

$$\det A^{-1} = \frac{1}{\det A}$$

$$A \rightarrow \text{diagonal} \rightarrow A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}, \quad A^{-1} = \begin{bmatrix} 1/2 & 0 \\ 0 & 1/3 \end{bmatrix}$$

$$\det A^2 = (\det A) (\det A) = (\det A)^2$$

$$\det 2A = \det(2I) \cdot \det(A)$$

$$= 2^n \det(A).$$

$$\begin{vmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & \dots & 0 \\ 0 & \dots & \dots & 2 \end{vmatrix}$$

Like volume: double the side.

$$3-d \rightarrow \text{null } 2^3 \times \text{volume}$$

$$n-d \rightarrow 2^n \times \text{volume.}$$

$$2 \times 2 \times 2 \begin{vmatrix} 1 & 0 & \dots \\ 0 & 1 & \dots \\ 0 & \dots & 1 \end{vmatrix}$$

↳ Each dimension one row.

$$\det A^{-1} = \frac{1}{\det A}$$

$$\text{written } \det A = 0$$

$\det A^{-1} \rightarrow \text{doesn't exist.}$

$$10) \quad \det A^T = \det A$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & c \\ b & d \end{vmatrix}$$

If column is all zero $\rightarrow \det A = 0$

Exchanging columns \rightarrow changes sign
odd $\rightarrow -ve$
Even $\rightarrow +ve$.

Proof:

$$|A^T| = |A|$$

$$\downarrow \quad \downarrow$$

$$|U^T L^T| = |LU|$$

'Lower triangular matrix'

$$|L| = 1.$$

$L^T \rightarrow$ also a lower triangular.

Solu-

$$|U^T| |L^T| = |L| |U|$$

$$|U^T| (1) = 1 |U|$$

$$\boxed{|U| = |A|}$$

$$|U^T| = |U|$$

Loose end: If we got \rightarrow matrices now exchanges after 7 and 10 row exchanges resp. \rightarrow

Is it means determinants equal to its negative?
 ↳ No (we need to have a proof).

Fact: Every permutations are either odd or even.
 I could get the permutation with seven row exchanges, or
 21 or twenty three or 101 - But absolutely not with
 even numbers of operations. → Odd one.
 Even one → with only even no. of operations.

Recitation.

Find det

$$A = \begin{bmatrix} 101 & 201 & 301 \\ 102 & 202 & 302 \\ 103 & 203 & 303 \end{bmatrix}, B = \begin{bmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & -4 & 5 \end{bmatrix} \quad ; D = \begin{bmatrix} 0 & 1 & 3 \\ -1 & 0 & 4 \\ -3 & -4 & 0 \end{bmatrix}$$

Solu:

$$A = \begin{bmatrix} 100+1 & 200+1 & 300+1 \\ 100+2 & 200+2 & 300+2 \\ 100+3 & 200+3 & 300+3 \end{bmatrix} \quad \left| \begin{array}{ccc|c} 101 & 201 & 301 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{array} \right| = 0$$

$$= \begin{bmatrix} 100 & 200 & 300 \\ 100 & 200 & 300 \\ 100 & 200 & 300 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= 0 + 0 = 0$$

$$B = \begin{vmatrix} 1 & a & a^2 \\ 0 & b-a & (b+a)(b-a) \\ 0 & c-a & (c+a)(c-a) \end{vmatrix} = (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 1 & c+a \end{vmatrix}$$

$$= (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & b+a \\ 0 & 0 & c-b \end{vmatrix}$$

upper triangular,

$$= (b-a)(c-a)(c-b)$$

$$\textcircled{1} \quad C = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} (1 - 4 \ 5) = \begin{pmatrix} 1 & -4 & 5 \\ 2 & -8 & 10 \\ 3 & -12 & 15 \end{pmatrix} \rightarrow \text{Linearly dependent}$$

(Rank 1) $\det C = 0$

$$\textcircled{2} \quad \begin{vmatrix} 0 & 1 & 3 \\ -1 & 0 & 4 \\ -3 & -4 & 0 \end{vmatrix} = \text{skew matrix}$$

$D^T = -D$

$$|D^T| = |-D|$$

$$= (-1)^n |D|$$

$$= (-1)^3 |D| = -|D|$$

$$\therefore |D^T| = |D| = -|D|$$

only true when
 $|D|=0$

$|D| = 0$

To $|D|=0$ goes all skew matrix?

Not necessarily \rightarrow when $n = \text{even}$

$$|D^T| = D$$

when $n = \text{odd}$

$$|D^T| = |D| = -|D| = 0$$

Lecture - 20 - Determinant formulas & cofactors

- * Formula goes det
- * To diagonal matrices
- * cofactors matrices.

- ① $\det I = 1$
- ② sign reverse with row exchange
- ③ det is linear in each row separately.

$$\textcircled{1} \quad \begin{vmatrix} a & b \\ c & d \end{vmatrix} \rightarrow \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix}$$

$$= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix}$$

$$= 0 + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + 0$$

column of zeros \swarrow

$$= ad - \begin{vmatrix} c & 0 \\ 0 & b \end{vmatrix} \rightarrow \text{flip 3.}$$

$$= ad - bc$$

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \begin{vmatrix} a & 0 & 0 \\ d & \text{we can} & \text{skip them to} \\ g & ; & ; \end{vmatrix} + \begin{vmatrix} 0 & b & c \\ 3d & e & f \\ g & h & i \end{vmatrix} \quad (\frac{1}{3})^{23}$$

That $3 \rightarrow$ TO 3 each \rightarrow

↓
↓
(each)

Most of them are zero'

$$\begin{vmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{vmatrix} + \begin{vmatrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ 0 & a_{32} & 0 \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & 0 \\ a_{21} & 0 & 0 \\ 0 & 0 & a_{23} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & 0 \\ 0 & 0 & a_{23} \\ a_{31} & 0 & 0 \end{vmatrix}$$

$$\left(\begin{array}{cccc} a_{11} & a_{22} & a_{33} & -a_{11}a_{23}a_{32} - a_{12}a_{11}a_{33} + a_{12}a_{23}a_{31} \\ & & & \xrightarrow{\text{to get a Identity}} \\ & & & \text{matrix, swap } R_2 \& R_3 \\ & & & + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} \end{array} \right)$$

