

Untitled

February 18, 2021

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[121]: """Hyperboloid manifold."""

import torch

from manifolds.base import Manifold
from utils.math_utils import arcosh, cosh, sinh

class Hyperboloid():
    """
    Hyperboloid manifold class.

    We use the following convention:  $-x_0^2 + x_1^2 + \dots + x_d^2 = -K$ 

     $c = 1 / K$  is the hyperbolic curvature.
    """

    def __init__(self):
        super(Hyperboloid, self).__init__()
        self.name = 'Hyperboloid'
        self.eps = {torch.float32: 1e-7, torch.float64: 1e-15}
        self.min_norm = 1e-15
        self.max_norm = 1e6

    def minkowski_dot(self, x, y, keepdim=True):
        #print(x.shape, y.shape)
        res = torch.sum(x * y, dim=-1) - 2 * x[..., 0] * y[..., 0]
        if keepdim:
            res = res.view(res.shape + (1,))
        return res

    def inner(self, p, c, x, y=None, keepdim=True):
        #print(x.shape, y.shape)
        if y == None:
            y = x
        res = torch.sum(x * y, dim=-1) - 2 * x[..., 0] * y[..., 0]
        if keepdim:
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        res = res.view(res.shape + (1,))
    return res

def minkowski_norm(self, u, keepdim=True):
    dot = self.minkowski_dot(u, u, keepdim=keepdim)
    return torch.sqrt(torch.clamp(dot, min=self.eps[u.dtype]))

def sqdist(self, x, y, c):
    K = 1. / c
    prod = self.minkowski_dot(x, y)
    theta = torch.clamp(-prod / K, min=1.0 + self.eps[x.dtype])
    sqdist = K * arcosh(theta) ** 2
    # clamp distance to avoid nans in Fermi-Dirac decoder
    return torch.clamp(sqdist, max=50.0)

def proj(self, x, c):
    K = 1. / c
    d = x.size(-1) - 1
    y = x.narrow(-1, 1, d)

    y_sqnorm = torch.norm(y, p=2, dim=1, keepdim=True) ** 2
    mask = torch.ones_like(x)
    mask[:, 0] = 0
    vals = torch.zeros_like(x)
    vals[:, 0:1] = torch.sqrt(torch.clamp(K + y_sqnorm, min=self.eps[x.
→dtype]))
    return vals + mask * x

def proj_tan(self, u, x, c):
    K = 1. / c
    d = x.size(1) - 1
    ux = torch.sum(x.narrow(-1, 1, d) * u.narrow(-1, 1, d), dim=1,
→keepdim=True)
    mask = torch.ones_like(u)
    mask[:, 0] = 0
    vals = torch.zeros_like(u)
    vals[:, 0:1] = ux / torch.clamp(x[:, 0:1], min=self.eps[x.dtype])
    return vals + mask * u

def proj_tan0(self, u, c):
    narrowed = u.narrow(-1, 0, 1)
    vals = torch.zeros_like(u)
    vals[:, 0:1] = narrowed
    return u - vals

def expmap(self, u, x, c, verbose=False):
    if verbose:

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        print(f'##### EXPMAP #####')
        print(f'Input: {torch.isnan(u).sum().item()} nans')

    K = 1. / c
    sqrtK = K ** 0.5
    normu = self.minkowski_norm(u)
    normu = torch.clamp(normu, max=self.max_norm)
    theta = normu / sqrtK
    theta = torch.clamp(theta, min=self.min_norm)
    result = cosh(theta) * x + sinh(theta) * u / theta
    if verbose:
        print(f'{(theta == 0).sum().item()} zeros in denominator')
    if verbose:
        print(f'theta: {torch.isnan(theta).sum().item()}, \
              cosh: {torch.isnan(cosh(theta)).sum().item()}, \
              sinh: {torch.isnan(sinh(theta)).sum().item()}')

    print(f'Before proj: {torch.isnan(result).sum().item()} nans')
    out = self.proj(result, c)
    if verbose:
        print(f'Output: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$ EXPMAP END $$$$$')
    return out

def logmap(self, x, y, c, verbose=False):
    if verbose:
        print(f'##### LOGMAP #####')
        print(f'Input: {torch.isnan(x).sum().item()} nans')
    K = 1. / c
    xy = torch.clamp(self.minkowski_dot(x, y) + K, max=-self.eps[x.dtype])
    ↪ - K
    u = y + xy * x * c
    normu = self.minkowski_norm(u)
    normu = torch.clamp(normu, min=self.min_norm)
    dist = self.sqdist(x, y, c) ** 0.5
    result = dist * u / normu
    if verbose:
        print(f'Before proj: {torch.isnan(result).sum().item()} nans')
    out = self.proj_tan(result, x, c)
    if verbose:
        print(f'Output: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$ LOGMAP END $$$$$')

    return out

def expmap0(self, u, c, verbose=False):
    if verbose:

