

## Lecture 12: Hash Table

**Read:** Carrano, Chpt.12.

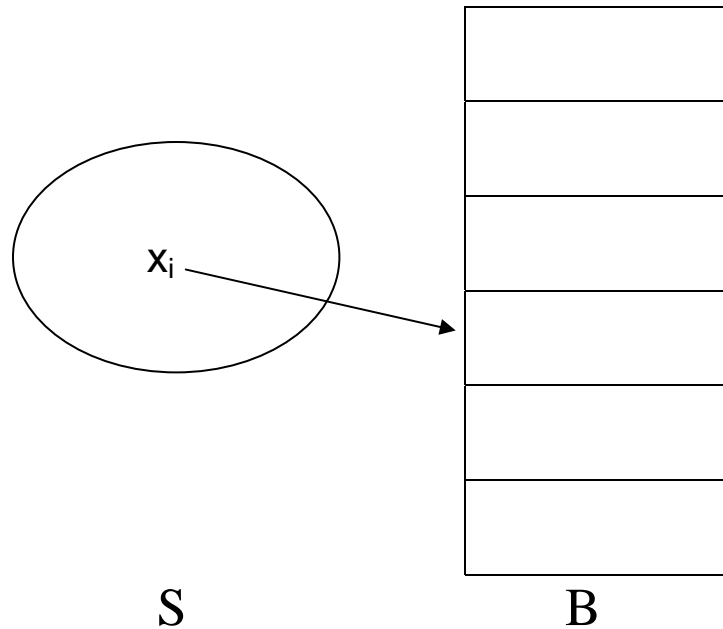
**ADT *Dictionary*:**

A collection class with *insert*, *delete* and *search* operations.

***Hash Table*:** An implementation of dictionary consisting of

- (1) *A set of  $m$  locations (buckets),  $B[0..m-1]$ :*  
Used for storing a set of  $n$  objects with keys  $S = \{x_1, x_2, \dots, x_n\}$ ,  $n \geq 0$ .
- (2) *A hash function  $h: S \rightarrow \{0, 1, \dots, m-1\}$ :*  
For any given data object with key  $x_i \in S$ , the location  $B[h(x_i)]$  will be used to store the given object if it is not already occupied by another object.
- (3) *A collision resolution scheme:*  
Used to determine an alternate location for storing an object whenever it is hashed into a location that is already occupied with an existing object. A ***collision*** is said to occur whenever two or more objects are hashed into the same location.

**Hashing:** A process in finding location in  $B[0..m-1]$  for storing any given object with key in  $S$ .



**Q:** How do we store an object in  $B$ ?

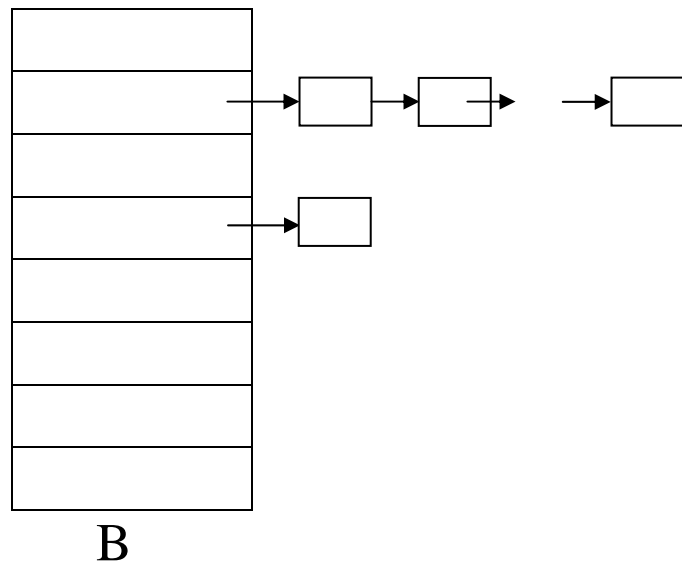
### Organizing a Hash Table:

1. *Open (External) hashing:* Locations store pointers (reference locations) to objects.
2. *Closed (Internal) hashing:* Locations store actual objects.

