

8/3/2021 Spherical Interconversion

$$\begin{bmatrix} \sin\theta & 0 & \cos\theta \\ \cos\theta & 0 & -\sin\theta \\ 0 & 1 & 0 \end{bmatrix}$$

Cartesian - cylindrical

$$\begin{bmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Cartesian - spherical

$$\begin{bmatrix} \sin\phi \cos\theta & \cos\phi \cos\theta & -\sin\theta \\ \sin\phi \sin\theta & \cos\phi \sin\theta & \cos\theta \\ \cos\phi & -\sin\phi & 0 \end{bmatrix}$$

Cylindrical - spherical

$$\begin{bmatrix} \frac{p}{\sqrt{p^2+z^2}} & \frac{z}{\sqrt{p^2+z^2}} & 0 \\ 0 & 0 & 1 \\ \frac{z}{\sqrt{p^2+z^2}} & \frac{-p}{\sqrt{p^2+z^2}} & 0 \end{bmatrix}$$

8/3/2021 Given point $P \rightarrow P(-2, 6, 3)$ & vector $\vec{A} = y\vec{a}_x + (x+z)\vec{a}_y$

express P both in cylindrical & spherical coordinates

Sol:

$$A = y\vec{a}_x + (x+z)\vec{a}_y$$

Cartesian to cylindrical:

$$\begin{bmatrix} Ap \\ A\phi \\ Az \end{bmatrix} = \begin{bmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} Ax \\ Ay \\ Az \end{bmatrix}$$

$$\begin{bmatrix} Ap \\ A\phi \\ Ax \end{bmatrix} =$$

Point

$$P = \sqrt{x^2+y^2} = \sqrt{4+36} = \sqrt{40} = 2\sqrt{10}$$

$$\phi = \tan^{-1}\left(\frac{y}{x}\right) = \tan^{-1}\left(\frac{6}{-2}\right) \neq \pi$$

$$\phi = 108.43^\circ$$

$$z=2$$

$$\boxed{z=3}$$

1)

$$\begin{aligned} P &= 6.325 \text{ units} \\ \phi &= 108.43^\circ \\ z &= 3 \end{aligned}$$

$$P(P = 6.325, \phi = 108.43^\circ, z = 3)$$

Cartesian to Spherical

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \cos^{-1} \left(\frac{z}{\sqrt{x^2 + y^2 + z^2}} \right)$$

$$\phi = \tan^{-1} \left(\frac{y}{x} \right)$$

$$r = \sqrt{4+36+9}$$

$$= \sqrt{49} = 7 \text{ units.}$$

$$\theta = \cos^{-1} \left(\frac{3}{7} \right)$$

$$\boxed{\theta = 64.62^\circ}$$

$$\phi = \tan^{-1} \left(\frac{y}{x} \right) = 108.43^\circ$$

$$P(r = 7, \theta = 64.62^\circ, \phi = 108.43^\circ)$$

Transform a vector $\vec{A} = y\vec{a}_x + x\vec{a}_y + z\vec{a}_z$ in to cylindrical coordinates

Solu:

2)

$$\begin{bmatrix} A_P \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \cos\phi & \sin\phi & 0 \\ -\sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} y \\ -x \\ z \end{bmatrix}$$

$$\vec{A} = A_x \vec{a}_x + A_y \vec{a}_y + A_z \vec{a}_z$$

$$A_P = y \cos\phi - x \sin\phi$$

$$A_\phi = -y \sin\phi - x \cos\phi$$

$$\boxed{A_z = z}$$

$$x = P \cos\phi$$

$$y = P \sin\phi$$

$$\vec{A} = (y \cos\phi - x \sin\phi) \vec{a}_P + (-y \sin\phi - x \cos\phi) \vec{a}_\phi + z \vec{a}_z$$

$$\vec{A} = (P \sin\phi \cos\phi - P \cos\phi \sin\phi) \vec{a}_P - (P \sin^2\phi + P \cos^2\phi) \vec{a}_\phi + z \vec{a}_z$$

$$\vec{A} = (P \sin\phi \cos\phi) \vec{a}_P - (P \sin^2\phi + P \cos^2\phi) \vec{a}_\phi + z \vec{a}_z$$

3) Obtain the spherical coordinates θ, ϕ, z at the point

$$P(x = -3, y = 2, z = 4)$$

Solu:

$$\begin{aligned} r &= \sqrt{x^2 + y^2 + z^2} = \sqrt{9 + 4 + 16} = \sqrt{39} = 5.3851 \\ \theta &= \tan^{-1} \left(\frac{y}{x} \right) = \tan^{-1} \left(\frac{2}{-3} \right) = 146.30^\circ \end{aligned}$$

$$\theta = \cos^{-1} \left(\frac{z}{\sqrt{x^2 + y^2 + z^2}} \right) = \cos^{-1} \left(\frac{4}{5.3851} \right) = 42.03034^\circ$$

$$\begin{bmatrix} \vec{a}_r \\ \vec{a}_\theta \\ \vec{a}_\phi \end{bmatrix} = \begin{bmatrix} \sin\theta \cos\phi & \sin\theta \sin\phi & \cos\theta \\ \cos\theta \cos\phi & \cos\theta \sin\phi & -\sin\theta \\ -\sin\phi & \cos\phi & 0 \end{bmatrix} \begin{bmatrix} 10 \\ 0 \\ 0 \end{bmatrix}$$

~~neatly done
good~~

$$A_r = 10 \sin\theta \cos\phi$$

$$A_\theta = 10 \cos\theta \cos\phi$$

$$A_\phi = -10 \sin\phi$$

$$\vec{A} = (10 \sin\theta \cos\phi) \vec{a}_r + (10 \cos\theta \cos\phi) \vec{a}_\theta + (-10 \sin\phi) \vec{a}_\phi$$

$$\vec{A} = -5.57 \vec{a}_r + (-6.179) \vec{a}_\theta - 5.5484 \vec{a}_\phi$$

$$\boxed{\vec{A} = -5.57 \vec{a}_r - 6.18 \vec{a}_\theta - 5.55 \vec{a}_\phi}$$

Express $\vec{B} = \frac{10}{r} \vec{a}_r + r \cos\theta \vec{a}_\theta + \vec{a}_\phi$ in carr and cyl cs

Find \vec{B} at $(-3, 4, 0)$ and $(5, \pi/2, -2)$

Solu:

Spherical to Cartesian

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \sin\theta \cos\phi & \cos\theta \cos\phi & -\sin\phi \\ \sin\theta \sin\phi & \cos\theta \sin\phi & \cos\phi \\ \cos\theta & -\sin\theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix}$$

$$= \begin{bmatrix} \sin\theta \cos\phi & \cos\theta \cos\phi & -\sin\phi \\ \sin\theta \sin\phi & \cos\theta \sin\phi & \cos\phi \\ \cos\theta & -\sin\theta & 0 \end{bmatrix} \begin{bmatrix} 10/r \\ r \cos\theta \\ 1 \end{bmatrix}$$

$$A_x = \frac{10}{r} \sin\theta \cos\phi + r \cos^2\theta \cos\phi - \sin\phi$$

$$A_y = \frac{10}{r} \sin\theta \sin\phi + r \cos^2\theta \sin\phi + \cos\phi$$

$$A_z = \frac{10}{r} \cos\theta - r \sin\theta \cos\theta$$

$$r = \sqrt{9+16}$$

$$\theta = \cos^{-1} \left(\frac{x}{\sqrt{x^2+y^2+z^2}} \right), \quad \phi = \tan^{-1} \left(\frac{y}{x} \right)$$

$$= \cos^{-1} (0)$$

$$\boxed{\phi = 126.86}$$

$$\boxed{\theta = 90^\circ}$$

$$A_x = 2 \sin 90^\circ \cos(126.86) + 5 \cos^2 90^\circ \cos(126.86) - \sin(126.86)$$

$$= 2(-0.599) + 5(0) - (0.8)$$

$$A_x = -1.998$$

$$A_x \approx -2$$

$$A_y = 2 \sin 90^\circ \sin(126^\circ - 86^\circ) + 5 \cos^2 90^\circ \sin(126^\circ - 86^\circ) + \cos(126^\circ - 86^\circ)$$

$$A_y = 1.0003$$

$$A_y \approx 1$$

$$A_z = 2 \cos 90^\circ - 5 \sin 90^\circ \cos 90^\circ$$

$$A_z = 0$$

$$\vec{A} = -\alpha \vec{a}_x + \vec{a}_y$$

spherical to cylindrical

$$\begin{bmatrix} A_p \\ A_\phi \\ A_z \end{bmatrix} = \begin{bmatrix} \frac{P}{\sqrt{P^2+z^2}} & \frac{z}{\sqrt{P^2+z^2}} & 0 \\ 0 & 1 & r \cos \theta \\ \frac{z}{\sqrt{P^2+z^2}} & \frac{-P}{\sqrt{P^2+z^2}} & 0 \end{bmatrix} \begin{bmatrix} 10/r \\ r \cos \theta \\ 1 \end{bmatrix}$$

$$A_\phi = 1$$

$$A_p = \frac{10}{r} \left(\frac{P}{\sqrt{P^2+z^2}} \right) + \frac{z}{r \cos \theta} \frac{\cos \theta}{\sqrt{P^2+z^2}}$$

$$A_z = \frac{10}{r} \left(\frac{z}{\sqrt{P^2+z^2}} \right) - \frac{r \cos \theta}{\sqrt{P^2+z^2}} \frac{P}{\sqrt{P^2+z^2}}$$

$$A_p = \frac{10}{\sqrt{29}} \left(\frac{5}{\sqrt{29}} \right) + \sqrt{29} \cos\left(\frac{\pi}{2}\right) \left(\frac{-\alpha}{\sqrt{29}} \right)$$

$$P(5, \frac{\pi}{2}, -2)$$

$$r \quad \phi \quad z$$

$$r = \sqrt{P^2+z^2}$$

$$A_p = \frac{50}{29}$$

$$A_z = \frac{10}{\sqrt{29}} \left(\frac{-\alpha}{\sqrt{29}} \right)$$

$$= \sqrt{\alpha^2 + 4}$$

$$A_p = 1.724$$

$$= \frac{-20}{(\sqrt{29})^2} = -0.689$$

$$\vec{A} = 1.72 \vec{a}_p - 0.69 \vec{a}_z + \vec{a}_p$$

$$\vec{A} = 1.72 \vec{a}_p + \vec{a}_p - 0.69 \vec{a}_z$$

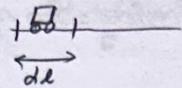
9/3/2021

Integral relationLine integral (straight line on curved path)

curved path - can be open or closed.

