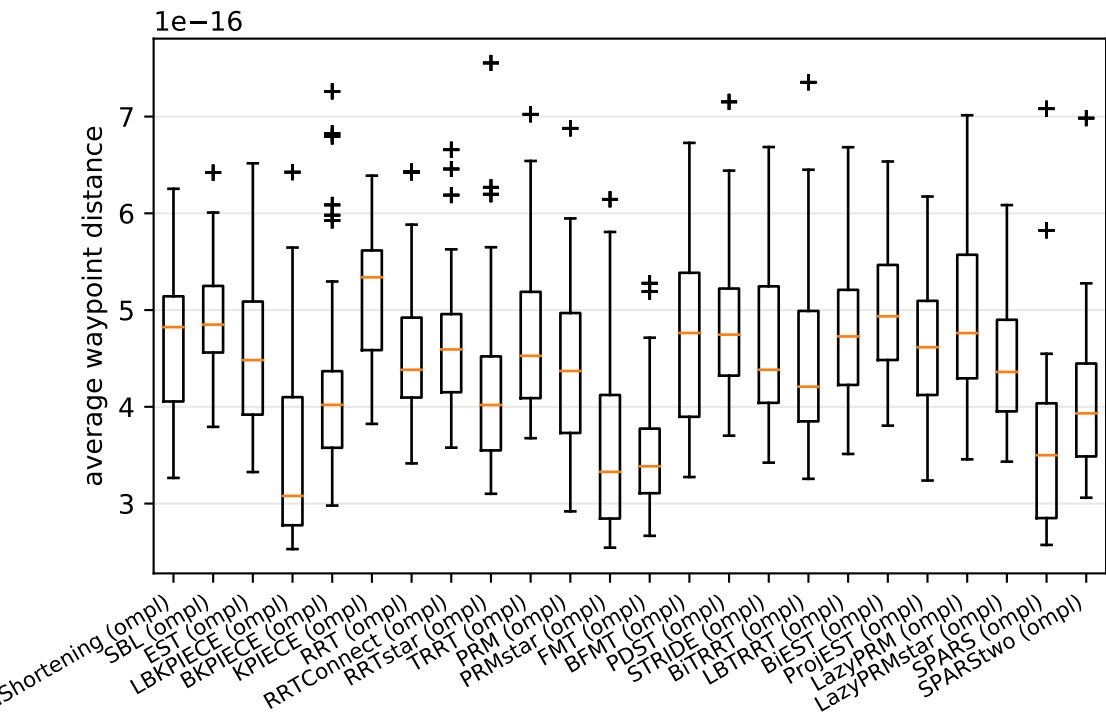
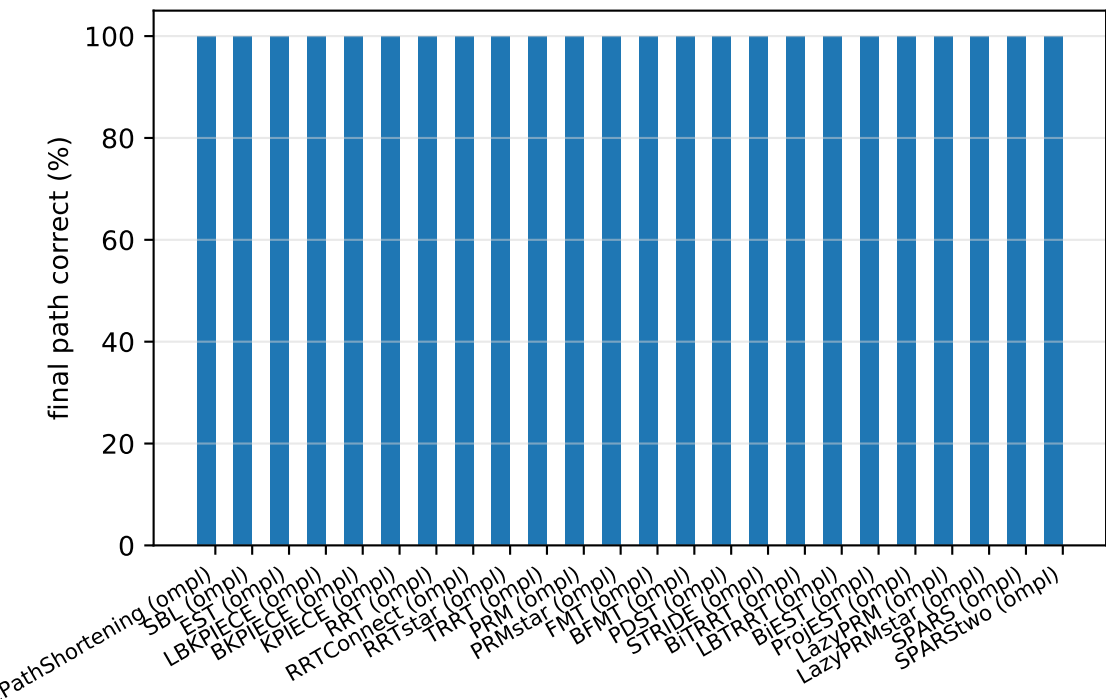


