Ankit Goyal

scholar.google.com/citations?user=RhN6jKIAAAAJ&hl=en&oi=ao

Work Experience

Aug'22-Now Research Scientist, NVIDIA Robotics Research Lab.

Mentor: Prof. Dieter Fox, Dr. Fabio Ramos

Sep'18-Aug'22 Graduate Student Research Assistant, Princeton University.

Mentor: Prof. Jia Deng

Jun'21-Nov'21 Research Intern, NVIDIA Robotics Research Lab.

Mentor: Prof. Dieter Fox

Dec'20-May'21 Research Intern, Intel Intelligent Systems Lab.

Mentor: Dr. Vladlen Koltun

Sep'16-Aug'18 Graduate Student Research Assistant, University of Michigan.

Mentor: Prof. Jia Deng

May'16–July'16 Research Intern, Microsoft Research (MSR).

Mentor: Dr. Prateek Jain

May'15-July'15 Research Intern, University of Southern California (USC).

Mentor: Prof. Shrikanth S. Narayanan

May'14-Apr'15 Research Assistant, IIT Kanpur.

Mentor: Prof. Nischal Verma

Education

2018–22 **Ph.D. in Computer Science**, *Princeton University*.

Advisor: Prof. Jia Deng

Thesis: Towards Geometric Intelligence: Seeing, Grounding and Reasoning over Geometries

2016–18 M.S. in Computer Science and Engineering, University of Michigan.

GPA: 3.97/4.0, Track: Artificial Intelligence A+ (outstanding grade above A) in 2/6 courses

2012–16 **B.Tech. in Electrical Engineering**, *Indian Institute of Technology (IIT) Kanpur.*

CPI: 9.8/10.0, Minor: Computer Science

Rank 2/150 students | A* (outstanding grade above A) in 10/45 courses

Awards and Recognition

- 2023 **RSS Pioneers Award**, Cohort of 30 most promising early-career robotics researchers in the world.
- 2022 NeurIPS Scholar Award.
- 2021 Qualcomm Innovation Fellowship, \$100k research grant, acceptance rate 15%.
- 2021 Outstanding Reviewer, ICCV, Top 5% of all reviewers.
- 2016 Sridhar Memorial Prize, IIT Kanpur, Best student in Electrical Engineering.
- 2015 Viterbi-India Scholarship, USC and Indo-US Science and Technology Forum (IUSSTF).
- 2013-2015 Academic Excellence Award, IIT Kanpur, Awarded thrice for academic performance.

Publications

2024 Discovering Robotic Interaction Modes with Discrete Representation Learning.

L Wang, **A Goyal**, H Xu, A Garg Conference on Robot Learning (CoRL),

2024 RVT-2: Learning Precise Manipulation from Few Examples.

A Goyal, V Blukis, J Xu, Y Guo, YW Chao, D Fox

Robotics: Science and Systems (RSS), Also, in DGR@RSS-2024 and GAS@RSS-2024 2023 RVT: Robotic View Transformer for 3D Object Manipulation.

A Goyal, J Xu, Y Guo, V Blukis, YW Chao, D Fox

Conference on Robot Learning (CoRL), Oral (Top 6.6% of submitted papers)

Also in NeuRL-RMW@CoRL-2023

2023 Shelving, Stacking, Hanging: Relational Pose Diffusion for Multi-modal Rearrangement.

A Simeonov, **A Goyal**, L Manuelli, L Yen-Chen, A Sarmiento, A Rodriguez, P Agrawal, D Fox *Conference on Robot Learning* (CoRL)

2023 Infinite Photorealistic Worlds using Procedural Generation.

A Raistrick, L Lipson, Z Ma, L Mei, M Wang, Y Zuo, K Kayan, H Wen, B Han, Y Wang, A Newell, H Law, A Goyal, K Yang, J Deng

Conference on Computer Vision and Pattern Recognition (CVPR)

2023 ProgPrompt: Generating Situated Robot Task Plans using Large Language Models.

I Singh, V Blukis, A Mousavian, **A Goyal**, D Xu, J Tremblay, D Fox, J Thomason, A Garg *International Conference on Robotics and Automation (ICRA)*

Also, in Autonomous Robots, LaRel@NeurIPS-2022 and LangRob@CoRL-2022

2022 Non-Deep Networks.

A Goyal, A Bochkovskiy, J Deng, V Koltun

Neural Information Processing Systems (NeuRIPS)

2022 IFOR: Iterative Flow Minimization for Robotic Object Rearrangement.

A Goyal, A Mousavian, C Paxton, Y W Chao, B Okorn, J Deng, D Fox Conference on Computer Vision and Pattern Recognition (CVPR)

2022 Coupled Iterative Refinement for 6D Multi-Object Pose Estimation.

L Lipson, Z Teed, A Goyal, J Deng

Conference on Computer Vision and Pattern Recognition (CVPR)

2021 Revisiting Point Cloud Classification with a Simple and Effective Baseline.

A Goyal, H Law, B Liu, A Newell, J Deng

International Conference on Machine Learning (ICML)

2020 Rel3D: A Minimally Contrastive Benchmark for Grounding Spatial Relations in 3D.

A Goyal, K Yang, D Yang, J Deng

Neural Information Processing Systems (NeuRIPS), Spotlight (Top 4% of submitted papers)

2020 Packlt: A Virtual Environment for Geometric Planning.

A Goyal, J Deng

International Conference in Machine Learning (ICML)

2019 Semantic Relation Detection Between Construction Entities To Support Safe Human-Robot Collaboration in Construction.