$$W = \text{Force} \times \text{displacement}$$

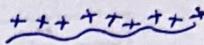
Distance - scalar
Displacement - vector



$$W = \int \vec{F} \cdot d\vec{l}$$

 \int_L (over the line)

'open-ended line'



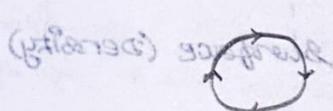
'open-ended curve'

'closed line integral'


 \oint_L → closed line.

'contours' - path traced along the circle'

closed line integral (or) circular integral (line)



Represents circulation of a vector field along a line

circulation - move along a closed path

Rotation - Along its own axis

Use:* Find total charge - if charge density is known ($P_e = \frac{Q}{dL}$)

$$Q = \int_L P_e dL$$

$$\text{Volume} = Q$$

22 ← north
116 ← south

$$P_s = \frac{Q}{ds}$$

(Surface charge density).

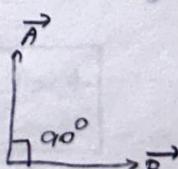
* Electric potential - when electric field intensity is known.

$$V = - \int E \cdot dL$$

* total current along a closed path is magnetic field intensity

is known.

$$I = \oint_L H \cdot dL$$



$$\begin{aligned} \vec{A} \cdot \vec{B} &= |\vec{A}| |\vec{B}| \cos 90^\circ \\ &= 1(1) \cdot \cos 90^\circ \\ &= 0 \end{aligned}$$

conservative opp Laminar field - when the angular distance is 90°
b/w two vectors (dot product will be zero).

Surface Integral

'distribution along surface'

$$P_s = \frac{\phi}{ds}$$

'surface charge density'

$$\phi = \oint_S P_s ds \rightarrow \text{Total S.C.D.}$$

Flux \rightarrow (Flow) $\rightarrow (\phi)$ \rightarrow total no. of Electric lines passing through the surface.

$$\phi = \oint_S \vec{B} \cdot d\vec{s}$$

(anti-) current \rightarrow magnetic field intensity

'total amount of current passing through a surface (density)'

$$I = \oint \vec{J} \cdot d\vec{A} \xrightarrow{\text{differential Area}}$$

Area $\rightarrow SS$
 volume $\rightarrow SSS$

Volume Integral:

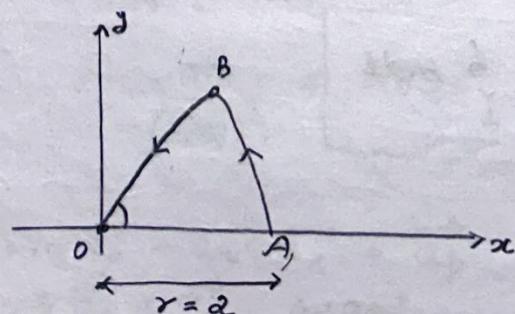
'No. of charges - in a Volume'

$$\phi = \int_V P_v dv$$

calculate the circulation of $\vec{A} = r \cos \phi \hat{a}_r + r \sin \phi \hat{a}_\theta$ around the edge L of the wedge defined by $0 \leq r \leq 2$, $0 \leq \phi \leq 60^\circ$

soln:

$$z=0$$



$$\vec{A}^2 = r \cos \phi \hat{a}_r \quad (z=0)$$

Circulation $\oint_{\vec{A}} = \int_{OP} + \int_{PB} + \int_{OY}$

(1) $\int_{OP} = \int_0^{\alpha} r \cos \phi \hat{a}_r \cdot d\vec{L}$

$$d\vec{L} = dr \hat{a}_r + rd\phi \hat{a}_\theta + dz \hat{a}_z$$

$$= \int_0^{\alpha} (r \cos \phi \hat{a}_r \cdot dr \hat{a}_r) + 0 + 0$$

$$= \int_0^{\alpha} r \cos \phi \, dr$$

$$= \cos \phi \left[\frac{r^2}{2} \right]_0^\alpha = \cos \phi \left[\frac{4}{2} \right]$$

$$= 2 \cos \phi \quad [\phi = 60^\circ]$$

$$= 2 \cos(60^\circ)$$

Circulation $\oint_{\vec{A}} = 2$

$\therefore \phi = 0$ in
 x axis (S)

angle b/w
P axes &
phi axes
 $\hookrightarrow 90^\circ$

(2) $\int_{PB} = \int_0^{\alpha} r \cos \phi \hat{a}_r \cdot (\hat{a}_r) dr \quad \phi = 90^\circ$

$$= \int_0^{\alpha} r (0) \cos \phi = 0$$

(3) $\int_{B_0} = \int_0^{\alpha} r \cos 60^\circ dr$

$$= \left[\frac{r^2}{2} \times \frac{1}{2} \right]_0^\alpha$$

get ans $\frac{1}{2} \left[-\frac{4}{2} \right] = -1$

\therefore Circulation $\oint_{\vec{A}} = 1$

$\vec{A}^2 = \nabla \times \vec{A}$

$\text{Circ } \oint_{\vec{A}} = 1$

Vector differentiation

$\nabla \rightarrow$ vector differentiation operators (nabla)

Gradient curl divergence

Gradient:

∇ operating on a scalar gives the vector \rightarrow Gradient.

The gradient at a point gives the direction of maximum change in a physical quantity.

Resulting gradient will be towards the maximum

Max change
 \rightarrow $\nabla \times \phi$

Properties:

1) Gradient is an operation performed on a scalar function which results in a vector function.

2) The magnitude of the gradient of a scalar function is the maximum rate of change of the function per unit distance.

3) The direction of the gradient of the scalar function is the direction in which the function changes most rapidly.

Represent 3 coordinate systems

$$\nabla F = \frac{1}{h_1} \frac{\partial F}{\partial u_1} \hat{a}_1 + \frac{1}{h_2} \frac{\partial F}{\partial u_2} \hat{a}_2 + \frac{1}{h_3} \frac{\partial F}{\partial u_3} \hat{a}_3$$

Cartesian: $h_1 = h_2 = h_3 = 1$

Cylindrical: $h_1 = 1, h_2 = r, h_3 = 1$

Spherical: $h_1 = 1, h_2 = r, h_3 = r \sin \theta$

Divergence.

$\nabla \cdot \vec{F} = \text{Scalar}$ (operates on a vector - gives the scalar quantity)

Source +ve divergence

Sink - (-)ve divergence

Zero divergence = [Incoming] = Outgoing

Divergence of \vec{F}

$$\operatorname{div} \vec{F} = \lim_{V \rightarrow 0} \left[\frac{\oint_S \vec{F} \cdot d\vec{s}}{V} \right]$$

vector field = \vec{F}

scalar field = F

Properties:

- 1) The result of divergence of a vector is a scalar.
- 2) Divergence of a scalar field (F) has no meaning.
- 3) Divergence may be +ve, -ve or zero.

when $\nabla \cdot \vec{F} = 0$ [solenoidal] vector field.

4) Divergence gives the magnitude & nature of the field.

source
sink
solenoidal

$$\nabla \cdot \vec{F} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} (F_1 h_2 h_3) + \frac{\partial}{\partial u_2} (F_2 h_1 h_3) + \frac{\partial}{\partial u_3} (F_3 h_1 h_2) \right]$$

In spherical system: $(u_1, u_2, u_3) = (r, \theta, \phi)$

$$F = \vec{F}_1 + \vec{F}_2 + \vec{F}_3$$

$$\vec{F}_1 = F \hat{a}_r$$

So $\nabla \cdot \vec{F}$ = curl (rotation)

'About rotation at a point' $\vec{Q}_{axis} = (x, y, z)$

$\nabla \times \vec{F}$ = vector (amount of twisting) \downarrow anti-clockwise

$$\text{curl } \vec{F} = \lim_{V \rightarrow 0} \left[\frac{\oint_S \vec{F} \times d\vec{s}}{V} \right]$$

$$\nabla \times \vec{F} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} \hat{a}_1 & \hat{a}_2 & \hat{a}_3 \\ \frac{\partial}{\partial u_1} & \frac{\partial}{\partial u_2} & \frac{\partial}{\partial u_3} \\ F_1 h_1 & F_2 h_2 & F_3 h_3 \end{vmatrix}$$

For spherical system

$$\nabla \times \vec{F} = \frac{1}{r^2 \sin \theta r \partial_r} \begin{vmatrix} \hat{a}_r & \hat{a}_\theta & \hat{a}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ F_1 \cos \theta \hat{a}_r & F_2 \hat{a}_\theta & F_3 \sin \theta \hat{a}_\phi \end{vmatrix}$$

Properties of curl:

- 1) Result - vector
- 2) curl of a scalar → has no meaning
- 3) $\nabla \times \vec{F} = 0$ (irrotational)

Right hand rule

Direction of the resulting vector - Normal to the plane.

