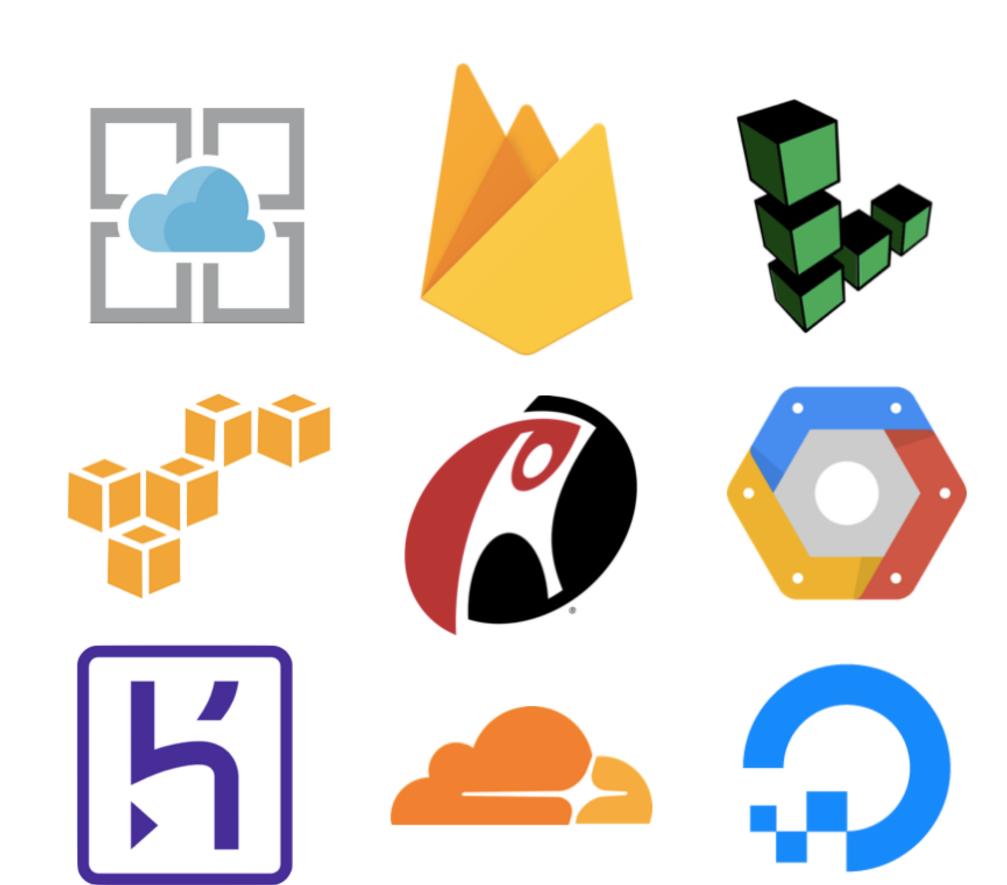
YSC3248: Parallel, Concurrent and Distributed Programming

Distributed Consensus

Consensus

- Common meaning:
 a way for a set of parties to come to a shared agreement.
- In distributed computing: ensuring that among the values proposed by a collection of processes, a *single one* is chosen.
 - Uniformity: Only a single value is chosen
 - Non-triviality: Only a value that has been proposed may be chosen
 - Irrevocability: Once agreed on a value, the processes do not change their decision.

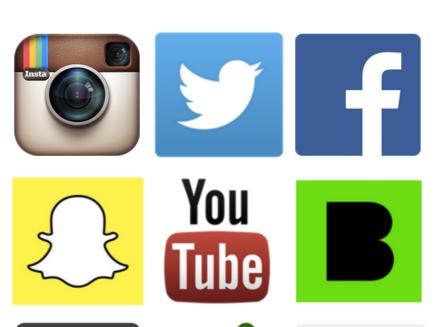
Why Consensus?













Why Distributed Consensus is difficult?

- Arbitrary message delays (asynchronous network)
- Independent parties (nodes) can go offline (and also back online)
- Network partitions
- Message reorderings
- Malicious (Byzantine) parties

Why Distributed Consensus is difficult?

- Arbitrary message delays (asynchronous network)
- Independent parties (nodes) can go offline (and also back online)
- Network partitions
- Message reorderings
- Malicious (Byzantine) parties

Reaching a Consensus

(and constructing a protocol for this)



Reaching a Consensus on where to have a dinner

Waa Cow!

Sapore

Hwang's

Waa Cow!

Sapore

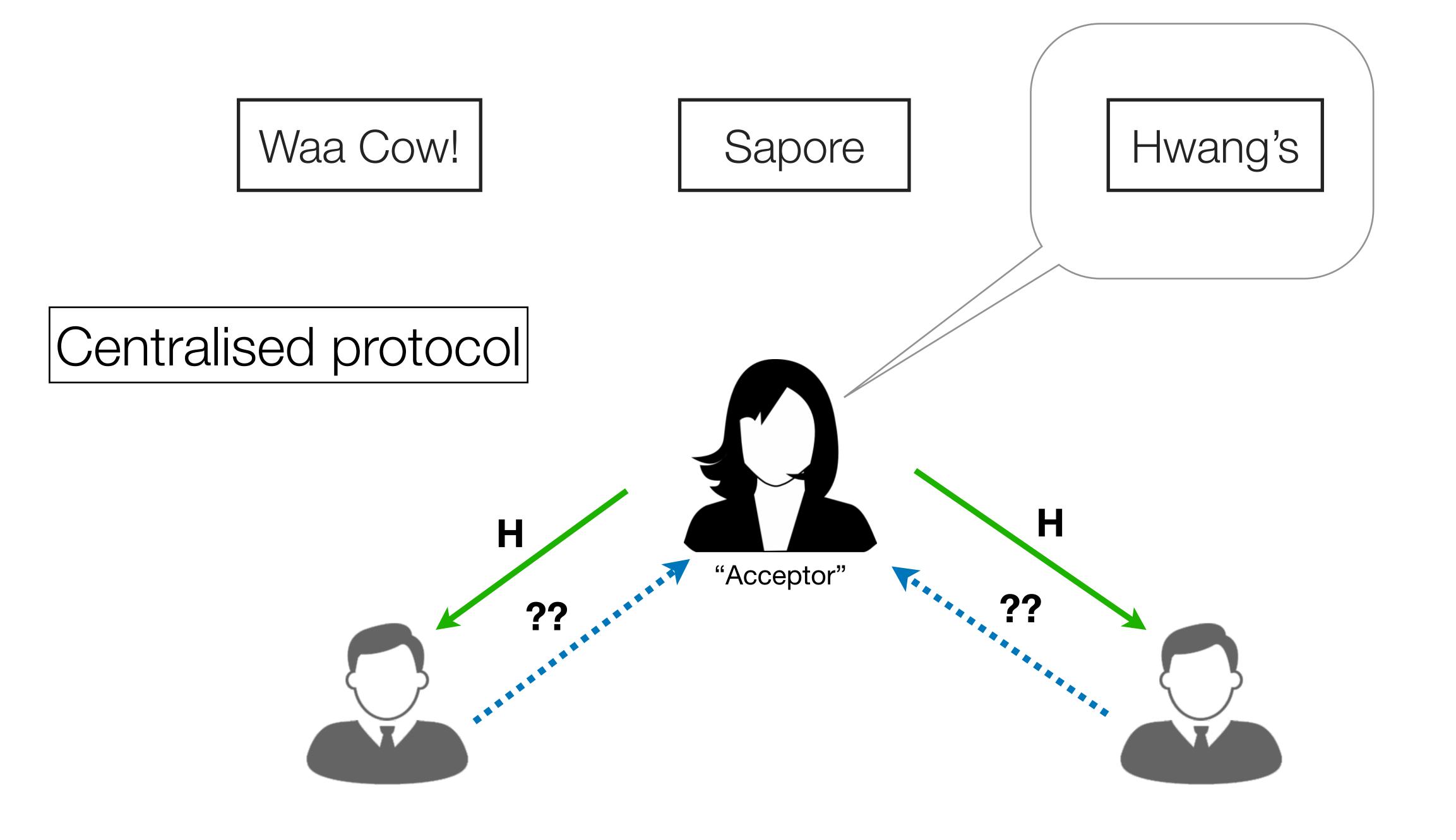
Hwang's

??



??