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        print(f'##### EXPMAP0 #####')
        print(f'Input: {torch.isnan(u).sum().item()} nans')
    K = 1. / c
    sqrtK = K ** 0.5
    d = u.size(-1) - 1
    x = u.narrow(-1, 1, d).view(-1, d)
    x_norm = torch.norm(x, p=2, dim=1, keepdim=True)
    x_norm = torch.clamp(x_norm, min=self.min_norm)
    theta = x_norm / sqrtK
    res = torch.ones_like(u)
    res[:, 0:1] = sqrtK * cosh(theta)
    res[:, 1:] = sqrtK * sinh(theta) * x / x_norm
    if verbose:
        print(f'max theta is: {torch.max(theta)}, sinh: {torch.
→max(sinh(theta))}, cosh: {torch.max(cosh(theta))}')
        print(f'res[0:1]: {torch.isnan(res[:, 0:1]).sum().item()} nans')
        print(f'res[1:]: {torch.isnan(res[:, 1:]).sum().item()} nans')
        print(f'x: {torch.isnan(x).sum().item()}, x/x_norm: {torch.isnan(x /
→ x_norm).sum().item()}')
    out = self.proj(res, c)

    if verbose:
        print(f'zeros in denominator {(x_norm == 0).sum().item()}')
        print(f'theta: {torch.isnan(theta).sum().item()}, cosh: {torch.
→isnan(cosh(theta)).sum().item()}, sinh: {torch.isnan(sinh(theta)).sum().
→item()}')
        print(f'Before proj: {torch.isnan(res).sum().item()} nans')

    if verbose:
        print(f'Output: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$ EXPMAP0 END $$$$$')

    return out

def logmap0(self, x, c, desc=None, verbose=False):
    if verbose:
        print(f'##### LOGMAP0 #####')
        print(f'Input: {torch.isnan(x).sum().item()} nans')

    K = 1. / c
    sqrtK = K ** 0.5
    d = x.size(-1) - 1
    y = x.narrow(-1, 1, d).view(-1, d)
    y_norm = torch.norm(y, p=2, dim=1, keepdim=True)
    y_norm = torch.clamp(y_norm, min=self.min_norm)
    res = torch.zeros_like(x)
    if len(x.shape) > 1:

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        theta = torch.clamp(x[:, 0:1] / sqrtK, min=1.0 + self.eps[x.dtype])
        res[:, 1:] = sqrtK * arcosh(theta) * y / y_norm
    else:
        theta = torch.clamp(x[0:1] / sqrtK, min=1.0 + self.eps[x.dtype])
        res[1:] = sqrtK * arcosh(theta) * y / y_norm
    if verbose:
        print(f'zeros in denominator {(y_norm == 0).sum().item()}')
        print(f'theta: {torch.isnan(theta).sum().item()}, \
              arcosh: {torch.isnan(arcosh(theta)).sum().item()}')
        print(f'Output: {torch.isnan(res).sum().item()} nans')
        print(f'$$$$$ LOGMAPO END $$$$$')

    return res

def mobius_add(self, x, y, c):
    u = self.logmap0(y, c)
    v = self.ptransp0(x, u, c)
    return self.expmat(v, x, c)

def mobius_matvec(self, m, x, c, desc=None, verbose=False):
    if verbose:
        print(f'##### MOBIUS MATVEC #####')
        print(f'Input: {torch.isnan(x).sum().item()} nans')
    u = self.logmap0(x, c)
    if verbose:
        print(f'After logmap0: {torch.isnan(u).sum().item()} nans')
        print(f'u shape: {u.shape}, w^T shape: {m.transpose(-1, -2).shape}')

    mu = u @ m.transpose(-1, -2)
    if verbose:
        print(f'After mu: {torch.isnan(mu).sum().item()} nans')
    out = self.expmat0(mu, c)
    if verbose:
        print(f'After expmat0: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$$$$$$$$$$$$ MOBIUS MATVEC END $$$$$$$$$$$$$$')
    return out

def ptransp(self, x, y, u, c):
    logxy = self.logmap(x, y, c)
    logyx = self.logmap(y, x, c)
    sqdist = torch.clamp(self.sqdist(x, y, c), min=self.min_norm)
    alpha = self.minkowski_dot(logxy, u) / sqdist
    res = u - alpha * (logxy + logyx)
    return self.proj_tan(res, y, c)

def ptransp0(self, x, u, c):

