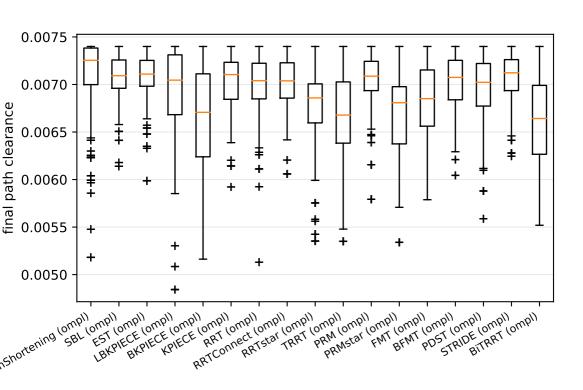
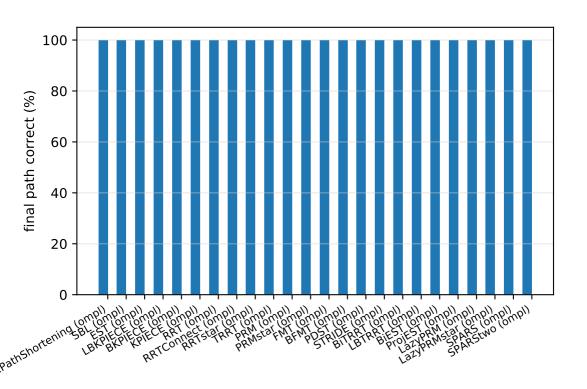