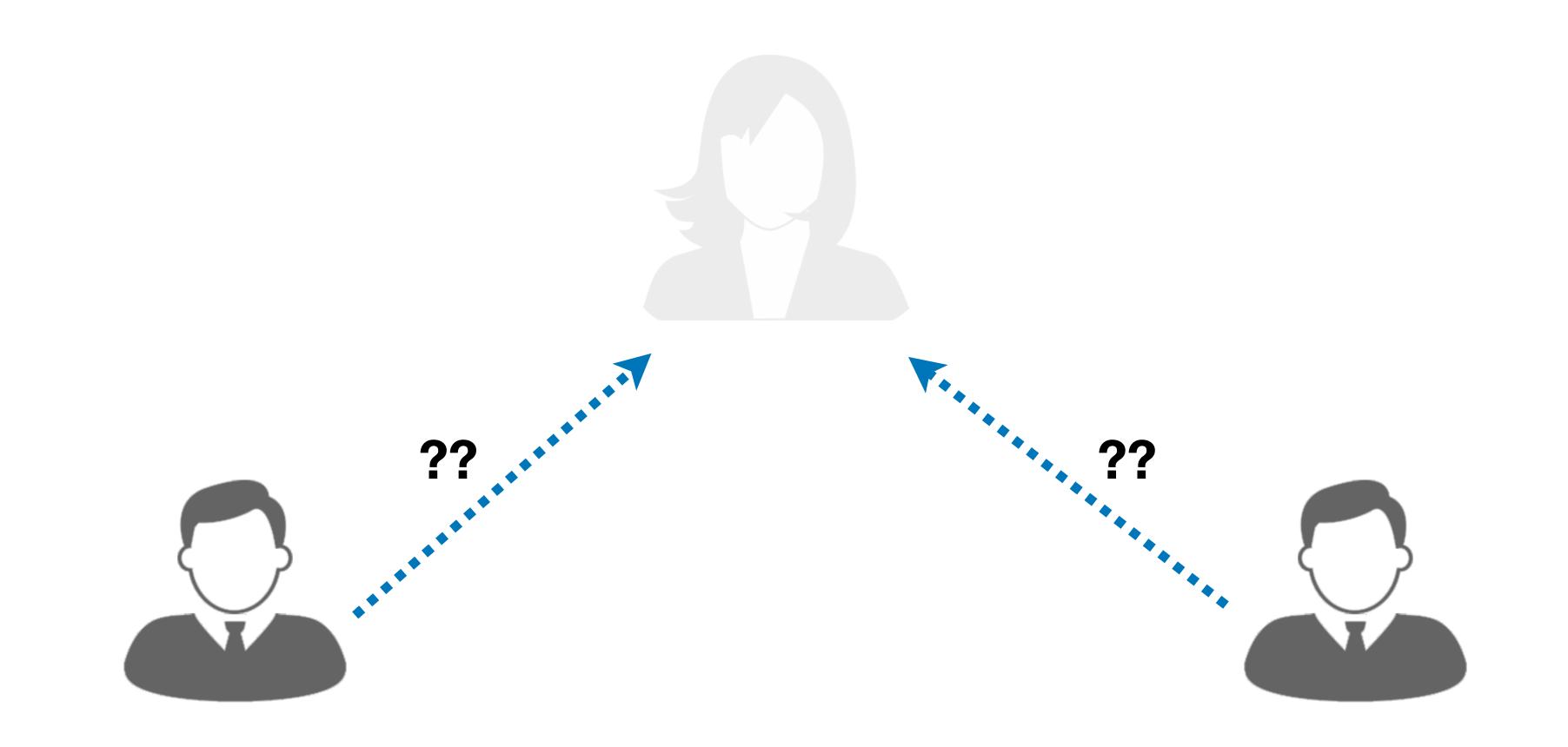
Problem 1

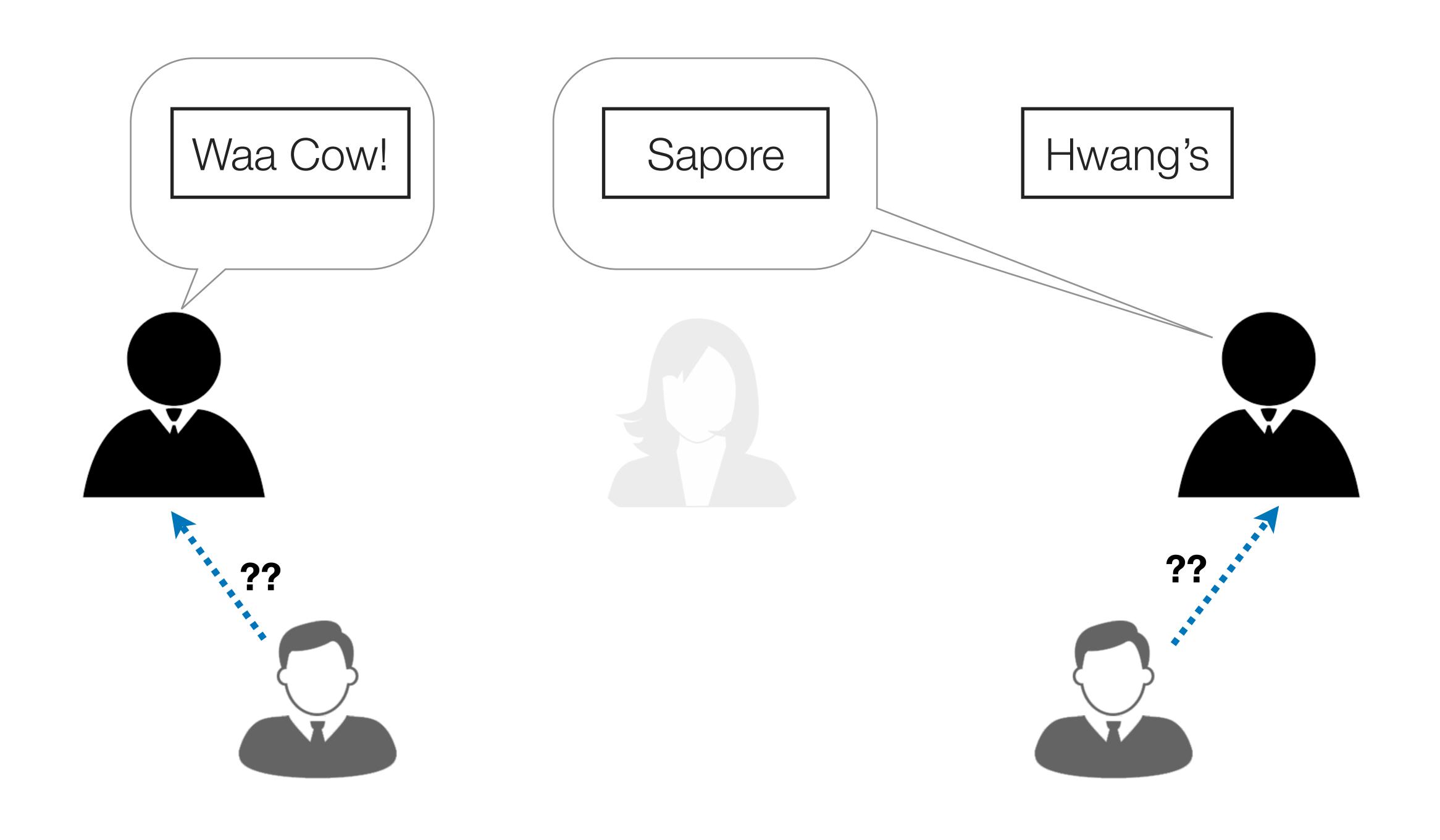
A single acceptor can go offline or take forever to answer.

Waa Cow!

Sapore

Hwang's





Problem 2

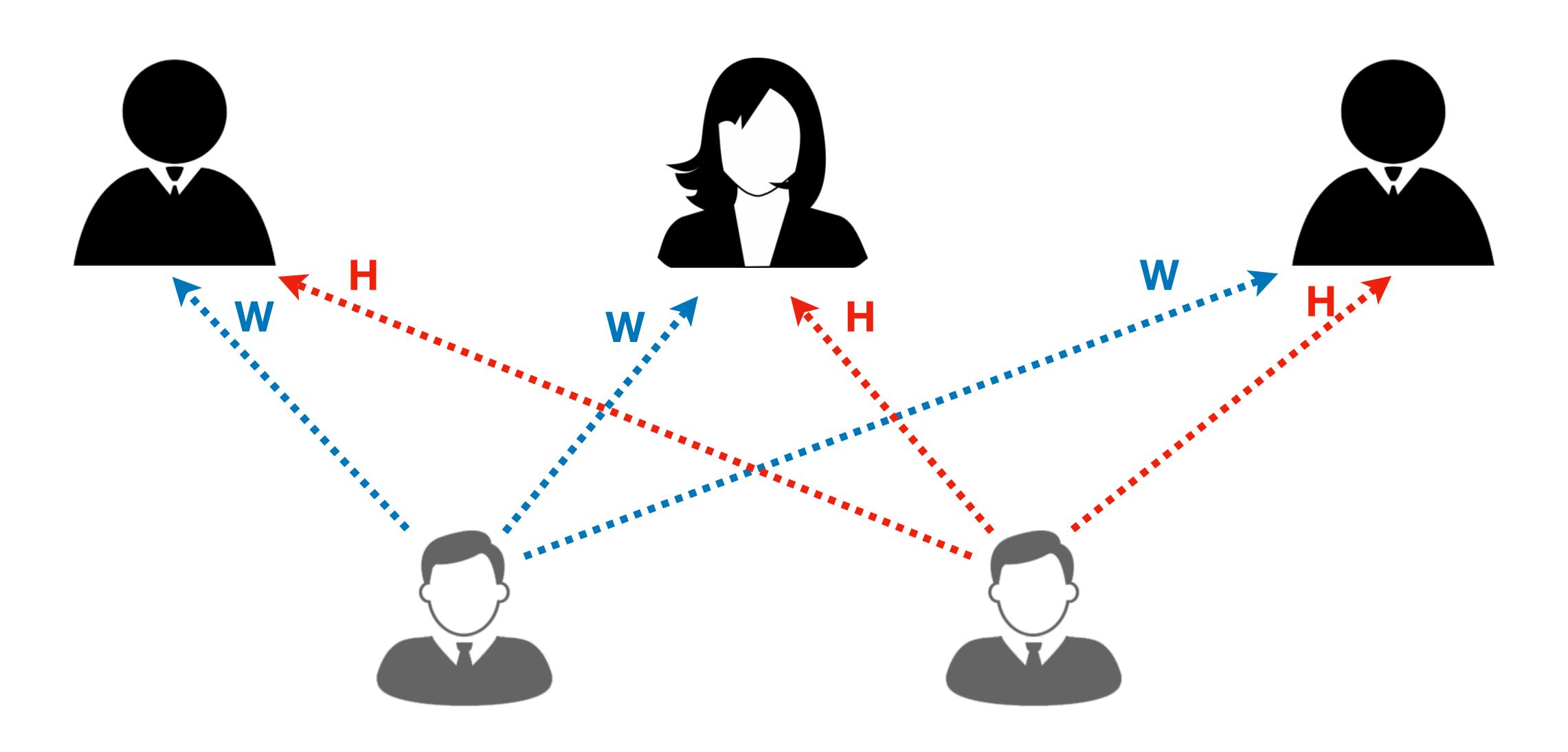
Multiple *acceptors* might disagree on the outcomes: now they need to *reach a consensus* themselves.

Separation of Concerns

- Proposers: suggest a value (a restaurant to go);
- Acceptors: support some proposal;
- The proposer with a *majority of acceptors* supporting its proposal wins.

Others learn the outcome by querying all the acceptors.

Acceptors

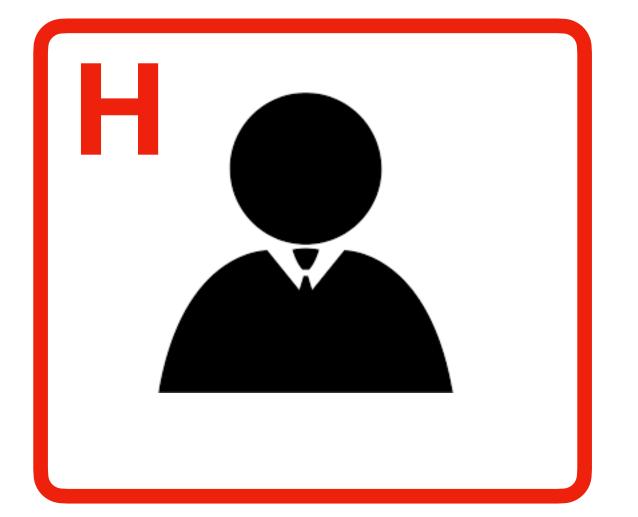


Proposers

Acceptors











Proposers

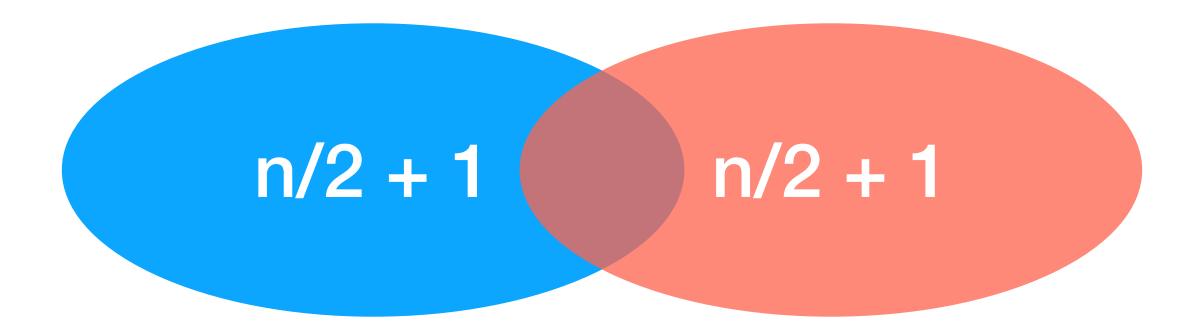
Key Idea 1

Rely on majority quorums for agreement to prevent the "split brain" problem.

- Common meaning: Quorum is the minimum number of members to conduct the business on behalf of the entire group they represent;
- In computing: quorum is a **necessary** number of processes to agree on the decision in the presence of potentially faulty ones.

Key Properties of Quorums

Property 1: any two quorums must have non-empty intersection

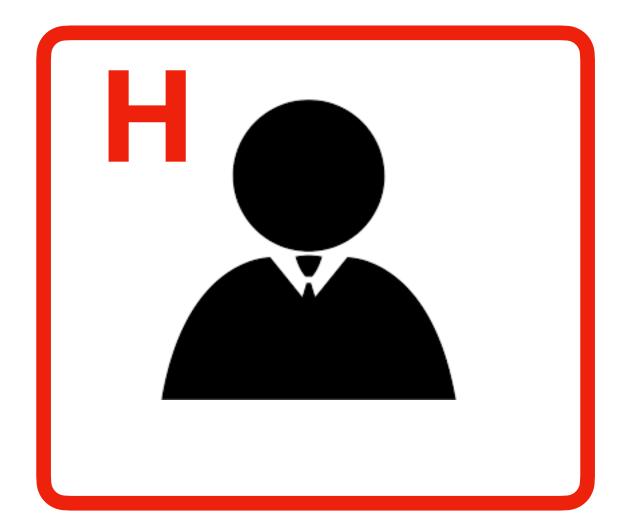


• Property 2: no need for the global agreement: can tolerate some faults

n = 3







Quorum of n/2 + 1 acceptors



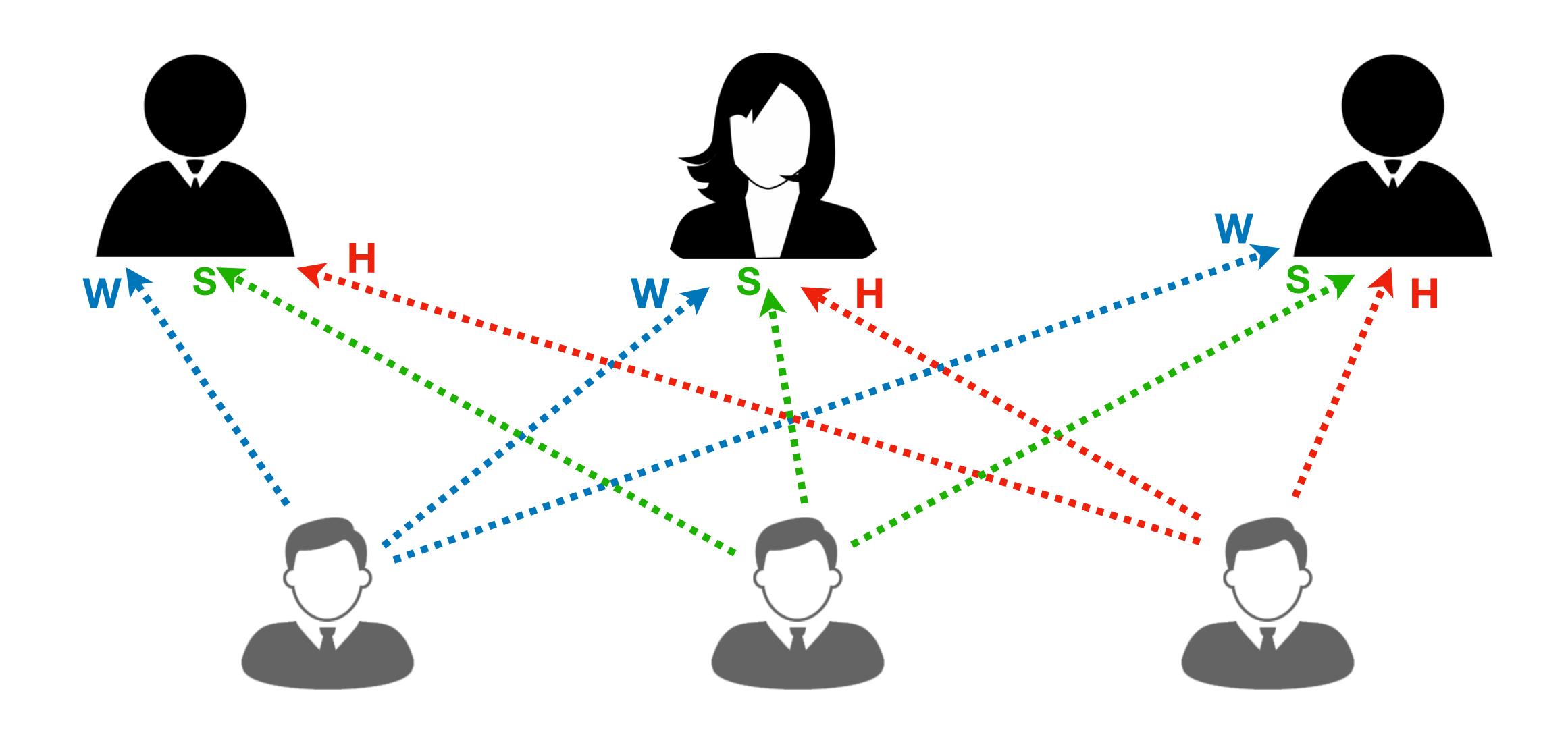


Problem

A quorum is difficult to obtain in a single interaction.