1) The temp in an auditorium is given by $x^2 + y^2 - z$. A mosquito at $(1, 1, 2)$ in the auditorium decides to fly in such a direction it will get warm as soon as possible. In what direction it must fly.

Solu..

$$x^2 + y^2 - z \rightarrow \text{scalar quantity.}$$

Gradient:

$$\nabla F = \frac{\partial F}{\partial x} \hat{a}_x + \frac{\partial F}{\partial y} \hat{a}_y + \frac{\partial F}{\partial z} \hat{a}_z$$

$$\nabla F = 2x \cdot \hat{a}_x + 2y \cdot \hat{a}_y - \hat{a}_z$$

$$\text{At } (1, 1, 2)$$

$$\boxed{\nabla F = 2 \hat{a}_x + 2 \hat{a}_y - \hat{a}_z}$$

$$\vec{F}(r, \theta, \phi) = r \sin \theta \hat{a}_r + r \cos \theta \hat{a}_\theta - \phi \hat{a}_\phi$$

find the gradient.

Solu.:

$$\nabla F = \frac{\partial F}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial F}{\partial \theta} \hat{a}_\theta + \frac{\partial F}{\partial \phi} \hat{a}_\phi$$

$$\nabla F = r \sin \theta \hat{a}_r + \frac{r \cos \theta}{r} \hat{a}_\theta$$

$$\nabla F = r \sin \theta \hat{a}_r + r \cos \theta \hat{a}_\theta$$

$$\nabla F = \frac{\partial F}{\partial r} \hat{a}_r + \frac{1}{r} \frac{\partial F}{\partial \theta} \hat{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial F}{\partial \phi} \hat{a}_\phi$$

$$= r \cos \theta \hat{a}_r + r \sin \theta \hat{a}_\theta \rightarrow \frac{r}{r \sin \theta} \hat{a}_\phi$$

\rightarrow If $r \neq 0$ not Stokes Divergence

$$\frac{1}{\sin \theta}$$

Divergence theorem

For any volume V surrounded by a closed surface S , the \iiint (volume integral) of the divergence of the vector field is equal to the total output flux of the vector through the surface that bounds the volume.

$$\int \nabla \cdot \vec{A} dV = \oint_S \vec{A} \cdot d\vec{S}$$

Application

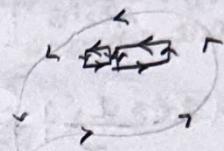
 'cancels' → only at boundaries.

Stokes theorem

It states that the surface integral of the curl of the vector field over an open surface is equal to the closed line integral of the vectors along the contours (path) bounding the surface.

$$\int_S \nabla \times \vec{A} dS = \oint_L \vec{A} d\vec{L}$$

↓
open surface'



$$A = r \sin \alpha \hat{\phi} + r \cos \alpha \hat{\phi} + z^2 \hat{a}_z \rightarrow \text{Divergence.}$$

$$\begin{aligned} \nabla \cdot \vec{F} &= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} (F_1 h_2 h_3) + \frac{\partial}{\partial u_2} (F_2 h_1 h_3) + \frac{\partial}{\partial u_3} (F_3 h_1 h_2) \right] \\ &= \frac{1}{r} \left[\frac{\partial}{\partial r} (F_1 \theta) + \frac{\partial}{\partial \phi} (F_2) + \frac{\partial}{\partial z} (F_3 z) \right] \\ &= \frac{1}{r} \left[\cancel{r^2 \sin \alpha \hat{a}_r} \right] = \frac{1}{r} \left[\frac{\partial}{\partial r} (r^2 \sin \alpha \theta) + \frac{\partial}{\partial \phi} (r \cos \alpha \theta) + \frac{\partial}{\partial z} (z^2 r) \right] \end{aligned}$$

$$= \frac{1}{r} \left[\cancel{\frac{\partial}{\partial r}} \right] = \frac{1}{r} \left[\cancel{r^2 \sin \alpha \theta} + r \sin \alpha \theta (\alpha) + r (\alpha z) \right]$$

$$\nabla \cdot \vec{F} = \cancel{r^2 \sin \alpha \theta} - \cancel{r \sin \alpha \theta} + \alpha z.$$

$$\boxed{\nabla \cdot \vec{F} = \alpha z}$$

$$\text{Divergence } A \text{ at } (100, \phi, 100) \text{ if } A = r \sin^2 \phi \hat{a}_r + r^2 \cos^2 \phi \hat{a}_z$$

$$\text{Soln. } \text{div } A = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial F_1}{\partial u_1} (F_1 h_2 h_3) + \frac{\partial F_2}{\partial u_2} (F_2 h_1 h_3) + \frac{\partial F_3}{\partial u_3} (F_3 h_1 h_2) \right]$$

$$\text{div } A = \frac{1}{r} \left[\frac{\partial}{\partial r} (r \sin^2 \phi \hat{a}_r) + \frac{\partial}{\partial z} (r^2 \cos^2 \phi) \right]$$

$$= \frac{1}{r} \left[r \sin^2 \phi + r z \cos^2 \phi \right]$$

$$\Rightarrow = \left[r \sin^2 \phi + r z \cos^2 \phi \right]$$

2) Show that the $\operatorname{div} \vec{A} = r^{-2} \sin\theta \vec{a}_r + r \cos\theta \vec{a}_\theta + r \sin\theta \cos\phi \vec{a}_\phi$
 is nowhere +ve.

soln:

$$1) A = r \sin^2\phi \vec{a}_r + r^2 \cos^2\phi \vec{a}_\theta + r^2 \cos\phi \sin\phi \vec{a}_\phi$$

$$\nabla \cdot \vec{A} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} [f_1 h_2 h_3] + \frac{\partial}{\partial u_2} [f_2 h_1 h_3] + \frac{\partial}{\partial u_3} [f_3 h_1 h_2] \right]$$

$$= \frac{1}{r} \left[\frac{\partial}{\partial r} [f_1 r] + \frac{\partial}{\partial \phi} [f_2] + \frac{\partial}{\partial z} [f_3 r] \right]$$

$$= \frac{1}{r} \left[\frac{\partial}{\partial r} [r^2 \sin^2\phi] + \frac{\partial}{\partial z} [r^2 \cos^2\phi] \right]$$

$$= \frac{1}{r} \left[\frac{\partial r \sin^2\phi}{\partial r} + \frac{\partial r \cos^2\phi}{\partial z} \right]$$

$$\nabla \cdot \vec{A} = 2 \sin^2\phi + 2 z \cos^2\phi$$

$$r = \sqrt{x^2 + y^2} = \sqrt{100^2 + 250^2} = 100\sqrt{1.25} = 100\sqrt{5}$$

$$\phi = \tan^{-1}(y/x) = \tan^{-1}(5/100) = 2.8624$$

$$z = z$$

$$z = 100$$

$$\nabla \cdot \vec{A} = 2 \sin^2(2.8624) + 2(100)(\cos^2 2.8624)$$

$$\boxed{\nabla \cdot \vec{A} = 199.506} \rightarrow \text{when } (100, 5, 100)$$

$$2) \operatorname{div} \vec{A} = \frac{1}{r^2 \sin\theta} \left[\frac{\partial}{\partial r} [f_1 h_2 h_3] + \frac{\partial}{\partial \theta} [f_2 h_1 h_3] + \frac{\partial}{\partial \phi} [f_3 h_1 h_2] \right]$$

$$= \frac{1}{r^2 \sin\theta} \left[\frac{\partial}{\partial r} [f_1 r^2 \sin\theta] + \frac{\partial}{\partial \theta} [f_2 r \sin\theta] + \frac{\partial}{\partial \phi} [f_3 r] \right]$$

$$= \frac{1}{r^2 \sin\theta} \left[\frac{\partial}{\partial r} [\sin^2\theta] + \frac{\partial}{\partial \theta} [r^2 \sin\theta \cos\theta] + \frac{\partial}{\partial \phi} [r^2 \sin\theta \cos\phi] \right]$$

$$= \frac{1}{r^2 \sin\theta} \left[r^2 \left(\frac{\sin 2\theta}{2} \right)' + r^2 \frac{\partial}{\partial \phi} [\cos\phi \sin\theta] \right]$$

$$= \frac{1}{r^2 \sin\theta} \left[\frac{1}{2} \cdot \cos 2\theta \cdot 2 - r^2 \sin\phi \cos\theta \right]$$

$$\begin{aligned}
 &= \frac{1}{\sin\theta} [\cos\phi - \sin\phi \sin\theta] \\
 &= \frac{1 - \sin^2\theta}{\sin\theta} - \sin\phi \\
 &= \frac{1}{\sin\theta} - \sin\theta - \sin\phi \\
 \text{div } \vec{A} &= \cos\phi - \sin\theta - \sin\phi \\
 \boxed{\text{div } \vec{A} = \frac{1}{\sin\theta} - \sin\theta - \sin\phi} \\
 0 < \phi < 2\pi \\
 \therefore \text{Always negative.}
 \end{aligned}$$

