

Title for Super Fancy Stuff

Generic Name

Some Super Fancy Institution

November 13, 2023

1 This is the First Section

- Taxonomy of Proximal type of Methods
- The Proximal Operator
- Strong Smoothness
- A Major Assumption

2 A New Fancy Section

- A Fancy Subsetction for Algorithm

3 Numerical Experiments

- LASSO
- Image Deconvolution with Noise

4 References

Formula Presented in Block

$$\min_x g(x) + h(x) \quad (1)$$

1. Throughout this presentation, we assume the objective of a function f is the sum of 2 functions.
2. We are interested in the paper: FISTA (Fast Iterative-Shrinkage Algorithm) by Beck and Teboulle [1].
1. When $h = \delta_Q$ with Q closed and convex with $Q \subseteq \text{ri} \circ \text{dom}(g)$, we use projected subgradient.
2. When g is **strongly smooth** and h is **closed convex proper** whose proximal oracle is easy to compute, we consider the use of FISTA.

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Definition (Definition of Something)

Let f be convex closed and proper, then the proximal operator parameterized by $\alpha > 0$ is a non-expansive mapping defined as:

$$\text{prox}_{f,\alpha}(x) := \arg \min_y \left\{ f(y) + \frac{1}{2\alpha} \|y - x\|^2 \right\}.$$

Remark

When f is convex, closed, and proper,

Prox is the Resolvent of Subgradient

Lemma (The Lemma)

When the function f is convex closed and proper, the $\text{prox}_{\alpha, f}$ can be viewed as the following operator $(I + \alpha \partial f)^{-1}$.

Proof.

Minimizer satisfies zero subgradient condition,

$$0 \in \partial \left[f(y) + \frac{1}{2\alpha} \|y - x\|^2 \right] (y^+)$$

$$0 \in \partial f(y^+) + \frac{1}{\alpha} (y^+ - x)$$

$$\frac{x}{\alpha} \in (\partial f + \alpha^{-1} I)(y^+)$$

$$x \in (\alpha \partial f + I)(y^+)$$

$$y \in (\alpha \partial f + I)^{-1}(x).$$



Equivalence of Strong Smoothness and Lipschitz Gradient

Theorem (Lipschitz Gradient Equivalence under Convexity)

Suppose g is differentiable on the entire of \mathbb{E} . It is closed convex proper. It is strongly smooth with parameter α if and only if the gradient ∇g is globally Lipschitz continuous with a parameter of α and g is closed and convex.

$$\|\nabla g(x) - \nabla g(y)\| \leq \alpha \|x - y\| \quad \forall x, y \in \mathbb{E}$$

Proof.

Using line integral, we can prove Lipschitz gradient implies strong smoothness without convexity. The converse requires convexity and applying generalized Cauchy Inequality to (iv) in Theorem 5.8 for Beck's textbook [2]. □

A Major Assumption

Assumption (Convex Smooth Nonsmooth with Bounded Minimizers)

*We will assume that $g : \mathbb{E} \mapsto \mathbb{R}$ is **strongly smooth** with constant L_g and $h : \mathbb{E} \mapsto \bar{\mathbb{R}}$ is **closed convex and proper**. We define $f := g + h$ to be the summed function and $ri \circ \text{dom}(g) \cap ri \circ \text{dom}(h) \neq \emptyset$. We also assume that a set of minimizers exists for the function f and that the set is bounded. Denote the minimizer using \bar{x} .*

The Accelerated Proximal Gradient Method

Momentum Template Method

Algorithm Template Proximal Gradient Method With Momentum

- 1: **Input:** $x^{(0)}, x^{(-1)}, L, h, g$; 2 initial guesses and stepsize L
 - 2: $y^{(0)} = x^{(0)} + \theta_k(x^{(0)} - x^{(-1)})$
 - 3: **for** $k = 1, \dots, N$ **do**
 - 4: $x^{(k)} = \text{prox}_{h, L^{-1}}(y^{(k)} + L^{-1}\nabla g(y^{(k)})) =: \mathcal{P}_{L^{-1}}^{g, h}(y^{(k)})$
 - 5: $y^{(k+1)} = x^{(k)} + \theta_k(x^{(k)} - x^{(k-1)})$
 - 6: **end for**
-

Some Fancy Results

The plot of Δ_k :

