

# Nonlinear Decoherence of an Offset Waterbag

Christopher Hall

September 6, 2018

**Abstract**

## 1 Introduction

The goal of this work is to provide a model for the centroid motion of bunch undergoing nonlinear decoherence. To begin we assume that the bunch starts out with some displacement  $\Delta x$  along one transverse axis at turn  $N = 0$ . We will then find a representation of  $\hat{x}(N)$  the normalized centroid position  $\langle x \rangle / \sigma_x$  as a function of turn number.

We begin by following SSC-N-360 and describe particle motion in the coordinates  $a = \sqrt{\beta_x \varepsilon_x} / \sigma_x$  and  $\varphi$ , for the amplitude and initial phase of a particle. This means that the actual particle displacement is then  $x = \sigma_x a \cos(2\pi\nu N + \varphi)$ .

Because of the presence of the nonlinear element there will be amplitude-dependence in the particle tune. may be characterized in terms of a unitless strength parameter  $t$  and geometric scale factor  $c$ , with units of  $m^{\frac{1}{2}}$ , that describes the location of two singularities in the x-plane. The first few terms of the multipole expansion for the elliptic potential in normalized coordinates  $\hat{x}, \hat{y} = x/\sqrt{\beta}, y/\sqrt{\beta}$  are given by

$$U(\hat{x}, \hat{y}) = \frac{-t}{c^2} \text{Im} \left\{ (\hat{x} + i\hat{y})^2 + \frac{2}{3c^2} (\hat{x} + i\hat{y})^4 + \frac{8}{15c^4} (\hat{x} + i\hat{y})^6 + \dots \right\}. \quad (1)$$

Note: this expansion is only valid in the region  $\sqrt{\hat{x}^2 + \hat{y}^2} < c$ . Because of the form of the potential we expect to see just the even terms in amplitude effecting the tune.

## 2 Nonlinear Decoherence and the Centroid

Due to the octupole and higher terms in the potential the tune  $\nu$  will have an amplitude dependence of the form

$$\nu = \nu_0 - \sum_{i=1} \mu_i a^{2i}, \quad (2)$$

where  $\nu_0$  is the unperturbed tune and  $\mu_i$  are coefficients determined by the octupole, duodecapole, etc. multipole components in the nonlinear element. The calculation of these coefficients becomes cumbersome beyond the lowest order. This is a major obstacle to the use of the formulation developed here. This issue will be discussed further on.

This amplitude-dependent tune will result in particles having a phase shift each turn of

$$\Delta\varphi(a, N) = -2\pi N \sum_{i=1} \mu_i a^{2i}, \quad (3)$$

when compared to the unperturbed phase advance  $\nu_0$ . From this the centroid motion for a distribution  $\rho(a, \varphi)$  as a function of turn number in a lattice with some nonlinearities will be

$$\hat{x}(N) = \int_0^\infty da \int_0^{2\pi} d\varphi a \cos(\varphi) \rho(a, \varphi - 2\pi N \nu). \quad (4)$$

### 3 Calculation for a Waterbag Distribution

Because all our simulation data we will compare to uses a waterbag distribution we are first interested in the calculation of Eq. 4 for such a distribution. here we define a 'waterbag' according to the definition of Reiser, that is the bunch has a uniform distribution of particle amplitudes from 0 to some cutoff, that is

$$\rho(a, \varphi) = \begin{cases} 1 & a \leq 1 \\ 0 & a > 1 \end{cases} \quad (5)$$

We then assume that the distribution starts out with a centroid offset, in our normalized coordinates is,  $Z = \Delta x / \sigma_x$ . This offset waterbag then takes form

$$\rho(a, \varphi) = \begin{cases} \frac{1+Z^2-2Z\cos(\varphi)}{\pi} & 0 < a \leq 1 \\ 0 & a > 1 \text{ or } a < 0 \end{cases} \quad (6)$$

Inserting Eq. 6 in Eq. 4 we can make a convenient change of variable  $u = a^2$  and perform the integration in  $\varphi$ , resulting in

$$\hat{x}(N) = \pi Z \int_0^1 du \cos(2\pi\nu_0 N) \cos(\Delta\varphi(u, N)) + \sin(2\pi\nu_0 N) \sin(\Delta\varphi(u, N)) \quad (7)$$

A second change of variable  $\hat{u} = 2\pi N u$  is then made to assist in numerical integration down the road. The general result for the centroid motion is then

$$\hat{x}(N) = \frac{Z}{2N} \int_0^{2\pi N} d\hat{u} \cos(2\pi\nu_0 N) \cos(\Delta\varphi(u, N)) - \sin(2\pi\nu_0 N) \sin(\Delta\varphi(u, N)) \quad (8)$$

