

PHYS 360A/B  
Experiment 20: Nuclear Magnetic Resonance

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# Contents

<b>1</b>	<b>Introduction</b>	<b>4</b>
<b>2</b>	<b>Theoretical Background</b>	<b>5</b>
<b>3</b>	<b>Experimental Design and Procedure</b>	<b>6</b>
<b>4</b>	<b>Analysis</b>	<b>7</b>
4.1	Finding Resonance . . . . .	7
4.1.1	Voltage at $t = 0$ s . . . . .	7
4.1.2	Free Induction Decay . . . . .	9
4.2	The Free Induction Decay and $T_2$ . . . . .	9
4.2.1	Finding $T_2$ . . . . .	9
4.3	Measurement of $T_1$ . . . . .	11
<b>5</b>	<b>Conclusion</b>	<b>12</b>

## Abstract

# 1 Introduction

Hello World!

## 2 Theoretical Background

### 3 Experimental Design and Procedure

## 4 Analysis

### 4.1 Finding Resonance

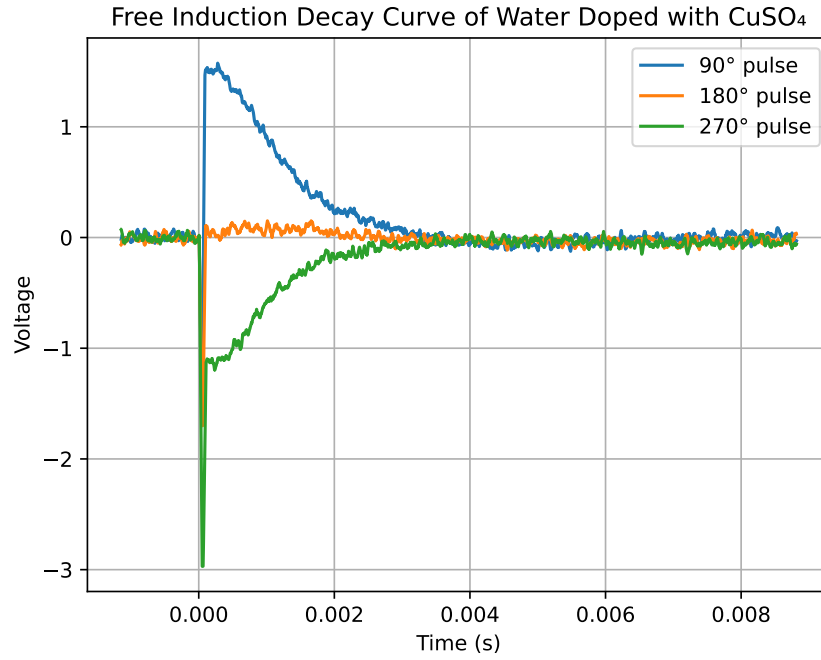
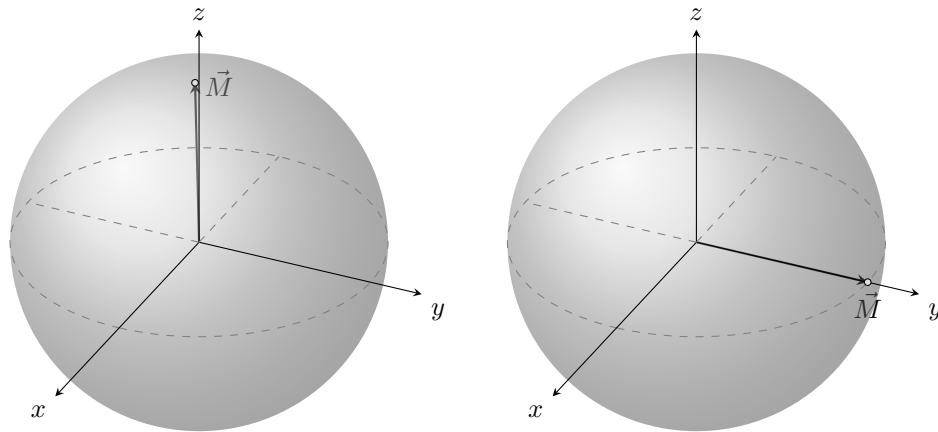