C. Survivor has

one entry
in each row
&
each column

$$\left| \begin{array}{ccc} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ 0 & a_{32} & 0 \end{array} \right| + \left| \begin{array}{ccc} 0 & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & 0 & 0 \end{array} \right|$$

$$\begin{vmatrix} a_{11} & a_{12} & a_{23} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \begin{vmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} a_{11} & a_{12} & 0 \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & 0 & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$$

$$\begin{array}{c}
 \textcircled{1} \quad \textcircled{2} \quad \textcircled{3} \quad \textcircled{4} \quad \textcircled{5} \quad \textcircled{6} \\
 \left[\begin{matrix} a_{11} & 0 & 0 \\ a_{21} & 0 & 0 \\ a_{31} & a_{32} & a_{33} \end{matrix} \right] \quad \left[\begin{matrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{matrix} \right] \quad \left[\begin{matrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ a_{31} & a_{32} & a_{33} \end{matrix} \right] \\
 \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\
 \left[\begin{matrix} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ a_{31} & a_{32} & a_{33} \end{matrix} \right] \quad \left[\begin{matrix} 0 & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{matrix} \right] \quad \left[\begin{matrix} 0 & 0 & a_{13} \\ 0 & 0 & a_{23} \\ a_{31} & a_{32} & a_{33} \end{matrix} \right]
 \end{array}$$

$$\begin{array}{c}
 \textcircled{7} \quad \textcircled{8} \quad \textcircled{9} \\
 \downarrow \qquad \downarrow \qquad \downarrow \\
 \left[\begin{array}{ccc}
 0 & a_{12} & 0 \\
 0 & a_{21} & 0 \\
 23 & a_{32} & a_{33}
 \end{array} \right] \quad \left[\begin{array}{ccc}
 0 & a_{12} & 0 \\
 0 & a_{22} & 0 \\
 a_{31} & a_{32} & a_{33}
 \end{array} \right] \quad \left[\begin{array}{ccc}
 0 & a_{12} & 0 \\
 0 & 0 & a_{23} \\
 a_{31} & a_{32} & a_{33}
 \end{array} \right]
 \end{array}$$

$$\begin{array}{ccc}
 \textcircled{1} & & \\
 \downarrow & \downarrow & \rightarrow \\
 \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ a_{21} & 0 & 0 \\ a_{31} & 0 & 0 \end{array} \right] & \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ a_{21} & 0 & 0 \\ 0 & a_{32} & 0 \end{array} \right] & \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ a_{21} & 0 & 0 \\ 0 & 0 & a_{33} \end{array} \right] \\
 \downarrow & \downarrow & \downarrow \\
 0 & 0 & 0
 \end{array}
 \quad
 \begin{array}{ccc}
 \textcircled{2} & & \\
 \downarrow & \downarrow & \downarrow \\
 \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ a_{31} & 0 & 0 \end{array} \right] & \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & a_{32} & 0 \end{array} \right] & \left[\begin{array}{ccc} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{array} \right] \\
 0 & 0 & 0
 \end{array}$$

③

$$\begin{bmatrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ 0 & a_{21} & 0 \end{bmatrix} \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ 0 & a_{32} & 0 \end{bmatrix} \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix}$$

④

$$\begin{bmatrix} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ a_{31} & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ 0 & a_{32} & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ 0 & 0 & a_{23} \end{bmatrix}$$

⑤

$$\begin{bmatrix} 0 & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & 0 & 0 \end{bmatrix}$$

⑥

$$0$$

⑦

$$\begin{bmatrix} 0 & a_{12} & 0 \\ a_{21} & 0 & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$$

⑧

$$0$$

⑨

$$\begin{bmatrix} 0 & a_{12} & 0 \\ 0 & 0 & a_{23} \\ a_{31} & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix} + \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & 0 & a_{23} \\ 0 & a_{32} & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & a_{13} \\ a_{21} & 0 & 0 \\ 0 & a_{32} & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & a_{12} & 0 \\ a_{21} & 0 & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$$

+

$$\begin{bmatrix} 0 & a_{12} & 0 \\ 0 & 0 & a_{23} \\ a_{31} & 0 & 0 \end{bmatrix}$$

$$= (a_{11} a_{22} a_{33} - a_{11} a_{32} a_{23} + a_{21} a_{32} a_{13} - a_{31} a_{22} a_{13} - a_{21} a_{12} a_{33} + a_{31} a_{12} a_{23}) I$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$$

$$- \begin{bmatrix} 0 & 0 & a_{13} \\ 0 & a_{22} & 0 \\ a_{31} & 0 & 0 \end{bmatrix}$$

For $n \times n$

$$\det A = \sum \pm a_{1\alpha} a_{2\beta} a_{3\gamma} \dots a_{n\omega}$$

2 terms $\rightarrow 2 \times 2$ $(\alpha, \beta, \dots \omega) \rightarrow$ permutations6 terms $\rightarrow 3 \times 3$ θ_3 24 terms $\rightarrow 4 \times 4$ $(1, 2, \dots, n)$ $n!$

$$\begin{vmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \end{vmatrix}$$

 $= 0 \rightarrow$ singular. 4×4 $(-)$
odd
numbers
of
exchanges $(+)$
even
numbers of
exchanges $(4, 3, 2, 1) \rightarrow +1$ $(3, 2, 1, 4) \rightarrow -1$

Cofactors

Breaking up the big formula $n \times n$ det to determinants
1 smaller.

$$a_{11}(a_{22}a_{33} - a_{23}a_{32}) + a_{12}(a_{31}a_{23} - a_{21}a_{33}) + a_{13}(a_{21}a_{32} - a_{31}a_{22})$$

→ cofactors.

a_{22}	a_{23}	a_{12}	a_{32}	a_{33}	a_{13}	a_{23}	a_{33}	a_{21}	a_{31}	a_{22}	a_{32}	a_{31}	a_{22}	a_{31}	a_{32}	a_{31}	a_{22}	a_{31}	a_{32}	a_{31}	a_{22}	a_{31}	a_{32}	a_{31}	a_{22}				
a_{33}	a_{32}	a_{21}	a_{31}	a_{23}	a_{33}																								

Cofactors e.g. $a_{23} = \pm \det \left(\begin{matrix} n-1 \text{ matrix} \\ \text{with row } 2, \text{ column } 3 \end{matrix} \right)$
erased
depending upon row exchanges.