## Examples of Hashing Schemes:

### 1. (Open) Hashing with Separate Chaining:

Objects hashed into the same address are simply linked (chained) together.



Consider the Search operation:

- (1) Compute  $h(x_i)$  to find location  $B[h(x_i)]$ .
- (2) Search the linked structure at  $B[h(x_i)]$  sequentially for object with key  $x_i$ .

$$T(n) = \text{cost in computing } h(x_i) + \text{cost in searching the linked list at } B[h(x_i)]$$

**Q:** How should a hash table be designed so that it will have good performance?

**Remark:** In the worst-case, a chain may contain all  $n$  objects. To minimize searching time, each table location should contain a chain with roughly  $n/m$  objects.

A “*good*” hash function is a function that

- (1) Can be computed in  $\Theta(1)$  time, and
- (2) Distributes the objects evenly over all locations with each location having roughly  $n/m$  items.

Define *load factor*  $= \lambda = n/m$ .

Assuming that a good hash function  $h$  is used, we have

**Unsuccessful search:**

$$\begin{aligned} T_a(n) &= \Theta(1) + \Theta(1)(n/m) \\ &= \Theta(n/m) \\ &= \Theta(\lambda) \end{aligned}$$

**Successful search:**

$$\begin{aligned} T_a(n) &= \Theta(1) + \Theta(1)[(n/m)/2] \\ &= \Theta(n/m) \\ &= \Theta(\lambda) \end{aligned}$$

When  $m = \Theta(n)$ , we have

$$\begin{aligned} T_a(n) &= \Theta(n/m) \\ &= \Theta(1), \text{ which is the best possible!} \end{aligned}$$

Observe that  $T_a(n) = \Theta(\lambda)$ . As  $n$  increases,  $\lambda$  also increases, and efficiency of operations decreases.

### A Simple (but not too good) Hash Function:

Define  $h(x_i) = x_i \bmod m$ , where  $m$  is chosen to be a prime.

**Example:** Take  $m = 7$ . Insert 64, 26, 56, 72, 8, 36, and 42 into an initially empty hash table using separate chaining and hash function  $h(x) = x \bmod m$

$$64 \% 7 = 1,$$

$$26 \% 7 = 5,$$

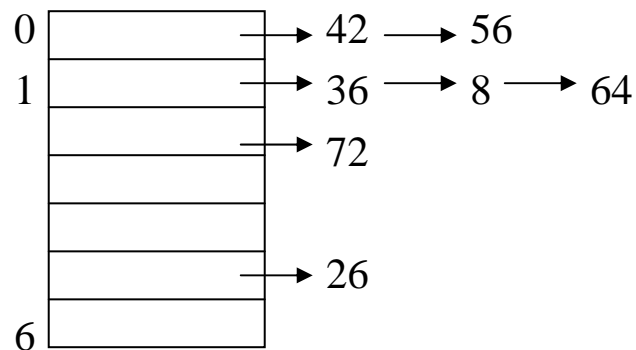
$$56 \% 7 = 0,$$

$$72 \% 7 = 2,$$

$$8 \% 7 = 1,$$

$$36 \% 7 = 1,$$

$$42 \% 7 = 0.$$



**B**

### Possible Extension

Singly linked list can be replaced with more advanced data structures so as to speed up searching once a location is found.

**HW:** Study other hash functions in text.

## **Advantages of Hashing with Chaining**

1. Simplicity (in concept and implementation).
2. Insertion is always possible; hence, a small table can be used to store any number of data (efficiency will suffer).

## **Disadvantages of Hashing with Chaining**

1. Can degenerate into a single chain with  $T_w(n) = O(n)$ .
2. Memory intensive: Need to implement/store pointers.
3. Slower speed: Indirect accessing data; need to follow pointers to data.

## **2. (Closed) Hashing with Open Addressing Scheme:**

Given hash function  $h$ . For some fixed integer  $k$ , define a sequence of hash functions  $h_i(x) = (h(x) + f_i) \bmod m$ , with  $0 \leq i \leq k$  and  $f_0 = 0$ .

The set of functions  $\{f_0, f_1, \dots, f_k\}$  is called *collision resolution functions*.

