

Exponential Smoothing for Off-Policy Learning

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Motivation



Why Revisit IPS?

Setting

Offline contextual bandit [7, 8, 9, 10] with logged data $\mathcal{D}_n = \{(X_i, A_i, R_i)\}_{i=1}^n$ from a known logging policy π_0 .

Goal: learn $\hat{\pi} \in \Pi$ maximizing $V(\pi) = \mathbb{E}_{X \sim \nu, A \sim \pi(\cdot|X)} [r(X, A)]$.

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Problem

IPS is unbiased but has high variance; **IW clipping** reduces variance but: (i) introduces high bias, (ii) is non-differentiable (flat regions), (iii) sensitive to hyperparameter tuning.

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Our answer

Exponential smoothing (ES): smooth, differentiable IW regularization, and two-sided PAC-Bayes generalization bounds that are *optimizable by SGD*.

Regularized IPS

IPS [8]

$$\hat{V}_{\text{IPS}}(\pi) = \frac{1}{n} \sum_{i=1}^n R_i w(A_i | X_i), \quad w(a | x) = \frac{\pi(a | x)}{\pi_0(a | x)}.$$

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Regularized IPS [5]

$$\hat{V}(\pi) = \frac{1}{n} \sum_{i=1}^n R_i \hat{w}(A_i | X_i), \quad \hat{w} \leq w.$$

Hard IW clipping: $\hat{w} = \min\{w, M\}$ or $\hat{w} = \frac{\pi}{\max(\pi_0, \tau)}$.

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Limitations of hard IW clipping

Non-differentiable (zero gradients beyond M), highly sensitive to M and τ , loses ordering when many $\pi_0(\cdot|x)$ are clipped to the same value.

Exponential Smoothing

Smooth variant

$$IPS-\alpha : \quad \hat{V}^\alpha(\pi) = \frac{1}{n} \sum_{i=1}^n R_i \frac{\pi(A_i \mid X_i)}{\pi_0(A_i \mid X_i)^\alpha}, \quad \alpha \in [0, 1].$$

Definition and Properties

Smooth variant

$$IPS-\alpha : \hat{V}^\alpha(\pi) = \frac{1}{n} \sum_{i=1}^n R_i \frac{\pi(A_i | X_i)}{\pi_0(A_i | X_i)^\alpha}, \alpha \in [0, 1].$$

Bias-variance trade-off for α

$$\begin{aligned} |\mathbb{B}(\hat{V}^\alpha)| &\leq \mathbb{E}_{X, A \sim \pi(\cdot|X)} [1 - \pi_0(A|X)^{1-\alpha}] , \\ \mathbb{V} [\hat{V}^\alpha] &\leq \frac{1}{n} \mathbb{E}_{X, A \sim \pi(\cdot|X)} \left[\frac{\pi(A|X)}{\pi_0(A|X)^{2\alpha-1}} \right] . \end{aligned}$$

$\alpha \rightarrow 1$: low bias (IPS); $\alpha \rightarrow 0$: low variance.

Why ES Beats Clipping in Optimization

- Smooth and everywhere differentiable \Rightarrow stable SGD; no flat regions.
- Preserves ranking induced by π_0 : if $\pi_0(a|x) < \pi_0(a'|x)$ then $\pi_0(a|x)^\alpha < \pi_0(a'|x)^\alpha$.
- Single bounded hyperparameter ($\alpha \in [0, 1]$) instead of $M \in [0, \infty)$.

Pessimism via PAC-Bayes

From One-Sided to Two-Sided

Prior pessimistic objectives

One-sided bounds [11, 12] lead to $V(\pi) \geq \hat{V}(\pi) - g(\cdot)$ but cannot certify estimator quality.

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Our approach

Two-sided, tractable PAC-Bayes bound directly optimized by SGD. Works without the bounded-IW assumption and applies to **standard IPS** ($\alpha = 1$).

