Lorum ipsum

Author 1 Name, Author 2 Name *

March 2, 2020

Abstract

Lorem ipsum dolor sit amet, dicta iudicabit consequat ex vix, veniam legimus appetere has id, an pri graece epicuri detraxit. Ea aliquam expetendis posidonium eos, nam invenire corrumpit imperdiet ei. Et constituto dissentias usu, mel solum erant et. Mel dolorem menandri in.

2010 Mathematics Subject Classification: Primary 47H05, 52A41, 90C25; Secondary 15A09, 26A51, 26B25, 26E60, 47H09, 47A63. **Keywords:**

1 Notations Demonstrations

Read the source to understand these user defined latex symbols. In the source, wang_scientific.tex contains these macros:

- (i) $\backslash To: \implies$
- (ii) $\c\sc \Gamma$
- (iii) \mal: m
- (iv) \mumu: $\mu\mu$
- $(v) \setminus paver: \mathcal{P}$

^{*}Subject type, Some Department of Some University, Location of the University, Country. E-mail: author.name@university.edu.

- (vi) \zzz: $X \times X^*$
- (vii) \rrr: $\mathbb{R} \times \mathbb{R}$
- (viii) \todo: \hookrightarrow TO DO:
- (ix) $lev{#1}: lev_{\leq #1}$
- (x) $\bmod{1}{2}: 21$
- $(xi) \ensuremath{\setminus} \mathtt{emp} : \varnothing$
- (xii) \infconv: \Box
- (xiii) \pair: $\langle x, y \rangle$
- (xiv) $scal{#1}{#2}: \langle #1, #2 \rangle$
- (xv) $Scal{#1}{#2}: \langle #1, #2 \rangle$
- (xvi) \pscal: $\langle \cdot, \cdot \rangle$
- (xvii) $\backslash Tt: \mathfrak{T}$
- (xviii) \YY: \mathcal{Y}
- (xix) $\backslash xx$: \mathcal{X}
- (xx) \HH: \mathcal{H}
- (xxi) \XP: \mathcal{X}^*
- (xxii) \st: |
- (xxiii) \zeroun:]0,1[
 - (i) \yosida
 - (ii) \exi
 - (iii) \GG
 - $(iv) \ \ RR$

 - (vi) \cc

- $(vii) \setminus Real$
- (viii) \ii
- $(ix) \ RP$
- (xi) \RPP
- (xii) \RX
- (xiii) \RXX
- (xiv) \KK
- $(xv) \setminus NN$
- (xvi) \nnn
- (xvii) \thalb
- (xviii) \zo
- (xix) \lzo

2 Schur's Cone and Its Polar

Example 2.1 Define

$$Q = \left\{ x \in \mathbb{R}^n \middle| \sum_{i=1}^k x_i \ge 0, \ k = 1, \dots, n-1, \ x_1 + \dots + x_n = 0 \right\}.$$
 (1)

Then

$$Q^{\circ} = \{ y \in \mathbb{R}^n | \langle y, x \rangle \ge 0 \ \forall x \in Q \}$$
 (2)

$$= \{ y \in \mathbb{R}^n | y_1 \ge y_2 \ge \dots \ge y_n \}. \tag{3}$$

Proof. We have $Q = H(\mathbb{R}^{n-1}_+)$, where

$$H = \begin{bmatrix} 1 & & & & \\ -1 & 1 & & & \\ & -1 & & & \\ & & \ddots & 1 & \\ & & & -1 \end{bmatrix}, \tag{4}$$

H is a bi-diagonal matrix with zeros on the diagonal and -1 on its sub-diagonals. Indeed, for $x = (x_1, \dots, x_{n-1}) \in \mathbb{R}^{n-1}_+$, we have

$$y = Hx \tag{5}$$

$$= \begin{bmatrix} 1 \\ -1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} x_1 + \begin{bmatrix} 0 \\ 1 \\ -1 \\ \vdots \\ 0 \end{bmatrix} x_2 + \dots + \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \\ -1 \end{bmatrix} x_{n-1}$$
 (6)

$$= \begin{bmatrix} x_1 \\ x_2 - x_1 \\ x_3 - x_2 \\ \vdots \\ -x_{n-2} + x_{n-1} \\ -x_{n-1} \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{n-1} \\ y_n \end{bmatrix},$$
 (7)

where $y_1 \geq 0, y_2 + y_1 \geq 0, \dots, y_{n-1} + \dots + y_1 \geq 0$, and $y_1 + \dots + y_n = 0$. So $y \in Q$. Hence $H(\mathbb{R}^{n-1}_+) \subseteq Q$. Similarly, one can write for $y \in Q$, $\exists x \in \mathbb{R}^{n-1}_+$ with y = Hx. In fact, $x = y_1, x_2 = y_1 + y_2, \dots, x_{n-1} = y_1 + \dots + y_{n-1}, -x_{n-1} = y_n$ because $y_1 + \dots + y_n = 0$. In particular, $x \in \mathbb{R}^{n-1}_+$.