$+ \rightarrow i+j \rightarrow \text{even}$

$- \rightarrow i+j \rightarrow \text{odd.}$

pattern

$$\begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix} \rightarrow 3 \times 3$$

without sign: $\begin{bmatrix} a_{22} & a_{23} \\ a_{33} & a_{32} \end{bmatrix} \rightarrow \text{minors.}$

Cofactor formula (Along row 1)

$$\det(A) = a_{11} (\text{cofactor}) + a_{12} C_{12} + \dots + a_{1n} C_{1n}$$

$$\boxed{\det(A) = a_{11} C_{11} + a_{12} C_{12} + \dots + a_{1n} C_{1n}.}$$

2x2 matrix:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad + b(-c)$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} \quad \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

$\rightarrow \text{odd}$

Applications:

'determinants form smaller determinants'

Example: Triangular matrix

$$A_4 = \begin{vmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{vmatrix}$$

$$|A_1| = 1, \quad |A_2| = \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} = 0, \quad A_3 = \begin{vmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix}$$

$$= 1(0) - 1(1) + 0(1)$$

$$\begin{vmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{vmatrix}$$

$$A_3 = -1(1) = -1.$$

$\rightarrow \text{odd}$

$$|A_4| = 1 \begin{vmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix}$$

{ we can use columns too. $\therefore \det(A^T) = \det(A)$ }

$$= 1 |A_3| - 1 (1) \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix}$$

$$= 1 |A_3| - 1 |A_2| = -1 - 0 = -1$$

{ $|A_n| = |A_{n-1}| - |A_{n-2}|$ }

$|A_4| = -1$

$$|A_5| = 0, \quad |A_6| = 1, \quad |A_7| = 1.$$

\rightarrow period = 6 (Repeats).

Recitation

Find the determinants of

$$A = \begin{bmatrix} x & y & 0 & 0 & 0 \\ 0 & x & y & 0 & 0 \\ 0 & 0 & xy & 0 & 0 \\ 0 & 0 & 0 & xc & y \\ y & 0 & 0 & 0 & x \end{bmatrix}, \quad B = \begin{bmatrix} x & y & y & y & y \\ y & xc & y & y & y \\ y & y & x & y & y \\ y & y & y & xc & y \\ y & y & y & y & x \end{bmatrix}$$

1) Elimination 2) $\sum \pm a_{1\alpha} a_{2\beta} \dots a_{5\gamma}$ 3) By cofactor

Solu:

$$\begin{bmatrix} x & y & 0 & 0 & 0 \\ 0 & x & y & 0 & 0 \\ 0 & 0 & xy & 0 & 0 \\ 0 & 0 & 0 & xc & y \\ y & 0 & 0 & 0 & x \end{bmatrix} \xrightarrow{\text{Lower } \Delta^* \text{ matrix}} \begin{bmatrix} x & y & 0 & 0 & 0 \\ 0 & x & y & 0 & 0 \\ 0 & 0 & x & y & 0 \\ 0 & 0 & 0 & xc & y \\ y & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{Upper } \Delta^* \text{ matrix.}}$$

Take column $\rightarrow \therefore$ It has
cofactors in the forms
of U and L

$$\det A = x \begin{vmatrix} x & y & 0 & 0 \\ 0 & x & y & 0 \\ 0 & 0 & xc & y \\ 0 & 0 & 0 & xc \end{vmatrix} + y \begin{vmatrix} y & 0 & 0 & 0 \\ xc & y & 0 & 0 \\ 0 & xc & y & 0 \\ 0 & 0 & xc & y \end{vmatrix}$$

'upper triangular'

$$= x \cdot x^4 + y \cdot y^4$$

$\det A = x^5 + y^5$

$$\begin{aligned} \det R_5 &\rightarrow R_5 - R_4 \\ R_4 &\rightarrow R_4 - R_3 \\ R_3 &\rightarrow R_3 - R_2 \\ R_2 &\rightarrow R_2 - R_1 \end{aligned}$$

$$\begin{bmatrix} x & y & y & y & y \\ y-x & x-y & 0 & 0 & 0 \\ 0 & y-x & x-y & 0 & 0 \\ 0 & 0 & y-x & x-y & 0 \\ 0 & 0 & 0 & y-x & x-y \end{bmatrix}$$

Operations on columns:

$$\begin{aligned} C_4 &\rightarrow C_4 + C_5 \\ C_3 &\rightarrow C_3 + C_4 \\ C_2 &\rightarrow C_2 + C_3 \\ C_1 &\rightarrow C_1 + C_2 \end{aligned}$$

$$\begin{bmatrix} x & y & 2y & 2y & y \\ y-x & x-y & 0 & 0 & 0 \\ 0 & y-x & x-y & 0 & 0 \\ 0 & 0 & 0 & x-y & 0 \\ 0 & 0 & y-x & 0 & x-y \end{bmatrix}$$

$$C_3 \rightarrow C_3 + C_5$$

$$\begin{bmatrix} x & y & 3y & 2y & y \\ y-x & x-y & 0 & 0 & 0 \\ 0 & y-x & x-y & 0 & 0 \\ 0 & 0 & 0 & x-y & 0 \\ 0 & 0 & 0 & 0 & x-y \end{bmatrix}$$

$$C_2 \rightarrow C_2 + C_3 + C_5$$

$$\begin{bmatrix} x & 4y & 3y & 2y & y \\ y-x & x-y & 0 & 0 & 0 \\ 0 & 0 & x-y & 0 & 0 \\ 0 & 0 & 0 & x-y & 0 \\ 0 & 0 & 0 & 0 & x-y \end{bmatrix}$$

$$C_1 \rightarrow C_1 + C_2$$

$$\begin{bmatrix} x+4y & 4y & 3y & 2y & y \\ 0 & x-y & 0 & 0 & 0 \\ 0 & 0 & x-y & 0 & 0 \\ 0 & 0 & 0 & x-y & 0 \\ 0 & 0 & 0 & 0 & x-y \end{bmatrix}$$

$$\det B = (x+4y)(x-y)^4 \quad \therefore \text{Upper triangular.}$$

$$\det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix} = 1, \text{ using } \det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 19 \end{bmatrix}$$

$$\therefore \det \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 6 \end{bmatrix} = 1.$$

solu:

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20-1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & 20 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 10 \\ 1 & 4 & 10 & -1 \end{bmatrix}$$

$$\det \begin{bmatrix} " \end{bmatrix} = 1 - 1 \quad \left| \begin{array}{cccc} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 3 & 6 & 6 \end{array} \right|$$

$$= 1 - 1$$

$$= 0$$

Lecture - 01

$$A^{-1} = \frac{1}{\det A} C^T \rightarrow C \rightarrow \text{matrix of cofactors of } A.$$

Absolute value of the determinant gives the volume of a box.