$\sin \rightarrow$ never be greater than 1
 $-1 < \sin\theta < 1$

Nowhere be positive. $-(1 + \sin\phi) \leq 0.$

12/03/2021 effect of flow No null derivatives?

$$\begin{aligned}
 (\text{div } \vec{A})'' &= + \nabla \times (\nabla \cdot \vec{V}) = 0 & \nabla \cdot (\nabla \times \vec{V}) = 0 \\
 &\text{short of gradient divergence} \\
 &\text{as a vector curl of a vector.}
 \end{aligned}$$

$$9) \quad \nabla = \left(\frac{\partial}{\partial x} \vec{a}_x + \frac{\partial}{\partial y} \vec{a}_y + \frac{\partial}{\partial z} \vec{a}_z \right)$$

$$\nabla V = \left(\frac{\partial V}{\partial x} \vec{a}_x + \frac{\partial V}{\partial y} \vec{a}_y + \frac{\partial V}{\partial z} \vec{a}_z \right)$$

$$\nabla \times (\nabla V) = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial V}{\partial x} & \frac{\partial V}{\partial y} & \frac{\partial V}{\partial z} \end{vmatrix} = \vec{a}_x \left(\frac{\partial^2 V}{\partial y \partial z} - \frac{\partial^2 V}{\partial z \partial y} \right) - \vec{a}_y \left(\frac{\partial^2 V}{\partial x \partial z} - \frac{\partial^2 V}{\partial z \partial x} \right) + \vec{a}_z \left(\frac{\partial^2 V}{\partial x \partial y} - \frac{\partial^2 V}{\partial y \partial x} \right)$$

$$\nabla \times \vec{E} = 0$$

(so E is a gradient)

$$= \vec{0} \quad (\text{irrotational})$$

$$11) \quad \nabla \cdot (\nabla \times \vec{V}) = 0$$

$$\nabla \times \vec{V} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \vec{V}_1 & \vec{V}_2 & \vec{V}_3 \end{vmatrix} \times \vec{V}$$

$$= \vec{a}_x \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) + \vec{a}_y \left(\frac{\partial v_3}{\partial x} - \frac{\partial v_1}{\partial z} \right) + \vec{a}_z \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right)$$

Divergence:

$$\nabla \cdot \vec{F} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial x} [f_1 h_2 h_3] + \frac{\partial}{\partial y} [f_2 h_1 h_3] + \frac{\partial}{\partial z} [f_3 h_1 h_2] \right]$$

$$\boxed{\nabla \cdot \vec{V} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}}$$

$$h_1 = h_2 = h_3 = 1$$

$$\begin{aligned} \nabla \cdot (\nabla \times \vec{F}) &= \frac{\partial v_1}{\partial x} \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) - \frac{\partial v_2}{\partial y} \left(\frac{\partial v_3}{\partial x} - \frac{\partial v_1}{\partial z} \right) + \frac{\partial v_3}{\partial z} \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) \\ &= \cancel{\frac{\partial^2 v_3}{\partial x \partial y}} - \cancel{\frac{\partial^2 v_2}{\partial x \partial z}} = \cancel{\frac{\partial^2 v_3}{\partial x \partial y}} + \cancel{\frac{\partial^2 v_1}{\partial y \partial z}} + \cancel{\frac{\partial^2 v_2}{\partial x \partial z}} - \cancel{\frac{\partial^2 v_1}{\partial z \partial y}} \end{aligned}$$

$$\boxed{\nabla \cdot (\nabla \times \vec{F}) = 0}$$

Divergence of a curl is zero
↓
Solenoidal.

$$F = \omega \vec{a}_r + \sin \phi \vec{a}_\phi = \omega \vec{a}_z \quad \rightarrow \text{curl}$$

Sol:

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{a}_r & r \vec{a}_\phi & \vec{a}_z \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & r \sin \phi & -2 \end{vmatrix} \cdot \frac{1}{r}$$

$$\frac{1}{r} \left(\vec{a}_r \left(-\frac{\partial z}{\partial \phi} - \frac{\partial (r \sin \phi) \cdot r}{\partial z} \right) - \vec{a}_\phi \left(-\frac{\partial z}{\partial r} - \frac{\partial (0)}{\partial z} \right) + \vec{a}_z \left(\frac{\partial (r \sin \phi)}{\partial r} - \frac{\partial (0)}{\partial \phi} \right) \right)$$

$$\frac{1}{r} \left(\vec{a}_r (0 - 0) - \vec{a}_\phi (0) + \vec{a}_z (r \cos \phi \cdot 1) \right)$$

$$= \frac{\vec{a}_z r \cos \phi \cdot \vec{a}_z}{r}$$

$$= \frac{1}{r} (\sin \phi) \cdot \vec{a}_z$$

$\vec{a}_z = \vec{e}_z$
(Axisymmetric at z axis)

12/03/2021 Helmholtz theorem - Fundamental theorem of vector calculus

$\vec{J} \rightarrow$ curl free vector

$$\nabla \times (\nabla V) = \vec{0}$$

vector calculus

$$\nabla \cdot (\nabla \times \vec{A}) = 0$$

$\vec{F} \rightarrow$ divergence free vector.

$$\nabla \cdot \vec{E} = 0$$

$$\text{so } E = -\nabla \phi$$

$$\nabla \cdot \vec{B} = 0$$

$$\vec{B} = \nabla \times \vec{H}$$

G
D
C
DT
ST

Helmholtz theorem: solenoidal + irrotational vectors

$$= (\nabla \times \vec{m}) + \nabla f$$

In a rapidly \downarrow vector field in 3D that vector is represented by a solenoidal vector + irrotational vectors

Any sufficiently smooth - rapidly decaying vector field in 3D can be resolved into the sum of an irrotational vector field and a solenoidal vector field.

$$1) H = \frac{I r}{2\pi a^2} (\hat{a}_\phi)$$

where I and a are constants

Show that this curl is invariant in space.

$$\nabla \times H = \frac{1}{r} \begin{vmatrix} \hat{a}_r & \hat{a}_\theta & \hat{a}_z \\ \frac{\partial}{\partial r}, & \frac{\partial}{\partial \theta}, & 0 \\ 0 & \frac{I r}{2\pi a^2} & 0 \end{vmatrix}$$

$$= \frac{1}{r} \left[\hat{a}_r \left(-\frac{\partial}{\partial z} \left(\frac{I r}{2\pi a^2} \right) \right) - \hat{a}_\theta \left(0 \right) + \hat{a}_z \left(\frac{\partial r}{\partial \theta} \left(\frac{I r}{2\pi a^2} \right) \right) \right]$$

$$= \frac{1}{r} \left[\left[0 + 0 + 0 \right] + \left[\hat{a}_z \left(\frac{I r}{2\pi a^2} \right) \right] \cdot \hat{a}_z \right]$$

$$= 0 \quad [\text{Inertial}] \quad \frac{1}{r} \left[\frac{I r}{2\pi a^2} \right] \cdot \hat{a}_z = \frac{I}{\pi a^2} \cdot \hat{a}_z$$

curl is invariant

$$\nabla \times H = \frac{I}{\pi a^2} \cdot \hat{a}_z$$

"No change in direction"

In a particular vector field $\vec{F} = r^2 \cos^2 \theta \hat{a}_r + r \sin \theta \hat{a}_\theta$

Find the flux emanating from the closed surface of the cylinder from $r=4$, $0 \leq \theta \leq 1$

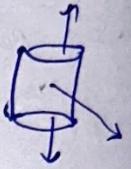
Solu:

$$\int_V \nabla \cdot \vec{F} dV = \oint_S \vec{F} \cdot d\vec{s}$$

→ verby
divergence
theorem.

flux emanating from the surface

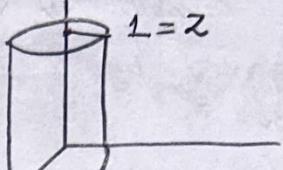
$$\oint_S \vec{F} \cdot d\vec{s} = \iint (\text{top} + \text{bottom} + \text{curved})$$



In top surface



In bottom surface



in short vector form we will write flux as $\oint_S \vec{F} \cdot d\vec{s}$ where $d\vec{s}$ is the unit normal vector to the surface element dS .