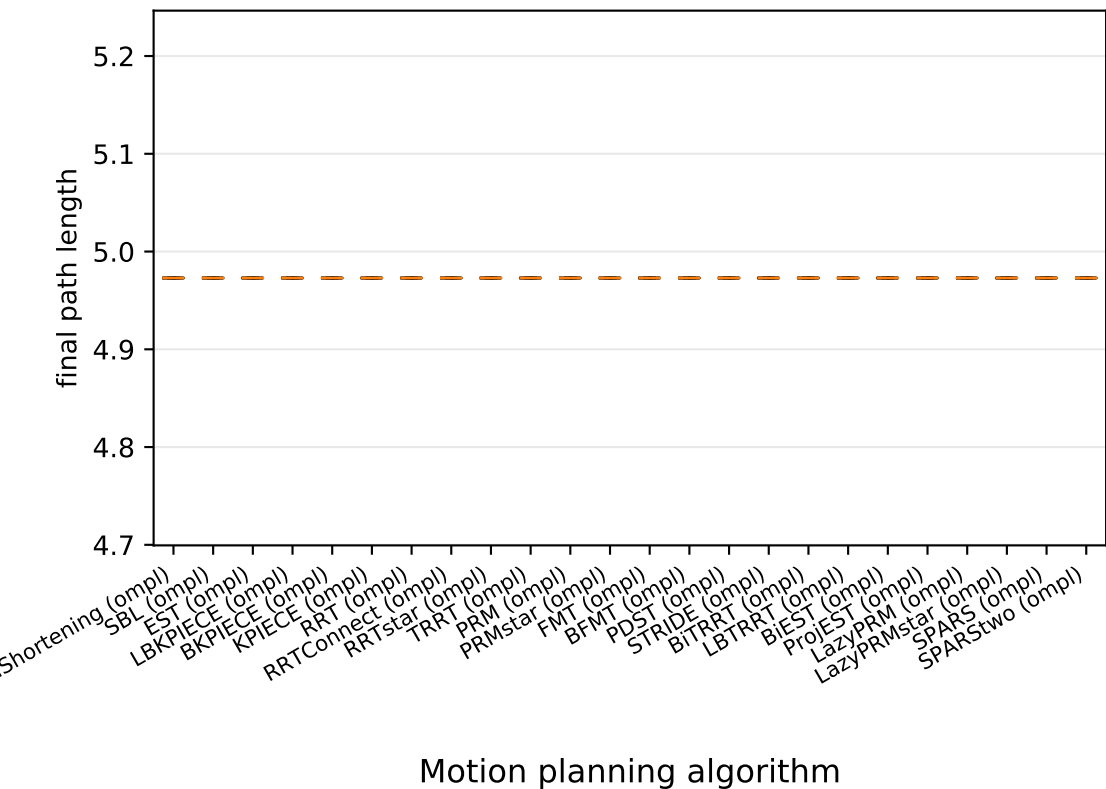
Motion planning algorithm

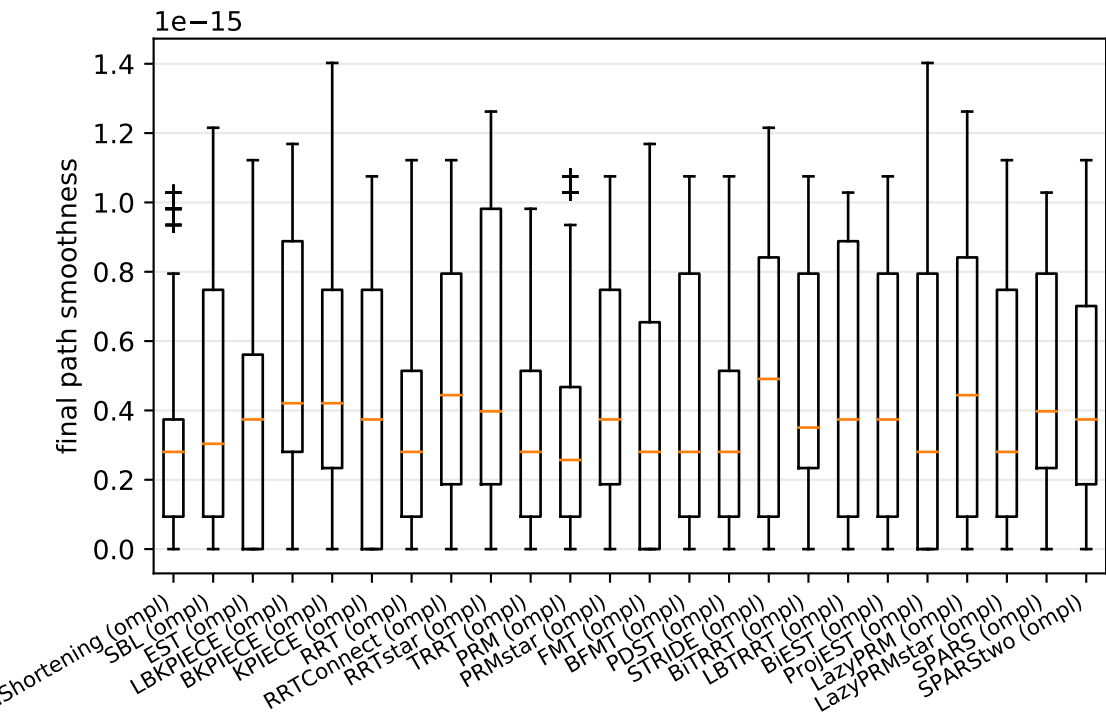


Motion planning algorithm

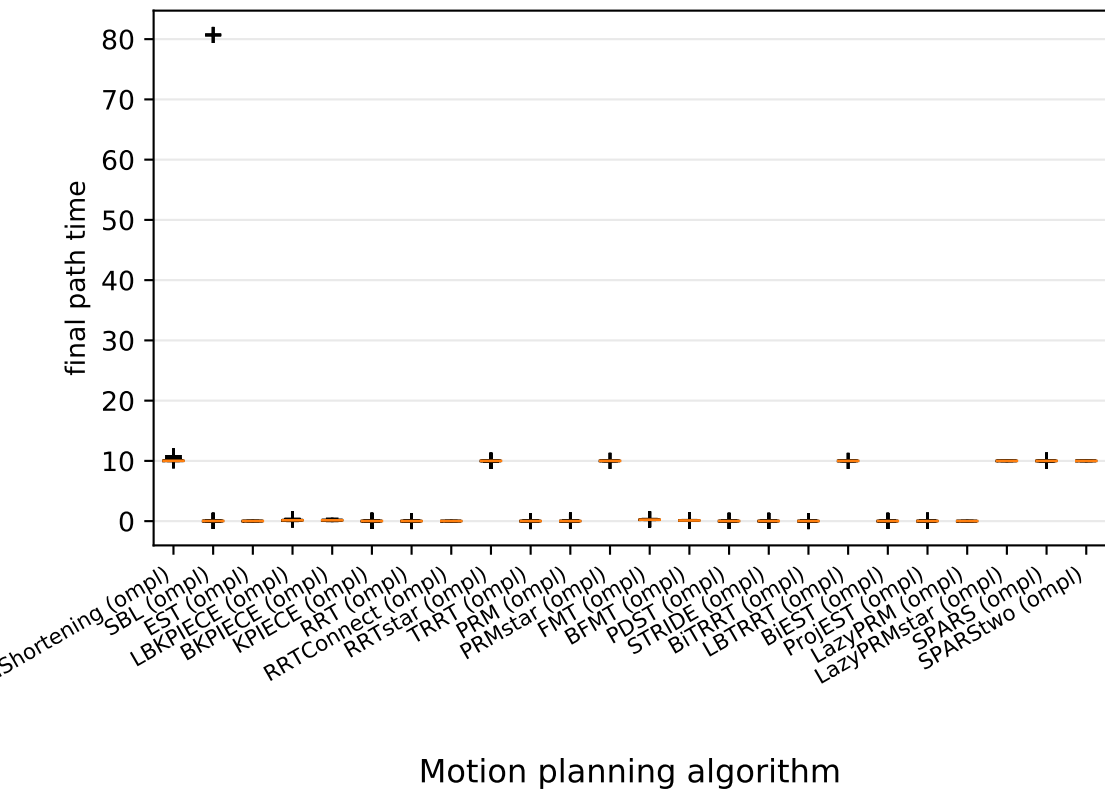


