

Problem 1.

Find the characteristic equation and reduced characteristic equation of the 3-step method

$$y_{n+1} = -\frac{27}{11}y_n + \frac{27}{11}y_{n-1} + y_{n-2} + h \left[\frac{3}{11}f_{n+1} + \frac{27}{11}f_n + \frac{27}{11}f_{n-1} + \frac{2}{11}f_{n-2} \right]$$

Find the (exact) roots of the reduced characteristic equation, and determine if this method is stable for small $h\lambda$ or not.

Solution

First let us rewrite the method as

$$y_{n+1} + \frac{27}{11}y_n - \frac{27}{11}y_{n-1} - y_{n-2} = h \left[\frac{3}{11}f_{n+1} + \frac{27}{11}f_n + \frac{27}{11}f_{n-1} + \frac{2}{11}f_{n-2} \right]$$

Note that for this method we have

$$a_0 = -1, a_1 = -\frac{27}{11}, a_2 = \frac{27}{11}$$

Which produces the characteristic polynomial

$$\begin{aligned} p(z) &= z^3 + \frac{27}{11}z^2 - \frac{27}{11}z - 1 \\ &= \frac{1}{11}(z-1)(11z^2 + 38z + 11) \\ &= \frac{1}{11}(z-1)\left(z + \frac{1}{11}(19 + 4\sqrt{15})\right)\left(z - \frac{1}{11}(4\sqrt{15} - 19)\right) \end{aligned}$$

From this we find the zeros for the characteristic polynomial

$$z = 1, z = -\frac{1}{11}(19 + 4\sqrt{15}), z = \frac{1}{11}(4\sqrt{15} - 19)$$

Note that $|\frac{1}{11}(19 + 4\sqrt{15})| \approx 3.1356303 > 1$.

This implies that this method is not stable for small values of $h\lambda$.

Problem 2.