$$d\vec{s}_T = r d\phi dr \vec{a}_z$$

$$d\vec{s}_B = r d\phi dr (-\vec{a}_z)$$

$$d\vec{s}_C = r d\phi dz (\vec{a}_r)$$

$$\oint_S \vec{F} \cdot d\vec{s} = \oint_T \vec{F} \cdot d\vec{s}_T + \oint_B \vec{F} \cdot d\vec{s}_B + \oint_C \vec{F} \cdot d\vec{s}_C$$

$$= \oint_T (\sigma^2 \cos^2 \phi \vec{a}_r + z \sin \phi \vec{a}_\phi) \cdot (r d\phi dr \vec{a}_z)$$

$$= \left[\left(\frac{\sigma^2}{r^2} \right) \frac{r^2}{2} + 0 \right]_0^{\pi/2} + \left[-B \left(\frac{\sigma^2}{r^2} \right) \frac{r^2}{2} \right]_0^{\pi/2} + \left[\sigma^2 \cos^2 \phi \right]_0^{\pi/2} \cdot (r d\phi dr (-\vec{a}_z))$$

$$+ \oint_C (\sigma^2 \cos^2 \phi) \cdot (r^2 d\phi dz)$$

$$= \left[\left(\frac{\sigma^2}{r^2} \right) \frac{r^2}{2} \right]_0^{\pi/2} + \left[0 + 0 + 0 \right]_0^{\pi/2}$$

$$= \int_0^{\pi/2} \int_0^{2\pi} r^3 \cos^2 \phi d\phi dz$$

$$= \int_0^{\pi/2} \int_0^{2\pi} \frac{r^4}{4} \cos^2 \phi d\phi dz$$

$$= \int_0^{\pi/2} \frac{1}{4} \cos^2 \phi d\phi$$

$$= \frac{1}{64} \left[\frac{(\cos \phi)^3}{3(-\sin \phi)} \right]_0^{2\pi} = -\frac{1}{64} \left[\frac{\cos^3 \phi}{\sin \phi} \right]_0^{2\pi}$$

$$= -\frac{r^4}{8} = \int_0^{\pi} \int_0^{\frac{1}{2}} r^3 \cos^2 \phi \, d\phi \, dz$$

$$\frac{r^2 \cos^2 \phi}{r^2 d\phi dz}$$

$$= \int_0^{\pi} \int_0^{\frac{1}{2}} r^3 \left(\frac{1 + \cos 2\phi}{2} \right) d\phi \, dz.$$

$$= \frac{r^3}{2} \int_0^{\frac{\pi}{2}} \left[\frac{1}{2} + \frac{\sin 2\phi}{2} \right] d\phi$$

$$= \int_0^{\pi} \left[\frac{r^3 z + r^3 z \cos 2\phi}{2} \right]_0^{\frac{\pi}{2}} d\phi$$

$$= \int_0^{\pi} \frac{r^3}{2} \left(\frac{1 + \cos 2\phi}{2} \right) d\phi$$

$$= \frac{r^3}{2} \left[\int_0^{\frac{\pi}{2}} \frac{1}{2} d\phi + \int_0^{\frac{\pi}{2}} \frac{\cos 2\phi}{2} d\phi \right]$$

$$= r^3 \left[\frac{\phi}{2} \right]_0^{\frac{\pi}{2}} + r^3 \left[\frac{\sin 2\phi}{4} \right]_0^{\frac{\pi}{2}}$$

$$= r^3 \left[\frac{\pi}{2} + \frac{\sin 4\pi}{4} \right],$$

$$= r^3 (\pi + 0)$$

$$= 64\pi \text{ units}^3.$$

$$\int \nabla \cdot \vec{F} \, dv = \int (\nabla \cdot \vec{F}) \, dv.$$

$$\nabla \cdot \vec{F} = \nabla \cdot \vec{F}$$

$$\vec{E} \cdot \vec{H} \cdot A = \vec{E} \cdot \vec{H} \cdot A$$

$$dv = r^2 d\phi \, dr \, dz$$

$$\nabla \cdot \vec{F} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial r} (F_1 h_2 h_3) + \frac{\partial}{\partial \phi} (F_2 h_1 h_3) + \frac{\partial}{\partial z} (F_3 h_1 h_2) \right]$$

$$= \frac{1}{r} \left[\frac{\partial}{\partial r} (r^3 \cos^2 \phi) + \frac{\partial}{\partial \phi} (z \sin \phi) \right]$$

$$= \frac{1}{r} \left[3r^2 \cos^2 \phi + z \cos \phi \right]$$

$$= 3r^2 \cos^2 \phi + \frac{z}{r} \cos \phi.$$

$$= \int \int \int (3r^2 \cos^2 \phi + \frac{z}{r} \cos \phi) r \, d\phi \, dr \, dz.$$

$$\begin{aligned}
 &= \int_0^1 \int_0^{2\pi} \int_0^{\frac{\pi}{2}} ((3r^2 \cos^2 \phi) + z \cos \phi) dr d\phi dz \\
 &= \int_0^1 \int_0^{2\pi} \left(\frac{3r^3}{3} \cos^2 \phi + z r \cos \phi \right)_0^4 d\phi dz \\
 &= \int_0^1 \int_0^{2\pi} (r^3 \cos^2 \phi + z r \cos \phi) d\phi dz \\
 &= \int_0^1 \int_0^{2\pi} (64 \cos^2 \phi + 4z \cos \phi) d\phi dz \\
 &= \int_0^1 \int_0^{2\pi} \left(\frac{64}{2} (\cos 2\phi + 1) + 4z \cos \phi \right) d\phi dz \\
 &= \int_0^1 32 \left[\left(\phi + \frac{\sin 2\phi}{2} \right)_0^{2\pi} + 4z \sin \phi \right] dz \\
 &= \int_0^1 32 \left(2\pi \right) dz \\
 &= \int_0^1 64\pi z dz \\
 &= [64\pi z]_0^1
 \end{aligned}$$

$$= 64\pi$$

$$\boxed{
 \begin{aligned}
 64\pi &= 64\pi \\
 L.H.S &= R.H.S
 \end{aligned}
 }$$

Given $\vec{a} = x^2 \vec{a}_x + xy \vec{a}_y + yz \vec{a}_z$ → Verify divergence theorem over one octant cube. Cube lies in 1st octant of the Cartesian coordinate system with one coordinate at origin.

Given: $\vec{A} = x^2 \vec{a}_x + xy \vec{a}_y + yz \vec{a}_z$ (1st octant).

$$(x=1, y=1, z=1)$$

$$\int \nabla \cdot \vec{A} dv = \oint \vec{A} d\vec{s}$$

$$\Delta \cdot \vec{A} = \frac{\partial}{\partial x} (x^2) + \frac{\partial}{\partial y} (xy) + \frac{\partial}{\partial z} (yz)$$

$$= 2x + x + y$$

$$= 3x + y$$

~~diff~~ ~~diff~~

~~so that sub~~ ~~state~~

~~works~~ ~~blow~~

$$= \int_0^1 \int_0^1 \int_0^1 (3x+y) dx dy dz.$$

$$= \int_0^1 \int_0^1 \left(\frac{3x^2}{2} + xy \right)_0^1 dy dz$$

$$= \int_0^1 \int_0^1 \left(\frac{3}{2} + y \right) dy dz$$

$$= \int_0^1 \left(\frac{3y}{2} + \frac{y^2}{2} \right)_0^1 dz$$

$$= \int_0^1 \left(\frac{3}{2} + \frac{1}{2} \right) dz$$

$$= \frac{3}{2} + \frac{1}{2}$$

$$= \frac{4}{2}$$

~~positioned - 2~~

~~so that~~ ~~= 2~~

$$= \int_0^1 \int_0^1 x^2 dy dz$$

$$= \int_0^1 \int_0^1 x^2 y dy dz$$

$$= \int_0^1 \left(x^2 y \right)_0^1 dy dz$$

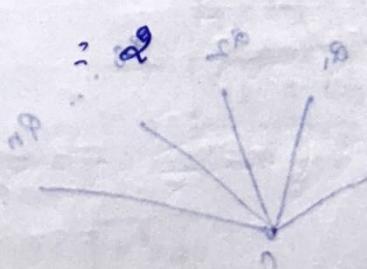
$$= \left(x^2 \right)$$

$$= 1$$

~~infinity number - graph~~

~~sheets aligned, so not separate when of rectangular~~

$$\oint_S \vec{A} \cdot d\vec{s} = \frac{1}{2} + \frac{1}{2} + 1$$



Surface.

$$\oint_S \vec{A} \cdot d\vec{s} = \oint_{S_1} \vec{A} \cdot d\vec{s}_1 + \oint_{S_2} \vec{A} \cdot d\vec{s}_2 + \oint_{S_3} \vec{A} \cdot d\vec{s}_3$$

$$\oint_S \vec{A} \cdot d\vec{s}$$

$$S \rightarrow H$$

$$\approx \oint S$$

Surface: 1

$$= \int_0^1 \int_0^1 (x^2 \vec{a_x} + xy \vec{a_y} + yz \vec{a_z}) dx dy \vec{a_z}$$

$$= \int_0^1 \int_0^1 yz dx dy$$

$$= \int_0^1 \int_0^1 xyz dy$$

$$= \int_0^1 yz dy$$

$$= \left(\frac{y^2}{2} z \right)_0^1$$

$$= \frac{1}{2} (2) z$$

$$= \frac{1}{2} z$$

Surface 3

$$= \int_0^1 \int_0^1 xy dz dx$$

$$= \frac{1}{2}$$

18/8/2021

Unit-2 - Electromatics

- * Coulomb's Law
- * Gauss's Law
- * Dielectric

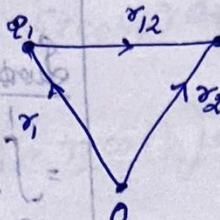
Static charges - stationary field.

Static Electric field → due to static charges

$$|F| \propto \frac{q_1 q_2}{r^2}$$

\vec{a}_{12}

Influence of charge 1 on 2.