* Cramer's rule after $x = A^{-1}b$

* $|\det A| = \text{volume of box.}$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

why this works?

3x3:

$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}^{-1} = \text{Gauss-Jordan algorithm}$$

↓
what's the algebra?

$\det A \rightarrow \text{product of } n \text{ entries}$

$C^T \rightarrow \text{product of } (n-1) \text{ entries}$

$$A^{-1} = \frac{1}{\det A} \cdot C^T$$

$$AA^{-1} = I$$

$$AC^T = \det(A) \cdot I$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ \dots & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} c_{11} & c_{12} & \dots \\ c_{21} & c_{22} & \dots \\ \vdots & \vdots & \vdots \\ & & c_{nn} \end{bmatrix}$$

$$a_{11} c_{11} + a_{12} c_{12} + \dots + a_{1n} c_{1n} = \det \text{ of Row 1.}$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ \dots & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} c_{11} & c_{21} & \dots \\ c_{12} & c_{22} & \dots \\ \vdots & \vdots & c_{nn} \end{bmatrix} = \begin{bmatrix} \det A & & 0 \\ & \det A & 0 \\ 0 & & \det A \end{bmatrix}$$

question: what about off-diagonal entries.

check:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = (a \ b) \begin{pmatrix} -b \\ a \end{pmatrix} = 0$$

Row 1 Cofactor of Row 2.

$$-ab + ab$$

$$A_2 = \begin{vmatrix} a & b \\ a & b \end{vmatrix} = ab - ab \rightarrow \text{determinant of matrix having similar rows.}$$

(Screamed up)

$$\text{cofactor of } a = b$$

$$\text{cofactor of } b = -a$$

$$\det A_2 = ab - ab$$

$$\det A_2 = 0$$

* why 0: determinant of taking 1st & last rows identical

$$\therefore \begin{bmatrix} a_{11} & \dots \\ a_{21} & \dots \\ \dots & a_{nn} \end{bmatrix} \begin{bmatrix} c_{11} & c_{21} & \dots \\ \vdots & \vdots & \vdots \\ c_{nn} \end{bmatrix} = \det A \begin{bmatrix} 1 & 0 & 0 & \dots \\ 0 & 1 & 0 & \dots \\ \dots & \dots & \dots & \dots \end{bmatrix}$$

$$A c^T = \det(A) I$$

$$A \cdot \frac{1}{\det(A)} c^T = AA^{-1}$$

$$\frac{1}{\det(A)} c^T = A^{-1}$$

Is I move all entry what happens to $A^{-1}b$

$$Ax = b$$

$$x = A^{-1}b$$

$$x = \frac{1}{\det A} C^T b$$

Gramm's rule:

formula from x:

$$x_1 = \frac{\det B_1}{\det(A)}$$

$C^T b$ = cofactor matrix (x)

Some numbers

$C^T b$ = determinant of something

$$x_2 = \frac{\det B_2}{\det(A)}$$

gramm realized what B_1, B_2 are?

$$B_1 = \begin{bmatrix} 1 & & & \\ b & & & \\ 1 & & & \end{bmatrix} \text{ n-1 columns } = A \text{ with column 1 replaced by } b.$$

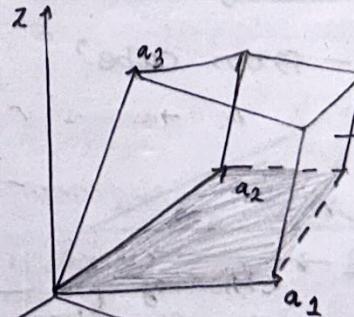
$B_2 = A$ with column 2 replaced by b .

$$x_3 = \frac{\det B_3}{\det A}$$

The above one has long calculations!

'Not efficient - disastrous way'

$\det A$ = volume of box.



$a_1 (a_{11}, a_{12}, a_{13})$
 $a_2 (a_{21}, a_{22}, a_{23})$
 $a_3 (a_{31}, a_{32}, a_{33})$

'Box - parallelopiped like shape'

Volume is given by determinant

Is that be (-)ve?



So we are taking it's absolute value.

If we change two rows \rightarrow changing (exchanging) two sides won't affect volume. (Right handed will be left handed.)

special case: If $A = I$

It's a unit cube

$$\text{volume} = 1 \text{ cu. units}$$

$$\therefore \det I = 1$$

Relating to orthogonality:

If $A = Q$ (orthogonal matrix)

$Q \rightarrow$ Columns orthogonal

shape of the box: cube (How different from Identity cube?)
↓
Rotated. (Turned in space)

$$\det Q = ?$$

is

$$\det Q = \pm 1$$

W.O.T.:

$$Q^T Q = I$$

$$\det(Q^T Q) = \det I$$

$$\det(Q^T) \det(Q) = \det I$$

$$\therefore \det Q^T = \det Q$$

$$(\det Q)^2 = \det I$$

$$\boxed{\det Q = \pm 1}$$

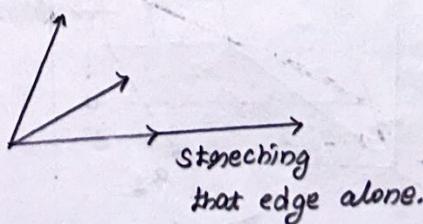
Rectangular boxes:

'Stretch the edges - from cube'

$$\text{cube} = a^3 \text{ cu. units}$$

$$\text{stretch} = a^2 \times (2a) \\ = 2a^3$$

$$= \text{double} \times \text{Volume of cube.}$$



say $(2 \times \text{edge})$
(Row alone)

$$= 2 \times \text{Volume.}$$

$R_1 = QR_1 \Rightarrow$ what about determinant?

determinant also doubles!

volume satisfies own 3(a) property.