As a reminder the phase slip  $\Delta\varphi$  has now become

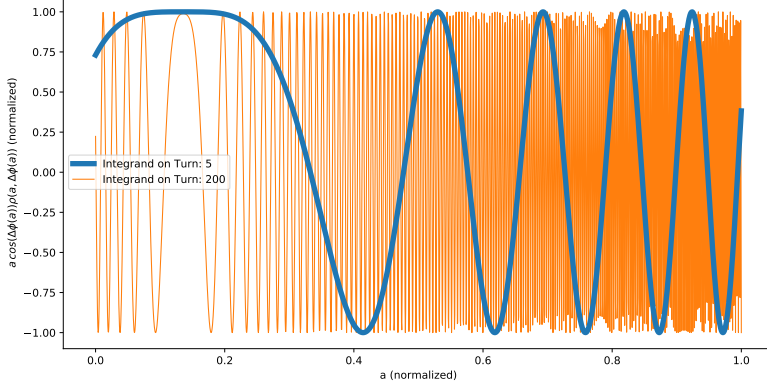


Figure 1: Integrand of Eq. 8 on turn 5 and turn 100.

$$\Delta\varphi(\hat{u}, N) = \sum_{i=1} \frac{\mu_i \hat{u}^i}{(2\pi N)^{i-1}}. \quad (9)$$

We now have a general solution for our original problem, the centroid motion as a function of turn number. Quite nicely, this solution is not iterative, any turn can be calculated independently. This does aid speeding up the turn-by-turn centroid motion, however, this is where the good news stops. We still have a set of unknown coefficients  $\mu_i$  that will depend on particulars of the nonlinear element in the lattice and must be iteratively derived from a perturbation method or found from numerical fitting. For this second option we can use simulation data from IOTA and fit up to the desired order (as well as  $\nu_0$  possibly). However, this numerical method is greatly complicated by the highly-oscillatory nature of the integrand of Eq. 8. As an example the integrand is plotted in Fig. 1 for two different values of  $N$ . For the case of  $N = 200$  the high-frequency oscillations tend to make the numerical integration both extremely slow and greatly limits accuracy in many cases.

Evaluation of the general waterbag case, Eq. 8, is available through the `rsbeams.rsphysics.decoherence` module. The general integration is performed with `scipy.integrate.quad` which in turns uses the Fortran QUADPACK library. (Note: This uses the Clenshaw-Curtis Quadrature, which has the possibility of introducing a weight function to the integrand that can ease integration of high-oscillatory functions. This has not been explored though.). For evaluating  $N$  turns we take advantage of the independent nature of each turn and use the `Pool` function from the `pathos.multiprocessing` package to parallelize the calculations. The standard `multiprocessing` library will not work in this instance as it is not able to be run from within a class instance and evaluate a method belonging to the class. The Pathos implementation does not

have this limitation.

### 3.1 Special Cases

While the general evaluation of Eq. 8 does not appear analytically tractable there are two special cases. If we truncate  $\Delta\varphi$  at  $\hat{a}$  there is an exact analytic solution, in the case of truncating at  $\hat{a}^2$  a solution can be found in terms of Fresnel integrals, which are relatively easy to calculate.

For just  $i = 1$  the exact solution is

$$\hat{x}(N) = \frac{Z}{2\pi N} \frac{\cos(2\pi\nu_0 N) \sin(2\pi N \mu_1) + 2 \sin(2\pi\nu_0 N) \sin^2(\pi N \mu_1)}{\mu_1}. \quad (10)$$

With both  $i = 1, 2$  the solution becomes

$$\hat{x}(\hat{u}, N) = \frac{Z}{\sqrt{8\pi N^2 \mu_2}} \left[ C \left( \frac{\pi N \mu_1 + \mu_2 \hat{u}}{\sqrt{\pi^2 N \mu_2}} \right) \cos \left( \frac{\pi N \mu_1^2}{2\mu_2} + 2\pi N \nu_1 \right) + S \left( \frac{\pi N \mu_1 + \mu_2 \hat{u}}{\sqrt{\pi^2 N \mu_2}} \right) \sin \left( \frac{\pi N \mu_1^2}{2\mu_2} + 2\pi N \nu_1 \right) \right] \Bigg|_0^{2\pi N}, \quad (11)$$

where  $C$  and  $S$  are the Fresnel integrals. The `rsbeams.rsphysics.decoherence` package includes both these representations and will automatically use them when appropriate.