Coulomb's law

Scalar form:

$$F = K \frac{q_1 q_2}{r^2}$$

$$\text{Unit vector} = \frac{\vec{a}_{12}}{|\vec{r}_{12}|}$$

$$\vec{F} = K \frac{q_1 q_2}{r^2} \frac{\vec{a}_{12}}{|\vec{r}_{12}|}$$

ϵ_0 - permittivity of free space.

$$\epsilon_0 = 8.854 \times 10^{-12} \text{ F/m}$$

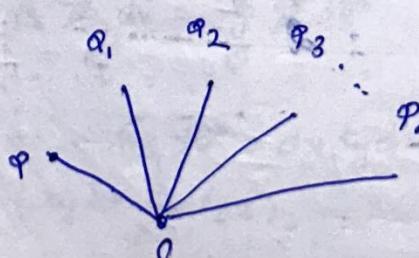
~~\vec{a}_{12}~~

$$\vec{r}_1 + \vec{r}_{12} = \vec{r}_2$$

$$\vec{r}_{12} = \vec{r}_2 - \vec{r}_1$$

'Superposition Principle'

Influences of many charge on a single charge



q_1 on φ , q_2 on φ , q_n on φ .

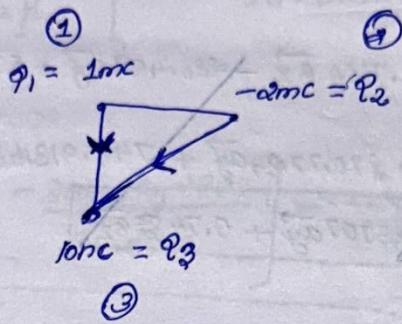
$$F = K \frac{q_1 q_2}{r^2} \frac{\vec{r}_0 - \vec{r}_1}{|\vec{r}_0 - \vec{r}_1|} + K \frac{q_1 q_3}{r^2} \frac{\vec{r}_0 - \vec{r}_3}{|\vec{r}_0 - \vec{r}_3|} + \dots$$

$$= \frac{1}{4\pi\epsilon_0 r} \sum_{n=1}^n q_n \left(\frac{\vec{r}_0 - \vec{r}_n}{|\vec{r}_0 - \vec{r}_n|} \right)$$

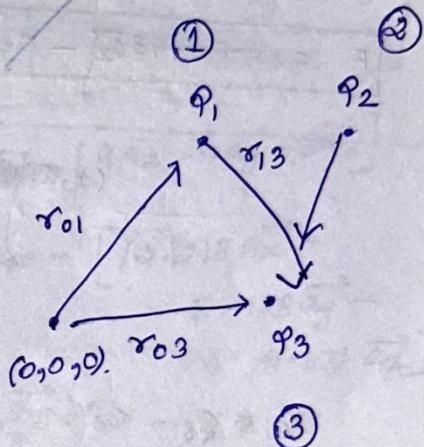
18/3/21

1) point charges 1nC and -2nC are located at $(3, 2, -1)$ and $(-1, -1, 4)$ respectively. calculate the force on 1nC charge located at $(0, 3, 1)$

given:



$$F = \frac{q_1 q_2}{4\pi\epsilon_0 r^2} \cdot \frac{\vec{r}}{|\vec{r}|}$$

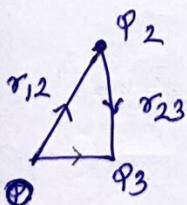


$$\vec{r}_{13} = \vec{r}_{03} - \vec{r}_{01}$$

$$\vec{r}_{13} = -3\hat{a}_x + \hat{a}_y + 2\hat{a}_z$$

$$|\vec{r}_{13}| = \sqrt{9+1+4} \\ = \sqrt{14}.$$

$$r^2 = 14$$



$$\vec{r}_{23} = \vec{r}_{13} - \vec{r}_{12}$$

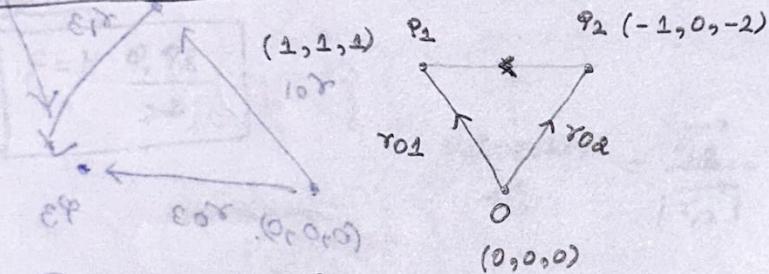
$$\vec{r}_{23} = (-\hat{a}_x - \hat{a}_y + 4\hat{a}_z) + (3\hat{a}_y + \hat{a}_z)$$

$$\boxed{\vec{r}_{23} = \hat{a}_x + 4\hat{a}_y - 3\hat{a}_z}$$

$$|\vec{r}_{23}| = \sqrt{1+16+9} \\ = \sqrt{26}.$$

$$\boxed{r^2 = 26}$$

$$\begin{aligned}
 F = F_1 + F_2 &= \frac{\varphi_1 q_3}{4\pi\epsilon_0} \left[\frac{-3a_x + \hat{a}_y + 3\hat{a}_z}{14\sqrt{14}} \right] + \frac{\varphi_2 q_3}{4\pi\epsilon_0} \left[\frac{a_x + 4\hat{a}_y - 3\hat{a}_z}{26\sqrt{26}} \right] \\
 &\quad \hookrightarrow |\vec{r}_{13}| \\
 &= \frac{\varphi_3 m}{4\pi\epsilon_0} \left[\frac{100(-3a_x + \hat{a}_y + 3\hat{a}_z)}{4\sqrt{14}} + \frac{(-\varphi_3 m)(a_x + 4\hat{a}_y - 3\hat{a}_z)}{26\sqrt{26}} \right] \\
 &= \frac{100 \times m \times \varphi_3}{4\pi\epsilon_0} \left[\frac{-3a_x + \hat{a}_y + 3\hat{a}_z}{52 \cdot 38.32} + \frac{-2a_x - 8\hat{a}_y + 6\hat{a}_z}{132 \cdot 5745} \right] \\
 &= \frac{0.089377}{6944.6765} \left[-397a_x + 132 \cdot 5745\hat{a}_y + 265 \cdot 149a_z - 104 \cdot 7664a_x - 419 \cdot 0656\hat{a}_y + 314 \cdot 2992a_z \right] \text{Nm} \\
 &= 1.204185 \left[-501.7664\hat{a}_x - 286.4911\hat{a}_y + 579.4482\hat{a}_z \right] \text{Nm} \\
 &= (-649.379\hat{a}_x + 370.7724\hat{a}_y + 749.9131687) \text{Nm} \\
 F &= -0.6493\hat{a}_x - 0.3707\hat{a}_y + 0.7499\hat{a}_z
 \end{aligned}$$



$$r_{01} = r_{02} - r_{21} = 0$$

$$r_{21} + r_{02} - r_{01} = 0$$

$$r_{21} = r_{01} - r_{02}$$

$$81.8^\circ = 81.8^\circ + 100^\circ$$

$$100^\circ - 81.8^\circ = 18.2^\circ$$

$$r_{21} = (2\hat{a}_x + \hat{a}_y + 3\hat{a}_z) \text{m}$$

$$r_{21} = \sqrt{(4+1+9) \text{m} \times \text{m}}$$

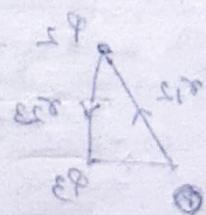
$$= \sqrt{14} \text{m}$$

$$A + I + P = \sqrt{81.8^\circ}$$

$$F = \frac{\varphi_1 q_2}{4\pi\epsilon_0} \left[\frac{2a_x + \hat{a}_y + 3\hat{a}_z}{14\sqrt{14} \text{m}^2 \times \text{m}} \right]$$

$$= \frac{100\mu \times 50\mu}{4\pi \times 8.854 \times 10^{-12}} \left[\frac{2a_x + \hat{a}_y + 3\hat{a}_z}{52 \cdot 38.32 \text{n}} \right]$$

$$\begin{aligned}
 &= \frac{5000}{4\pi \times 8.854 \text{n}} \left[2a_x + \hat{a}_y + 3\hat{a}_z \right] = 4.494 \times 10^{10} (2a_x + \hat{a}_y + 3\hat{a}_z) \\
 &= 44.94 G (2a_x + \hat{a}_y + 3\hat{a}_z)
 \end{aligned}$$



A source located in a rectangular at $(1, 1, 1)$ m and another $q_2 = 50 \mu C$ $(-1, 0, -2)$ m. Find the vector force on the first charge.