For any given object with key  $x$ . Compute  $h_0(x) = h(x)$ ,  $h_1(x)$ , ...,  $h_k(x)$  to find the first available location for inserting  $x$ .

## Some Simple Open Addressing Schemes:

### (i) Linear Probing:

Assume that  $h(x) = j$  and  $B[j]$  is occupied.

Search  $B[j+1]$ ,  $B[j+2]$ , ...,  $B[m-1]$ ,  $B[0]$ ,  $B[1]$ , ...,  $B[j-1]$  sequentially to find the first available location to insert  $x$ . If no empty location is found, report overflow.

Recall that  $h_i(x) = (h(x) + f_i) \bmod m$ ,  $0 \leq i \leq k$ , and  $f_0 = 0$ .

Define  $f_i = i$ , which is a *linear function*, we have

$$\begin{aligned} h_0(x) &= (h(x) + 0) \bmod m \\ &= h(x), \end{aligned}$$

$$\begin{aligned} h_1(x) &= (h(x) + f_1) \bmod m \\ &= (h(x) + 1) \bmod m, \end{aligned}$$

$$\begin{aligned} h_2(x) &= (h(x) + f_2) \bmod m \\ &= (h(x) + 2) \bmod m, \end{aligned}$$

...

$$\begin{aligned} h_k(x) &= (h(x) + f_k) \bmod m \\ &= (h(x) + k) \bmod m. \end{aligned}$$

**Example:** Take  $m = 7$ . Insert 64, 26, 56, 72, 8, 36, 42, using linear probing and hash function  $h(x) = x \bmod m$ , into an initially empty hash table.

$$64 \% 7 = 1,$$

$$26 \% 7 = 5,$$

$$56 \% 7 = 0,$$

$$72 \% 7 = 2,$$

$$8 \% 7 = 1 \rightarrow 2 \rightarrow 3,$$

$$36 \% 7 = 1 \rightarrow 2 \rightarrow 3 \rightarrow 4,$$

$$42 \% 7 = 0 \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6.$$

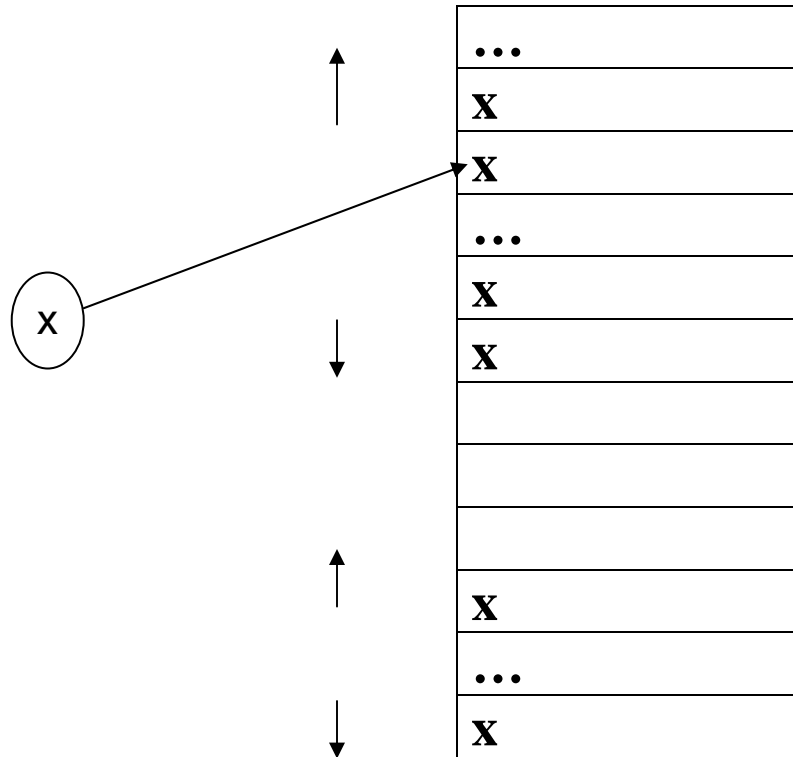
**Hash table using linear probing:**

56
64
72
8
36
26
42

**Remark:** When blocks of locations are occupied, closed hashing with linear probing may result in *primary clustering*, which are blocks of occupied locations.