Note that $y \in Q^{\circ} \Leftrightarrow y^{\mathsf{T}} a_i \geq 0$ for $i = 1, \dots, n-1$. Where

$$a_{1} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ \vdots \\ 0, \end{bmatrix}, a_{2} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ \vdots \\ 0, \end{bmatrix}, \dots, a_{n} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ -1 \end{bmatrix}.$$
 (8)

Now $y^{\mathsf{T}}a_i \geq 0 \Leftrightarrow y_i - y_{i+1} \geq 0$, for $i = 1, \dots, n-1$. Hence $Q^{\circ} = \{y \in \mathbb{R}^n | y_1 \geq y_2 \geq \dots \geq y_n\}$.

3 Lorentz Cone and its Polar

Example 3.1

$$L = \{ (\xi, t) \in \mathbb{R}^n \mid ||\xi|| \le t, \xi \in \mathbb{R}^{n-1} \}.$$
 (9)

Then the polar cone of L is $L^{\circ} = \{(x,s) \mid \langle (x,s), (\xi,t) \rangle \geq 0\}\} = L$.

4

Proof.

Let
$$(x,s) \in L^{\circ}$$
. Then $\langle (x,s), (\xi,t) \rangle \geq 0$, $\forall (\xi,t) \in L$, i. e. $\langle x, \xi \rangle + st \geq 0$.

For t > 0, we have $\langle x, \xi/t \rangle \ge -s$, i.e. $\langle x, -\xi/t \rangle \le s$. Using $\|\xi\| \le t$ and by taking supremum over $\|\xi/t\| \le 1$, we obtain $\|x\| \le s$.

Hence
$$L^{\circ} = L$$
.

Corollary 3.2 Let $A \in \mathbb{R}^{n \times n}$ be positive definite. Define

$$L_A = \left\{ (\xi, t) \in \mathbb{R}^n \middle| \sqrt{\langle \xi, A\xi \rangle} \le t \right\}.$$

Then
$$(L_A)^{\circ} = \{(\xi, t) \mid \sqrt{\langle \xi, A^{-1} \xi \rangle} \le t\}.$$

Acknowledgments

XW were supported by NSERC Discovery grants.

References

- [1] H.H. Bauschke and P.L. Combettes, Convex Analysis and Monotone Operator Theory in Hilbert Spaces, second edition, Springer, 2017.
- [2] H. H. Bauschke, M. Krishan Lal, and X. Wang, The projection onto the cross, (2021), https://arxiv.org/abs/2108.04382.
- [3] D.P. Bertsekas, *Nonlinear Programming*, third edition, Athena Scientific, Belmont, Massachusetts, USA, 2016.
- [4] R. L. Burden and J.D. Faires, Numerical Analysis, 9th edition, 2011.
- [5] N. Chernov and H. Ma, Least squares fitting of quadratic curves and surfaces, *Computer Vision* 285, p302, 2011.
- [6] N. Chernov and S. Wijewickrema, Algorithms for projecting points onto conics, *Journal of Computational and Applied Mathematics*, 251, (2013), 8-21.
- [7] D. Eberly, Robust and Error-free Geometric Computing, CRC Press, 2021.

- [8] V. Elser, Learning without loss, Fixed Point Theory and Algorithms for Sciences and Engineering 2021, article 12 (2021). https://doi.org/10.1186/s13663-021-00697-1
- [9] V. Elser, Matrix product constraints by projection methods, *Journal of Global Optimization* 68, no 2, (2017), 329-355.
- [10] Planiden C, Wang X. Strongly Convex Functions, Moreau Envelopes, and the Generic Nature of Convex Functions with Strong Minimizers[J]. SIAM Journal on Optimization, 2015, 26(2):1341-1364.
- [11] E. Kreyszig, *Introductory Functional Analysis with Applications*, John Wiley & Sons, Inc., New York, 1989.
- [12] D.G. Luenberger, Optimization by Vector Space Methods, Wiley, 1969.
- [13] D. R. Luke. and A.L. Martins, Convergence Analysis of the Relaxed Douglas–Rachford Algorithm. SIAM Journal on Optimization, 30(1), (2020), pp.542-584.
- [14] R. T. Rockafellar and R. J-B Wets, *Variational Analysis*, Springer-Verlag, New York, 1998.