As the result, such a system will often get stuck.

Acceptors



Proposers

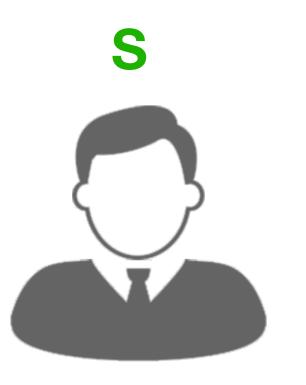
Acceptors













Proposers

Key Ideas 2 and 3

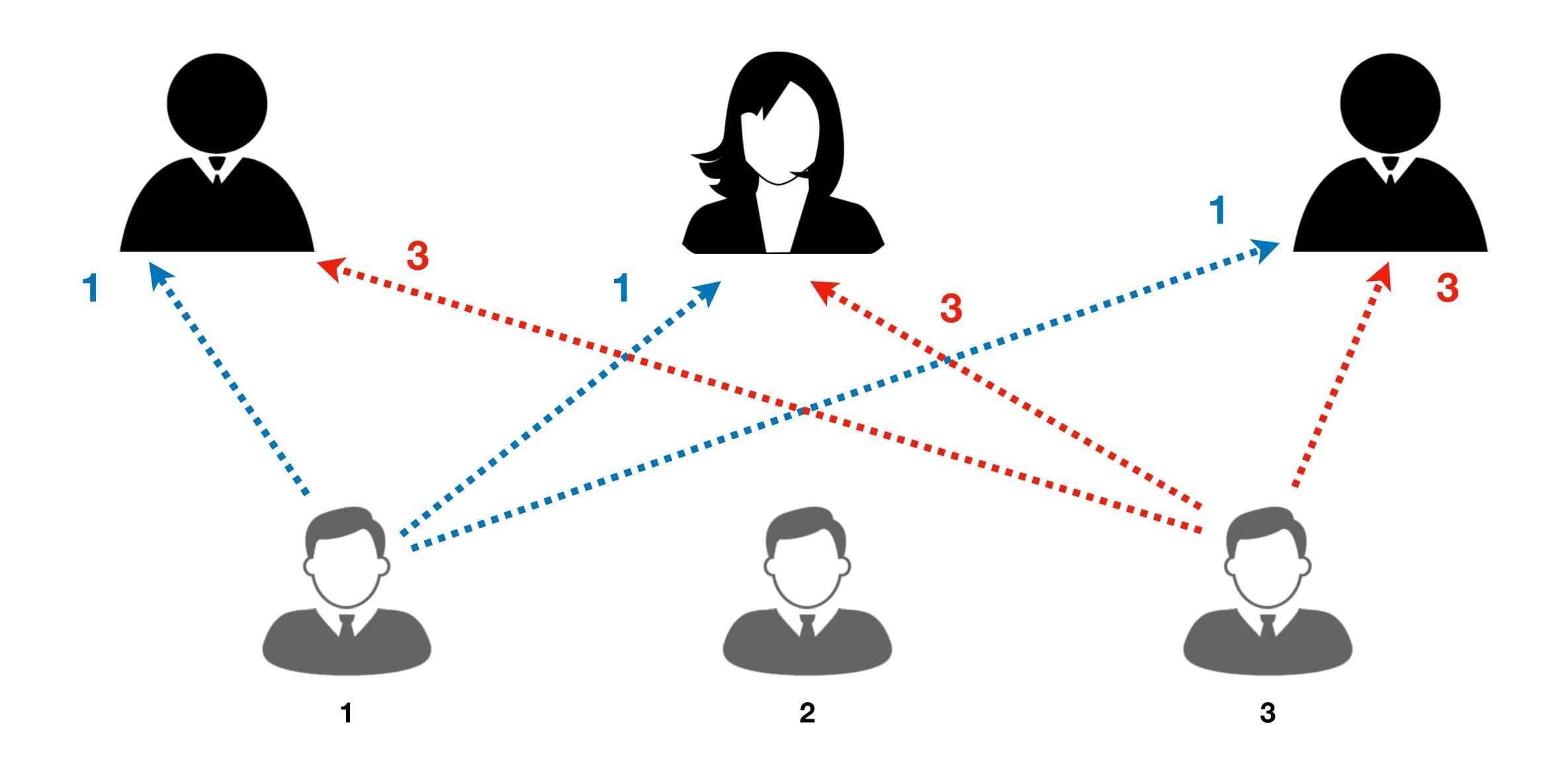
Proceed in rounds:

- A proposer first "secures" itself a quorum, willing to support its proposal (i.e., becomes a "leader");
- Only if a quorum is secured, it goes on to "propose" a value.
- Introduce fixed globally known priorities between proposers to "break ties" when securing quorums.
 - Acceptors only "choose to support" proposers with higher priorities than they have already seen.

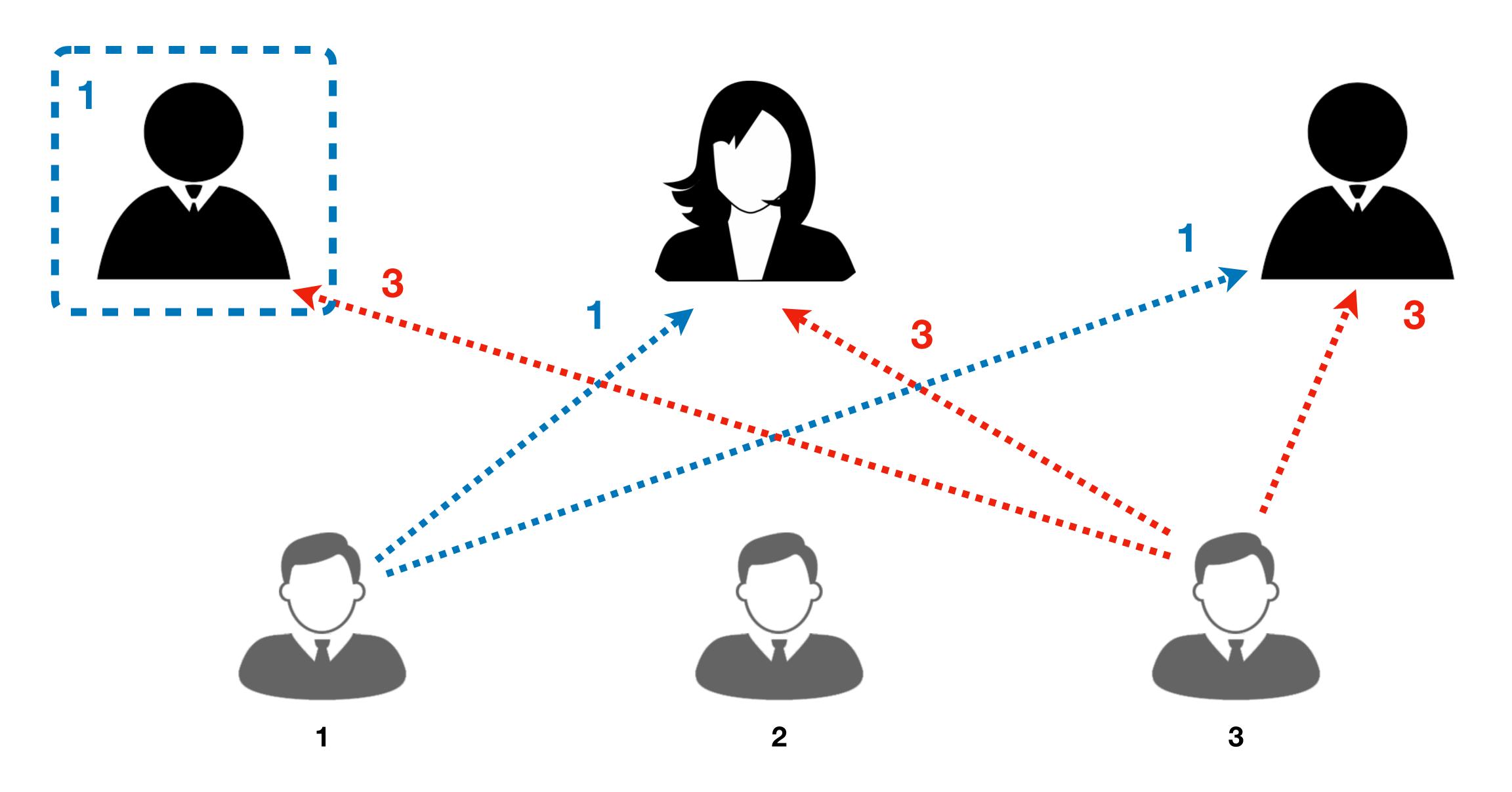
Some Terminology

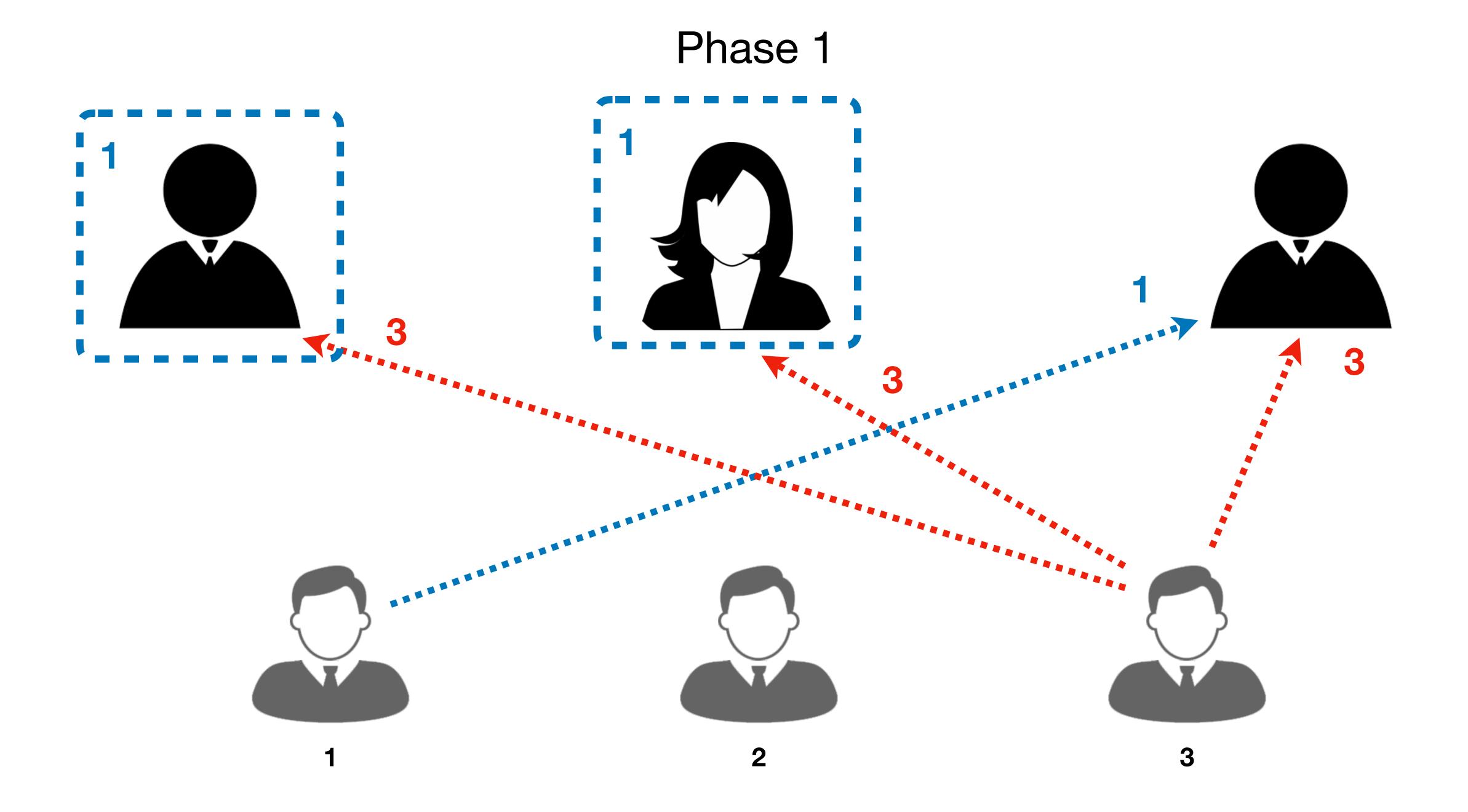
- Rounds Phases
 - Phase 1 "prepare", securing quorums to propose
 - Phase 2 "accept", sending values to accept
- Fixed priorities Ballots