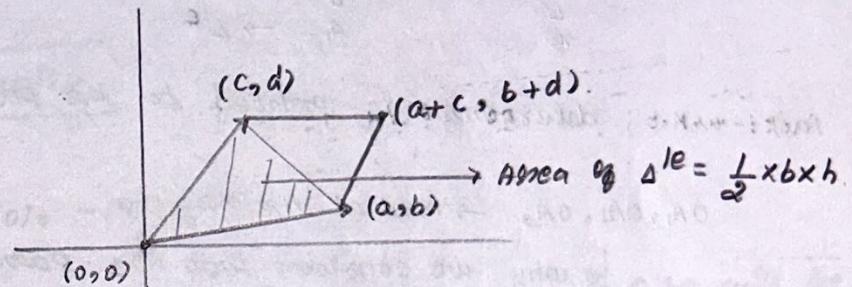
Prove 3(b) property

satisfied \rightarrow prop 1 ✓

prop 2 $|\det A| = \text{volume of box}$ ✓

prop 3(a) ✓

$$3(b): \begin{vmatrix} a+a' & b+b' \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} a' & b' \\ c & d \end{vmatrix}$$



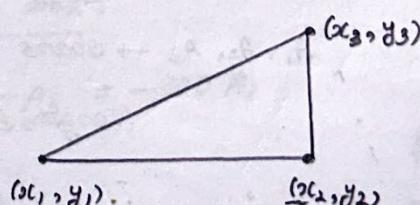
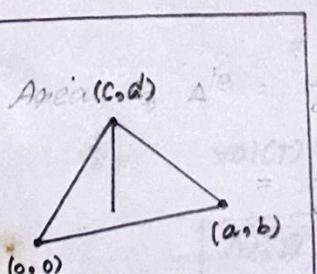
Area of the parallelogram: base \times height.

$$\text{Area} = \det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow \text{parallelogram}$$

$$= ad - bc$$

$$\text{Area of } \Delta^{12} = \frac{1}{2} (ad - bc)$$

Area of $\Delta^{12} = \frac{1}{2} \text{ Area of parallelogram}$



$$\text{Area} = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$

2 axis of parallelogram.

Recitation

T is a tetrahedron with vertices

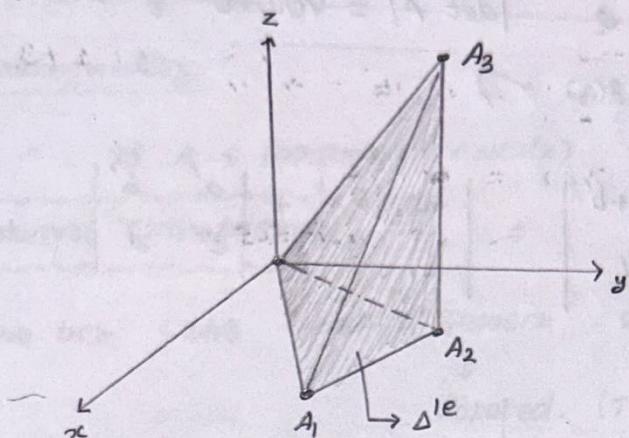
$$O(0,0,0), A_1(2,2,-1), A_2(1,3,0), A_3(-1,1,4)$$

Compute volume (T)

If A_1, A_2 are fixed but A_3 is moved to $A_3'(-20, -199, 104)$

compute volume (T')

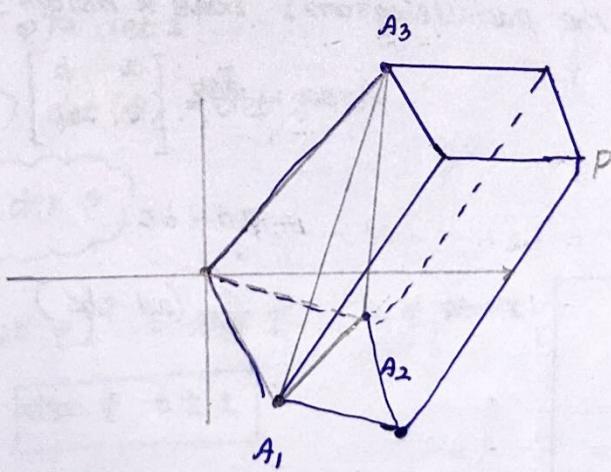
Sol:



Fact: w.r.t determinant is related to the parallelepiped.

$OA_1, OA_2, OA_3 \rightarrow$ meet at the origin

↳ why we consider that the parallelopiped is spanned by this same three edges?



$A_1, A_2, A_3 \rightarrow$ spans parallelopiped.

$A_1, A_2, A_3 \rightarrow$ spans those edges

(Lengths breadth & height).

Volume of tetrahedron = $\frac{1}{3}$ Area of base \times height.

Base be $O A_1 A_2$

$$\text{Vol}(T) = \frac{1}{3} A(\Delta OA_1A_2) \cdot h$$

$$h = A_3$$

$$\text{Vol}(P) = \text{Area of base} \times h$$

$$\text{Vol}(P) = 2A(\Delta OA_1A_2) \times h$$

$$\text{Vol}(T) = \frac{1}{6} \text{Vol}(P)$$

$$\text{Vol}(P) = \text{abs} \begin{vmatrix} 2 & 2 & -1 \\ 1 & 3 & 0 \\ -1 & 1 & 4 \end{vmatrix} = 2(12) - 2(4) - 1(1+3) \\ = 24 - 8 - 4 \\ = 12 \text{ cu. units}$$

$$\text{Vol}(T) = \frac{1}{6} \times 12$$

$$\boxed{\text{Vol}(T) = 2 \text{ cu. units}}$$

changing $A_3 (-20, -199, 104)$

$$\text{Vol}(P) = \text{cabs} \begin{vmatrix} 2 & 2 & -1 \\ 1 & 3 & 0 \\ -20 & -199 & 104 \end{vmatrix}$$

height will be very high ↓

shape will be like a needle.

$$= 2(3 \times 104) - 2(104) - 1(-199 + 3(-20)) \\ = 624 - 208 - 404 \\ = 12$$

$$\text{Vol}(T) = \frac{1}{6} \cdot 12$$

$$\boxed{\text{Vol}(T) = 2 \text{ cub. units}}$$

Pay attention to the last now:

$$\text{How much moved: } A'_3 - A_3 = -100A_1$$

A_3 is the linear combination of R_1 .

$$\det \begin{vmatrix} 2 & 2 & -1 \\ 1 & 3 & 0 \\ -20 & -199 & 104 \end{vmatrix} = \begin{vmatrix} 2 & 2 & -1 \\ 1 & 3 & 0 \\ -1 & 1 & 4 \end{vmatrix} + \begin{vmatrix} 2 & 2 & -1 \\ 1 & 3 & 0 \\ -200 & -200 & 100 \end{vmatrix}$$

$$\therefore A_3 = -100A_1$$

$$= 2 + 0 = 2$$

$A_1, A_2 \rightarrow \text{Fixed}$ \rightarrow Base is fixed

\hookrightarrow Changing height must not change base.

