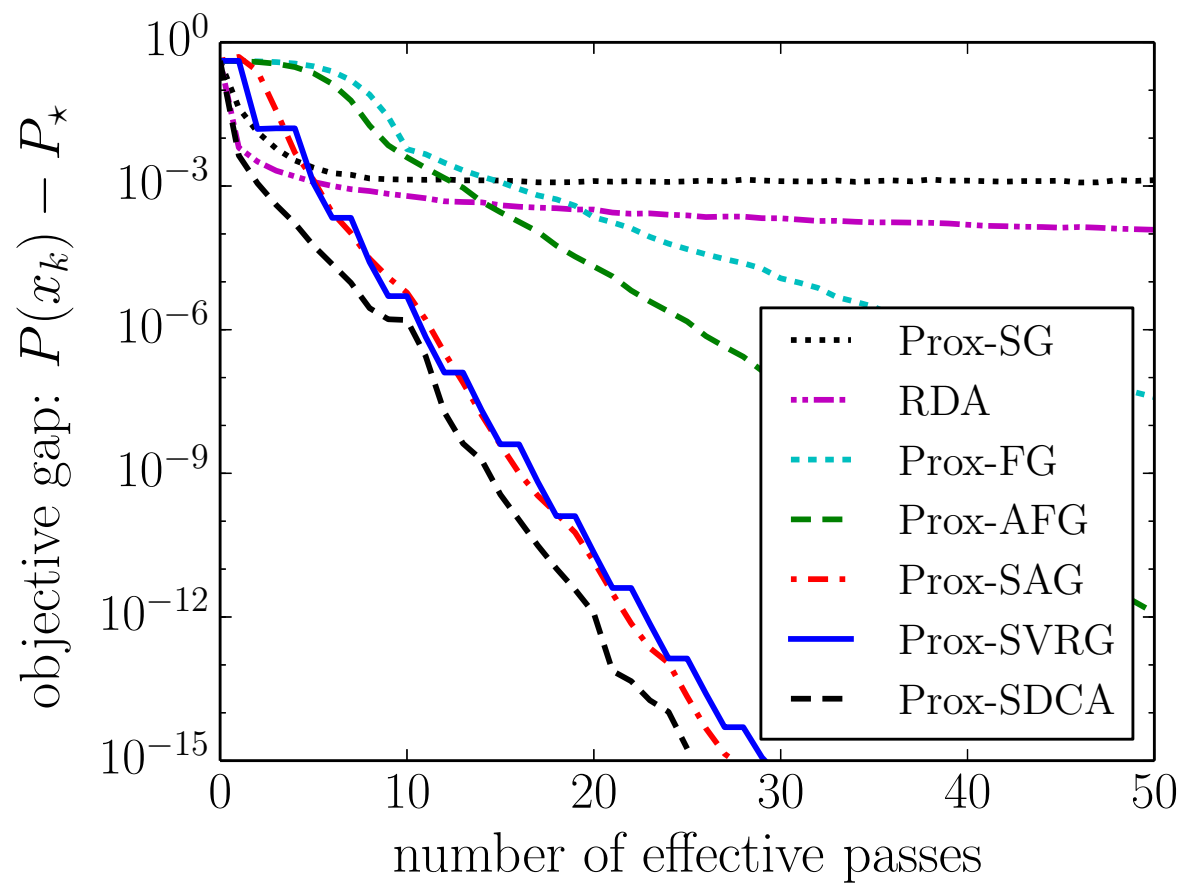
SVRG on rcv1 dataset: varying step size η with $m = 2n$



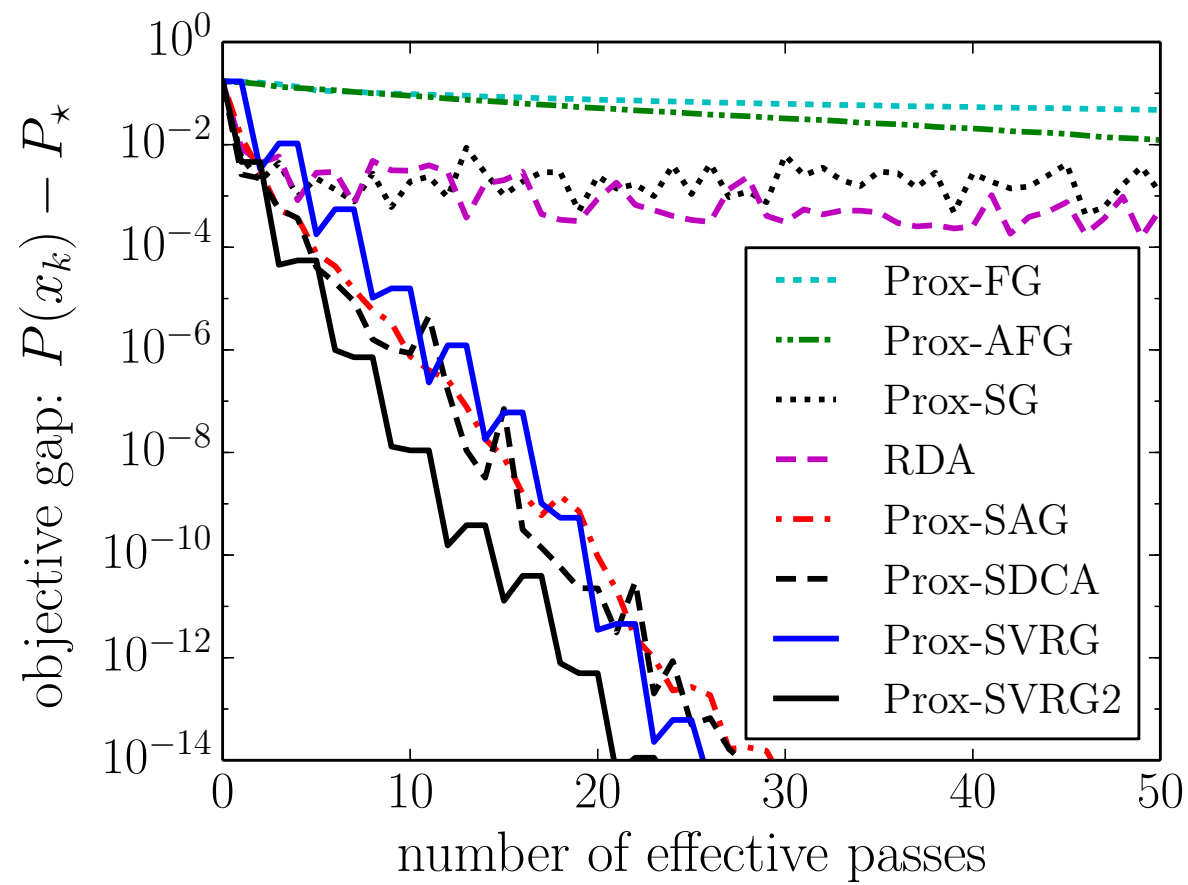
SVRG on rcv1 dataset with $\lambda_2 = 10^{-4}$ and stepsize $\eta = 0.1/L$:
 varying the period m between full gradient evaluations