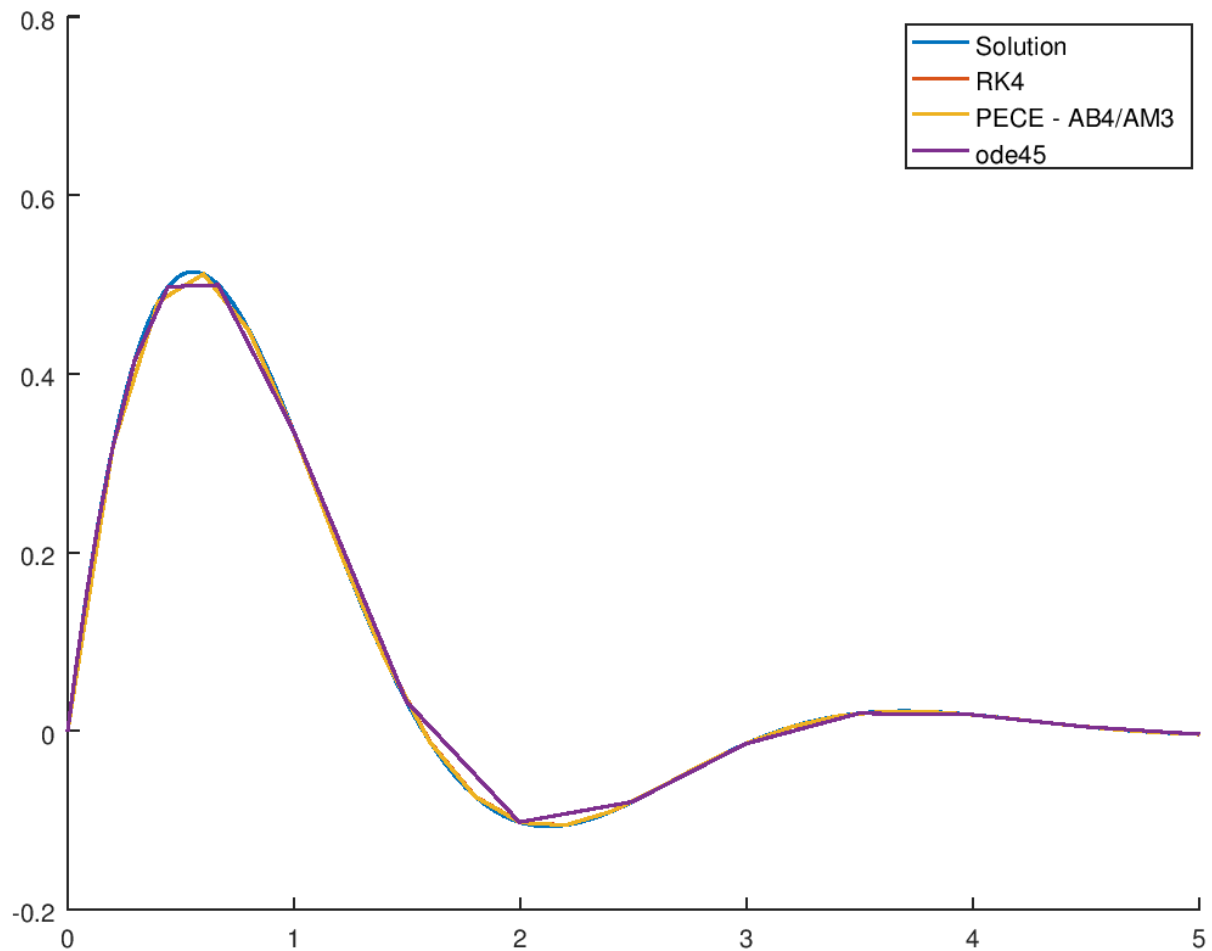
The IVP

$$\begin{aligned}y' &= -y + 2e^{-t} \cos(2t) \\ y(0) &= 0\end{aligned}$$

has the true solution $y(t) = e^{-t} \sin(2t)$.

Solve it numerically from $t=0$ to $t=5$, using

- (a) the classical 4-stage Runge-Kutta method with $h=0.2$
- (b) a PECE predictor-corrector method based on 4-step AB, 3-step AM, $h=0.2$
Use RK values from part (a) for the startup.
- (c) the Matlab built-in ODE45. This routine will pick its own steps.

Solution

	Actual	RK4	PECE - AB4/AM3	ODE45 (h unknown)
h = 0.2				
Value	-0.013911	-0.013911	-0.013776	-0.014068
Error		$2.1822 * 10^{-7}$	$1.3560 * 10^{-4}$	$1.5663 * 10^{-4}$
h = 0.1				
Value	-0.013911	-0.013911	-0.013908	
Error		$1.2907 * 10^{-8}$	$3.3871 * 10^{-6}$	

```

1 function p2
2
3 clear all;
4 close all;
5 hold on;
6
7 % Actual solution.
8 _f = @(t) e.^(-t) .* sin(2 .* t);
9 _t = linspace(0, 5, 200);
10 _y = _f(_t);
11
12 plot(_t, _y, 'DisplayName', 'Solution', 'LineWidth', 1);
13 val = _f(3)
14
15 % Numerical Solutions
16 f = @(t, y) -y + 2 .* e.^(-t) * cos(2*t);
17 h = 0.2; % Step Size
18 t = 0:h:5; % Interval
19 y = [0]; % Initial point
20 steps = length(t);
21
22 % RK4
23 for n = 1:(steps-1)
24
25     % 4-Step
26     k1 = f(t(n), y(n));
27     k2 = f(t(n) + h/2, y(n) + (h/2) * k1);
28     k3 = f(t(n) + h/2, y(n) + (h/2) * k2);
29     k4 = f(t(n) + h, y(n) + h * k3);
30
31     % Compute y_{n+1}
32     y(n+1) = y(n) + (h/6) * (k1 + 2*k2 + 2*k3 + k4);
33
34 end
35
36 val = y((3/h) + 1)
37 err = norm(_f(3) - val, inf)

```

```
38 plot(t, y, 'DisplayName', 'RK4', 'LineWidth', 1);
39
40 % PECE
41 y = y(1:4); % Pull startup values from RK4
42
43 for n = 5:steps
44
45     % P: 4-Step AB
46     y(n) = y(n-1) + h * (
47         (55/24) * f(t(n-1), y(n-1)) -
48         (59/24) * f(t(n-2), y(n-2)) +
49         (37/24) * f(t(n-3), y(n-3)) -
50         (3/8) * f(t(n-4), y(n-4))
51     );
52
53     % C: 3-Step AM
54     y(n) = y(n-1) + h * (
55         (3/8) * f(t(n), y(n)) +
56         (19/24) * f(t(n-1), y(n-1)) -
57         (5/24) * f(t(n-2), y(n-2)) +
58         (1/24) * f(t(n-3), y(n-3))
59     );
60
61 end
62
63 val = y((3/h) + 1)
64 err = norm(_f(3) - val, inf)
65 plot(t, y, 'DisplayName', 'PECE - AB4/AM3', 'LineWidth', 1);
66
67 % ODE45
68 % Note I am using octave, so the implementation may differ slightly
69 % from the one provided by Matlab.
70
71 [solx, soly] = ode45(f, [0 5], [0 0]);
72 val = interp1(solx, soly(:,1), 3, method='linear')
73 err = norm(_f(3) - val, inf)
74 plot(solx, soly(:,1), 'DisplayName', 'ode45', 'LineWidth', 1);
75
76 legend('show');
77
78 end
```

Problem 3.

Use the Matlab routine *fzero* or something comparable to find the two solutions of

$$e^x - x - 2 = 0.$$

There is one positive and one negative solution.

Solution

Zeros exist at the points $x = -1.8414$ and $x = 1.1462$.

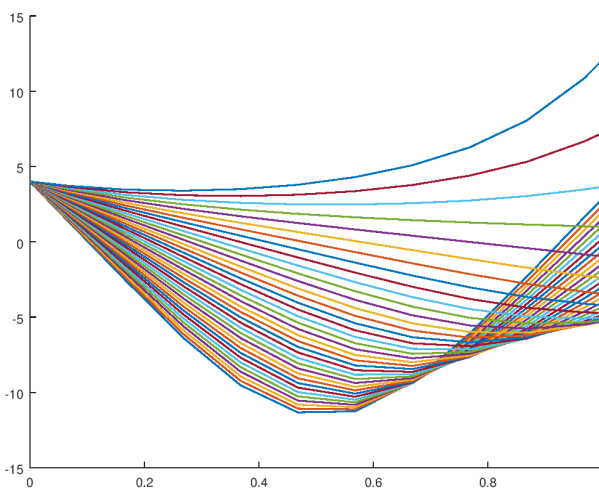
```
1 function p3
2
3 y = @(x) (e.^x) - x - 2;
4 % -1.8414
5 fzero(y, [-10, 0])
6 % 1.1462
7 fzero(y, [0, 10])
8
9 end
```

Problem 4.

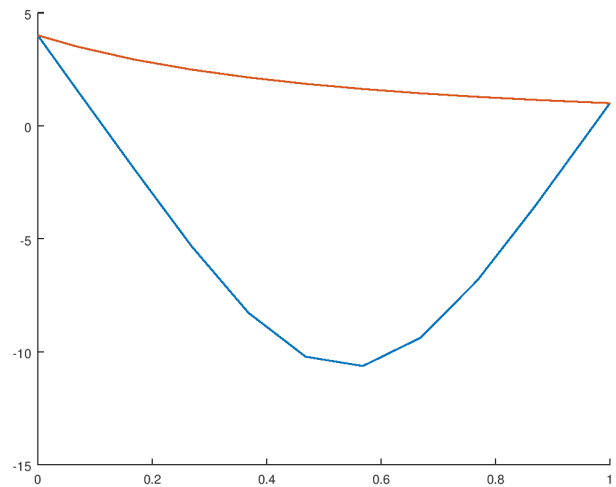
Solve the boundary value problem

$$\begin{aligned} y''(t) &= \frac{3}{2}y^2(t) \\ y(0) &= 4 \\ y(1) &= 1 \end{aligned}$$

by a shooting method.

Solution

(a) $s \in [-40, -5]$



(b) Solutions

Using `fzero` to find zeros of the function $\phi(s)$ produces values of $s = -35.859$ and $s = -8$. Figure (a) shows the solutions for integer s values in the interval $[-40, -5]$, where figure (b) displays only the solutions for $s = -35.859$ and $s = -8$ that satisfy the IVP with $y(0) = 4$ and $y(1) = 1$. The code to produce these solutions may be found below.

```
1 function p4
2
3 clear all;
4 close all;
5 hold on;
6
7 for s = -40:-5
8     [err, solx, soly] = phi(s);
9     plot(solx, soly(:,1), 'DisplayName', 'ode45', 'LineWidth', 1);
10 end
11
12 % -35.859
13 zero0 = fzero(@phi, -40)
14 % -8
15 zero1 = fzero(@phi, -5)
16
17 [err, solx, soly] = phi(zero0);
18 plot(solx, soly(:,1), 'DisplayName', 'ode45', 'LineWidth', 1);
19 [err, solx, soly] = phi(zero1);
20 plot(solx, soly(:,1), 'DisplayName', 'ode45', 'LineWidth', 1);
21
22 end
```

```
1 function [err, solx, soly] = phi(s)
2
3 dy = @(t, y) [y(2), (3/2) * (y(1) .^ 2)];
4
5 [solx, soly] = ode45(dy, [0, 1], [4, s]);
6 est = interp1(solx, soly(:,1), 1, method='linear');
7 err = est - 1;
8
9 end
```

Problem 5.

- (a) This is a stiff ODE. Solve the equations on the interval $[0, 0.001]$, using a stiff solver such as `ode15s`. Plot the result.
- (b) Answer the following questions.
- How many steps did the stiff solver take? How much computer time?
 - How many steps does a non-stiff solver, such as `ode113` take? How much computer time does it take?
 - What is the clock period?

Solution

TODO