\downarrow
not possible (so height not changing)

we are moving in the ~~reverse~~ direction -
to A_1 . (Height not changing)

Lecture - 22

Eigen values & Eigen vectors,

If the product Ax points in the same direction as the vector x , we say that x is an Eigen vector of A . Eigen values & Eigen vectors describe what happens when a matrix is multiplied by a vector.

* Eigen values - Eigen vectors

* $\det [A - \lambda I] = 0$

$$\text{Trace} = \lambda_1 + \lambda_2 + \dots + \lambda_n.$$

$\xrightarrow{\text{vector}} Ax$
 x
(Input) (output)

'Interested: ones that come out in the same direction'

' Ax - parallel to x ' - Eigen vectors.

$AX = \lambda X$ \rightarrow Eigen vector.
 \downarrow some multiple.
(Eigen value)

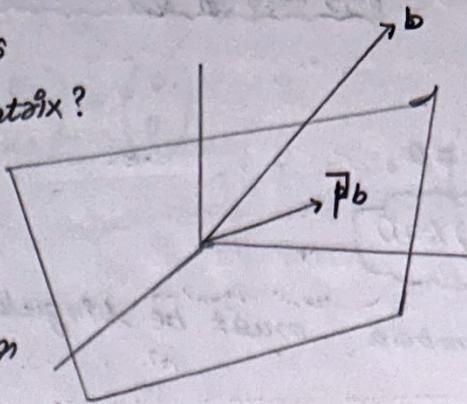
If $A \rightarrow$ singular, then $\lambda = 0$ is an Eigen value:

$x \rightarrow$ Some non-zero vector.

'we can't use elimination'

'Examples - projection matrix'

what are x 's and λ 's
from a projection matrix?



$b \rightarrow$ not a Eigen vector

$Pb \rightarrow$ has different direction.

What vectors are Eigen vectors of P ?

Any x in the plane: projected will give me x .
(unchanged - so x is an Eigen vector.
multiplication by P is an Eigen value).

3-d - 3-Eigen vectors: 2 inside (2-D) plane & 1 outside

'Any x perpendicular to the plane':

$$Px = 0x$$

'permutation matrix'

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \quad x = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}, \quad \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \end{pmatrix}$$

$$Ax = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \rightarrow \begin{array}{l} \text{Eigen value} = 1 \\ \text{Eigen vector} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \end{array} \quad \begin{array}{l} \text{Eigen value} = -1 \\ \text{Eigen vector} = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \end{pmatrix} \end{array}$$

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad x = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

multiply by A reverses the two components

$$Ax = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$n \times n \rightarrow n$ eigen values

'Sum of the Eigen values = Sum of the diagonals'

$$Ax = -\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Fact

$$Ax = -x$$

↓
Trace of the matrix

In this example \rightarrow This is 0.

How to find Eigen values & vectors

$$Ax = \lambda x$$

Rewrite,

$$Ax - \lambda x = 0$$

$$(A - \lambda I)x = 0$$

A shifted by Lambda must be singular else the only solution is $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$.

$$\therefore \det(A - \lambda I) = 0$$

Characteristic eqn (or) Eigen value eqn:

$\lambda \rightarrow$ could be repeated.

Finding $x \rightarrow$ null space (By elimination).

Example:

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \rightarrow \text{symmetric}$$

constant down the diagonal
 2×2 .

Eigen values: Real for symmetric matrix

The Eigen vectors are \perp^r

e.g: $(1 \ 1) \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 0 \rightarrow$ previous example.

$$\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix} = 0$$

$$(3-\lambda)^2 - 1 = 0$$

$$(3-\lambda)^2 = 1$$

$$\lambda^2 - 6\lambda + 8 = 0$$

↓

trace determinant

$$\lambda^2 - 6\lambda + 9 = 1$$

$$\lambda^2 - 6\lambda + 8 = 0$$

$$(\lambda - 4)(\lambda - 2) = 0$$

$$\lambda_1 = 4, \lambda_2 = 2.$$

→ Real.

8

-4 1 -2

-6

w when $\lambda = 4$

$$\begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
$$x_1 = 1, x_2 = 1$$
$$x_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

w when $\lambda = 2$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
$$x_1 = 1, x_2 = -1$$
$$x_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

'we have a line of Eigen vectors - we are giving a basis'

relation b/w

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$$

Common Eigen vectors (not Eigen values)

$$\therefore A = B - 3I$$

'observation: If I add $3I$ to a matrix, its eigen vectors don't change' \rightarrow It's Eigen values are three (sum) bigger.

$$AX = \lambda X$$

$$(A+3I)X = \lambda X$$

$$(A+3I)X = AX + 3X$$

$$(A+3I)X = \lambda X + 3X$$

$$(A+3I)X = (\lambda+3)X$$

Eigen vectors same X from both matrices.

Special:

$$AX = \lambda X \quad (X, \lambda \rightarrow \text{Known})$$

Adding some other matrix B

'Caution'

B has eigen values $\alpha_1, \alpha_2, \dots$

$$Bx = \alpha_1 x$$

$$(A+B)x \neq (\lambda + \alpha) x \rightarrow \text{False.}$$

\rightarrow False case.

$x \rightarrow$ is not the Eigen vector of B

Eigen values \rightarrow Not linear (Not multiply).

Example: 'Rotation matrix' \rightarrow Rotates Every Vector by 90° .

$$\varphi = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad \cos 90^\circ = 0 \quad \sin 90^\circ = 1$$

$$\varphi = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

\hookrightarrow Orthogonal matrix?

Soluⁿ Eigen values & Eigen vectors!

$$\text{Trace} = 0$$

$$\text{Sum of Eigen values} = \lambda_1 + \lambda_2 = 0 \quad (\text{trace})$$

\therefore determinant = product of Eigen values

$$\det(\varphi) = \lambda_1 \lambda_2$$

$$\lambda_1 \lambda_2 = \begin{vmatrix} 0 & -1 \\ 1 & 0 \end{vmatrix} = 1$$

Rotation: what vectors can come out parallel after a 90° rotation? \rightarrow trouble.

