

# Ignat Georgiev

## Research Engineer | Robotics & Machine Learning

Young professional with a passion for Robotics and ML on a mission to bring intelligent Star-Wars-like one step closer to reality. I love taking ideas from research to production. My strength is that I am an excellent robotics programmer, ML engineer, proven team leader and successful project manager. I am eager to work on bleeding-edge innovative products and contribute to team success through my unique skill set, hands-on experience, and drive.

## Work Experience

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### Robotics Engineer

*Kopernikus Automotive, Germany*

August 2020 - Nov 2021

- ✓ Worked on autonomous valet parking product with deep learning CV and Rust
- ✓ Developed, tested and deployed a planning and control system based on random sampling and numerical optimization
- ✓ Successfully led a project to integrate with 5 OEMs and demo product

### Founder & AI Team Lead

*Edinburgh University Formula Student, UK*

September 2017 - June 2020

- ✓ Founded and led a student project to develop an autonomous racecar
- ✓ The team won 2 international competitions and raised a budget of over £70,000
- ✓ Architected and led the development of the AV stack with ROS / C++ / Python
- ✓ Involved in development of DL camera and lidar object detection, multi-sensor EKF, particle filter SLAM, elastic band path planning, model predictive control, functional safety, software integration, CI/CD, and a custom simulation
- ✓ Worked on end-to-end autonomous driving from camera images with DRL

### Research Engineer

*Roborace, UK*

June 2019 - April 2020

- ✓ Worked on developing a reference autonomous racing software stack
- ✓ Developed path planning and ML motion control algorithms with C++ and CUDA

## Education

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### MSc Robotics and Artificial Intelligence

*The University of Edinburgh, UK*

2015 - 2020

- ✓ First-Class Honours (4.0 GPA)
- ✓ Focus on linear algebra, probability, robotics, machine learning, reinforcement learning, and optimal control
- ✓ Thesis: Adaptive Motion Control for Autonomous Racing using Reinforcement Learning under Prof Michael Mistry. Published as a research paper at Conference of Robot Learning 2020.

## Contact Details

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GitLab: [imgeorgiev](https://gitlab.com/imgeorgiev)

## Technical skills

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C++ (11/14/17)

Rust

Python

PyTorch

CUDA

ROS & ROS2

Unix / Linux / bash

Git / Gitlab CI / Jenkins

Robot simulators

Algorithms & Structures

Distributed & Concurrent systems

Data Science & Visualization

## Professional Skills

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Analytical thinking

Teamwork

Project Management

Leadership

## Honours & Awards

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Inspirational Graduate

Best Robotics Thesis

Student Employee of the Year