Main Theorem (Two-Sided PAC-Bayes, Informal)

$$|R(\pi_{\mathbb{Q}}) - \hat{R}_n^{\alpha}(\pi_{\mathbb{Q}})| \leq \mathcal{O}\left(\frac{D_{\text{KL}}(\mathbb{Q}||\mathbb{P}) + \bar{V}_n^{\alpha}(\pi_{\mathbb{Q}})}{\sqrt{n}} + B_n^{\alpha}(\pi_{\mathbb{Q}})\right),$$

where

- $\hat{R}_n^{\alpha}(\pi_{\mathbb{Q}}) = \frac{1}{n} \sum_{i=1}^n \frac{\pi_{\mathbb{Q}}(a_i|x_i)}{\pi_0(a_i|x_i)^{\alpha}} c_i$, $\forall \alpha \in [0, 1]$.
- $\pi_0 = \pi_{\mathbb{P}}$.
- $B_n^{\alpha}(\pi_{\mathbb{Q}})$ is a bias term.
- $\bar{V}_n^{\alpha}(\pi_{\mathbb{Q}})$ is a variance term.

Tuning α

Grounded and data-**adaptive** principle to simultaneously optimize $\alpha \in [0, 1]$ and $\mathbb{Q} \in \mathcal{M}_1(\mathcal{H})$ as

$$\arg \min_{\mathbb{Q} \in \mathcal{M}_1(\mathcal{H}), \alpha \in [0, 1]} \hat{R}_n^\alpha(\pi_{\mathbb{Q}}) + \mathcal{O}\left(\frac{D_{\text{KL}}(\mathbb{Q} \parallel \mathbb{P}) + \bar{V}_n^\alpha(\pi_{\mathbb{Q}})}{\sqrt{n}} + B_n^\alpha(\pi_{\mathbb{Q}})\right).$$

Experiments

- Supervised-to-bandit conversion on vision datasets: *MNIST, FashionMNIST, EMNIST, CIFAR100*.
- Policies: Gaussian and Mixed-Logit (PAC-Bayes-friendly); priors tied (optionally) to π_0 .
- Optimization: Adam; we compare **two-sided** bound vs. prior one-sided baselines.

ES vs. Clipped-PAC Baselines

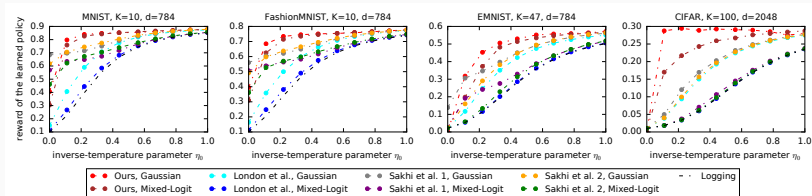


Figure 1: Across logging-quality η_0 , ES + two-sided PAC-Bayes outperforms [11]. Gaussian policies typically strongest.

Tuning Sensitivity and Adaptive α

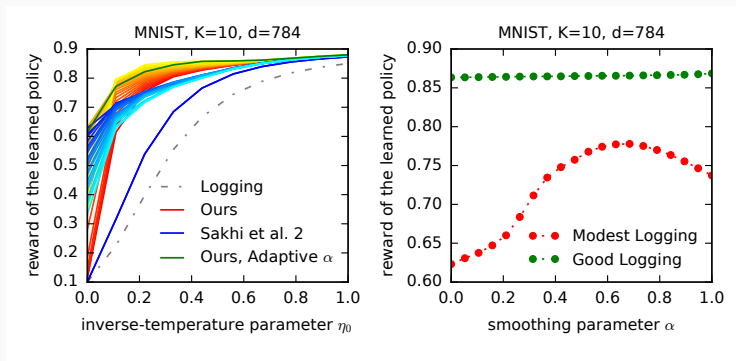


Figure 2: *Left:* grid over τ (clip) and α (ES); adaptive α close to best fixed choice. *Right:* average reward value for varying α using either modest or good logging; IW regularization is much needed for modest logging policies.

Takeaways

Key Takeaways

- **Exponential smoothing:** smooth IW regularization with explicit bias-variance control; better optimization behavior than clipping.
- **Two-sided, tractable PAC-Bayes bounds:** applicable to standard IPS; SGD-friendly.
- **Theory extended to any IW regularization technique [5].**

Limitations: Data-dependent quantities in the bound; symmetric tails may be loose. Performance breaks in large-scale settings [3] where Bayesian direct methods with informative priors [1, 2, 4, 6] perform better when the number of actions is high.

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