

# Lab Experiment No. 5

## Objective

To implement and analyze Priority Queues using arrays, linked list and heaps.

## Theory

A **priority queue** is an abstract data type where each element is associated with a **priority**, and elements are served based on **priority order**, not just insertion order.

- **Higher priority elements** are dequeued **before** lower priority ones.
- If priorities are the same, it can be FIFO or based on tie-breaking rules.

### T-5.1. Implementation using Arrays

#### Working Principle

- Elements are stored in an array along with their priorities.
- During insertion, append the element.
- During deletion, **search for the element with highest priority** and remove it.

#### Operations

Operation	Description	Time Complexity
Insert	Add to the end of the array	O(1)
Pop	Linear scan for highest priority item	O(n)
Top	Linear scan to find top priority	O(n)

#### Pros

- Easy to implement
- Good for small data sizes

#### Cons

- Inefficient for large datasets (pop/top = O(n))

## T-5.2. Implementation using Linked List

### Working Principle

- Maintain a **sorted linked list** based on priority.
- Insertions ensure the list is sorted by priority (descending).
- The **head node** always contains the highest priority.

### Operations

Operation	Description	Time Complexity
Insert	Traverse list to insert in order	$O(n)$
Pop	Remove head	$O(1)$
Top	Return head	$O(1)$

### Pros

- Efficient removal ( $O(1)$ )
- Better than arrays for frequent pop/top operations

### Cons

- Slower insertions ( $O(n)$ )
- Requires extra memory for pointers

## T-5.3. Implementation using Binary Heaps

### Working Principle

- Use a **binary heap** (min-heap or max-heap) to maintain priority.
- In a **max-heap**, parent nodes are always greater than or equal to children.

### Operations

Operation	Description	Time Complexity
Insert	Add at end, heapify up	$O(\log n)$
Pop	Remove root, heapify down	$O(\log n)$
Top	Return root	$O(1)$

### Pros

- Efficient for all operations
- Well-suited for dynamic datasets and large-scale applications

### Cons

- Slightly more complex to implement
- Cannot search arbitrary elements in less than  $O(n)$ .

## Code

### T-5.1. Implementation using Arrays. Depth-First Search (DFS)

<pre>#include &lt;iostream&gt; #include &lt;cstdlib&gt; using namespace std;  #define MAX 100  // Array-based Priority Queue struct PriorityQueueArray {     int data[MAX];     int priority[MAX];     int size; };  // Linked List Node struct Node {     int data;     int priority;     Node* next; };  // Heap-based Priority Queue struct PriorityQueueHeap {     int data[MAX];     int priority[MAX];     int size; };  int counter = 0; // For analysis  // ----- Array Implementation ----- void insertArray(PriorityQueueArray* pq, int val, int pri) {     cout &lt;&lt; "Inserting " &lt;&lt; val &lt;&lt; " with priority " &lt;&lt; pri &lt;&lt; " in Array\n";     int i = pq-&gt;size;     while (i &gt; 0 &amp;&amp; pq-&gt;priority[i - 1] &gt; pri) {         pq-&gt;data[i] = pq-&gt;data[i - 1];         pq-&gt;priority[i] = pq-&gt;priority[i - 1];         i--;     }     pq-&gt;data[i] = val;     pq-&gt;priority[i] = pri;     pq-&gt;size++;     counter++; }</pre>	<pre>void deleteLinkedList(Node** head) {     if (*head == nullptr) {         cout &lt;&lt; "Linked List is empty\n";         return;     }     cout &lt;&lt; "Deleting " &lt;&lt; (*head)-&gt;data &lt;&lt; " from Linked List\n";     Node* temp = *head;     *head = (*head)-&gt;next;     delete temp;     counter++; }  // ----- Heap Implementation ----- void heapify(PriorityQueueHeap* pq, int i) {     int smallest = i;     int left = 2 * i + 1;     int right = 2 * i + 2;      if (left &lt; pq-&gt;size &amp;&amp; pq-&gt;priority[left] &lt; pq-&gt;priority[smallest])         smallest = left;     if (right &lt; pq-&gt;size &amp;&amp; pq-&gt;priority[right] &lt; pq-&gt;priority[smallest])         smallest = right;      if (smallest != i) {         swap(pq-&gt;data[i], pq-&gt;data[smallest]);         swap(pq-&gt;priority[i], pq-&gt;priority[smallest]);         counter++;         heapify(pq, smallest);     } }  void insertHeap(PriorityQueueHeap* pq, int val, int pri) {     cout &lt;&lt; "Inserting " &lt;&lt; val &lt;&lt; " with priority " &lt;&lt; pri &lt;&lt; " in Heap\n";     int i = pq-&gt;size++;     pq-&gt;data[i] = val;     pq-&gt;priority[i] = pri;     heapify(pq, i);     counter++; }</pre>
---	--

```

    }
    pq->data[i] = val;
    pq->priority[i] = pri;
    pq->size++;
}

void deleteArray(PriorityQueueArray* pq) {
    if (pq->size == 0) {
        cout << "Array is empty\n";
        return;
    }
    cout << "Deleting " << pq->data[0] << " from
Array\n";
    for (int i = 0; i < pq->size - 1; i++) {
        pq->data[i] = pq->data[i + 1];
        pq->priority[i] = pq->priority[i + 1];
        counter++;
    }
    pq->size--;
}

// ----- Linked List Implementation
-----
void insertLinkedList(Node** head, int val, int pri) {
    cout << "Inserting " << val << " with priority " <<
pri << " in Linked List\n";
    Node* newNode = new Node{val, pri, nullptr};
    if (*head == nullptr || (*head)->priority > pri) {
        newNode->next = *head;
        *head = newNode;
        return;
    }
    Node* temp = *head;
    while (temp->next != nullptr &&
temp->next->priority <= pri) {
        temp = temp->next;
        counter++;
    }
    newNode->next = temp->next;
    temp->next = newNode;
}