D Kim, A Goyal, A Newell, S Lee, J Deng, V Kamat

ASCE International Conference on Computing in Civil Engineering (i3CE)

2018 Think Visually: Question Answering through Virtual Imagery.

A Goyal, J Wang, J Deng

Annual Meeting of the Association of Computational Linguistics (ACL)

2017 ProtoNN: Compressed and Accurate kNN for Resource-scarce Devices.

C Gupta, AS Suggala, **A Goyal**, HV Simhadri, B Paranjape, A Kumar, S Goyal, R Udupa, M Varma, P Jain *International Conference in Machine Learning* (ICML)

2016 A Multimodal Mixture-of-Experts Model for Dynamic Emotion Prediction in Movies.

A Goyal, N Kumar, T Guha, SS Narayanan

IEEE International Conference on Acoustics, Speech, and Signal Processing (ICASSP)

2015 Object Matching using Speeded Up Robust Features.

NK Verma, A Goyal, AH Vardhan, RK Sevakula, A Salour

Asia Pacific Symposium on Intelligent and Evolutionary Systems (IES)

2015 Template Matching for Inventory Management using Fuzzy Histogram and Spatial Filters.

NK Verma, A Goyal, A Chaman, RK Sevakula and A Salour

IEEE Conference on Industrial Electronics and Applications (ICIEA)

Pre-prints

2024 Differentiable GPU-Parallelized Task and Motion Planning.

W Shen, C Garrett, **A Goyal**, T Hermans, F Ramos arXiv:2411.11833,

Also, in DiffOpt@CoRL 2024

2024 3D-MVP: 3D Multiview Pretraining for Robotic Manipulation.

S Qian, K Mo, V Blukis, D Fouhey, D Fox, A Goyal arXiv:2406.18158

2024 AdaDemo: Data-Efficient Demonstration Expansion for Generalist Robotic Agent. ation Expansion for Generalist Robotic Agent T Mu, Y Guo, J Xu, A Goyal, H Su, D Fox, A Garg arXiv:2404.07428

Notable Talks

- Sep '24 MILA Robot Learning Seminar, View Transformers for 3D Manipulation in Robotics.
- May '24 Keynote Manipulation Skills@ICRA-24, Towards fast and precise sensorimotor skill learning.
- Nov '23 Spotlight NeuRL-RMW@CoRL-23, RVT: Robotic View Transformer for 3D Object Manipulation.
- Oct '23 UW Robotics colloquium, RVT: Robotic View Transformer for 3D Object Manipulation.
- Aug '23 Seattle Robotics Club, Towards General Purpose Robotic Learning.
- Apr '23 MILA Vision Reading Group, RVT: Robotic View Transformer for 3D Object Manipulation.
- Feb '23 NVIDIA NVCV All-hands, RVT: Robotic View Transformer for 3D Object Manipulation.

Mentoring

- 2024 Yi Li, PhD UW.
- 2023 Shengyi Qian, Research Scientist: Meta, PhD UMich.
- 2022 Anthony Simeonov, PhD MIT.
- 2022 Ishika Jain, PhD USC, Primary Mentor: Valts Bulkis.
- 2020 Bowei Liu, BS Princeton.

Teaching Experience

- Fall 2019 COS529 Advanced Computer Vision, Princeton University, Graduate Student Instructor.
- Fall 2018 COS429 Computer Vision, Princeton University, Head Teaching Assistant.
- Fall 2017 **EECS442 Computer Vision**, *University of Michigan*, Graduate Student Instructor.

Winter 2018

Service

2024 Program Committee Member.

RSS Pioneers

2024 Area Chair.

ICLR

2020-24 **Reviewer**.

- 2024: RSS
- o 2023: CVPR, RSS
- o 2022: ICLR, CVPR, ECCV, ICML, NeurIPS
- o 2021: ICLR, CVPR, ICCV, ICML, NeurIPS
- o 2020: ICLR, CVPR, ECCV, TPAMI

2013-15 **Counselling Service**, *IIT Kanpur*.

- Assistant Coordinator: Responsible for managing sensitive situations in the undergraduate community and organizing week-long orientation for over 800 freshers
- o Academic Mentor: Mentored students struggling academically.
- Student Guide: Ensured smooth induction of 6 freshmen into the college environment.