## Primary Clustering:



**Remark:** Primary clustering behaves like long chain and degrades the performance of the table!

**Remedy:** Use quadratic probing to eliminate primary clustering.

## (ii) Quadratic Probing:

Recall that  $h_i(x) = (h(x) + f_i) \bmod m$ ,  $0 \leq i \leq k$ , and  $f_0 = 0$ .

Define  $f_i = i^2$ , which is a *quadratic function*, we have

$$\begin{aligned} h_0(x) &= (h(x) + 0^2) \bmod m \\ &= h(x), \end{aligned}$$

$$\begin{aligned} h_1(x) &= (h(x) + f_1) \bmod m, \\ &= (h(x) + 1^2) \bmod m, \end{aligned}$$

$$\begin{aligned} h_2(x) &= (h(x) + f_2) \bmod m, \\ &= (h(x) + 2^2) \bmod m, \end{aligned}$$

...

$$\begin{aligned} h_k(x) &= (h(x) + f_k) \bmod m, \\ &= (h(x) + k^2) \bmod m. \end{aligned}$$

**Example:** Take  $m = 7$ . Insert 64, 26, 56, 72, 8, 36, 42, using quadratic probing and hash function  $h(x) = x \bmod m$ , into an initially empty hash table.

**Addresses Computation:**

$$64 \% 7 = 1,$$

$$26 \% 7 = 5,$$

$$56 \% 7 = 0,$$

$$72 \% 7 = 2,$$

$$8 \% 7 = 1 \rightarrow 2 \rightarrow 5 \rightarrow 3,$$

$$36 \% 7 = 1 \rightarrow 2 \rightarrow 5 \rightarrow 3 \rightarrow 3 \rightarrow 5 \rightarrow 2 \rightarrow \dots$$

**Hash table using quadratic probing:**

56
64
72
8
26

**Problems with Closed Hashing:**

1. Insertion may fail even though the table is not empty.
2. May form *secondary clustering*.

## More Problems with Closed Hash Table:

Consider the following example.

**Example:** Take  $m = 7$ . Insert 64, 56, 72, 8, followed by delete 64 and then delete 8, using linear probing and hash function  $h(x) = x \bmod m$ , into an initially empty hash table.

### Addresses Computation:

$$64 \% 7 = 1,$$

$$56 \% 7 = 0,$$

$$72 \% 7 = 2,$$

$$8 \% 7 = 1 \rightarrow 2 \rightarrow 3,$$

**Hash table after inserting 64, 56, 72 and 8:**

56
64
72
8

## Hash table after deleting 64:

56
72
8

**Q:** How do we delete 8?

Recall that  $8 \% 7 = 1$  but  $B[1]$  is empty. Hence, we must continue searching for  $x$  even though an empty bucket is found!

**Q:** When can we stop searching?

### Observation:

Two types of empty buckets:

1. A bucket that is always empty: Searching terminates.
2. A bucket that is emptied by deletion: Searching must continue.

## **Data Structure for Bucket:**

Using an extra flag/Boolean field:

flag = true  $\Rightarrow$  Bucket is emptied by deletion;  
searching must continue.

flag = false  $\Rightarrow$  Bucket is always empty; searching  
terminates.

## **Advantages of Closed Hashing with Open Addressing:**

1. Faster speed: No need to follow pointers.
2. Less memory consumption: No need to implement pointers.

## **Disadvantages of Hashing with Open Addressing**

1. Much more complex.
2. Can degenerate into primary or secondary clustering.
3. Deletion/Find operations are much more complex.
4. Insertion is not always possible even though the table is not empty.

**Theorem:** When  $m$  is prime and the table is at least half-empty; i.e.,  $\lambda < 1/2$ , we can always insert a new item into a closed hash table using quadratic probing.

## Conclusions:

1. To guarantee good performance in a hash table, a prime number should be chosen for  $m$  such that  $\lambda < 1$  for open hashing and  $\lambda < 1/2$  for closed hashing.
2. Must monitor  $\lambda$  during the lifetime of your hash table.
3. Hashing with open addressing (eg. quadratic probing) outperforms hashing with chaining only if implemented correctly!