```

```

    pq->priority[i] = pri;
    while (i > 0 && pq->priority[(i - 1) / 2] >
pq->priority[i]) {
        swap(pq->data[i], pq->data[(i - 1) / 2]);
        swap(pq->priority[i], pq->priority[(i - 1) / 2]);
        i = (i - 1) / 2;
        counter++;
    }
}

```

```

void deleteHeap(PriorityQueueHeap* pq) {
    if (pq->size == 0) {
        cout << "Heap is empty\n";
        return;
    }
    cout << "Deleting " << pq->data[0] << " from
Heap\n";
    pq->data[0] = pq->data[--pq->size];
    pq->priority[0] = pq->priority[pq->size];
    heapify(pq, 0);
}

```

// ----- Main Function -----

```

int main() {
    PriorityQueueArray arrPQ = {.size = 0};
    Node* lIPQ = nullptr;
    PriorityQueueHeap heapPQ = {.size = 0};

```

```

    // Array Implementation
    insertArray(&arrPQ, 15, 2);
    insertArray(&arrPQ, 25, 1);
    insertArray(&arrPQ, 35, 3);
    deleteArray(&arrPQ);

```

```

cout << "Array Priority Queue iterations: " << counter
<< "\n";
    counter = 0;

```

```

    // Linked List Implementation
    insertLinkedList(&lIPQ, 15, 2);
    insertLinkedList(&lIPQ, 25, 1);
    insertLinkedList(&lIPQ, 35, 3);
    deleteLinkedList(&lIPQ);
    cout << "Linked List Priority Queue
iterations: " << counter << "\n";
    counter = 0;

```

```

    // Heap Implementation
    insertHeap(&heapPQ, 15, 2);
    insertHeap(&heapPQ, 25, 1);
    insertHeap(&heapPQ, 35, 3);
    deleteHeap(&heapPQ);
    cout << "Heap Priority Queue iterations: " <<
counter << "\n";

```

	<pre> return 0; } </pre>
--	--------------------------

## Sample Output

Inserting 15 with priority 2 in Array  
 Inserting 25 with priority 1 in Array  
 Inserting 35 with priority 3 in Array  
 Deleting 25 from Array  
 Array Priority Queue iterations: 3  
 Inserting 15 with priority 2 in Linked List  
 Inserting 25 with priority 1 in Linked List  
 Inserting 35 with priority 3 in Linked List  
 Deleting 25 from Linked List  
 Linked List Priority Queue iterations: 2  
 Inserting 15 with priority 2 in Heap  
 Inserting 25 with priority 1 in Heap  
 Inserting 35 with priority 3 in Heap  
 Deleting 25 from Heap  
 Heap Priority Queue iterations: 2

## Complexity Analysis

Table 5.1 Analysis of time complexity for Priority Queue

Operation	Array-based (Unsorted)	Array-based (Sorted)	Linked List-based	Heap-based
Insertion	$O(1)$	$O(n)$	$O(n)$	$O(\log n)$
Deletion (max/min)	$O(n)$	$O(1)$	$O(1)$	$O(\log n)$
Access to max/min	$O(n)$	$O(1)$	$O(1)$	$O(1)$
Memory Usage	Efficient	Less efficient	Less efficient	Efficient

## Conclusion

In this lab, we implemented and analyzed Priority Queues using arrays, linked lists and heaps.