From,

$$\lambda_1 + \lambda_2 = 0$$

$$\boxed{\lambda_1 = -\lambda_2}$$

How

$$\lambda_1 \lambda_2 = +ve ?$$

$$\det \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

$$\lambda^2 = -1$$

$$\lambda = \sqrt{-1}$$

$$\lambda = \pm i$$

\rightarrow Complex Eigen values even though the matrix is real.

Real matrix $\xrightarrow{\text{give}}$ complex Eigen values.

complex conjugates of each other: Switched Signs of imaginary
Eigen vectors

fact: Symmetric matrix \rightarrow it won't happen. Eigen values are real.

$$\varphi \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \varphi^T = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

$\boxed{\varphi = -\varphi^T} \rightarrow$ Anti-symmetric. pure Imaginary Eigen values.

Good possibilities: 1^o Eigen vectors, Real Eigen values

bad possibilities: Complex Eigen values

Even worse: possibly Symmetrical & non-Symmetrical
Both Imag + Real numbers)

$$A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix} \rightarrow \text{rectangular matrices.}$$

Solu:- $\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 0 & 3-\lambda \end{vmatrix} = (3-\lambda)^2 = 0$
 $(\lambda^2 - 6\lambda + 9 = 0)$

problem: Eigen vectors:

$$\lambda = 3, 3$$

when $\lambda = 3$

$$(A - \lambda I)x = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}(x) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

\hookrightarrow singular

when

$$x_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \lambda_2 = 3 \text{ (again)}$$

$\therefore x_2$ must be independent. (possibility of repeated eigen values \rightarrow opens the shortage of Eigen vectors)

1 \rightarrow Eigen vector, instead of 2.

$\{ x_2 = \text{No second independent Eigen vectors.} \}$

\rightarrow No Complete Eqty given by Eigen vectors.

Recitation

Invertible

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 1 & 4 \end{pmatrix}, \text{ Find the Eigen values \& vectors of } A^2, (A^{-1} - I)$$

Solu:

$$AV = \lambda V$$

$$A^2V = A(AV) = A(\lambda V)$$

$$A^2V = \lambda(AV)$$

\hookrightarrow scalars

$$A^2V = \lambda^2 V$$

Now

$$A^{-1}A V = A^{-1}\lambda V$$

$$A^{-1}V = A^{-1} \frac{AV}{\lambda} \quad (\lambda \neq 0)$$

$$A^{-1}V = \frac{1}{\lambda} V$$

$$(A^{-1} - I)V = \left(\frac{1}{\lambda} - 1\right)V$$

$$(A^{-1} - I)V = \left(\frac{1}{\lambda} - 1\right)V$$

\therefore Eigen values \& Eigen vectors of $A^2, (A^{-1} - I)$:

$$\det(A - \lambda I) = 0$$

$$\det \begin{vmatrix} 1-\lambda & 2 & 3 \\ 0 & 1-\lambda & -2 \\ 0 & 1 & 4-\lambda \end{vmatrix} = (1-\lambda) [(1-\lambda)(4-\lambda) + 2] = (1-\lambda) [4 - \lambda - 4\lambda + \lambda^2 + 2]$$

$$0 = (1-\lambda) [\lambda^2 - 5\lambda + 6]$$

$$0 = (1-\lambda)(\lambda^2 - 5\lambda + 6)$$

$$\begin{array}{ccc} & & 6 \\ & / & \backslash \\ -2 & & -3 \\ & \backslash & / \\ & -5 & \end{array}$$

$$0 = (1-\lambda)(\lambda-2)(\lambda-3)$$

$$\lambda = 1, 2, 3.$$

when $\lambda = 1$	when $\lambda = 2$	when $\lambda = 3$
$0 = (A - \lambda I) v$	$0 = \begin{pmatrix} -1 & 2 & 3 \\ 0 & -1 & -2 \\ 0 & 1 & 2 \end{pmatrix} v$	$0 = \begin{pmatrix} -2 & 2 & 3 \\ 0 & -2 & -2 \\ 0 & 1 & 1 \end{pmatrix} v$
$0 = \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & -2 \\ 0 & 1 & 3 \end{pmatrix} v$	$v = \begin{pmatrix} -\frac{1}{2} \\ -2 \\ 1 \end{pmatrix}$	$v = \begin{pmatrix} -\frac{1}{2} \\ -1 \\ 1 \end{pmatrix} \text{ (or)} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$
$v = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$		$-2+3=1-1=0$

	A	A^2	$A^{-1} - 2$
Eigen values	λ	λ^2	$\lambda^{-1} - 1$
Eigen vectors	v	v	v

$$A = \begin{bmatrix} 2.0 & 0 \\ 1.0 & 3.0 \end{bmatrix}$$

Eigen values : α_1, α_2

Eigen vectors : $\begin{pmatrix} 0.71 \\ -0.71 \end{pmatrix}, \begin{pmatrix} 0.00 \\ -1 \end{pmatrix}$

Trace : 5

Determinant : 6

$$\begin{array}{l} \downarrow \lambda x \\ \downarrow Ax \end{array}$$

"Eigen vectors"

Powers A^K have eigen values λ^K

$$A^\alpha x = A(\lambda x) = \lambda^\alpha x$$

u_0 is a combination $c_1 x_1 + \dots + c_n x_n$

Then $A u_0$ is $u_1 = c_1 \lambda_1 x_1 + \dots + c_n \lambda_n x_n$

Dynamics in discrete time:

$$u_{K+1} = A u_K \text{ starting from } u_0$$

$$A^K u_0 \text{ as } u_K = c_1 (\lambda_1)^K x_1 + \dots + c_n (\lambda_n)^K x_n.$$

$u_0 \rightarrow \text{combination } c_1 x_1 + \dots + c_n x_n$ [Combination of Eigen Vectors]

$$A u_0 = u_1 = c_1 \lambda_1 x_1 + \dots + c_n \lambda_n x_n.$$

Dynamics in discrete time:

$$u_{K+1} = A u_K$$

$$A^K u_0 = u_K = c_1 (\lambda_1)^K x_1 + \dots + c_n (\lambda_n)^K x_n$$

Diagonalisation

Needs n independent Eigen vectors: Automatic if the Eigenvalues are all different.