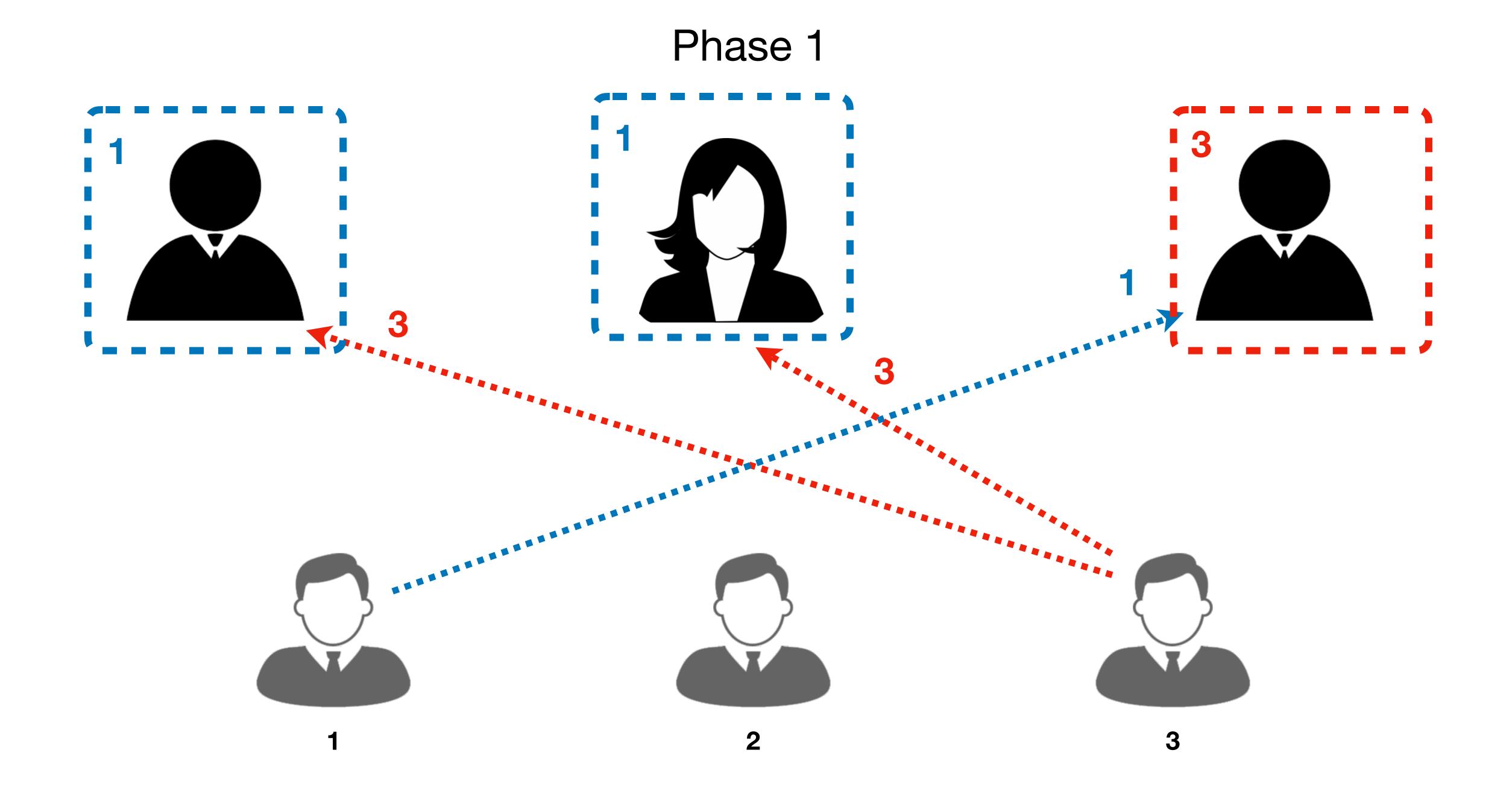
Phase 1

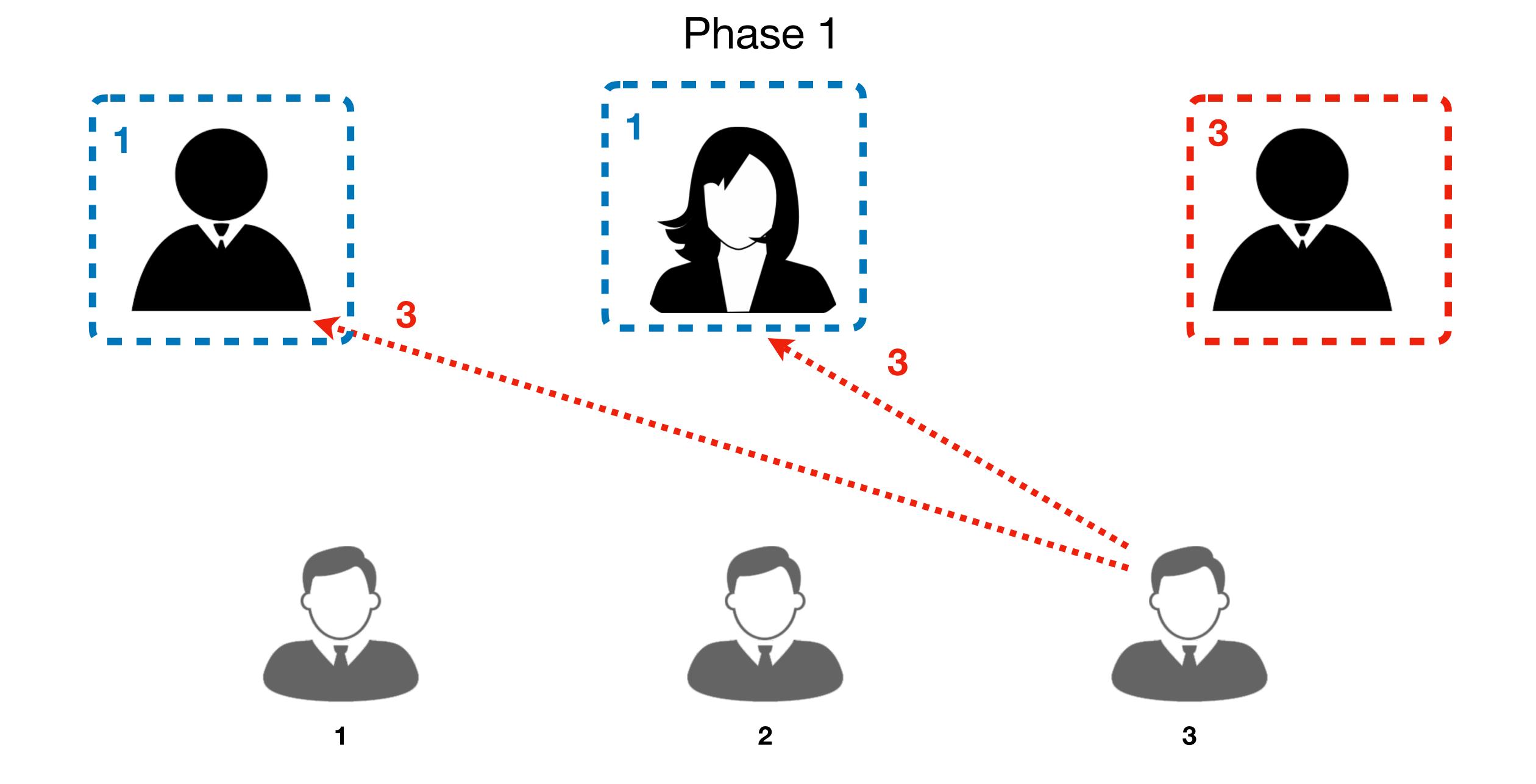


Phase 1



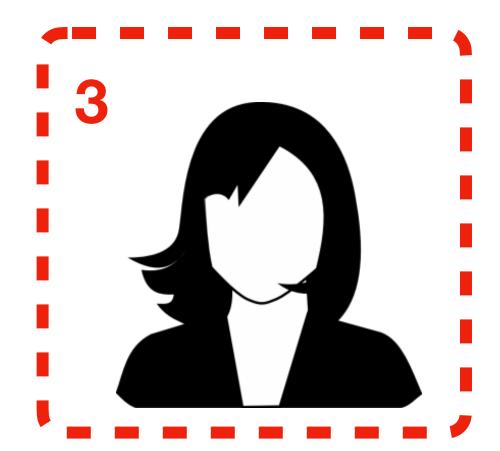


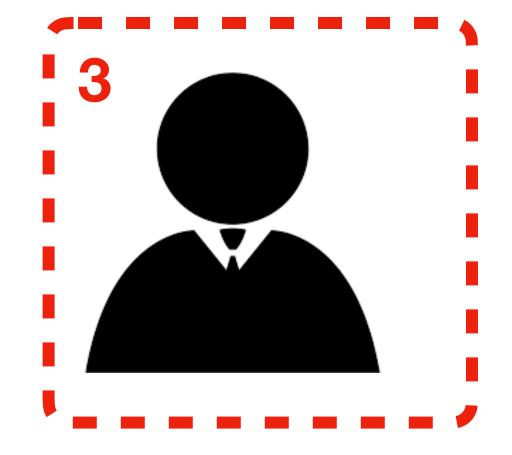




Phase 1





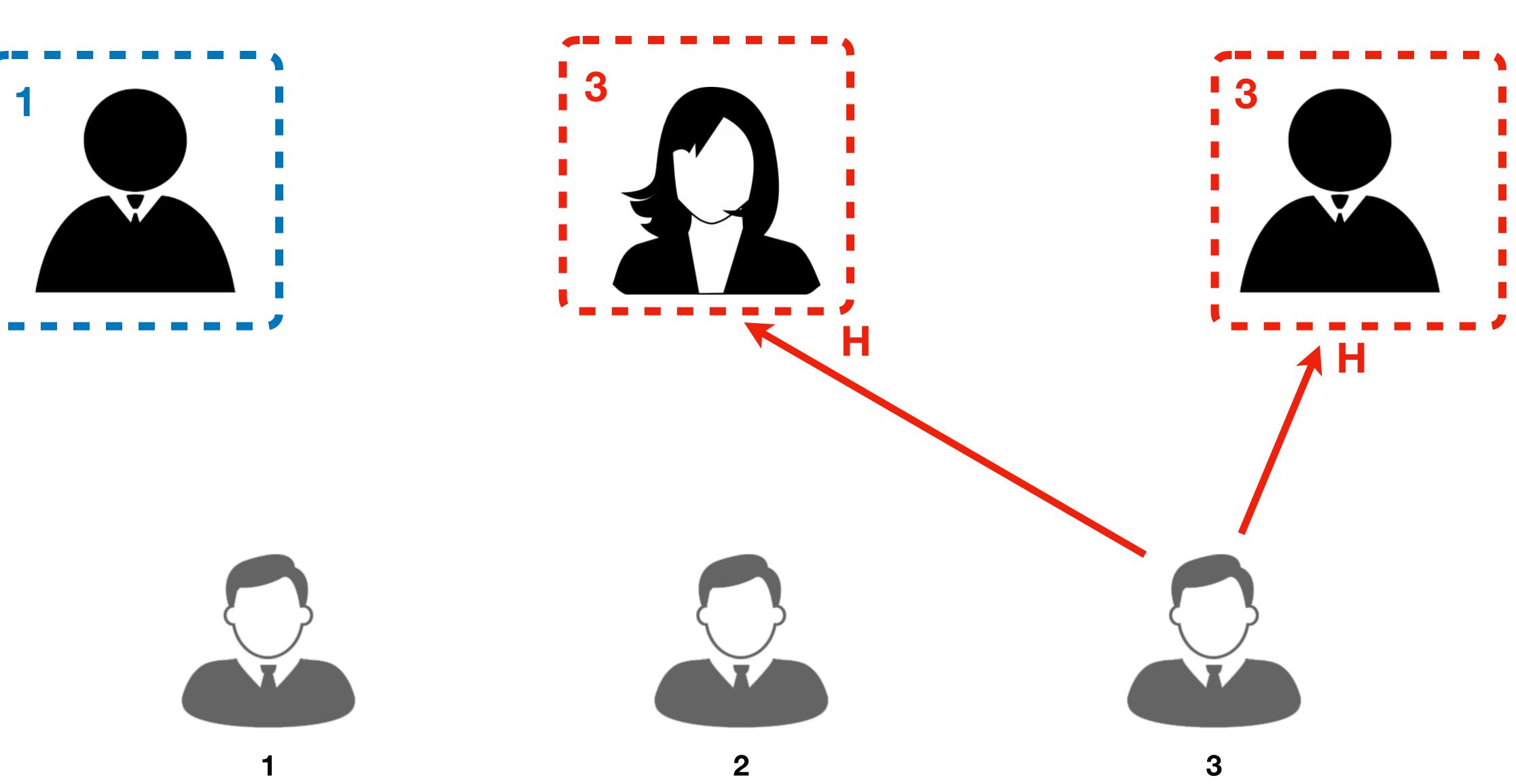






