

Finalist Interactive Paper

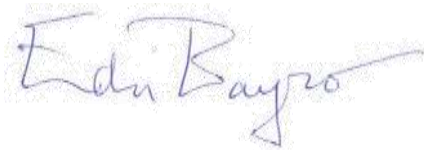
IEEE International Conference on Humanoid Robots – Humanoid 2016

is presented to

**Mavrakis, Nikos; Ghalamzan Esfahani, Amir Masoud;
Stolkin, Rustam; Baronti, Luca; Kopicki, Marek; Castellani, Marco**

for the paper entitled

**Analysis of the Inertia and Dynamics of Grasped Objects, for Choosing Optimal
Grasps to Enable Torque-Efficient Post-Grasp Manipulations**



Eduardo Bayro Corrochano
General Chair, *Humanoids 2016*

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