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        K = 1. / c
        sqrtK = K ** 0.5
        x0 = x.narrow(-1, 0, 1)
        d = x.size(-1) - 1
        y = x.narrow(-1, 1, d)
        y_norm = torch.clamp(torch.norm(y, p=2, dim=1, keepdim=True), min=self.
→min_norm)
        y_normalized = y / y_norm
        v = torch.ones_like(x)
        v[:, 0:1] = - y_norm
        v[:, 1:] = (sqrtK - x0) * y_normalized
        if len(u.shape) > 1:
            alpha = torch.sum(y_normalized * u[:, 1:], dim=1, keepdim=True) /
→sqrtK
        else:
            alpha = torch.sum(y_normalized * u[1:], dim=1, keepdim=True) / sqrtK
        res = u - alpha * v
        return self.proj_tan(res, x, c)

def to_poincare(self, x, c, verbose=False):
    if verbose:
        print(f'##### TO POINCARE #####')
        print(f'Input: {torch.isnan(x).sum().item()} nans')
    K = 1. / c
    sqrtK = K ** 0.5
    d = x.size(-1) - 1
    out = sqrtK * x.narrow(-1, 1, d) / (x[:, 0:1] + sqrtK)
    if verbose:
        print((x[:, 0:1] + sqrtK == 0).sum().item())
        print(f'Input: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$$ TO POINCARE END $$$$$$')
    return out

def to_hyperboloid(self, x, c, verbose=False):
    if verbose:
        print(f'##### TO HYPERBOLOID #####')
        print(f'Input: {torch.isnan(x).sum().item()} nans')
    K = 1. / c
    sqrtK = K ** 0.5
    sqnorm = torch.norm(x, p=2, dim=1, keepdim=True) ** 2
    out = sqrtK * torch.cat([K + sqnorm, 2 * sqrtK * x], dim=1) / (K -
→sqnorm)

    if verbose:
        print(f'Zeros in denominator: {(K - sqnorm == 0).sum().item()}')
        print(f'Output: {torch.isnan(out).sum().item()} nans')
        print(f'$$$$$$ TO HYPERBOLOID END $$$$$$')

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        return out

    def egrad2rgrad(self, p, dp, c):
        K = 1. / c
        sqrtK = K ** 0.5
        u = dp
        x = p
        u.narrow(-1, 0, 1).mul_(-1 / sqrtK)
        u.addcmul_(self.minkowski_dot(x, u, keepdim=True).expand_as(x), x)

        return u

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[117]: a = torch.tensor([[1, 2, 3], [10, 10, 10]]).float()
hyp = Hyperboloid()
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[118]: a_exp = hyp.expmat0(a, 1)
a_exp
```

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[118]: tensor([[1.8415e+01, 1.0199e+01, 1.5299e+01],
              [6.9314e+05, 4.9012e+05, 4.9012e+05]])
```

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[119]: hyp.minkowski_dot(a_exp, a_exp)
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[119]: tensor([[ -0.9999],
              [ 0.0000]])
```

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[61]: hyp.minkowski_norm(hyp.proj(a_exp, 2))
```

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[61]: tensor([[0.0003],
              [0.0003]])
```

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[63]: a_proj = hyp.proj_tan0(a, 2)
a_exp = hyp.expmat0(a_proj, 2)
a_exp
```

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[63]: tensor([[5.7936e+01, 3.2135e+01, 4.8202e+01],
              [1.6254e+05, 1.0578e+05, 1.2341e+05]])
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[67]: hyp.minkowski_dot(a_exp, a_exp)
```

