Los Angeles, CA imamanr@gmail.com

Cell: (617) 682-2743 imama.github.io

#### **EXPERIENCE:**

#### Break Mar 2024 - Present

- Consulting, building evaluation pipeline for intention triage from audio. typescript, Bedrock models, boto, huggingface, Llava, Kubernetes, ray, AWS, S3.

## Applied Scientist June 2023 - Feb 2024

Flawless AI, Santa Monica CA

Worked on face tracking algorithms

- Work on multimodal 3D facial tracking-refinement algorithm accuracy and speed. Pose-conditional regressor, Transformers, wave2vec, CelebV-HQ dataset, Pytorch, VOCA dataset, docker, poetry, AWS.
- Defining new metrics to improve post-production 3D facial tracking-refinement workflow. Python, Image based spatial and temporal stability metrics, RAFT(optical flow), docker, poetry, AWS.
- Keep sync with latest research in the areas of Generative AI, computer vision, audio and text.

# Senior Staff Computer Vision Engineer August 2020 – Oct 2022

NIO Inc. San Jose CA

Worked on expanding digital cockpit features.

- Lead a team of engineers to design and launch, Sentry mode feature using 4 surround fisheye cameras based on object distance from the vehicle. Qualcomm Snapdragon SOC, Fisheye, Depth estimation, Detection. Tracking, Tensorflow, FastCV, jira, confluence.
- Stereo Calibration and rectification for fisheye and omni-directional cameras. OpenCV, C++.
- Multi-task network design and implementation for various cabin camera applications. Multi-task learning, Pytorch.
- Semantic and Instance segmentation, Object detection for edge devices. Yolact, MSCOCO, TikTok dataset, Pytorch, Selective object contrastive learning, Qualcomm Snapdragon SOC, Detectron2, quantization, AWS.
- Keep sync with latest research in the areas of representation/transfer learning, computer vision and language.

### Member of Technical Staff Nov 2016 - July 2020

Urus Graphics (stealth-mode startup - Harvard), Burbank CA

Worked on 3D geometry reconstruction.

- Reconstruct 3D models from a single image and extend to multiple images. C++,
   Autoencoder/Decoder, Unsupervised learning, Differential geometry, Optimization, Eigen, Shape from shading, Neural Radiance Fields(NeRF).
- Build 3D scans library from stereo RGBD camera setup. 3D Registration, Kinect Azure, C++, Blendshape Models, Mesh deformation, Volumetric TSDF Fusion, Pose estimation.
- Keep sync with latest research in the areas of representation/transfer learning, computer vision and generative modeling.

# Research Engineer June 2013 – Feb 2016

Video Analytics Department, Motorola Solutions, Boston MA

Worked to improve existing and build new applications for surveillance camera for object detection, recognition and tracking

- Design and implement classical machine learning algorithms to improve on existing algorithms for human detection, identification and tracking in surveillance videos. C++, openCV, Adaboost, HOG, cascade classifier
- Build SVM, CNNs and RNNs based learning algorithms for detection, classification and reasoning. PyTorch, Tensorflow, Caffe

## Research Assistant Jan 2009 – May 2013

Department of Electrical and Computer Engineering, University of Memphis, Memphis TN Worked at Center for advanced sensors with focus on compressive sensing for real time video imaging and taught /assisted Digital Image Processing and Random Signal Analysis.

- Adaptive Sampling scheme for real time Video Acquisition and reconstruction Using a Single Pixel Camera Compressed Sensing, Motion Detection, C++, OpenCV, 64x64 DMD kit, focal lens, half- wave plate and single pixel detector
- Compressive Sensing for a Sub-millimeter Wave Single Pixel Imager Compressed Sensing, C++, STL, Matlab. Single pixel detector, mirrors, spatial modulator.

# **EDUCATION**

2013 Ph.D, Image Processing, Department of Electrical and Computer Engineering, University of Memphis; Memphis TN. GPA 3.74

2008 M.Sc. Electronics, Quaid-i-Azam University; Islamabad GPA 4.0

#### **TECHNICAL SKILLS:**

Platforms: Linux, Windows, QNX and OSX

Languages: Python 3.x, C/C++/C++ 11-17, Intel Assembly 8051MC

Tools & Libraries: Pytorch, Tensorflow, Keras, Numpy, Kuberentes, TFlite, TensorRT, STL, Eigen, OpenCV, sklearn, QNX Momentics, Boost, Opengl, QT, SNPE, CUDA, Matlab, Octave 3.4.2, VS Code, LaTeX, Weka, Office 20xx, git, subversion, bash.

#### ACHIEVEMENTS AND INVOLVEMENT:

- 1st Class 1st, Master of Electronics 2008, Quaid-i-Azam University

- Isl. Class 1st, Master of Electronics 2006, Qualid-i-Azam University
   Merit Scholarship Fall 2004 and Spring 2007, Quaid-i-Azam University
   Speaker at SPIE DSS 2011 Orlando, FL and 2012 Baltimore, MD
   Reviewer ICML, CVPR, ECCV, JEI, SPIE Optical Engineering & Electronic Imaging, IEEE Signal Processing and openreview.

# **ACHIEVEMENTS AND INVOLVEMENT:**

- 1st Class 1st, Master of Electronics 2006, Quaid-i-Azam University
   Merit Scholarship Fall 2004 and Spring 2005, Quaid-i-Azam University
   Speaker at SPIE DSS 2011 Orlando, FL and 2012 Baltimore, MD
   Reviewer ICML, CVPR, ECCV, JEI, SPIE Optical Engineering & Electronic Imaging, IEEE Signal Processing and openreview.

# **PUBLICATIONS/PATENTS:**

- Imama Noor and Eddie Jacobs, "Adaptive Sampling scheme for real time Video Acquisition and reconstruction Using a Single Pixel Camera" SPIE Journal Electronic Imaging
- Imama Noor and Eddie Jacobs, "Adaptive Compressive Sampling Scheme for real time Video Capture
- and reconstruction Using a Single Pixel Camera" SPIE Compressive Sensing Proceedings
   Imama Noor, Orges Furxhi and Eddie Jacobs, "Compressive Sensing for a Sub-millimeter Wave single Pixel Imager" SPIE Passive Millimeter-Wave Imaging Technology XIV Proceedings
  - Imama Ali, US Patent June 2024 - Systems and methods for Vehicle surveillance US-20230226998-A1
  - Imama Ali, US Patent July 2023 - Cabin Al design and architecture for single camera. US-11999316-B2

**REFERENCES:** Provided on Request