$$F = \frac{100 \times 50 \times 10^{-12}}{4\pi \times 8.854 \times 10^{-12}} \left[\frac{2\vec{a}_x + \vec{a}_y + 3\vec{a}_z}{52.3832} \right]$$

$$= 0.8578 (2\vec{a}_x + \vec{a}_y + 3\vec{a}_z)$$

$$= 1.715 \vec{a}_x + 0.857 \vec{a}_y + 2.57 \vec{a}_z$$

$$= \frac{(2m)(10 \mu C)}{4\pi \times \frac{1}{36\pi} \times 1} \left[\frac{-3\vec{a}_x + \vec{a}_y + 2\vec{a}_z}{52.3832} \right] + \frac{(-2m)(10 \mu C)}{4\pi \times \frac{1}{36\pi}}$$

$$\left[\frac{9\vec{a}_x + 4\vec{a}_y - 3\vec{a}_z}{132.574} \right]$$

$$= \frac{20m}{19} \left[\frac{-3\vec{a}_x + \vec{a}_y + 2\vec{a}_z}{52.3832} \right] - \frac{20m}{19} \left[\frac{9\vec{a}_x + 4\vec{a}_y - 3\vec{a}_z}{132.574} \right]$$

$$= 0.718 (-3\vec{a}_x + \vec{a}_y + 2\vec{a}_z) - 0.357 \left[9\vec{a}_x + 4\vec{a}_y - 3\vec{a}_z \right]$$

$$= (-5.154 \vec{a}_x + 1.718 \vec{a}_y + 3.436 \vec{a}_z) - [12.213 \vec{a}_x + 5.428 \vec{a}_y - 4.071 \vec{a}_z]$$

$$= (-17.367 \vec{a}_x - 3.71 \vec{a}_y + 7.507 \vec{a}_z) \text{ m}$$

$$= -0.017 \vec{a}_x - 0.00371 \vec{a}_y + 0.007507 \vec{a}_z$$

Electric field intensity

19/02/2021



will be more

→ Field exp
is less

Intensity varies

'Electric field intensity'

$$\frac{\phi(\infty)}{r} = \frac{\psi}{r}$$

$$E = \frac{F}{q_{\text{test}}}$$

$q_{\text{test}} \rightarrow \text{Test charge}$.

$$E = \frac{q_1 q_k}{4\pi \epsilon_0 r^2} \cdot \frac{\vec{r}_{1k}}{|r_{1k}|}$$

$$E = \frac{q_1 q_k}{4\pi \epsilon_0 |r_{1k}|^3} + \frac{\hat{r}_{1k}}{r_{1k}}$$

$$\boxed{E = \frac{q_1}{4\pi \epsilon_0 |r_{1k}|^3} \cdot \frac{\hat{r}_{1k}}{r_{1k}}} \rightarrow \text{vector.} \quad \text{N/C (or) } \frac{\text{V/m}}{\text{m}}$$

Cases: i) q_1 is at the origin ii) when there are many charges existing from q_1, q_2, \dots

$$i) E = \frac{q_1}{4\pi \epsilon_0 |r_{1k}|^3} \cdot \frac{\hat{r}_{1k}}{r_{1k}}$$

At origin - \vec{q}_1

$$\therefore r_1 = \sqrt{0+0+0}$$

$$= \frac{q_1}{4\pi \epsilon_0 |r_{1k} - r_1|^3} \cdot (\hat{r}_k - \hat{r}_1)$$

$$= 0 \quad \text{since } r_k - r_1 = r_k$$

$$E = \frac{q_1}{4\pi \epsilon_0 |r_{1k}|^3} \cdot (\hat{r}_k)^3 = (q_1 + q_2 + q_3 + \dots) \text{ m.v.}$$

ii) Let n charges.

$$q_1, q_2, q_3, \dots, q_n$$

$$\vec{E} = \sum \frac{q_1}{4\pi \epsilon_0 |r_{1k}|^2} \frac{\hat{r}_k - \hat{r}_1}{|r_k - r_1|} + \frac{q_2}{4\pi \epsilon_0 |r_{2k}|^2} \frac{\hat{r}_k - \hat{r}_2}{|r_k - r_2|} + \dots$$

$$= \sum_{n=1}^{\infty} \frac{q_n}{4\pi \epsilon_0 |r_{nk}|^2} \frac{\hat{r}_k - \hat{r}_n}{|r_k - r_n|}$$

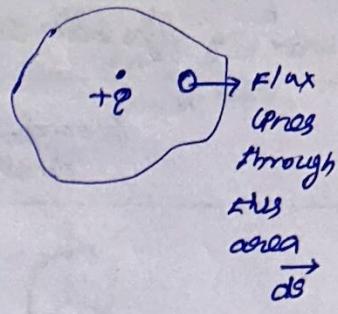
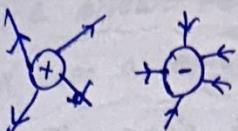
D - Electric flux density
↓ flow

'No. of flux lines passing per unit area'

$$D = \frac{\Psi}{A} \text{ (or) } \frac{\phi}{A}$$

No. of field lines emanating from a closed surface
passing through the surface \perp by,

Divergence theorem



$$\Psi = \oint_S \mathbf{D} \cdot d\mathbf{S}$$

total surface.

Assume spherical coordinate:

$$\text{Area of curved surface of sphere} = 4\pi r^2$$

$$D =$$

$$D = \int \frac{\rho}{4\pi r^2} d\vec{S} \cdot \vec{ar}$$



$$d\vec{S} = r^2 \sin\theta dr d\phi \vec{a_\theta} + r^2 \sin\theta d\theta \vec{a_\phi} + r dr d\theta \vec{a_r}$$

'Along radius'

22/03/21 [Magnitude of Electric field $\uparrow \rightarrow$ density also \uparrow]

Electric flux density (D) $\rightarrow D = \frac{\Phi}{A}$ (vectors \perp to the surface)

$$\vec{D} = \frac{\Phi}{4\pi r^2} \vec{ar}$$

(Area of sphere = $4\pi r^2$)
(Along the radius vector)

$$d\vec{S} = r^2 \sin\theta d\phi \vec{a_r} + r \sin\theta dr d\phi \vec{a_\theta} + r dr d\phi \vec{a_\phi}$$

$$\Psi = \oint_S \mathbf{D} \cdot d\mathbf{S}$$

$$= \oint_S \frac{\Phi}{4\pi r^2} \vec{ar} \cdot d\vec{S}$$

$$= \oint_S \frac{\Phi}{4\pi r^2} -r^2 \sin\theta d\phi d\theta$$

$$= \oint_S \frac{\Phi \sin\theta}{4\pi} d\phi d\theta$$

$$= \frac{\Phi}{4\pi} \int_0^{2\pi} \int_0^\pi \sin\theta d\theta d\phi$$

$$= \frac{\Phi}{4\pi} \int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi$$

$$= \frac{\Phi}{4\pi} [-\cos\theta]_0^\pi \cdot [\phi]_0^{2\pi}$$

$$= \frac{\Phi}{4\pi} [+1 + 1] (2\pi) = \frac{\Phi}{4\pi} \cdot 4\pi$$

$$\boxed{\Psi = \Phi}$$

\downarrow
Gauss law.

The total flux crossing or emanating from a surface is equal to the algebraic sum of all the charges present in the surface.

Electric flux density \rightarrow also known as Displacement density.

Relation b/w E and D

Electric field intensity

Flux density,

$$E = \frac{F}{\epsilon_0} \quad \text{or} \quad F = \epsilon_0 E$$

$$F = \frac{q_1 q_k}{4\pi\epsilon_0 r^2}$$

$$\therefore D = \frac{q_1}{4\pi r^2}$$

$$\frac{F}{\epsilon_0} = \frac{q_1}{4\pi\epsilon_0 r^2}$$

$$E = \frac{q_1}{4\pi\epsilon_0 r^2}$$

$$\frac{E}{D} = \frac{q_1}{4\pi\epsilon_0 r^2}$$

$$\frac{q_1}{4\pi r^2}$$

$$\frac{E}{D} = \frac{1}{\epsilon_0}$$

$$D = \epsilon_0 E$$

$\epsilon_0 \rightarrow$ Permittivity of free space.

$$\phi = \oint \vec{D} \cdot d\vec{s}$$

App. of Gauss law

* Electric field intensity at a point at various distributions.

→ point
→ line
→ surface
→ charge disc

Steps: Applying Gauss law

* Symmetry (Identify) associated with charge distribution is obtained.

* Gaussian surface is identified & the direction of E is determined.

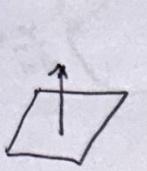
* Field space is divided into different regions.

* For each region - the net charge enclosed by the Gaussian surface is calculated.

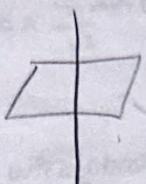
* ϕ is calculated for each region

* calculate the magnitude of E .

- Gaussian Surface - Point charge
- * E should be same at all points. (E varies with radius normally but here must not)
 - * For a sphere - radius is normal.
 - * The angle b/w E and area vector should be same throughout.

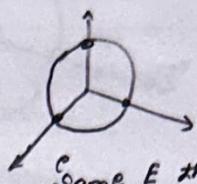


surface vector



Flux

\therefore Angle b/w E & area vector = 0° (same)



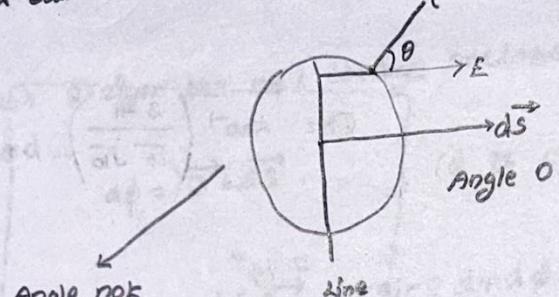
'Same E throughout'

Gaussian surface.

0° angle b/w E & A

Gaussian surface does a lone charge.

- * Can a sphere be taken $\rightarrow ?$

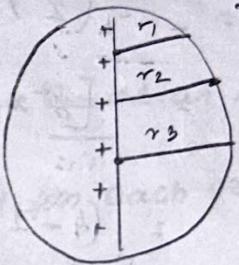


Angle not same.

line

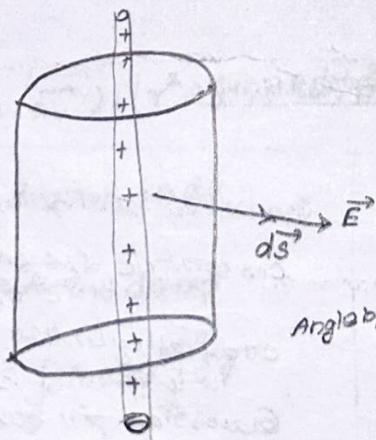
Angle α

'Angle' - not same throughout.