Figure 1: Free Induction Decay NMR signals for 90°, 180°, and 270° pulses

#### 4.1.1 Voltage at $t = 0$ s

##### 90° Pulse

- A 90° pulse is a pulse that is applied long enough to tip the magnetization vector by 90° from its initial direction (at a small angle with the positive z-axis) in the rotating frame:



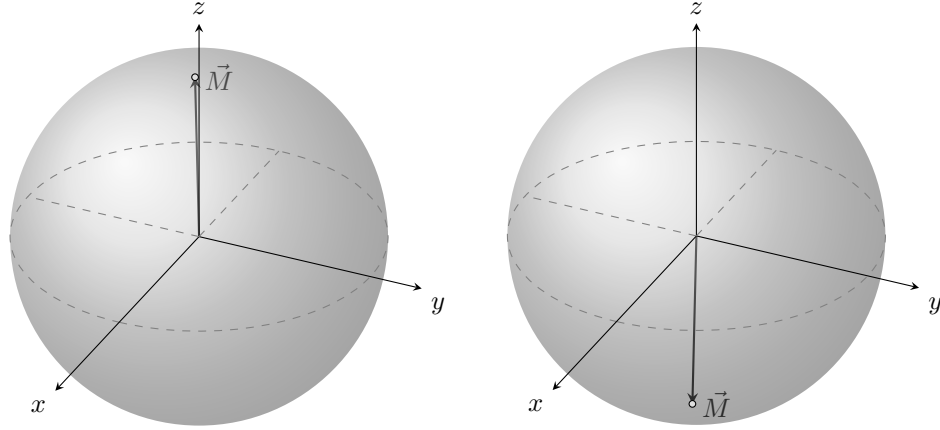
- Now, nearly half the spins are in the “up” state and the other half are in the “down” state.
- Since  $\vec{M}$  is in the x-y plane, the z component of the magnetization vector vanishes:

$$M_z = 0$$

- This is a higher energy state than the equilibrium state with the magnetization vector,  $\vec{M}$ , pointing along the positive z-axis.
- The receiver gain was adjusted so that the precessing  $\vec{M}$  induced<sup>1</sup> a current in the coil as shown in the 90° trace of Figure 1.

### 180° Pulse

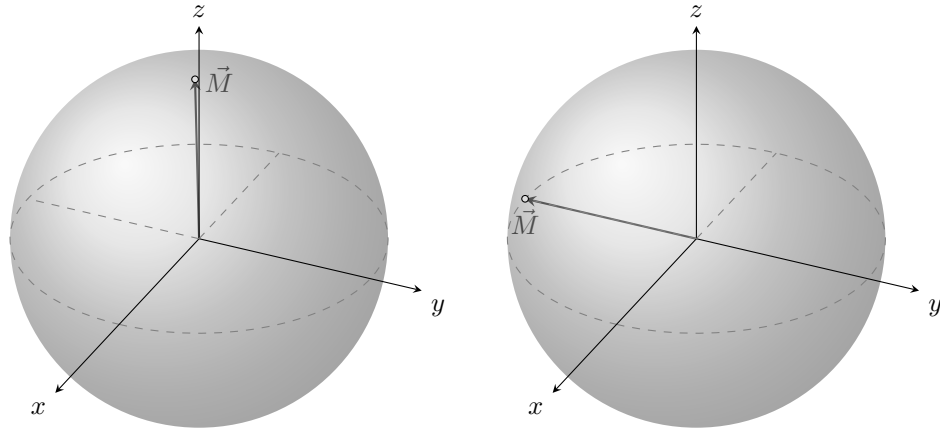
- If we apply the pulse for twice as long (increase the pulse width to twice that of the 90° pulse), we rotate the magnetization vector by 180° :



- Most of the spin are now in the “down” state.
- However, this magnetization vector doesn’t induce current in the coils since the component in the x-y plane is nearly 0.

