

IMAMA ALI

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EXPERIENCE:

R&D Scientist/Manager Sep 2024 - Present Utopia Compression, Los Angeles CA

- Led integration of Swarming capabilities into a US-airforce collaborative autonomy framework, enabling coordinated multi-UAS missions such as target interception, following, and entrapment in GPS-denied environments using passive imaging sensors. C++, Docker, golden horde autonomy(GHA), Neural Radiance Fields(NeRF).
- Develop advanced algorithms for autonomous drones and maritime vessels in diverse operational conditions, including adverse weather, occlusions, and contested environments. Python, TensorRT, Sensor Fusion, vision transformers(ViT), Reinforcement learning(RL), depth estimation.
- Building an evaluation pipeline for multi-modal machine learning models for intentions triage from image/audio/text. typescript, Bedrock models, boto, RAG/LoRA, huggingface transformer, Llava, clearML, MLFlow, ray, AWS, S3.

Applied Scientist June 2023 - Feb 2024 Flawless AI, Santa Monica CA

Worked on face tracking algorithms

- Work on multimodal 3D facial tracking-refinement algorithm accuracy and speed. Pose-conditional regressor, Transformers, wave2vec, CelebV-HQ dataset, Pytorch, VOCA dataset, docker, poetry, AWS.
- Defining new metrics to improve post-production 3D facial tracking-refinement workflow. Python, Image based spatial and temporal stability metrics, RAFT(optical flow), docker, poetry, AWS.
- Keep sync with latest research in the areas of Generative AI, computer vision, audio and text.

Senior Staff Computer Vision Engineer August 2020 – Oct 2022 NIO Inc. San Jose CA

Worked on expanding digital cockpit features.

- Lead a team of engineers to design and implement, Sentry mode feature using 4 surround fisheye cameras based on object distance from the vehicle. Depth estimation, Fisheye, Detection, Tracking, Tensorflow, FastCV, Qualcomm Snapdragon SOC, jira, confluence.
- Stereo Calibration and rectification for fisheye and omni-directional cameras. OpenCV, C++.
- Multi-task network design and implementation for various cabin camera applications. Multi-task learning, Pytorch.
- Semantic and Instance segmentation, Small object detection for edge devices. Yolact, MSCOCO, TikTok dataset, Pytorch, Selective object contrastive learning, Qualcomm Snapdragon SOC, Detectron2, quantization, AWS.
- Keep sync with latest research in the areas of representation/transfer learning, computer vision and language.

Member of Technical Staff Nov 2016 – July 2020

Urus Graphics (stealth-mode startup - Harvard), Burbank CA

Worked on 3D geometry reconstruction.

- Reconstruct 3D models from a single image and extend to multiple images. C++, Autoencoder/Decoder, Unsupervised learning, Differential geometry, Optimization, Eigen, Shape from shading, Generative Adversarial Networks(GANs), NeRF.
- Build 3D scans library from stereo RGBD camera setup. 3D Registration, Kinect Azure, C++, Blendshape Models, Mesh deformation, Volumetric TSDF Fusion, Pose estimation.
- Keep sync with latest research in the areas of representation/transfer learning, computer vision and generative modeling.

Research Engineer June 2013 – Feb 2016

Video Analytics Department, Motorola Solutions, Boston MA

Worked to improve existing and build new applications for surveillance camera for object detection, recognition and tracking

- Design and implement classical machine learning algorithms to improve on existing algorithms for human detection, identification and tracking in surveillance videos. C++, openCV, Adaboost, HOG, cascade classifier
- Build SVM, CNNs and RNNs based learning algorithms for detection, classification and reasoning. PyTorch, Tensorflow, Caffe

Research Assistant Jan 2009 – May 2013

Department of Electrical and Computer Engineering, University of Memphis, Memphis TN

Worked at Center for advanced sensors with focus on compressive sensing for real time video imaging and taught /assisted Digital Image Processing and Random Signal Analysis.

- Adaptive Sampling scheme for real time Video Acquisition and reconstruction Using a Single Pixel Camera – Compressed Sensing, Motion Detection, C++, OpenCV, 64x64 DMD kit, focal lens, half- wave plate and single pixel detector
- Compressive Sensing for a Sub-millimeter Wave Single Pixel Imager – Compressed Sensing, C++, STL, Matlab, Single pixel detector, mirrors, spatial modulator.

EDUCATION

2013 Ph.D, Image Processing, Department of Electrical and Computer Engineering, University of Memphis; Memphis TN. GPA 3.74

2008 M.Sc. Electronics, Quaid-i-Azam University; Islamabad GPA 4.0

TECHNICAL SKILLS:

Platforms: Linux, Windows, QNX and OSX

Languages: Python 3.x, C/C++/C++ 11-17, Intel Assembly 8051MC

Tools & Libraries: Pytorch, Tensorflow, TensorRT, Keras, Numpy, GHA, Kubernetes, MLFlow, Sagemaker, ClearML, AWS, TensorRT, SNPE, STL, Eigen, OpenCV, sklearn, QNX Momentics, Boost, Opengl, Pytorch3D, QT, CUDA, Matlab, Octave 3.4.2, VS Code, LaTeX, Weka, Office 20xx, git, subversion, bash.

ACHIEVEMENTS AND INVOLVEMENT:

- 1st Class 1st, Master of Electronics 2008, Quaid-i-Azam University
- Merit Scholarship - Fall 2004 and Spring 2007, Quaid-i-Azam University
- Speaker at SPIE DSS 2011 Orlando, FL and 2012 Baltimore, MD
- Reviewer ICML, CVPR, ECCV, JEL, SPIE Optical Engineering & Electronic Imaging, IEEE Signal Processing and openreview.

PUBLICATIONS/PATENTS:

- Imama Ali, US Patent June 2024 - Systems and methods for Vehicle surveillance US-20230226998-A1
- Imama Ali, US Patent July 2023 - Cabin AI design and architecture for single camera. US-11999316-B2
- Imama Noor and Eddie Jacobs, "Adaptive Sampling scheme for real time Video Acquisition and reconstruction Using a Single Pixel Camera" SPIE Journal Electronic Imaging
- Imama Noor and Eddie Jacobs, "Adaptive Compressive Sampling Scheme for real time Video Capture and reconstruction Using a Single Pixel Camera" SPIE Compressive Sensing Proceedings
- Imama Noor, Orges Furxhi and Eddie Jacobs, "Compressive Sensing for a Sub-millimeter Wave single Pixel Imager" SPIE Passive Millimeter-Wave Imaging Technology XIV Proceedings

REFERENCES: Provided on Request