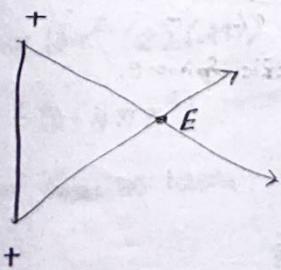


'radius charging'

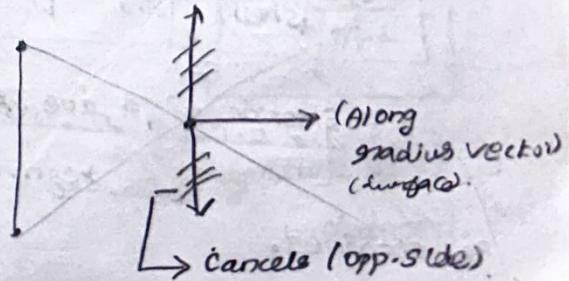
Cylinder - Gaussian Surface



Angle b/w them = 0° (throughout)

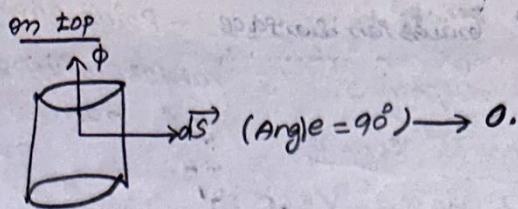


Resolving into two components



(Along
radius vector
(surface))

→ cancels opp.-side)



$$\mathbf{D} = \alpha xy \mathbf{i} + 3yz \mathbf{j} + 4xz \mathbf{k}$$

$$\phi = D \cdot A$$

$$= \iint_{\text{cyl}} (\alpha xy \mathbf{i} + 3yz \mathbf{j} + 4xz \mathbf{k}) \cdot dA$$

$$= \iint_{0 \rightarrow 1} \alpha xy \cdot dy dz$$

$$a, b = a \cdot b \cos \theta$$

$$= \left(\frac{\alpha y^2}{2} \right) z$$

$$= [y^2 x]_0^4$$

$$= (4 - 0)$$

$$= 3x$$

$$= 3x(4)$$

$$= 12 \times 3$$

$$= 36$$

$$\theta = \tan^{-1} \left(\frac{3-1}{\sqrt{6} \sqrt{10}} \right) \\ \approx 14^\circ$$

26/3/2021.

Applications of Gauss law

S.no	System	Symmetry	Gaussian Surface
1	Point charge	Spherical	Concentric sphere
2	Infinite rod	Cylindrical	Coaxial cylinders
3	Infinite plane	Planar	Gaussian pill box
4	Sphere, spherical shell	Spherical	Concentric spheres.

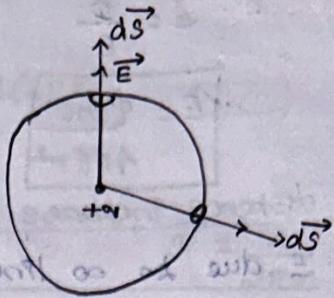
Electric field due to point charge:

* Symmetry associated with charge distribution

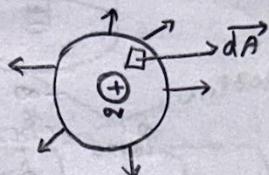
is obtained.

- * E should be definite at all points (same)
- * Angle b/w E and area vectors should be same throughout

$$E = \frac{q}{r^2}$$



- * Symmetry associated with charge distribution \rightarrow spherical
- * Gaussian surface & direction of E is determined \rightarrow sphere
- * Field space - divided in to different regions



For each region the net charge enclosed by the Gaussian surface is calculated.

$$d\phi = \vec{D} \cdot \vec{dS}$$

(ϕ is calculated from each region)

$$\vec{dS} = r^2 \sin\theta \, d\theta \, d\phi \, \vec{ar} + r \sin\theta \, dr \, d\phi \, \vec{a\theta} + r \, dr \, d\theta \, \vec{a\phi}$$

$$\vec{D} = \vec{D} \cdot \vec{ar}$$

$$\phi = \oint \vec{D} \cdot \vec{dS}$$

$$\phi = f(\vec{D} \cdot \vec{ar}) \cdot (r^2 \sin\theta \, d\theta \, d\phi \, \vec{ar} + r \sin\theta \, dr \, d\phi \, \vec{a\theta} + r \, dr \, d\theta \, \vec{a\phi})$$

$$= f(\vec{D} \cdot \vec{ar}) \cdot r^2 \sin\theta \, d\theta \, d\phi$$

$$= \iint D r^2 \sin\theta \, d\theta \, d\phi$$

$$= D r^2 \int_0^\pi \sin\theta \, d\theta \int_0^{2\pi} d\phi$$

$$= D r^2 (2) (2\pi)$$

$$= D (4\pi r^2)$$

From Gauss law, $\phi = \Phi_{enc}$

$$\Phi = D (4\pi r^2)$$

$$\Phi_{enc} = D \cdot (4\pi r^2)$$

$$D = \frac{\Phi_{enc}}{4\pi r^2}$$

Magnitude of D is deduced.

$$D = \epsilon E$$

$$E = \frac{D}{\epsilon}$$

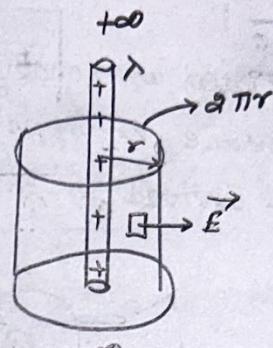
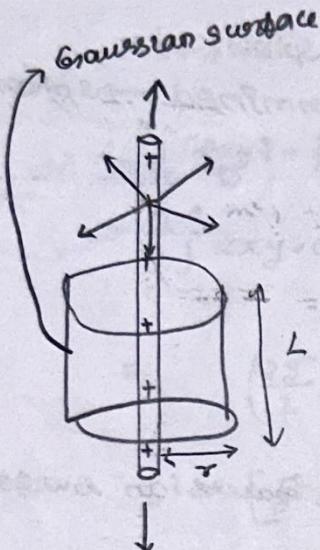
$$E = \frac{\Phi_{\text{enc}}}{4\pi\epsilon r^2}$$

Induction



As distance increase no. of field lines passing ↓.

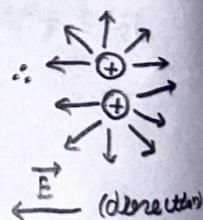
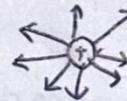
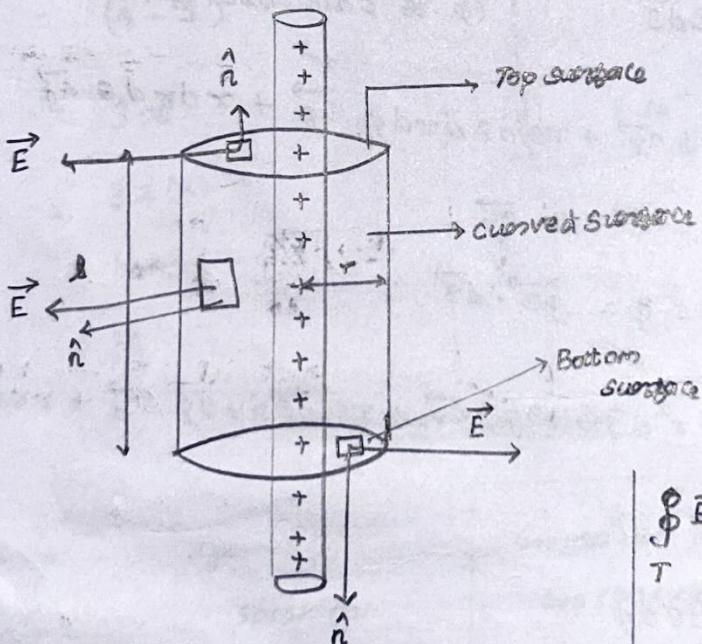
E due to ∞ line charge



$$\Phi = \Phi_{\text{enc}}$$

$$\Phi_{\text{enc}} = \text{charge density} \times \text{length}$$

$$\Phi_{\text{enc}} = \lambda \cdot L$$



$$\oint \vec{E} \cdot d\vec{s} = \oint |E| / |ds| \cos 90^\circ$$

$$\therefore 90^\circ$$

$$= 0$$

$$\oint \vec{E} \cdot d\vec{s} = \oint |E| / |ds| \cos 90^\circ$$

$$8$$

$$90^\circ$$

$$= 0$$

$$\oint \vec{E} \cdot d\vec{s} = \oint |E| / |ds| \cos 90^\circ$$

$$= E \oint ds \quad (1)$$

$$\phi = \oint D \cdot dS$$

(ex)

$$\phi = \oint E \cdot dS$$

$$\phi = E \left[\oint_T + \oint_B + \oint_C \right]$$

$$\phi = E \left[\oint_T E \cdot dS + \oint_B E \cdot dS + \oint_C E \cdot dS \right]$$