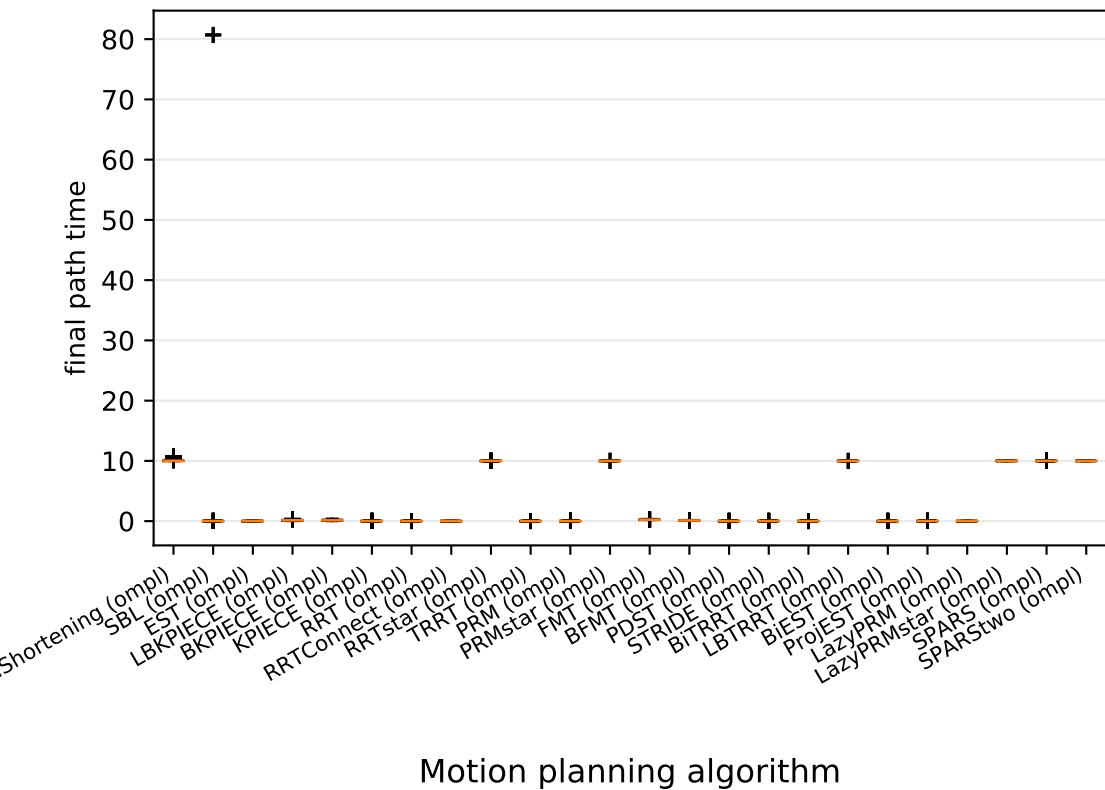
Motion planning algorithm

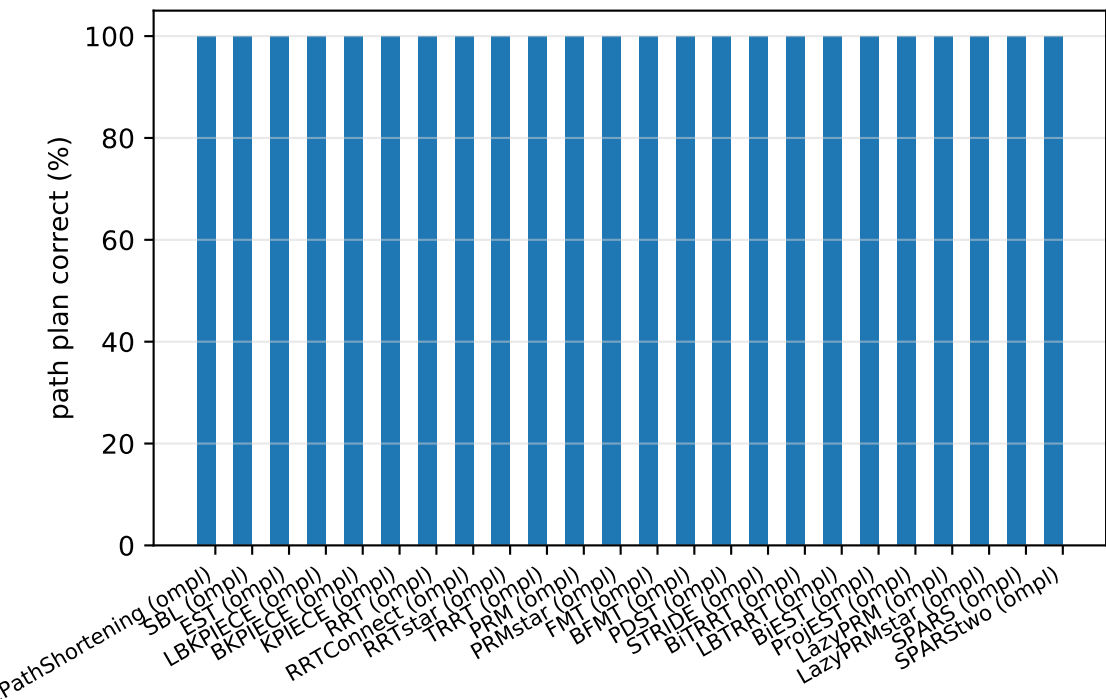




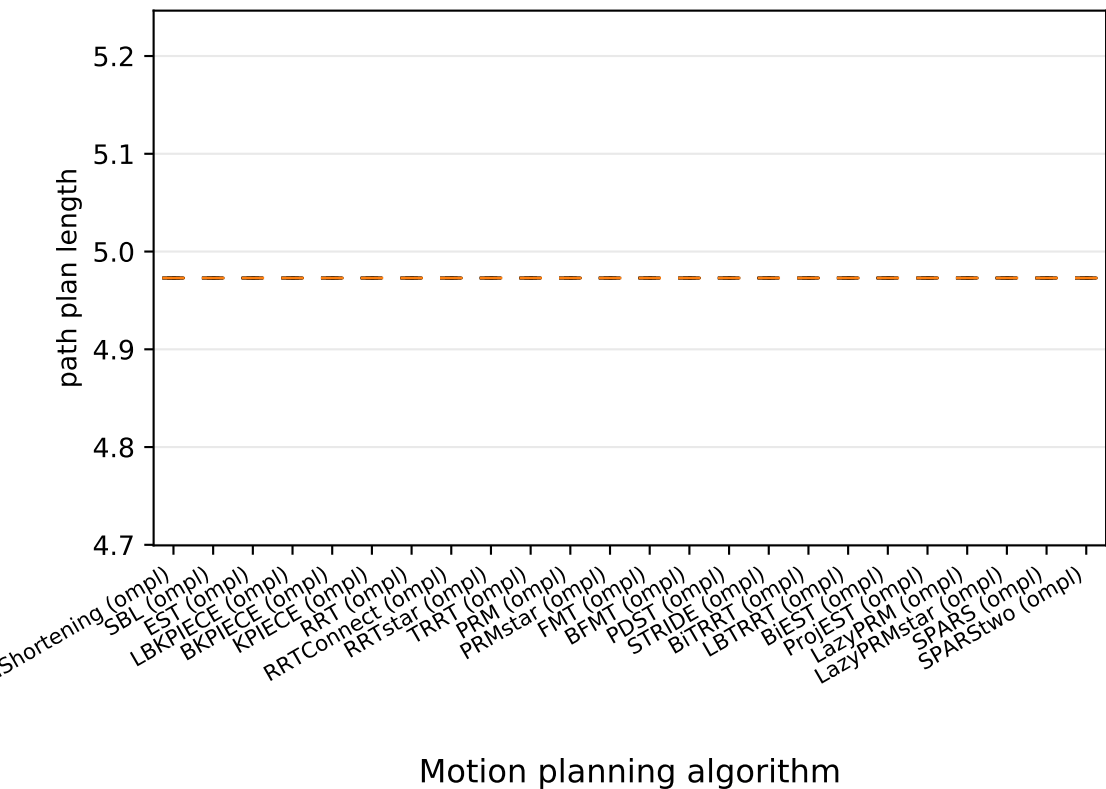