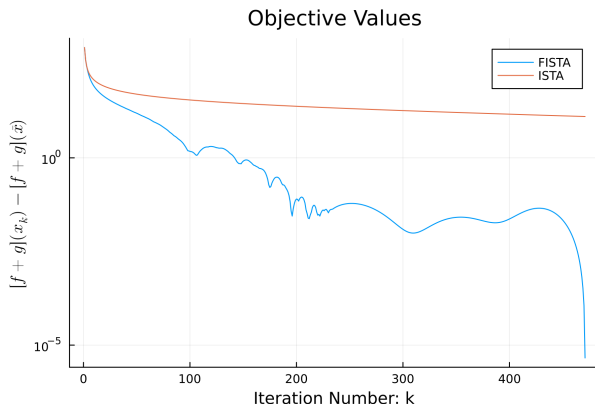
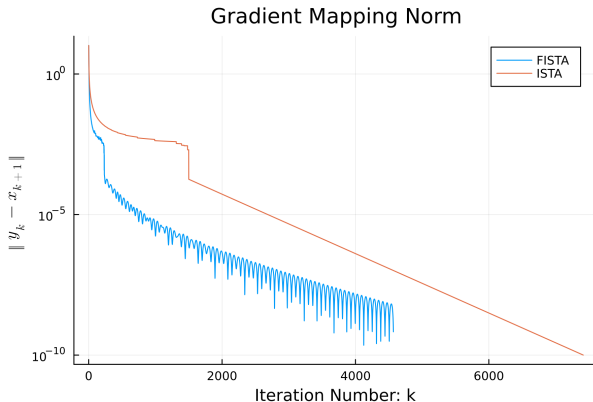


Figure: The left is the objective value of the function during all iterations.

Results

The plot of $\|y^{(k)} - x^{(k+1)}\|_\infty$:



Experiment Setup

Given an image that is convoluted by a Gaussian kernel with some gaussian noise, we want to recover the image, given the parameters for convolutions.

1. Gaussian blur with a discrete 15 by 15 kernel is a linear transform represented by a sparse matrix A in the computer.
2. When an image is 500 by 500 with 3 color channels, A is 750000×750000 .
3. Let the noise be on all normalized colors values with $N(0, 10^{-2})$
4. We let $\lambda = \alpha \times (3 \times 500^2)^{-1}$.
5. Implemented in Julia, and the code is too long to be shown here.

One Big Image for Some Fancy Results

We consider blurring the image of a pink unicorn that I own.

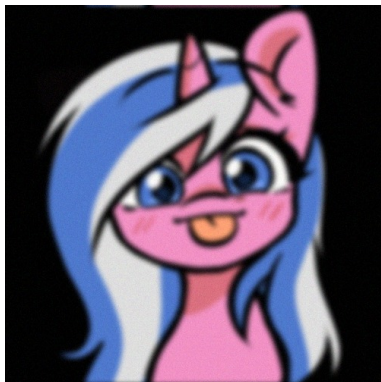
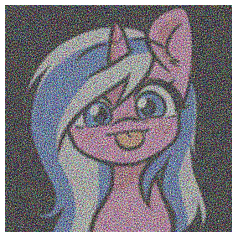
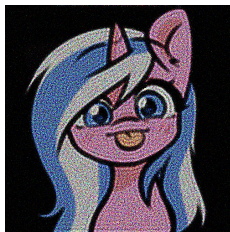


Figure: The image is blurred by the Gaussian Blurred matrix A with a tiny amount of noise on the level of 2×10^{-2} that is barely observable. Zoom in to observe the tiny amount of Gaussian noise on top of the blur.

Moer Image to Show Impressive Results



(a) Graph 1



(b) Graph 2



(c) Graph 3

Figure: (a) $\alpha = 0$, without any one norm penalty, is not robust to the additional noise. (b) $\alpha = 0.01$, there is a tiny amount of λ . (c) $\alpha = 0.1$, it is more penalty compared to (a).



A. Beck and M. Teboulle, “A fast iterative shrinkage-thresholding algorithm for linear inverse problems,” *SIAM Journal on Imaging Sciences*, vol. 2, no. 1, pp. 183–202, 2009. [Online]. Available: <https://doi.org/10.1137/080716542>



A. Beck, *First-Order Methods in Optimization*. Philadelphia, PA: Society for Industrial and Applied Mathematics, 2017. [Online]. Available: <https://epubs.siam.org/doi/abs/10.1137/1.9781611974997>