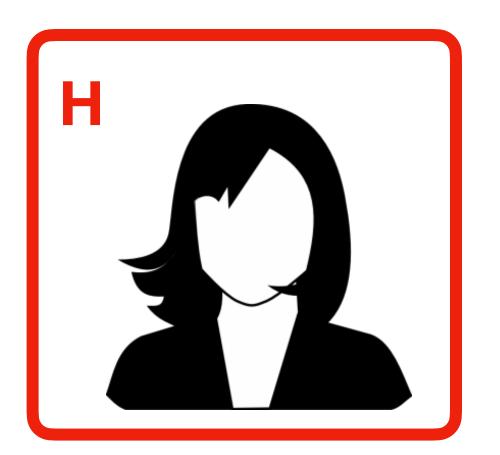


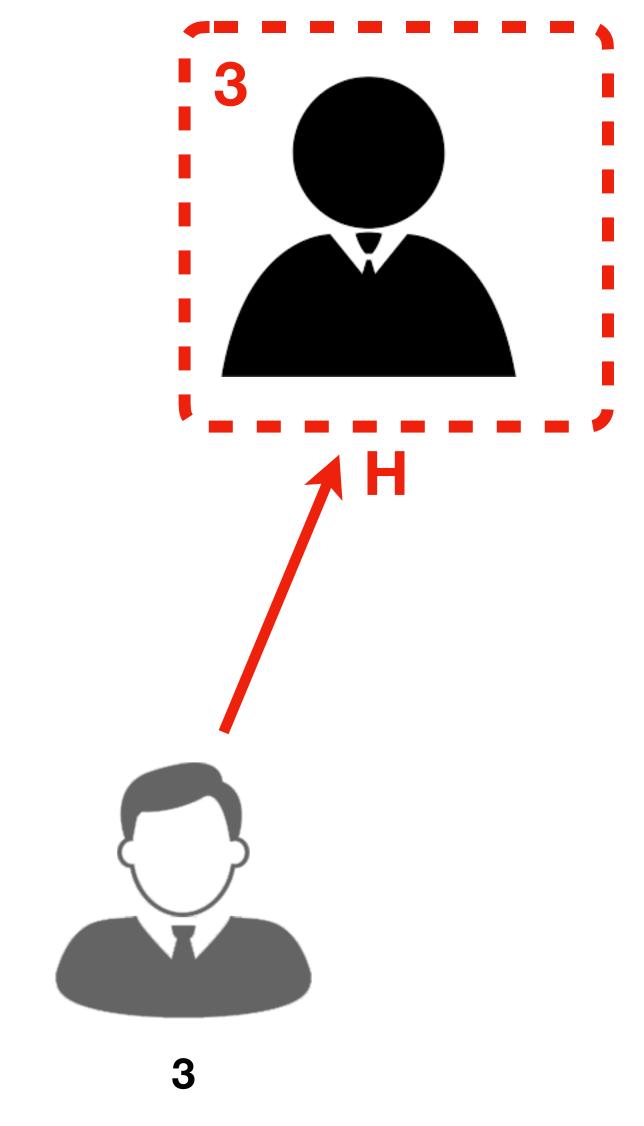
Phase 2



Phase 2







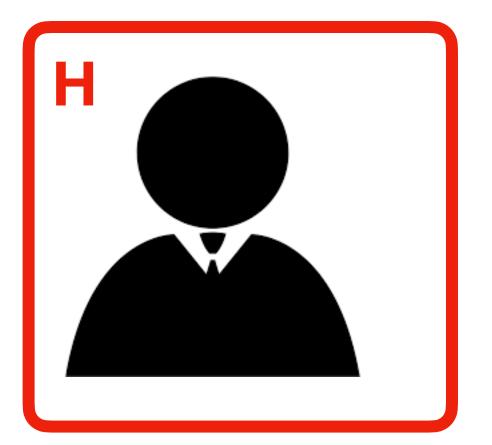




Phase 2







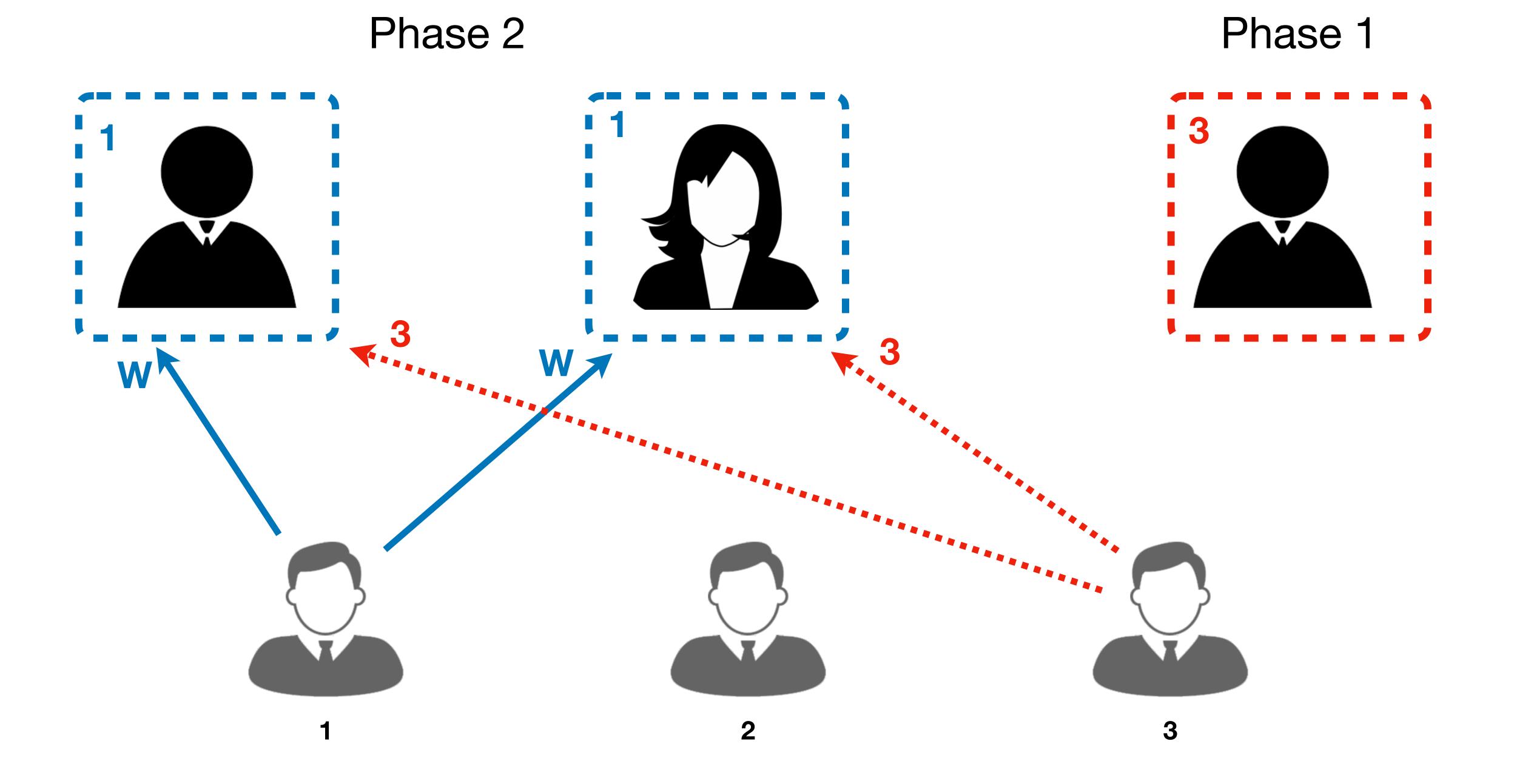


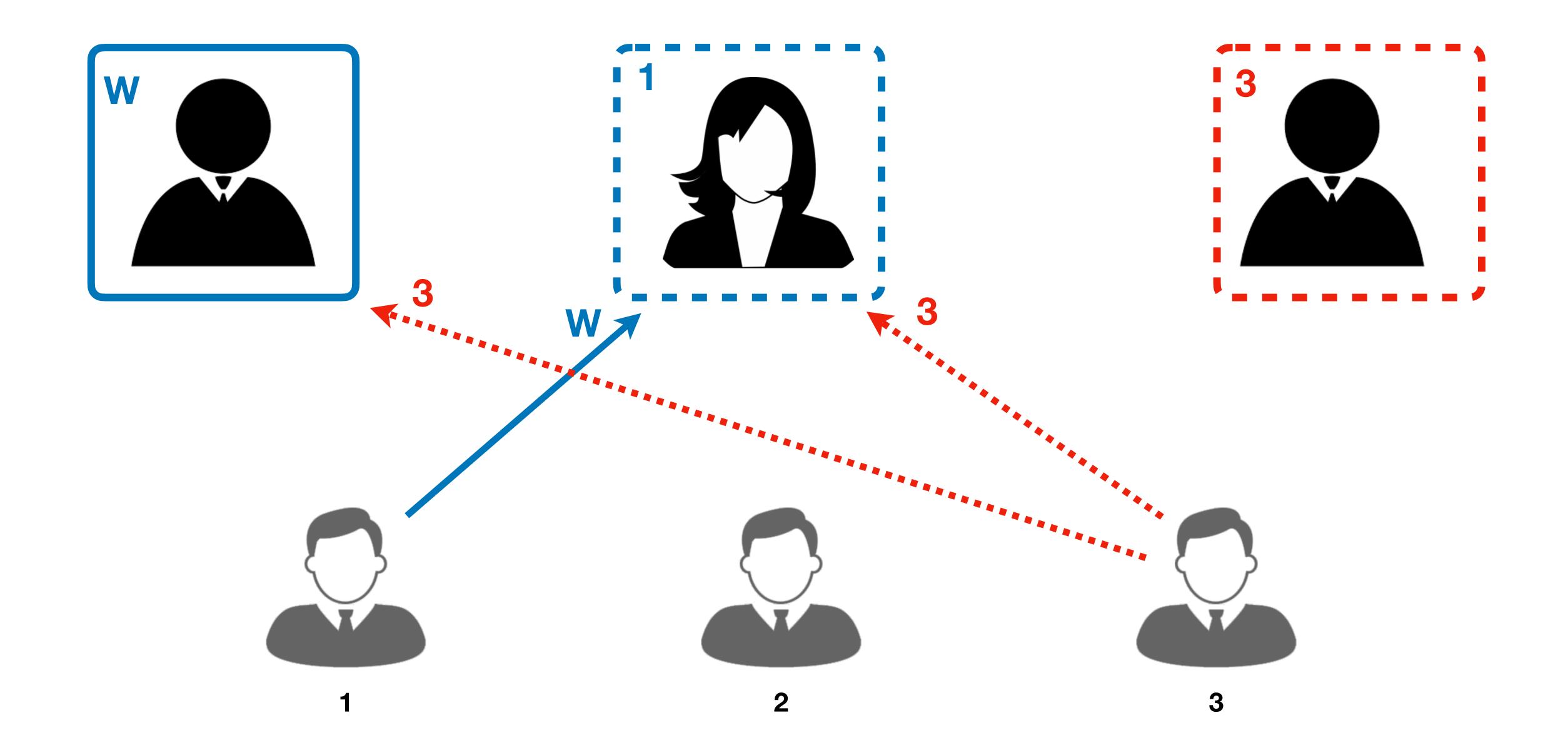