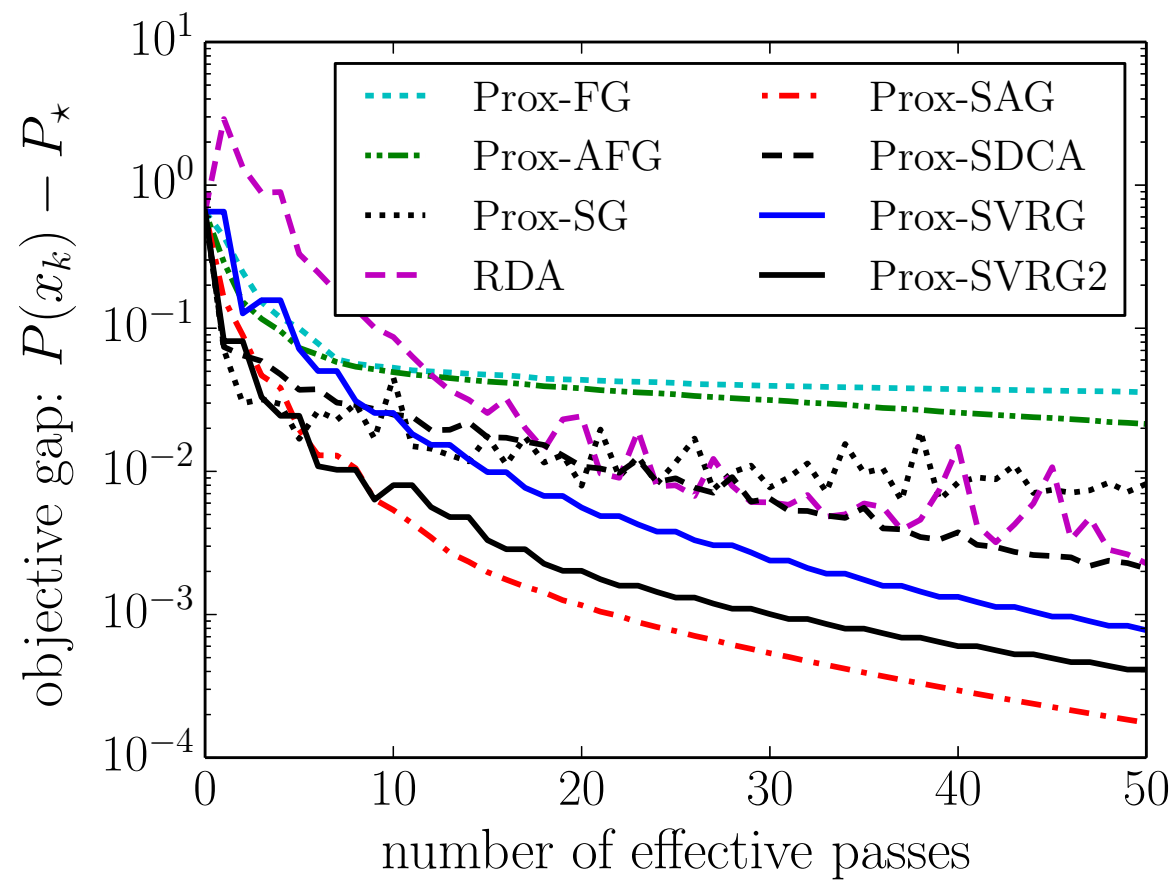
SVRG on rcv1 dataset with $\lambda_2 = 10^{-5}$ and stepsize $\eta = 0.1/L$:
 varying the period m between full gradient evaluations



comparison with related algorithms on rcv1 datasets



comparison with related algorithms on covertypes datasets



comparison with related algorithms on sido0 datasets

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