Motion planning algorithm

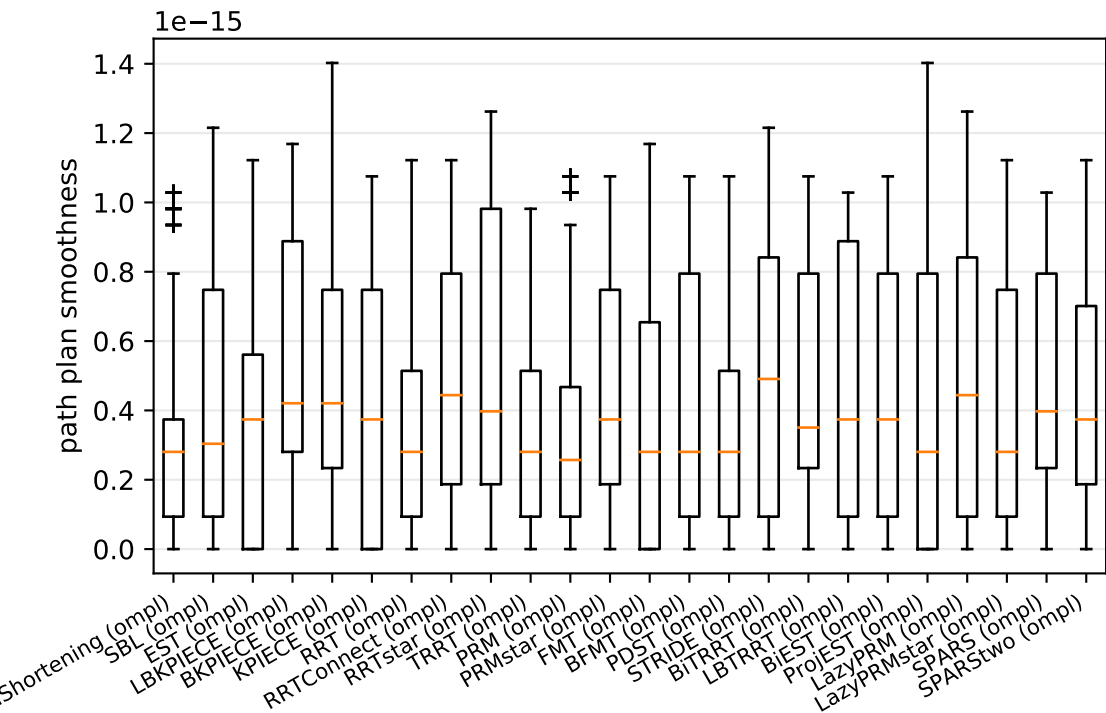




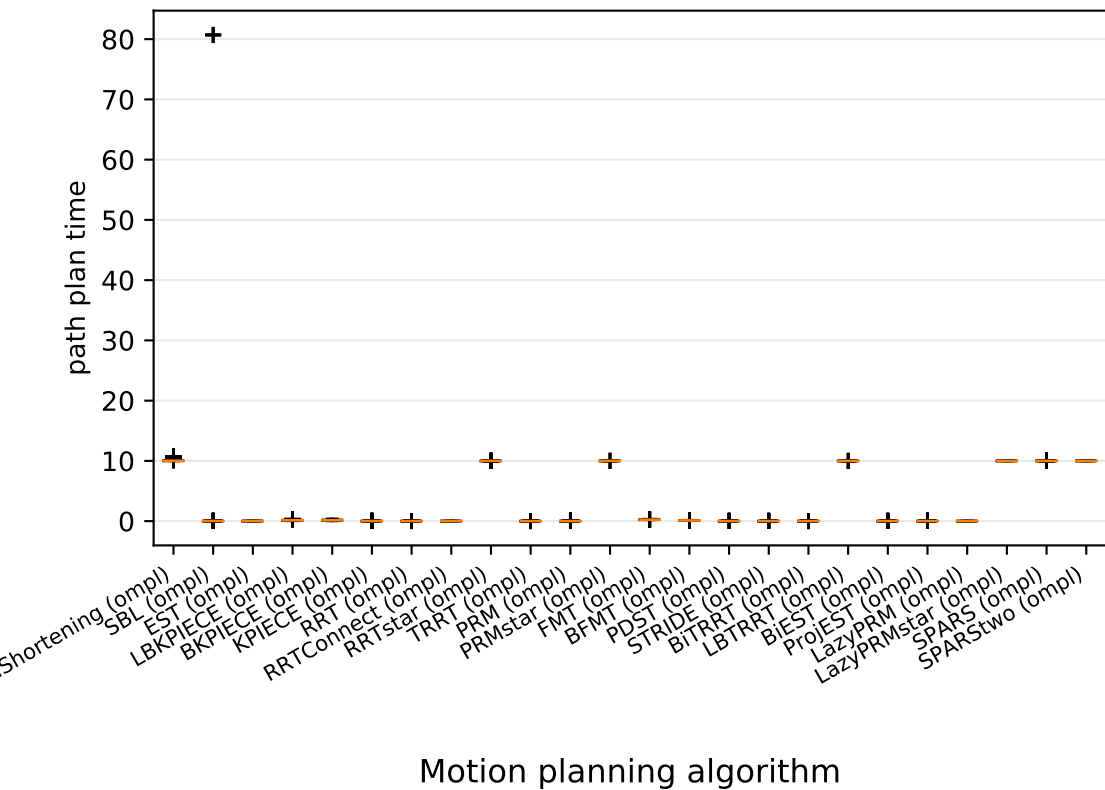


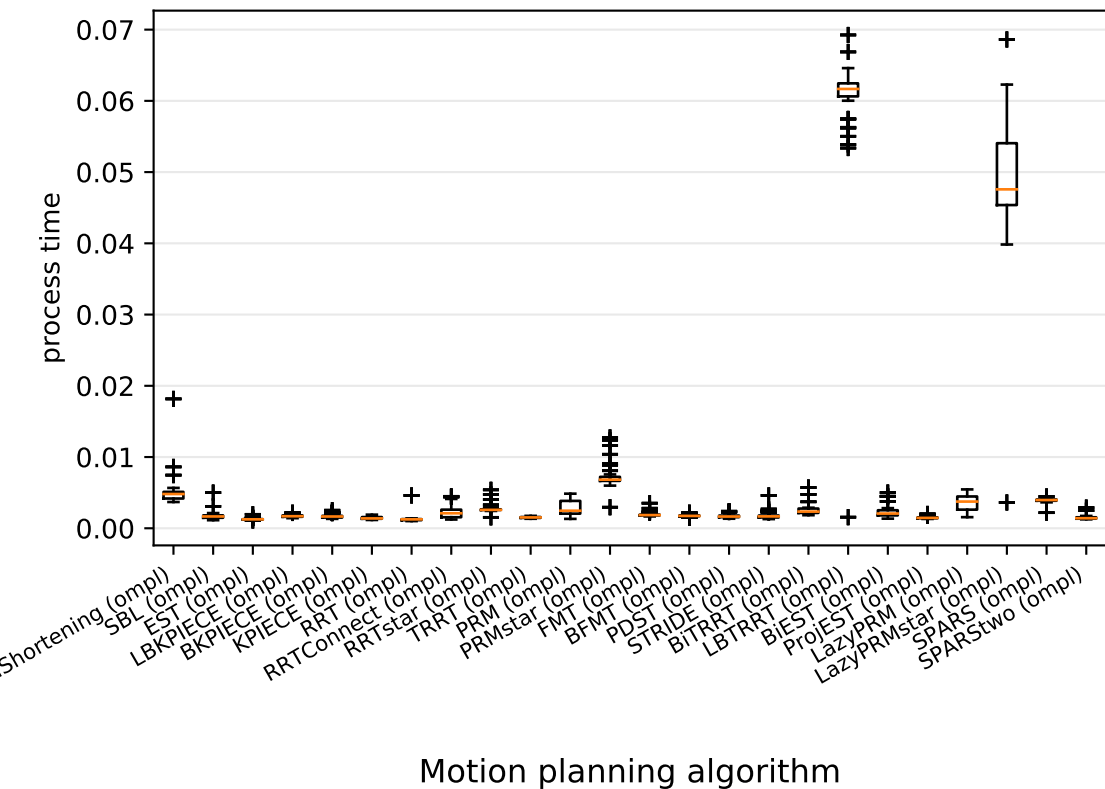