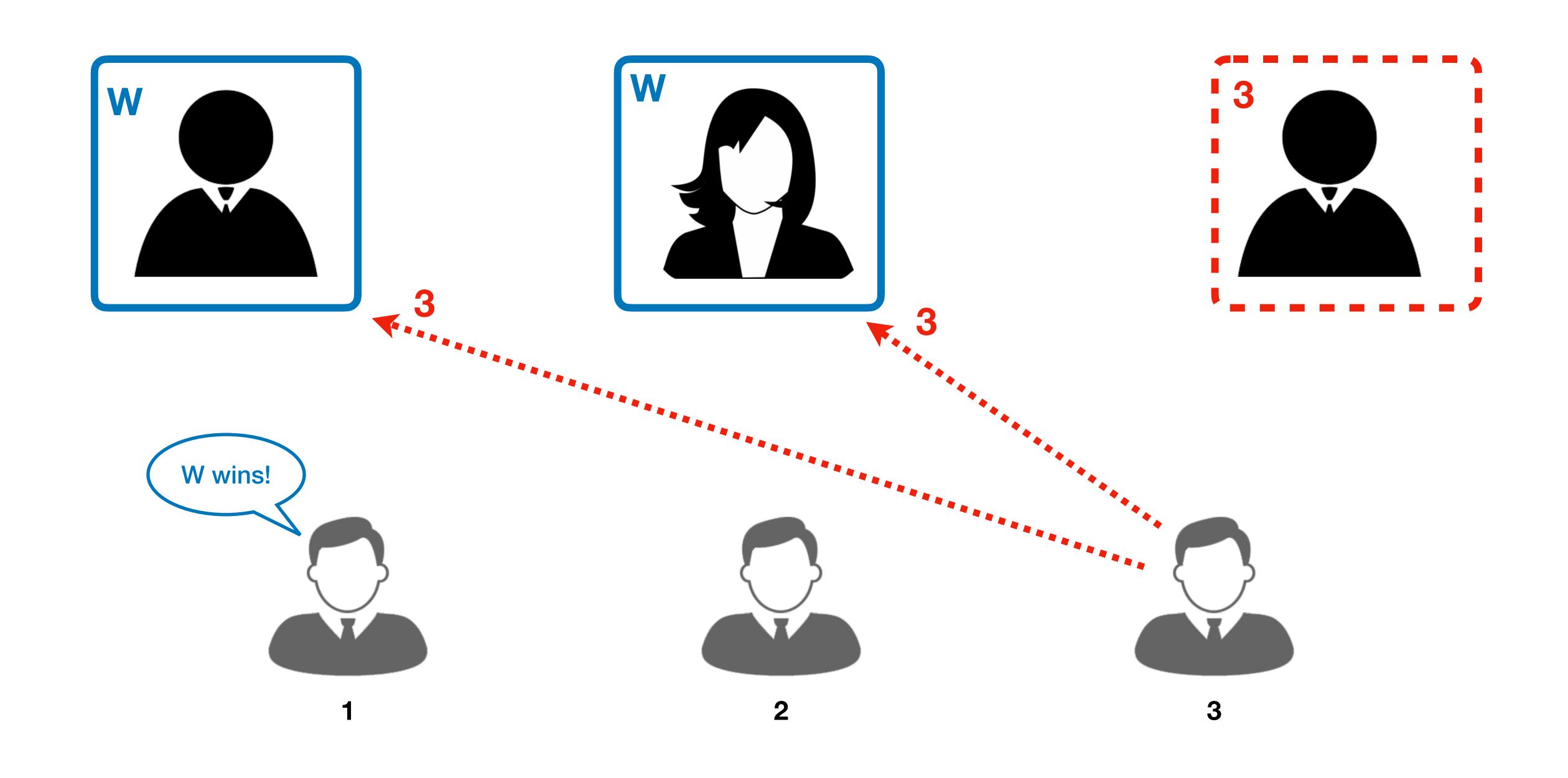


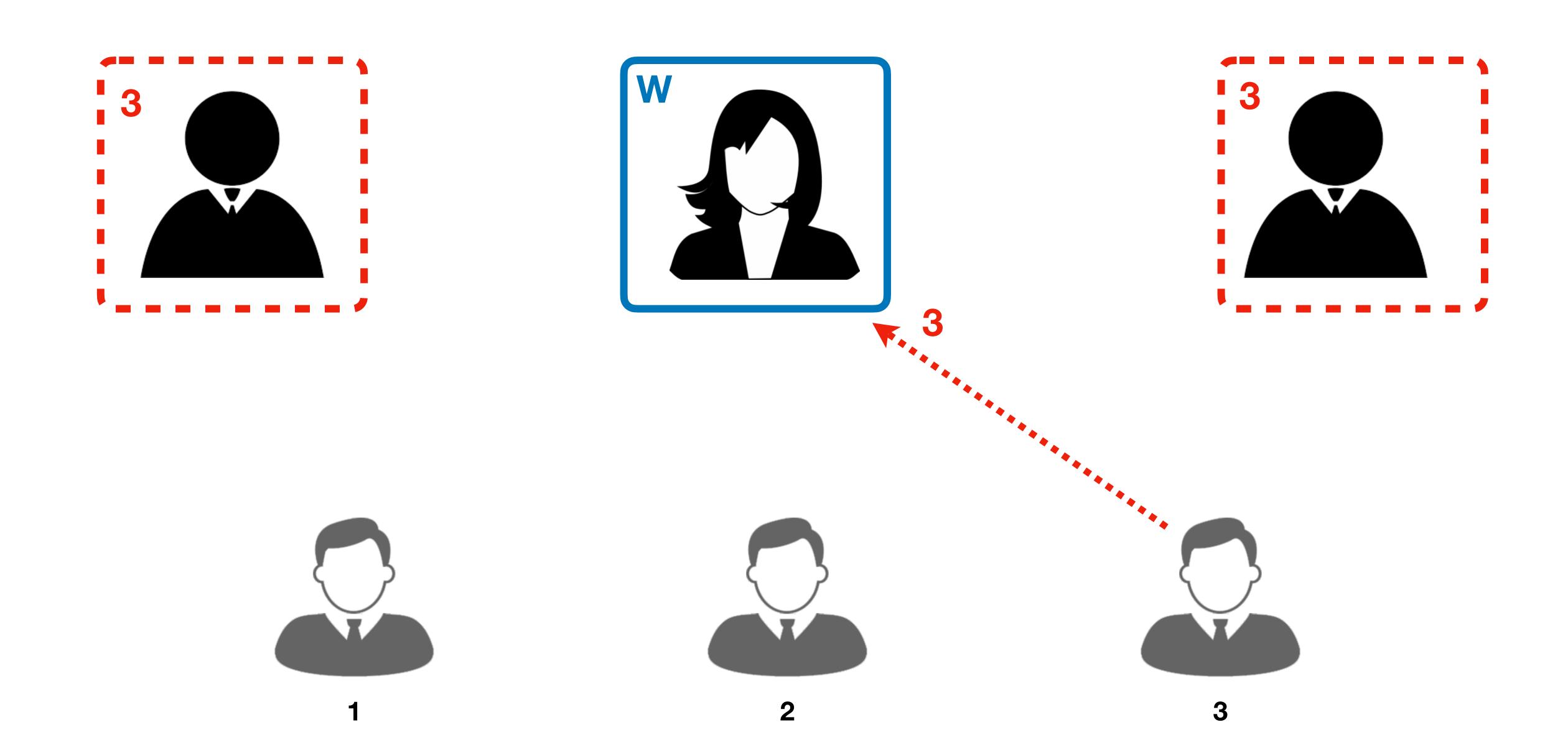
Problem 3

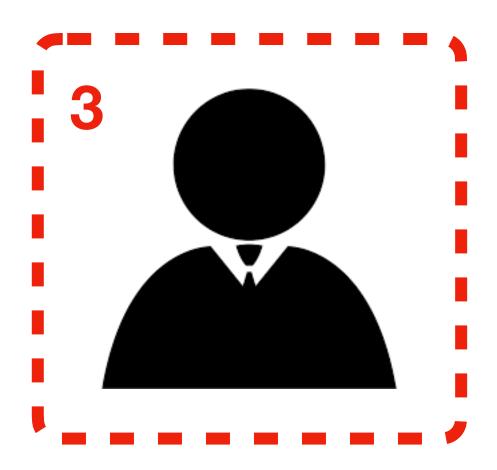
Because of asynchrony, low-priority Phase 2 can be interrupted by a high-priority Phase 1