```
[67]: tensor([[ -0.4995],
              [ 0.0000]])
```

```
[147]: def minkowski_dot(x, y, keepdim=True):
        #print(x.shape, y.shape)
        res = torch.sum(x * y, dim=-1) - 2 * x[..., 0] * y[..., 0]
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    if keepdim:
        res = res.view(res.shape + (1,))
    return res

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[154]: a = torch.ones(100).float().unsqueeze(0)
a_exp = hyp.expmmap0(hyp.proj_tan0(a, c=1), c=1)
a_exp = hyp.proj(a_exp, c=1)
hyp.minkowski_dot(a_exp, a_exp).item()

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[154]: -16.0

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[156]: %pylab inline

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Populating the interactive namespace from numpy and matplotlib

/opt/conda/lib/python3.7/site-packages/IPython/core/magics/pylab.py:160:
UserWarning: pylab import has clobbered these variables: ['cosh', 'sinh']
`%matplotlib` prevents importing * from pylab and numpy
  "\n`%matplotlib` prevents importing * from pylab and numpy"

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[201]: scales = np.arange(start=0, stop=0.2, step=0.01)
vec = torch.ones(100).float().unsqueeze(0)
dots = np.zeros_like(scales)

hyp = Hyperboloid()

for i, scale in enumerate(scales):
    vec_scaled = vec * scale
    exp = hyp.expmmap0(vec_scaled, c=10)
    dots[i] = hyp.minkowski_dot(exp, exp)

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[202]: scales

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[202]: array([0.   , 0.01, 0.02, 0.03, 0.04, 0.05, 0.06, 0.07, 0.08, 0.09, 0.1 ,
        0.11, 0.12, 0.13, 0.14, 0.15, 0.16, 0.17, 0.18, 0.19])

```

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[203]: dots

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[203]: array([-0.1       , -0.09999999, -0.10000001, -0.10000002, -0.09999973,
        -0.10000014, -0.10000062, -0.10000086, -0.09999657, -0.09999918 ,
        -0.10000038, -0.09996796, -0.09998322, -0.10009766, -0.09991455,
        -0.09991455, -0.09985352, -0.09960938, -0.1015625 , -0.10302734])

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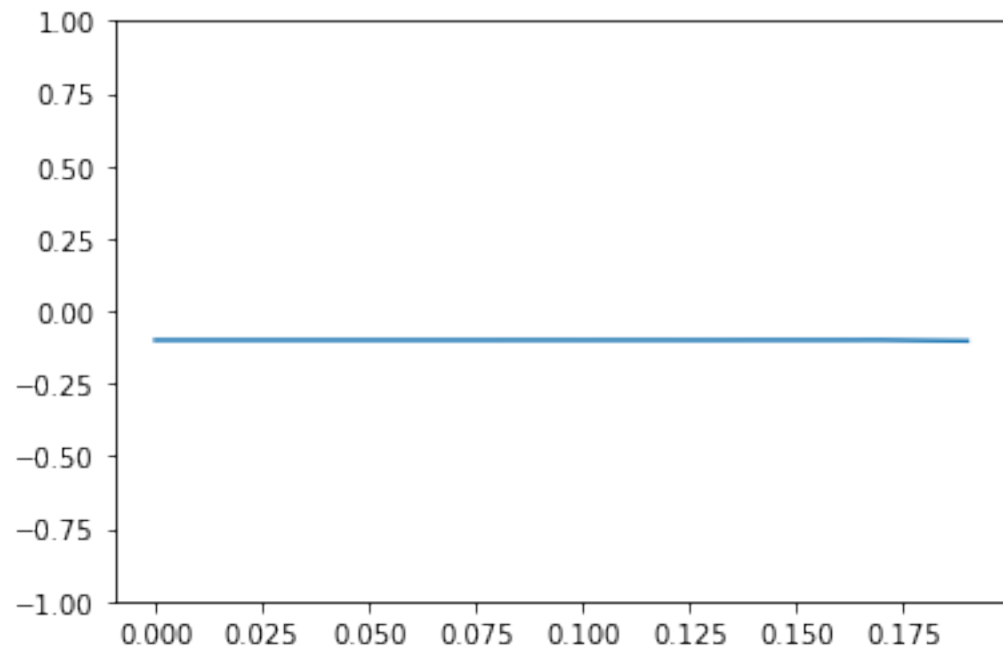
[204]: plt.plot(scales, dots)
plt.ylim(-1, 1)

```

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[204]: (-1.0, 1.0)

```

[]: