10 Kronecker积

定义1:设 $A = (a_{ij}) \in P^{m \times n}, B = (b_{ij}) \in P^{p \times q},$

$$A \otimes B = \begin{pmatrix} a_{11}B & a_{12}B & \cdots & a_{1n}B \\ a_{21}B & a_{22}B & \cdots & a_{2n}B \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}B & a_{m2}B & \cdots & a_{mn}B \end{pmatrix}$$

则 $A \otimes B$ 称为A与B的Kronecker积.

(直积direct product、张量积tensor product).

Kronecker积的最代表性的应用在信号处理与系统理论中的多变元时间序列的高阶统计量理论与方法中的应用.

多变元时间序列的高阶累积量、高阶谱(多谱)和描述 输入、输出与多信道冲击响应三者关系变得非常简洁.

例1 设
$$A = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$
与 $B = \begin{pmatrix} 2 & 1 \\ 2 & 3 \end{pmatrix}$. 则

$$A \otimes B = \begin{pmatrix} B & 2B & 3B \\ 3B & 2B & B \end{pmatrix} = \begin{pmatrix} 2 & 1 & 4 & 2 & 6 & 3 \\ 2 & 3 & 4 & 6 & 6 & 9 \\ 6 & 3 & 4 & 2 & 2 & 1 \\ 6 & 9 & 4 & 6 & 2 & 3 \end{pmatrix}$$

 $A \otimes B \neq B \otimes A$.

例2
$$I_2 \otimes B = \begin{bmatrix} B & 0 \\ 0 & B \end{bmatrix}$$

例3
$$B\otimes I_2=egin{bmatrix} b_{11}&0&b_{12}&0\0&b_{11}&0&b_{12}\b_{21}&0&b_{22}&0\0&b_{21}&0&b_{22}\end{bmatrix}$$

例4 设 $x \in R^m, y \in R^n$

$$x \otimes y = \begin{bmatrix} x_1 y^T, & \dots, & x_m y^T \end{bmatrix}^T \in R^{mn}$$

例5 设 $x \in R^m, y \in R^n$

$$x \otimes y^T = \begin{bmatrix} x_1 y, & \dots, & x_m y \end{bmatrix}^T$$

$$= \begin{bmatrix} x_1 y_1 & \cdots & x_1 y_n \\ \vdots & \ddots & \vdots \\ x_m y_1 & \cdots & x_m y_n \end{bmatrix} \in R^{m \times n}$$

定理1: Kronecker积的性质:

设
$$A \in P^{m \times n}, B \in P^{p \times q}, C \in P^{r \times s}, D \in P^{k \times h}$$

- $(1) \quad E_m \otimes E_n = E_{mn}$
- (2) $\lambda(A \otimes B) = (\lambda A) \otimes B = A \otimes (\lambda B)$
- (3) $(A \pm B) \otimes C = (A \otimes C) \pm (B \otimes C)$

$$A \otimes (B \pm C) = (A \otimes B) \pm (A \otimes C)$$

- $(4) \quad (A \otimes B) \otimes C = A \otimes (B \otimes C)$
- (5) $(A \otimes B)^T = A^T \otimes B^T, \overline{A \otimes B} = \overline{A} \otimes \overline{B},$ $(A \otimes B)^H = A^H \otimes B^H.$

(6) 当
$$n = r, q = k$$
时, $(A \otimes B)(C \otimes D) = (AC) \otimes (BD)$

(7) 当
$$m = n, p = q$$
时,且 A, B 可逆,则
$$(A \otimes B)^{-1} = A^{-1} \otimes B^{-1}$$

- (8) $rank(A \otimes B) = rankA \cdot rankB;$
- (9) 当m = n, p = q时, $tr(A \otimes B) = trA \cdot trB$ $det(A \otimes B) = (detA)^{p} \cdot (detB)^{n}$

证明:

(6)
$$(A \otimes B)(C \otimes D)$$

$$= \begin{bmatrix} a_{11}B & \cdots & a_{1n}B \\ \vdots & \ddots & \vdots \\ a_{m1}B & \cdots & a_{mnB} \end{bmatrix} \begin{bmatrix} c_{11}D & \cdots & c_{1s}D \\ \vdots & \ddots & \vdots \\ c_{n1}D & \cdots & c_{ns}D \end{bmatrix}$$

$$= \sum_{k=1}^{n} a_{1k}c_{k1}BD \cdots \sum_{k=1}^{n} a_{1k}c_{ks}BD$$

$$= \sum_{k=1}^{n} a_{mk}c_{k1}BD \cdots \sum_{k=1}^{n} a_{mk}c_{ks}BD$$

 $= AC \otimes BD$

$$(9)A = P^{-1} \begin{pmatrix} \lambda_1 & & * \\ 0 & \lambda_2 & \\ \vdots & \ddots & \\ 0 & \cdots & 0 & \lambda_n \end{pmatrix} P = P^{-1}J_1P$$

$$(9)A = P^{-1} \begin{pmatrix} \lambda_1 & & * \\ 0 & \lambda_2 & \\ \vdots & \ddots & \\ 0 & \cdots & 0 & \lambda_n \end{pmatrix} P = P^{-1}J_1P$$

$$B = Q^{-1} \begin{pmatrix} \mu_1 & & * \\ 0 & \mu_2 & \\ \vdots & \ddots & \\ 0 & \cdots & 0 & \mu_p \end{pmatrix} Q = Q^{-1}J_2Q$$

$$A \otimes B = (P^{-1}J_{1}P) \otimes (Q^{-1}J_{2}Q)$$

$$= (P \otimes Q)^{-1}(J_{1} \otimes J_{2})(P \otimes Q) \Rightarrow$$

$$det(A \otimes B) = det(J_{1} \otimes J_{2})$$

$$= (\prod_{j=1}^{p} \lambda_{1}\mu_{j})(\prod_{j=1}^{p} \lambda_{2}\mu_{j}) \cdots (\prod_{j=1}^{p} \lambda_{n}\mu_{j})$$

$$= (\lambda_{1})^{p}(\prod_{j=1}^{p} \mu_{j}) \cdot (\lambda_{2})^{p}(\prod_{j=1}^{p} \mu_{j}) \cdots (\lambda_{n})^{p}(\prod_{j=1}^{p} \mu_{j})$$

$$\therefore \det(A \otimes B) = (\det A)^p \cdot (\det B)^n$$

定义2

Kronec ker 积的乘幂: $A^{[k]} = A \otimes A \otimes \cdots \otimes A$.

定理2

- (1) 当 $A^T = A, B^T = B$ 时, $A \otimes B$ 也是对称矩阵; 当 $A^H = A, B^H = B$ 时, $A \otimes B$ 也是Hermite矩阵;
- (2) 当U,V均为酉矩阵时, $U\otimes V$ 也是酉矩阵;
- $(3) (AB)^{[k]} = A^{[k]}B^{[k]}.$

例6:以1或-1为元素的m阶矩阵H,如果有 $HH^T=mE_m$

则称H 为m阶Hadamard矩阵.设 H_m , H_n 分别为m,n阶Hadamard矩阵,则 $H_m \otimes H_n$ 为mn阶Hadamard矩阵.

TIE:
$$(H_m \otimes H_n)(H_m \otimes H_n)^T$$

$$= (H_m \otimes H_n)(H_m^T \otimes H_n^T)$$

$$= H_m H_m^T \otimes H_n H_n^T$$

$$= mE_m \otimes nE_n = mnE_{mn}$$

二、Kronecker积的特征值

定理3: 设 $\lambda_i(i=1,2,\cdots,m)$ 为 $A \in C^{m \times m}$, $x_i(i=1,2,\cdots,m)$ 为相应的特征向量; $\mu_j(j=1,2,\cdots,n)$ 为 $B \in C^{n \times n}$, $y_j(j=1,2,\cdots,n)$ 为相应的特征向量,则 $A \otimes B$ 有mn个特征值 $\lambda_i \mu_j$,对应的特征向量为 $x_i \otimes y_j$. (6)($A \otimes B$)($C \otimes D$) = (AC) \otimes (BD)

$$Ax_{i} = \lambda_{i}x_{i}, By_{j} = \mu_{j}y_{j} \Rightarrow$$

$$(A \otimes B)(x_{i} \otimes y_{j}) = Ax_{i} \otimes By_{j} = \lambda_{i}x_{i} \otimes \mu_{j}y_{j}$$

$$= \lambda_{i}\mu_{j}(x_{i} \otimes y_{j})$$

定义3 m阶矩阵A与n阶矩阵B的Kronecker 和:

$$A \oplus_k B = A \otimes E_n + E_m \otimes B$$

$$(A \oplus_k B = E_n \otimes A + B \otimes E_m)$$

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解 $A \oplus_k B = A \otimes E_2 + E_3 \otimes B$

$$= \begin{bmatrix} 1 & 0 & 2 & 0 & 3 & 0 \\ 0 & 1 & 0 & 2 & 0 & 3 \\ 3 & 0 & 2 & 0 & 1 & 0 \\ 0 & 3 & 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 & 4 & 0 \\ 0 & 1 & 0 & 1 & 0 & 4 \end{bmatrix} + \begin{bmatrix} 2 & 1 & 0 & 0 & 0 & 0 \\ 2 & 3 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 & 3 \end{bmatrix}$$

定理4: 设 $\lambda_i(i=1,2,\cdots,m)$ 为 $A \in C^{m \times m}, x_i(i=1,2,\cdots,m)$ 为相应的特征向量; $\mu_j(j=1,2,\cdots,n)$ 为 $B \in C^{n \times n}, y_j(j=1,2,\cdots,n)$ 为相应的特征向量, 则 $\lambda_i + \mu_j$ 是 $A \oplus_k B$ 的特征值, $x_i \otimes y_j$ 为对应的特征向量.

$$(A \oplus_k B)(x_i \otimes y_j)$$

$$= (A \otimes E_n)(x_i \otimes y_j) + (E_m \otimes B)(x_i \otimes y_j)$$

$$= (Ax_i) \otimes y_j + x_i \otimes (By_j) = (\lambda_i + \mu_j)x_i \otimes y_j$$

2、向量化算符

设
$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

记
$$A$$
的列为 $A_{c1}, A_{c2}, ..., A_{cn} \Rightarrow A = (A_{c1}, A_{c2}, ..., A_{cn})$

向量化算符:
$$\operatorname{Vec} A = \begin{pmatrix} A_{c1} \\ A_{c2} \\ \vdots \\ A_{cn} \end{pmatrix}$$

例:
$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \Rightarrow Vec(A) = \begin{pmatrix} 1 \\ 3 \\ 2 \\ 4 \end{pmatrix}$$

性质1: Vec(kA+lB) = kVec(A) + lVec(B)

若矩阵 $A_{m\times n}=ab^T$,则 $Vec\ (ab^T)=b\otimes a$.

定理5: 设 $A \in C^{m \times n}, X \in C^{n \times r}, B \in C^{r \times s}, 则$

$$Vec(AXB) = (B^T \otimes A)Vec X$$

证明: 设
$$X_{n \times r} = \begin{bmatrix} x_1, x_2, \dots, x_r \end{bmatrix}$$
, 且 e_1, e_2, \dots, e_r 是 $r \times 1$ 的单位向量,则 $X_{n \times r} = \sum_{i=1}^r x_i e_i^T$,
$$\operatorname{Vec}(AXB) = \operatorname{Vec}(\sum_{i=1}^r Ax_i e_i^T B) = \sum_{i=1}^r \operatorname{Vec}\left[(Ax_i)(e_i^T B)\right]$$

$$\operatorname{divec}(ab^T) = b \otimes a \operatorname{orall}$$

$$= \sum_{i=1}^r \operatorname{Vec}\left[(Ax_i)(B^T e_i)^T\right] = \sum_{i=1}^r (B^T e_i \otimes Ax_i)$$

$$= (B^T \otimes A) \sum_{i=1}^r (e_i \otimes x_i) = (B^T \otimes A) \sum_{i=1}^r \operatorname{Vec}(x_i e_i^T)$$

$$= (B^T \otimes A) \operatorname{Vec}(X).$$

推论1: 设 $A \in C^{m \times m}, B \in C^{n \times n}, X \in C^{m \times n}, \emptyset$

- (1) $\operatorname{Vec}(AX) = (E_n \otimes A)\operatorname{Vec}X;$
- (2) $\operatorname{Vec}(XB) = (B^T \otimes E_m) \operatorname{Vec} X;$

(3)
$$\operatorname{Vec}(AX + XB) = \left[(E_n \otimes A) + (B^T \otimes E_m) \right] \operatorname{Vec} X$$

性质2 $A_1, A_2, \dots, A_k \in C^{m \times n}$ 线性无关

 $\Leftrightarrow \operatorname{Vec}(A_1), \operatorname{Vec}(A_2), \cdots, \operatorname{Vec}(A_k)$ 线性无关

例8: 解矩阵方程

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} x_1 & x_3 \\ x_2 & x_4 \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix}$$

$$AX = C \Rightarrow Vec(AX) = (E \otimes A)VecX = Vec(C) \Rightarrow$$

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ & a_{11} & a_{12} \\ & a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} c_{11} \\ c_{21} \\ c_{12} \\ c_{22} \end{pmatrix}$$

3. Kronecker 乘积的应用

矩阵方程的求解

(1):
$$AX + XB = D(Sylvester equation)$$

$$\Leftrightarrow \operatorname{Vec}(AX + XB) = [(E \otimes A) + (B^T \otimes E)]\operatorname{Vec}(X) = \operatorname{Vec}(D)$$

$$(2): AXB = D$$

$$\Leftrightarrow \operatorname{Vec}(AXB) = (B^T \otimes A)\operatorname{Vec}(X) = \operatorname{Vec}(D)$$

$$(3): A_1 X B_1 + A_2 X B_2 = D$$

$$\Leftrightarrow [(B_1^T \otimes A_1) + (B_2^T \otimes A_2)] \operatorname{Vec}(X) = \operatorname{Vec}(D)$$

补子空间(不唯一);正交补子空间(唯一).

和与直和(主要区别:向量分解是否唯一) 维数定理

线性子空间($W \subset V, W \forall V$ 中的+,×封闭)

线性空间 $(V, P, +, \cdot) P = R(C)$ 实(复)空间

线性变换T

 $T:\alpha$ -基下矩阵

 β -基下矩阵B.

 α -基到 β -基矩阵P

 $B=P^{-1}AP$.

投影变换 $T^2=T$

内积空间(欧式空间, 酉空间)

内积由 α -基下度量矩阵A唯一确定.

β-基下的度量矩阵为 $B B = P^T A P$.

正交投影 $T^2=T$, $R^\perp(T)=N(T)$

保距变换T: 正交变换、酉变换. Householder变换; Givens变换; Gauss变换 ⇒初等矩阵

Kronecker乘积