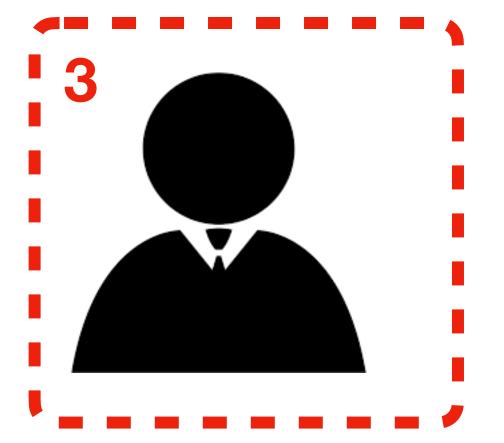








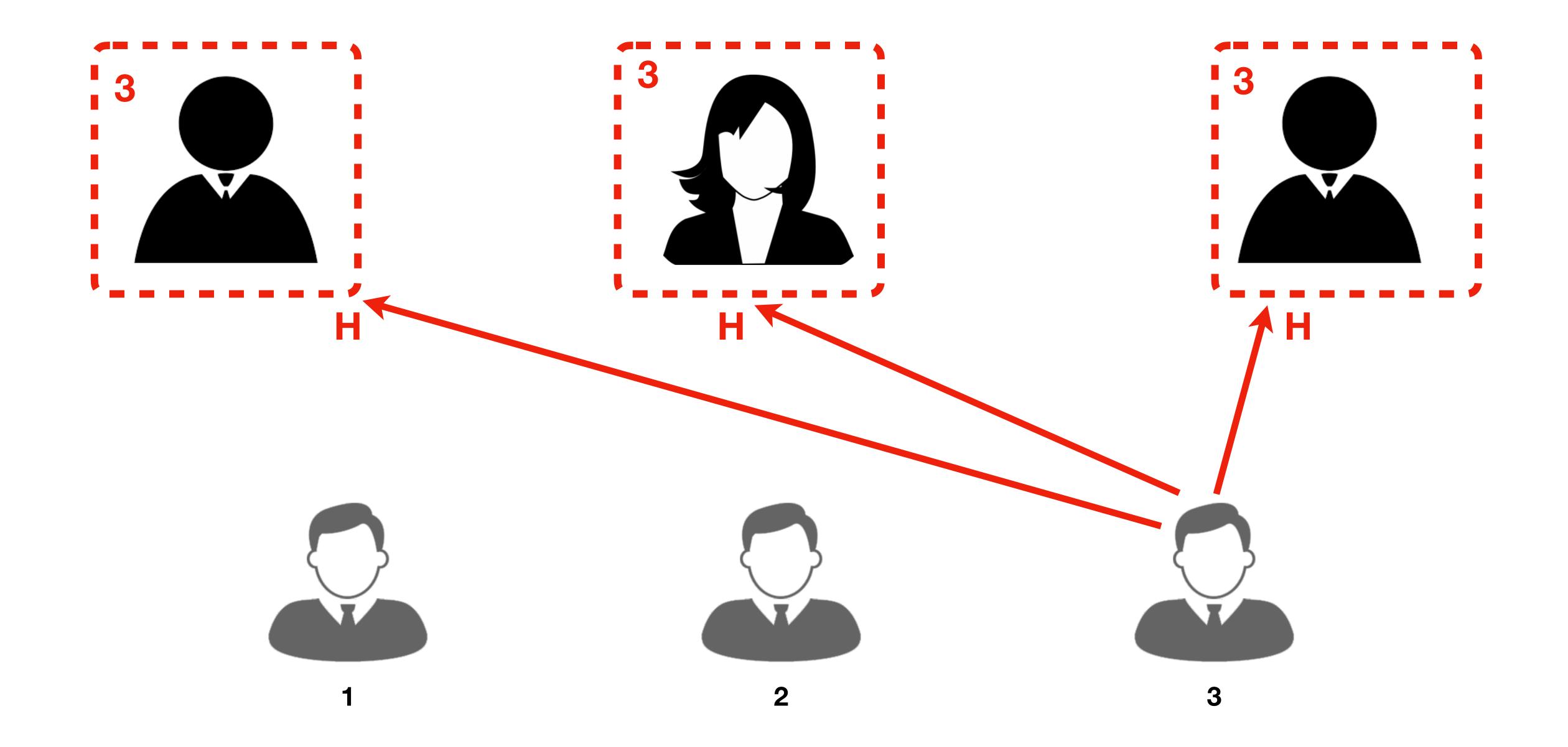


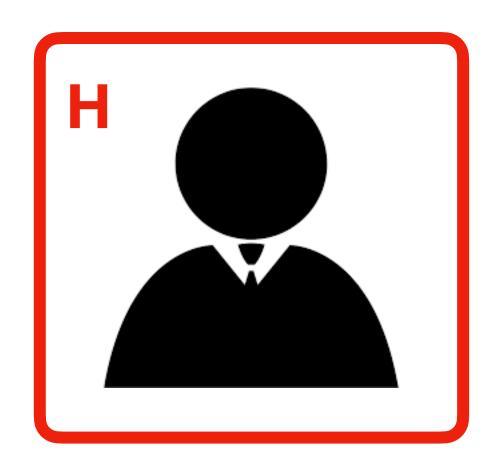






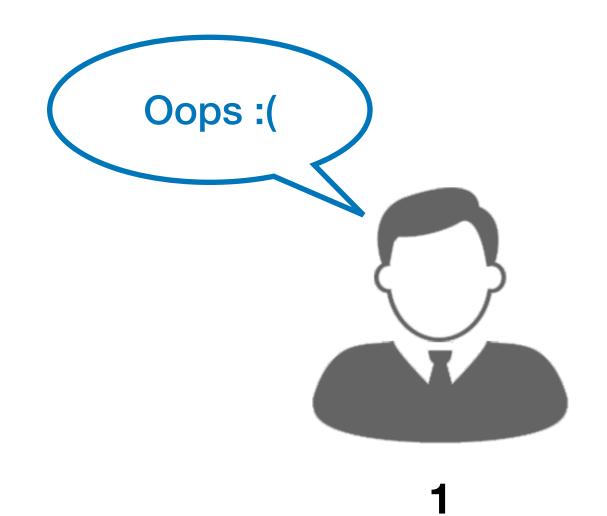














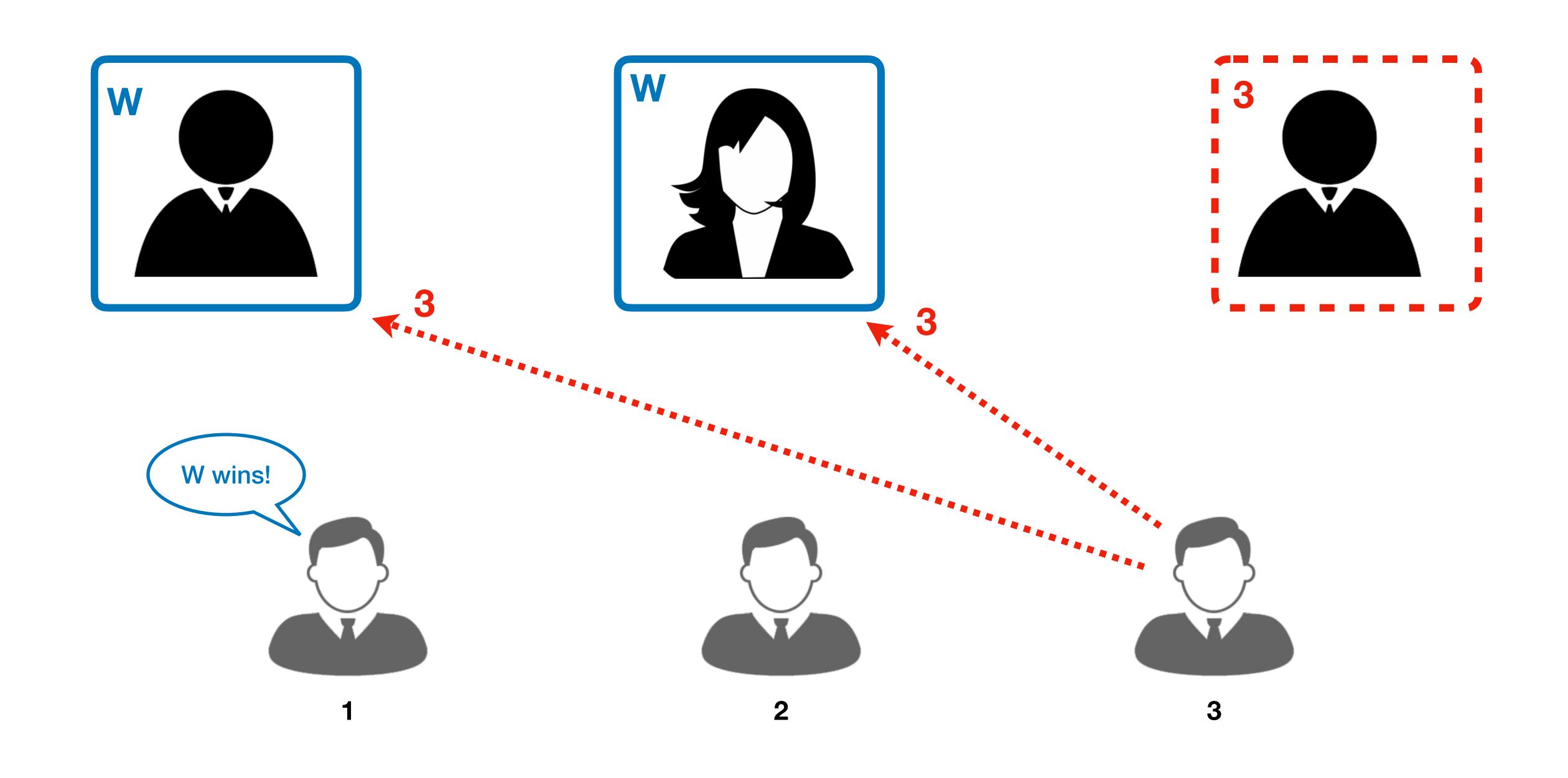


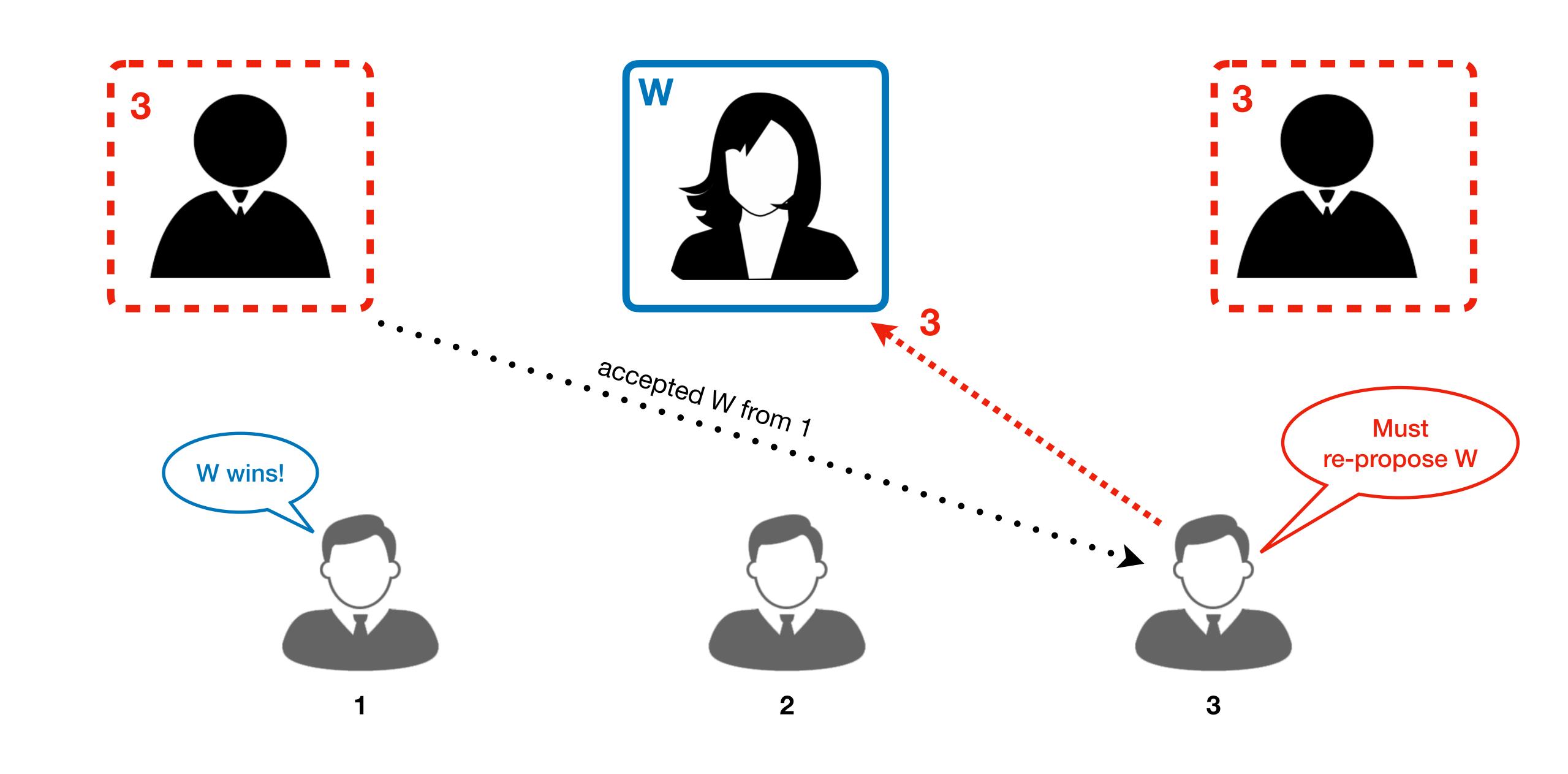
Problem 3

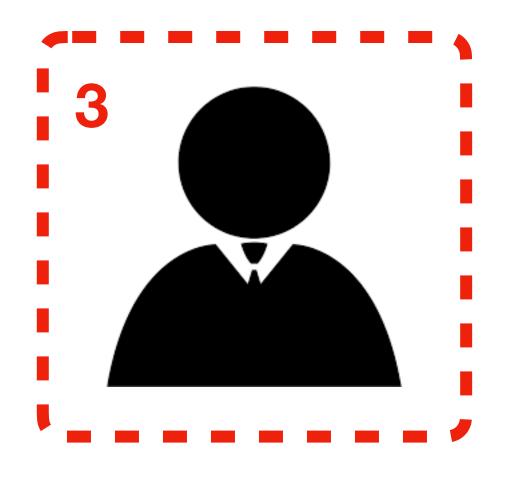
How to ensure irrevocability of consensus in the presence of *priorities* and *asynchrony*?

Key Idea 4

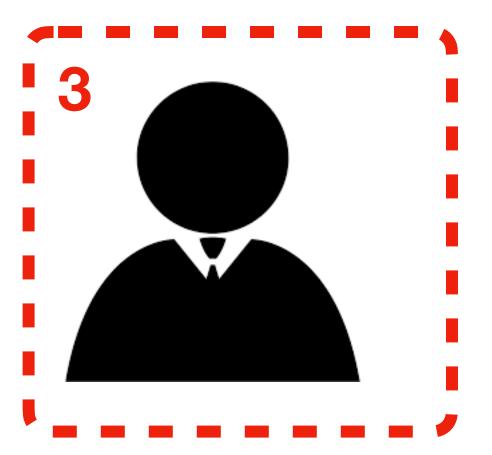
- Cooperation between Proposers and Acceptors:
 - Acceptors, when agreeing to support a proposer, must "tell" what was
 the highest-ballot value they have accepted;
 - Higher-ballot proposers re-propose already (partially) accepted values from the lower-ballot proposers, who secured the quorum before.
- This way, a proposer "knows" that, once it secured its quorum, either
 - its own proposal, or some higher-ballot one will be accepted
 - if its proposal got accepted, it will not be revoked (thanks to quorum intersection)