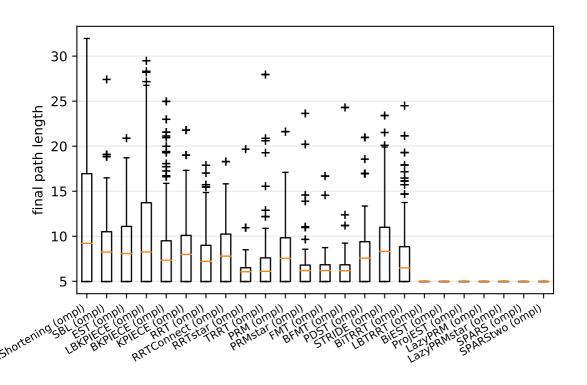
Motion planning algorithm



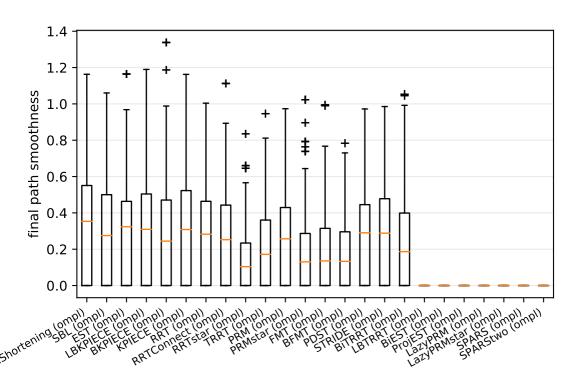
Motion planning algorithm



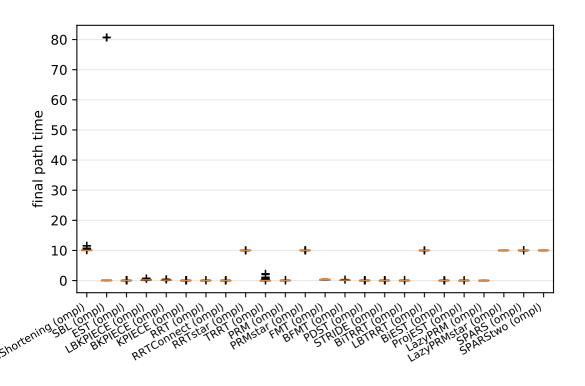
Motion planning algorithm



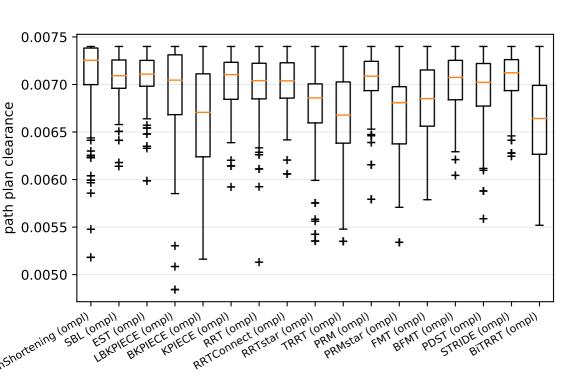
Motion planning algorithm



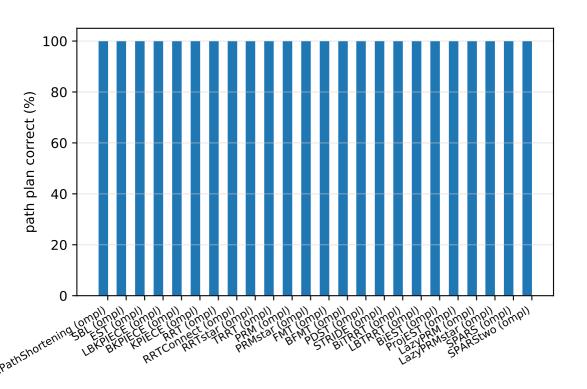
Motion planning algorithm



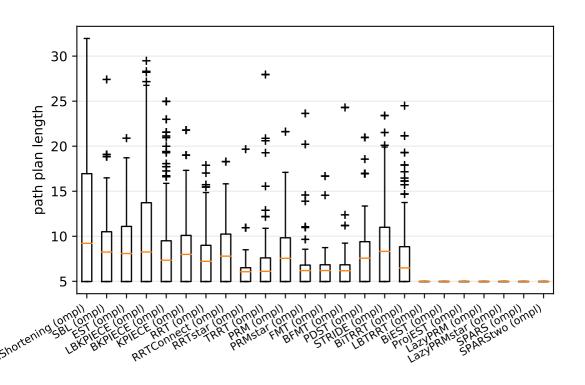
Motion planning algorithm



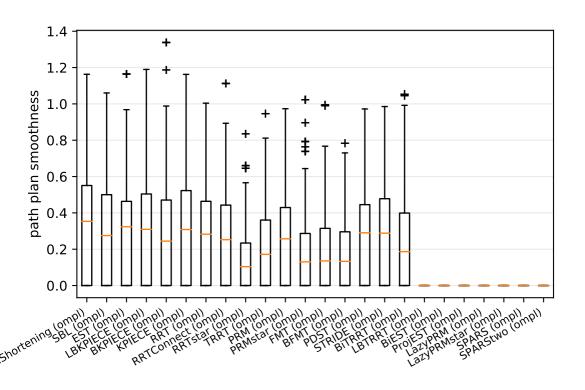
Motion planning algorithm



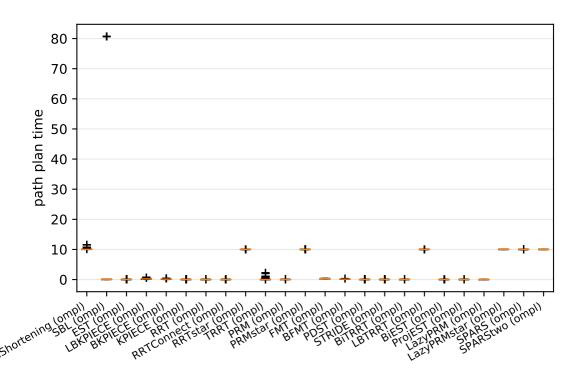
Motion planning algorithm



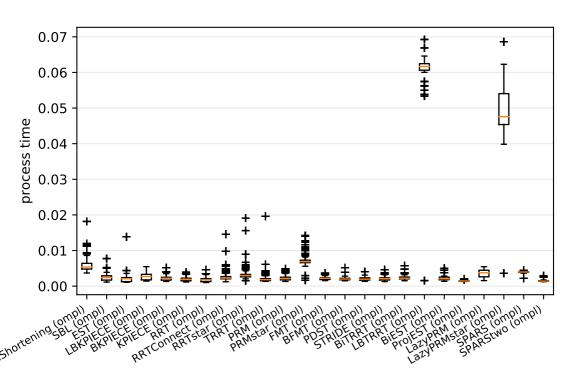
Motion planning algorithm



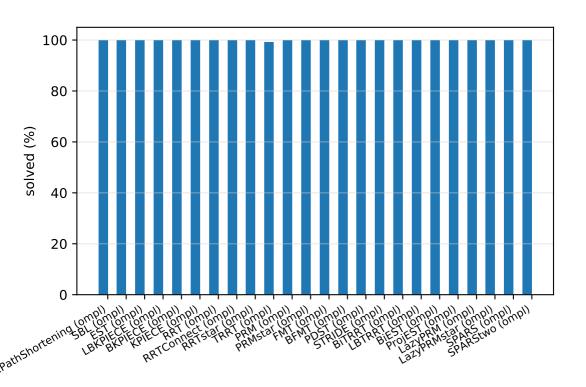
Motion planning algorithm



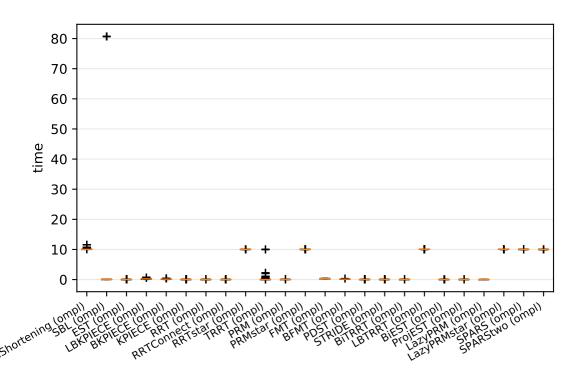
Motion planning algorithm



Motion planning algorithm



Motion planning algorithm



Motion planning algorithm

Experiment "all_experiments" Number of averaged runs: 50

Time limit per run: 3637.46 seconds

Memory limit per run: 3637.46 MB

Experiment "Start1_Pick1"

Number of averaged runs: 50

Time limit per run: 10 seconds

Memory limit per run: -1 MB

Experiment "all_experiments"

Number of averaged runs: 50 Time limit per run: 3637.46 seconds

Memory limit per run: 3637.46 MB

Experiment "Start1_Pick1"

Number of averaged runs: 50
Time limit per run: 10 seconds

Memory limit per run: -1 MB

Experiment "all_experiments"