Exercise RTOS-10P. FreeRTOS -timers

REAL TIME OPERATING SYSTEMS LABORATORIUM SYSTEMÓW STEROWNIA PRZEMYSŁOWEGO I AUTOMATYKI BUDYNKÓW

KATEDRA ENERGOELEKTRONIKI I AUTOMATYKI SYSTEMÓW PRZETWARZANIA ENERGII WWW.KANIUP.AGH.EDU.PL

AKADEMIA GÓRNICZO-HUTNICZA WWW.AGH.EDU.PL

Subject: FreeRTOS real time operating system – time

manipulating, timers

Tools: Visual Studio Express, FreeRTOS sources

Required skills: Basic knowledge of issues related to programming in C

language and real-time systems

Introduction.

Timer - a system mechanism that realizes precise timekeeping that can be used to:

- measuring time intervals with high accuracy and repeatability
- unblocking ("waking") the process at a specific time
- cyclical stimulation of the process to work
- securing locking operations against excessive blocking

the timer can result in the generation of:

- events
- signals
- deposites
- callbacks

Timer features functions:

TimerHandle_t xTimerCreate

```
( const char * const pcTimerName,
  const TickType_t xTimerPeriod,
  const UBaseType_t uxAutoReload,
  void * const pvTimerID,
  TimerCallbackFuncticon_t pxCallbackFunction );
```

pcTimerName – timer name (string)

xTimerPeriod – timer period

uxAutoReload – auto-reload timer (when True), or one-shot (when False)

pvTimerId – timer identifier (most often used in the callback function to identify

the timer)

pcCallbakFunction – function called after the timer has expired

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Purpose of the exercise.

The purpose of the exercise is to learn about the possibilities of measuring time in the real-time operating system.

Exercise program.

- 1. Use project 013-Timers_1 and test the operation in each of the following cases:
 - 1.1. Run two tasks (Callbacks) triggered from two timers counting with a) the same time, b) different times.
 - 1.2. Run two time driven tasks (Callbacks). One with auto-reload timer, the other with one-shoot timer.
- 2. Use project 014-Timers_2 and test the operation in each of the following cases:
 - 2.1. Run three timer driven tasks (Callback) with different period times. In one callback calculate the time between successive calls of two other callbacks function.