**Q:** What happens when insertion/deletion become increasingly difficult?

Need a new hash table with larger/smaller size!

## Rehashing:

A process in hashing all the elements of an existing hash table  $H$  into a new hash table  $H^*$ .

$$H \leftrightarrow H^*$$

$$\text{tableSize } m \text{ (prime)} \leftrightarrow \text{tableSize } \sim 2m \text{ (prime)}$$

**Remark:** Rehashing is a very expensive process and should only be performed infrequently.

**Q:** When do we rehash?

1. When  $\lambda \rightarrow 1$  for open hashing and  $\lambda \rightarrow 1/2$  for closed hashing.
2. Use a pre-specified  $\lambda$  to determine when to rehash.
3. When insertion becomes increasingly difficult or fails.
4. When deletion becomes increasingly difficult.

(iii). **Another Open Addressing Scheme: Double Hashing:**

Use two hash functions  $h$  and  $h^+$  such that the collision functions  $f_i$ 's are functions of  $i$  and  $h^+$ .

Now, define  $f_i = ih^+$ . (or  $i^2h^+$ , or others)

Observe that

$$\begin{aligned}h_0(x) &= (h(x) + 0h^+(x)) \bmod m \\ &= h(x),\end{aligned}$$

$$\begin{aligned}h_1(x) &= (h(x) + f_1) \bmod m, \\ &= (h(x) + 1h^+(x)) \bmod m,\end{aligned}$$

$$\begin{aligned}h_2(x) &= (h(x) + f_2) \bmod m, \\ &= (h(x) + 2h^+(x)) \bmod m,\end{aligned}$$

...

$$\begin{aligned}h_k(x) &= (h(x) + f_k) \bmod m, \\ &= (h(x) + kh^+(x)) \bmod m.\end{aligned}$$



### **A Simple $h^+$ Function:**

Define  $h^+(x) = R - (x \bmod R)$ , where  $R < m$  is a prime.

**Example:** Take  $m = 7$ ,  $R = 5$ . Insert 64, 26, 56, 72, 8, 36, 42, using double hashing with hash functions  $h(x) = x \bmod m$ ,  $h^+(x) = R - (x \bmod R)$ , and  $f_i = ih^+$ , into an initially empty hash table.

### **Addresses Computation:**

$$64 \% 7 = 1,$$

$$26 \% 7 = 5,$$

$$56 \% 7 = 0,$$

$$72 \% 7 = 2,$$

$$8 \% 7 = 1,$$

$$h^+(x) = R - (x \bmod R) = 5 - (8 \bmod 5) = 2,$$

$$h_1(x) = (h(x) + 1h^+(x)) \bmod m = (1 + 2) \bmod 7 = 3,$$

$$36 \% 7 = 1,$$

$$h^+(x) = R - (x \bmod R) = 5 - (36 \bmod 5) = 4,$$

$$h_1(x) = (h(x) + 1h^+(x)) \bmod m = (1 + 4) \bmod 7 = 5,$$

$$h_2(x) = (h(x) + 2h^+(x)) \bmod m = (1 + 8) \bmod 7 = 2,$$

$$h_3(x) = (h(x) + 3h^+(x)) \bmod m = (1 + 12) \bmod 7 = 6,$$

$$42 \% 7 = 0,$$

$$h^+(x) = R - (x \bmod R) = 5 - (42 \bmod 5) = 3,$$

$$h_1(x) = (h(x) + 1h^+(x)) \bmod m = (0 + 3) \bmod 7 = 3,$$

$$h_2(x) = (h(x) + 2h^+(x)) \bmod m = (0 + 6) \bmod 7 = 6,$$

$$h_3(x) = (h(x) + 3h^+(x)) \bmod m = (0 + 9) \bmod 7 = 2,$$

$$h_4(x) = (h(x) + 4h^+(x)) \bmod m = (0 + 12) \bmod 7 = 5,$$

$$h_5(x) = (h(x) + 5h^+(x)) \bmod m = (0 + 15) \bmod 7 = 1,$$

$$h_6(x) = (h(x) + 6h^+(x)) \bmod m = (0 + 18) \bmod 7 = 4.$$

### Hash table using double hashing:

56
64
72
8
42
26
36