Motion planning algorithm

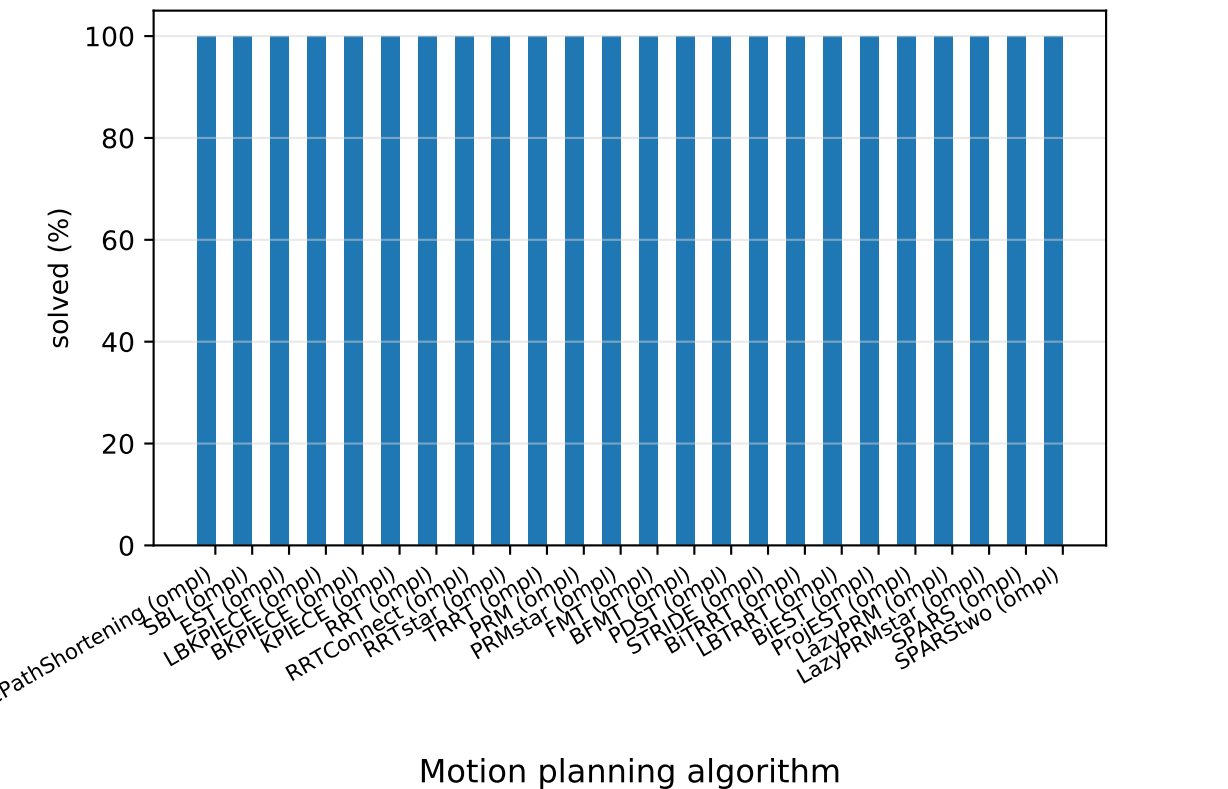


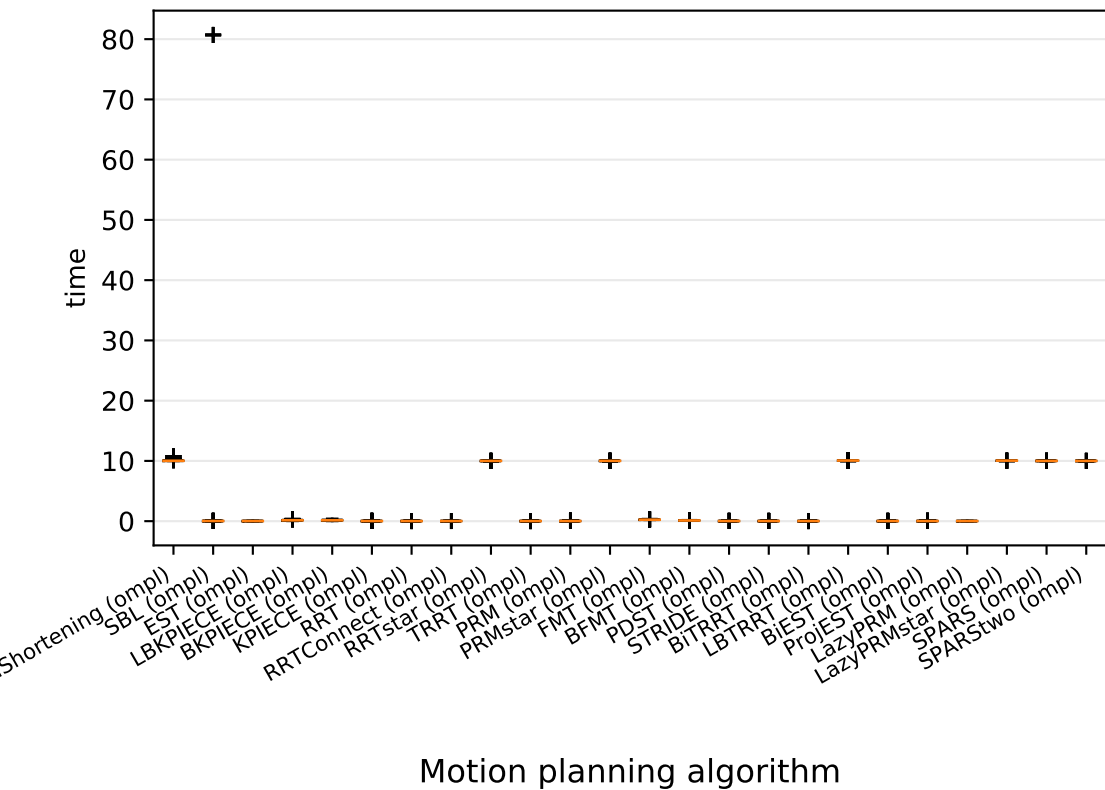


Motion planning algorithm









Experiment "all_experiments"

Number of averaged runs: 50

Time limit per run: 3637.46 seconds

Memory limit per run: 3637.46 MB

Experiment "Start1_Pick1"

Number of averaged runs: 50

Time limit per run: 10 seconds

Memory limit per run: -1 MB

Experiment "all_experiments"

Number of averaged runs: 50

Time limit per run: 3637.46 seconds

Memory limit per run: 3637.46 MB

Experiment "Start1_Pick1"

Number of averaged runs: 50

Time limit per run: 10 seconds

Memory limit per run: -1 MB