### 270° Pulse

- This time, the pulse is applied long enough to rotate  $\vec{M}$  by an additional 180° from the 90° case:



- That is,  $\vec{M}$  returns to the x-y plane but is anti-parallel to  $\vec{M}$  in the 90° pulse case:

$$\vec{M}_{270^\circ} = -\vec{M}_{90^\circ}$$

- It hence precesses in the opposite sense of rotation as the 90° case<sup>2</sup>.

<sup>1</sup>According to Faraday’s law.

<sup>2</sup>And vice versa.



- According to Faraday's law, the direction of the current  $\vec{M}_{180^\circ}$  induces in the coil is opposite to that of  $\vec{M}_{90^\circ}$ .
- This is why we see a current that is  $-I_{90^\circ}$  induced in the  $270^\circ$  case in Figure 1.

#### 4.1.2 Free Induction Decay

- For all three pulses, we see that the signal vanishes over time.
- Recall that for the  $90^\circ$  and  $270^\circ$  pulses, the magnetization vector is in the x-y plane.
- Because of small variations in the magnetic field that the magnetic moments,  $\vec{\mu}$ , for each particle experience, the magnetic moments being to randomly dephase.
- They spread out in the x-y plane causing the magnetization vector and hence the induced current to vanish as a whole.

### 4.2 The Free Induction Decay and $T_2$

- In this section, we take a closer look at the FID observed in the  $90^\circ$  and  $270^\circ$  traces of Figure 1 (for different samples).
- For the same  $90^\circ$  pulse, we have the following FID traces:

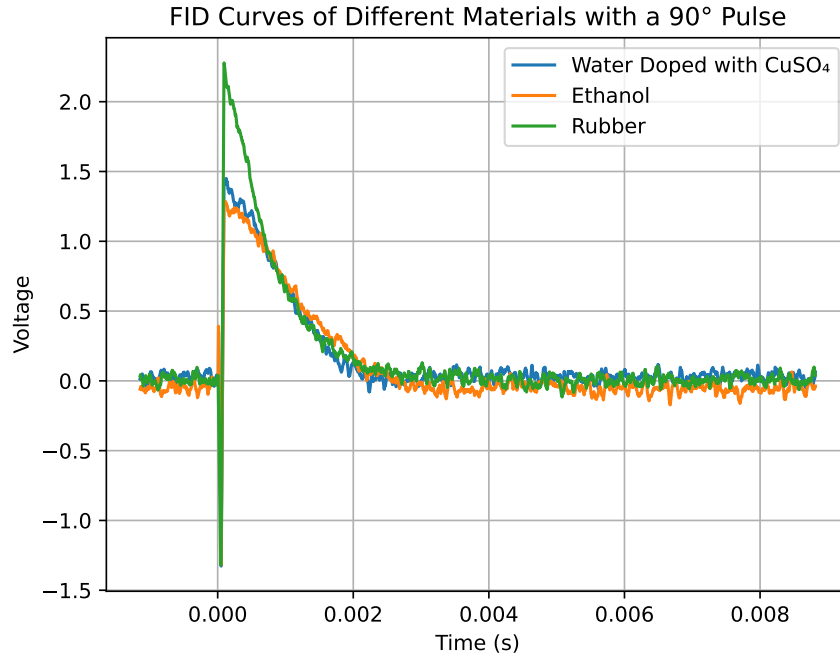


Figure 2: FID for the  $90^\circ$  pulse in water doped with  $\text{CuSO}_4$ , ethanol, and rubber

#### 4.2.1 Finding $T_2$

##### Analytically

- On plotting the traces in Figure 2 on a semi-log graph (along with the best fit lines), we get:

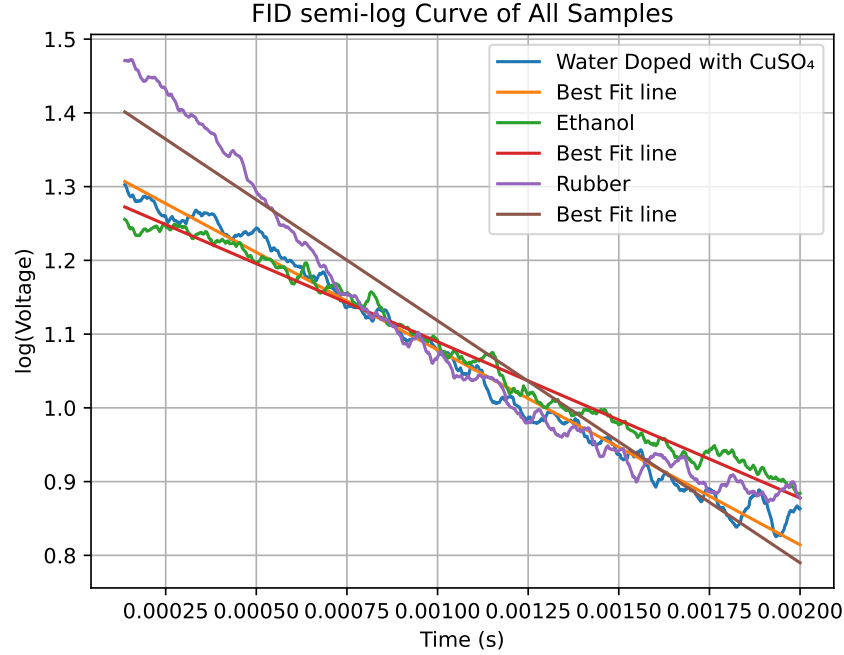


Figure 3:  $\ln(M_{xy}) = -\frac{t}{T_2^*} + \ln(M_0)$  plotted for the three traces in Figure 2

- We can find  $T_2^*$  using the following equation:

$$M_{xy}(t) = M_0 e^{-\frac{t}{T_2^*}}$$

Here,  $M_{xy}(t)$  is the trace seen in Figure 2,  
 $M_0$  is the magnetization at  $t = 0$ ,  
 $t$  is the time.

- We can take the  $\ln$  of both sides to get:

$$\ln(M_{xy}) = \ln(M_0) + \ln\left(e^{-\frac{t}{T_2^*}}\right)$$

$$\ln(M_{xy}) = -\frac{t}{T_2^*} + \ln(M_0)$$

- Comparing this to  $y = mx + c$ , we see that the slope,  $m$ , is given by:

$$m = -\frac{1}{T_2^*}$$

$$\Rightarrow T_2^* = -\frac{1}{m}$$

### Sample Calculation

- Consider  $m = -328.236\text{s}^{-1}$  for Doped Water in Table 1:

$$T_2^* = -\frac{1}{-328.236\text{s}^{-1}}$$

$$T_2^* = -\frac{1}{-328.236}$$

$$T_2^* = 0.003047\text{s}$$

	Slope	$T_2$ (s)
Doped Water	-328.236	0.003047
Ethanol	-264.426	0.003782
Rubber	-211.89	0.004719

Table 1: Slopes of best fit lines and calculated  $T_2^*$

- We can hence find  $T_2^*$  from the slopes of the best fit lines in Figure 3 for the other samples:

#### Estimation

- We can find an estimation for  $T_2^*$  directly from the FID traces.
- For  $t = T_2^*$ , we have:

$$M_{xy}(T_2^*) = M_0 e^{-1}$$

$$\frac{M_{xy}(T_2^*)}{M_0} \approx 0.37$$

$$M_{xy}(T_2^*) \approx 0.37 M_0$$

- We can estimate the time at which  $M_{xy}(T_2^*)$  is approximately  $0.37 \cdot M_0$ :

	$M_0$	$0.37 M_0$	$T_2$ (s)
Doped Water	1.46	0.540	0.00112
Ethanol	1.40	0.518	0.00122
Rubber	2.40	0.888	0.00089

Table 2: Estimate of  $T_2^*$  using the initial magnetization

### 4.3 Measurement of $T_1$

## 5 Conclusion