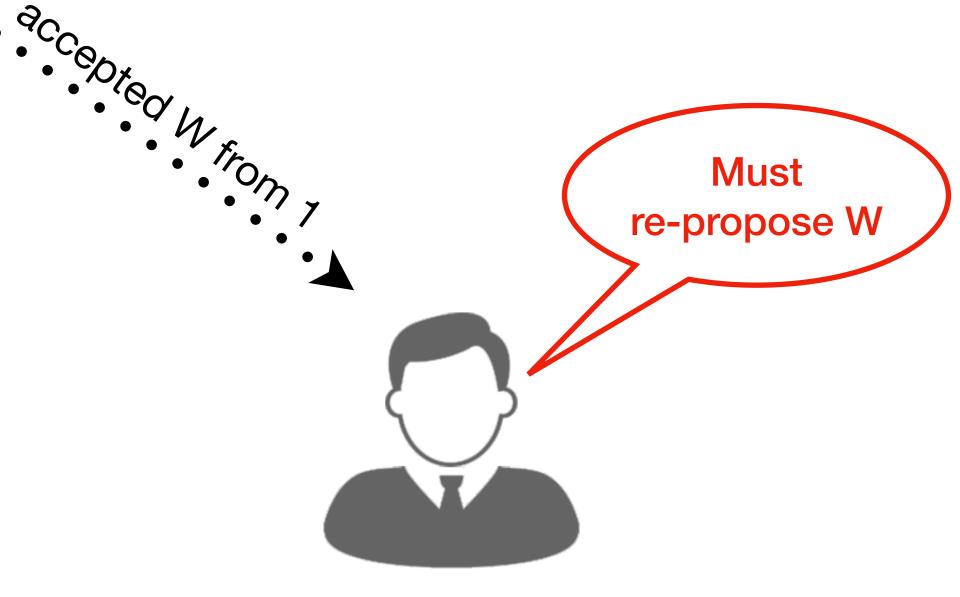


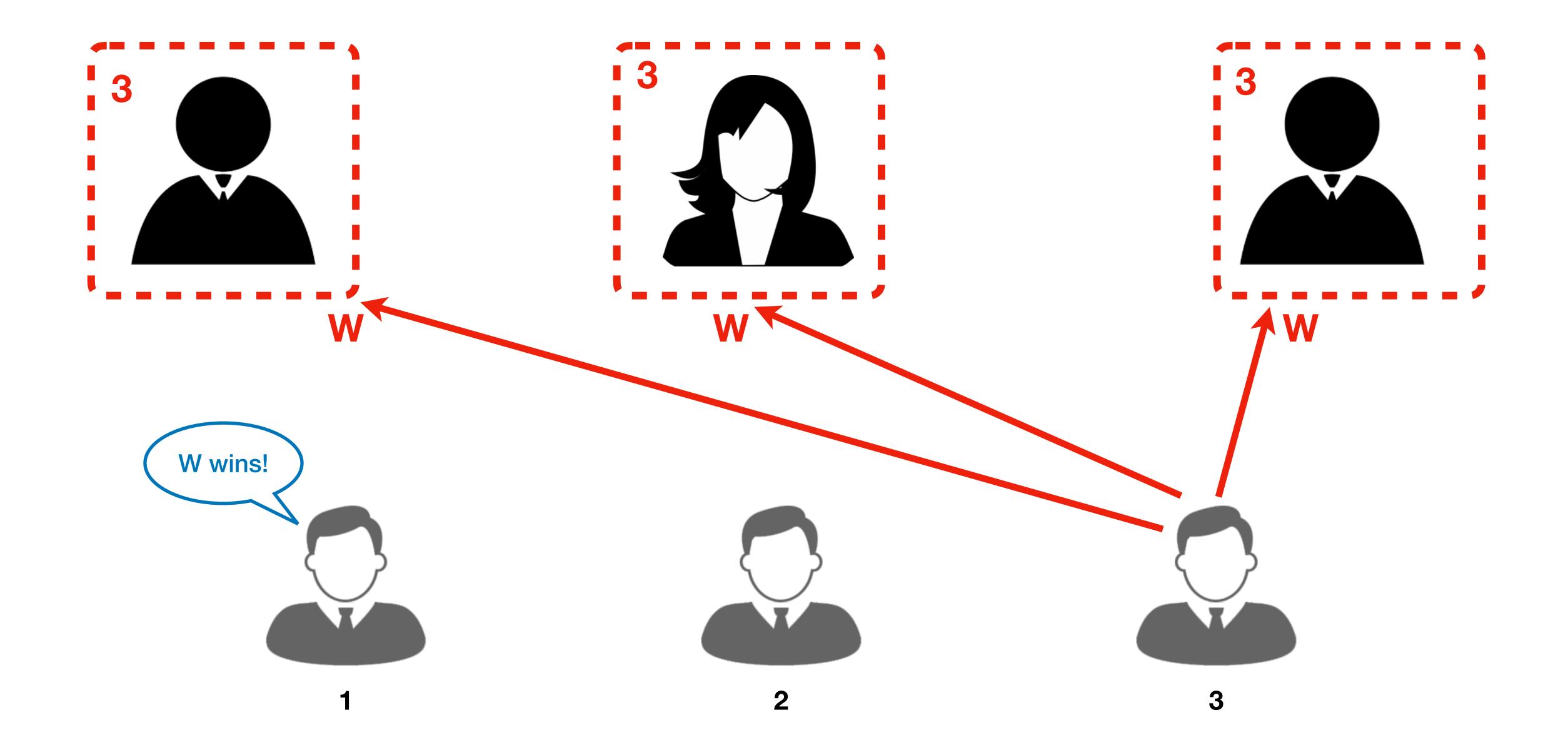






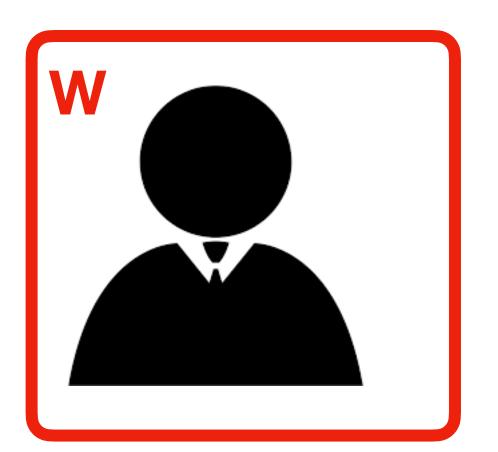






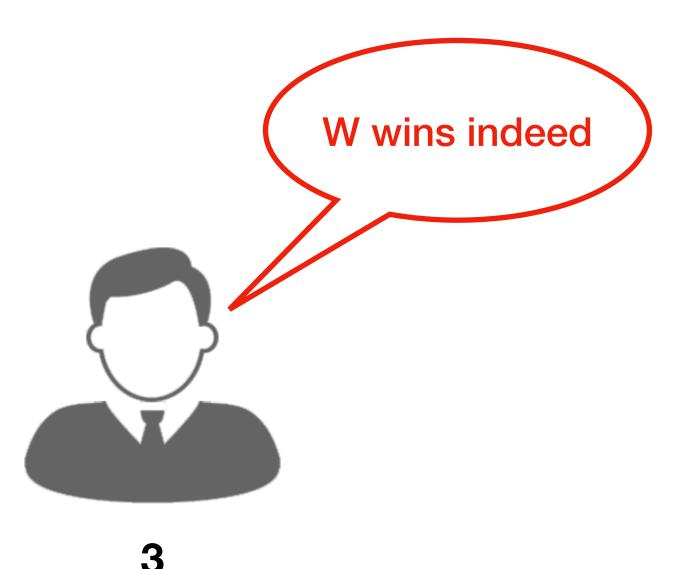












Two-Phase Ballot-based Consensus

- Proposers suggest values, acceptors decide upon acceptance;
- Each proposal goes in two rounds:
 - Phase 1: securing a quorum of acceptors for a proposal
 - Phase 2: sending out the proposal
- Acceptors agree only to support ballots higher than what they've seen;
- They inform proposers of *previously accepted values*, which those then re-propose.

The Algorithm in a Nutshell

Proposer

Acceptor

Phase 1

- Send my ballot **b** to all acceptors
- Wait for response of at least n/2 + 1 acceptors
- Upon receiving a ballot b
 - if it's the first one, remember it and send "ok" back.
 - if it's higher than **b'** we supported before, send back a previously accepted (b', v'), and remember **b** as what's currently supported.

Phase 2

- When heard back from n/2 + 1 acceptors, send them back (b, w), where
 - **b** is my ballot
 - w is the value from the acceptors with the highest ballot, or my own value.

Accept incoming value w if it comes with a ballot **b**, which we currently support; ignore otherwise.

Learning an Accepted Value

- A dedicated *learner* sends request to all acceptors;
- If at least n/2 + 1 acceptors respond back with *the same* value **v**, this is an accepted value.
- Correctness of this reasoning follows from irrevocability.

Learning an Accepted Value

- A dedicated *learner* sends request to all acceptors;
- If at least n/2 + 1 acceptors respond back with the same value v, this is an accepted value.
- Correctness of this reasoning follows from irrevocability.
- And what if n/2 + 1 have the value, but one of them does not respond?
- In this case we need to introduce a time out (synchrony).

Impossibility of Distributed Consensus with One Faulty Process

MICHAEL J. FISCHER

Yale University, New Haven, Connecticut

NANCY A. LYNCH

Massachusetts I

AND

If we expect failures, we should rely on time-outs.

MICHAEL S. PATERSON

University of Warwick, Coventry, England

Abstract. The consensus problem involves an asynchronous system of processes, some of which may be unreliable. The problem is for the reliable processes to agree on a binary value. In this paper, it is shown that every protocol for this problem has the possibility of nontermination, even with only one faulty process. By way of contrast, solutions are known for the synchronous case, the "Byzantine Generals" problem.

Paxos

- A practical fault-tolerant distributed consensus algorithm;
- Invented in 1990, published in 1998;
- Nowadays used everywhere: Google (Bigtable, Chubby), IBM, Microsoft;
- You have just seen it explained.

History of Paxos

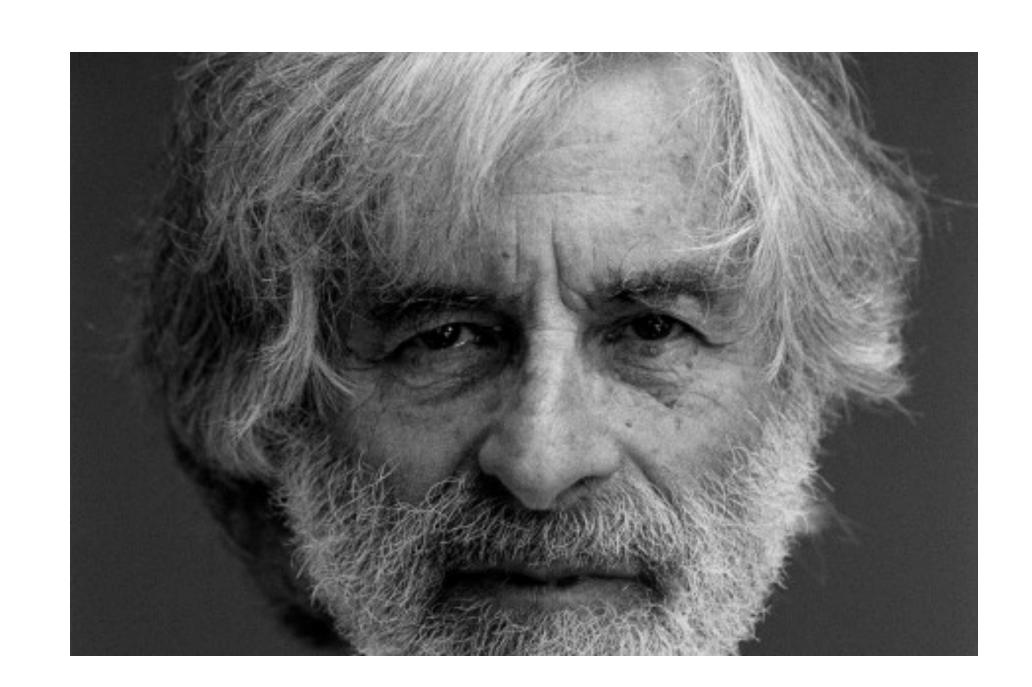
1990: Paxos first described

1998: Paxos paper published

2005: First practical deployments

2010: Widespread use!

2014: Lamport gets Turing Award



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

History of Paxos

1990: Paxos first described

1998: Paxos paper published

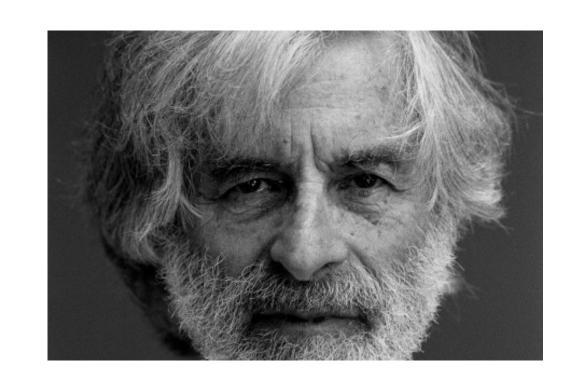
2005: First practical dep

2010: Widespread use!

2014: Lamport gets Turii

Recent archaeological discoveries on the island of Paxos reveal that the parliament functioned despite the peripatetic propensity of its part-time legislators.

The legislators maintained consistent copies of the parliamentary record, despite their frequent forays from the chamber and the forgetfulness of their messengers.



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

History of Paxos

1990: Paxos first described

1998: Paxos paper published

2014: La

• The ABCDs of Paxos [2001]

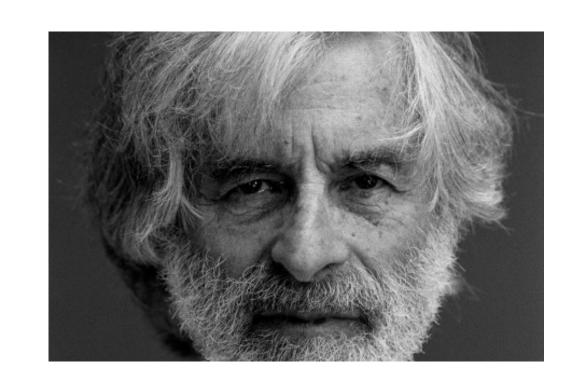
2005: Fi Paxos Made Simple [2001]

2010: w • Paxos Made Practical [2007]

Paxos Made Live [2007]

• Paxos Made Moderately Complex [2011]

• Paxos Consensus, Deconstructed and Abstracted [2018]



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

Multi-Paxos

- Presented in the original Lamport's 1998 paper.
- Uses the described idea for a sequence of "slots" (think transactions).
- Includes reconfiguration (changing set of acceptors on the fly).
- Naive implementation: run Simple Paxos for each slot.
 - Better approach secure a quorum for several slots.

Running Paxos with Scala Actors

```
def createProposers(system: ActorSystem, numProposers: Int, acceptors: Seq[ActorRef]) = {
   for (i <- 0 until numProposers) yield {
      system.actorOf(Props(ProposerClass, this, acceptors, i), name = s"Proposer-P$i")
   }
}</pre>
```

Live Demo

Alternative Consensus Protocols

- View-Stamped Replication
 by Brian M. Oki and Barbara Liskov, 1989
- Raft
 by Diego Ongaro and John K. Ousterhout, 2014

To Take Away

- Fault-Tolerant Consensus Protocols are a critical component of modern distributed systems and applications
- Consensus properties are uniformity, non-triviality, and irrevocability
- The key ideas of Lamport's Paxos protocol are:
 - Majority *quorums* (avoiding split brain and enabling fault-tolerance);
 - Two-phase structure (secure-then-commit);
 - Dichotomy and cooperation between proposers and acceptors.