Eigen vectors x_1, \dots, x_n are columns of invertible Eigen vectors matrix S .

Multiply the columns x by A : $AS = [\lambda_1 x_1 \dots \lambda_n x_n]$

$$\text{This equals } \begin{bmatrix} x_1 & \dots & x_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} = S \Lambda$$

Then $S^{-1} AS = \text{diagonal Eigenvalue matrix } \Lambda$.

In other words

$$A = S \Lambda S^{-1}$$

$\Lambda \rightarrow \text{diagonal matrix.}$

Differential equation

$S = \text{Eigen vectors, } \Lambda = \text{Eigen values, } A = S \Lambda S^{-1}$

$$A^K = (S \Lambda S^{-1}) \dots (S \Lambda S^{-1})$$

$$= S \Lambda^K S^{-1}$$

$$e^{At} = S e^{\Lambda t} S^{-1} \text{ for differential equations}$$

$$e^{At} u(0) \text{ as } u(t) = c_1 e^{\lambda_1 t} x_1 + \dots + c_n e^{\lambda_n t} x_n$$

Then $u(t)$ solves $\frac{du}{dt} = Au$ starting from $u(0)$

'Simpler' $B = M^{-1} AM$ has the same eigen values as A

Symmetry:

1) Real Eigen values

2) perpendicular eigen vectors.

$$A^T = A \text{ takes } A = SAS^{-1} \text{ leads to } A = Q \Lambda Q^T$$

Eigen vector matrix Q has orthonormal columns

$$\begin{bmatrix} v_1^T \\ \vdots \\ v_n^T \end{bmatrix} \begin{bmatrix} v_1 & \dots & v_n \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$Q^{-1} = Q^T$$

$A^T = A$: Real λ , $A^T = -A$: Imaginary λ

orthogonal matrix Q : Au , $|\lambda| = 1$.

stable for computing

Positive definite

Positive definite matrices come from $A^T A$

Energy $u^T A^T A u = (Au)^T (Au) = \|Au\|^2 \geq 0$

Eigen values of $A^T A$ never negative: $x^T A^T A x = x^T \lambda x$

Upper left determinants of $A^T A$ never negative.

Pivots of $A^T A$ never negative.

All are positive if A has independent columns.

SVD

single value decomposition of A (m by n) 'Factorize'

$$A = U \Sigma V^T = (\text{orthogonal}) (\text{diagonal}) (\text{orthogonal})$$

u_1, \dots, u_m in U are eigen vectors of $A^T A$

v_1, \dots, v_n in V are eigen vectors of $A^T A$.

$\sigma_1, \dots, \sigma_r$ in Σ are positive singular values of A .

$$AV = U\Sigma \text{ means each } AV_j = \sigma_j u_j$$

Every A is diagonalized by a orthonormal matrices

Diagonalization and powers of A

If A has n independent eigen vectors, we can write
 $A = SAS^{-1}$, where $\Lambda \rightarrow$ diagonal matrix having eigen values

of A. This allows us to easily compute powers of A in which in turn allows us to solve differential equations

$$u_{k+1} = Au_k$$

Lecture - 23

Diagonalize a matrix

$$S^{-1}AS = \Lambda$$

$S^{-1} \rightarrow$ Inversion: Independent Eigen vectors.

Suppose n independent eigen vectors of A, put them in columns of S.

$S \rightarrow$ Eigen vectors matrix

$$Ax = \lambda x$$

$\hookrightarrow x$ -Eigen vectors

$$AS = A \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} = \begin{bmatrix} Ax_1 & Ax_2 & \dots & Ax_n \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 x_1 & \lambda_2 x_2 & \dots & \lambda_n x_n \end{bmatrix}$$

$$= \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 & 0 \\ 0 & 0 & \ddots & \ddots & 0 \\ 0 & 0 & 0 & \ddots & \lambda_n \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$= S \Lambda$$

\hookrightarrow Diagonal matrix

Column times

Row

multiplication

$\Lambda \rightarrow$ capital lambda

n independent Eigen vectors

$$AS = SA$$

$$S^{-1}AS = S^{-1}S\Lambda$$

$$S^{-1}AS = \Lambda$$

Also other way:

$$AS S^{-1} = S\Lambda S^{-1}$$

$$A = S\Lambda S^{-1}$$

New factorization
Replacement of LU.

what about A^2 ?

$$AX = \lambda X$$

$$A^2 X = A(AX) = A(\lambda X) = \lambda(AX) = \lambda^2 X$$

$$A^2 X = \lambda^2 X$$

'same Eigen vectors X as A'

$$A^2 = (S \Lambda S^{-1})(S \Lambda S^{-1})$$

$$A^2 = S \Lambda^2 S^{-1}$$

'Eigen vectors are the same'
diagonal matrix is unchanged

↳ In matrix form.

$$A^k = S \Lambda^k S^{-1}$$

Eigen values are k^{th} powers
Eigen vectors are the same.

In $LU \rightarrow$ multiplying 100 times with give $(LU)^{100 \text{ times}}$

↳ Here Λ^k

$$A^{100} = S \Lambda^{100} S^{-1}$$

when to the powers of the matrix goes to zero?
stable matrix

$A^k \rightarrow 0$ as $k \rightarrow \infty$ if all $|\lambda_i| < 1$.

where is the information about stability:

'Not in pivots'

'In the Eigen values'

Note: we have n independent Eigen vectors: Else diagonalization is not possible.

which matrices are diagonalizable?

A is said to have n independent Eigen vectors. (If all the lambdas are different).
↳ No repeated Eigen values.

command: `eig()`

Repeated Eigen values:

may or may not have n independent Eigen vectors

$I_{10 \times 10}$ = Eigen values (diagonal element)

$$\lambda = 1, 1, 1, 1, 1, 1, 1, 1, 1$$

But non-repeated Eigen vectors.

If $A = I$

$$S^{-1} A S = I$$

$$S^{-1} I S = I$$

$I = I \rightarrow \therefore$ Already diagonalized.

case: Triangular.

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$$

Eigen values $\lambda = 2, 2$.

'upper Δ^{∞} '

$$\begin{vmatrix} 2-\lambda & 1 \\ 0 & 2-\lambda \end{vmatrix} = 0$$

$$(2-\lambda)^2 = 0$$

$$\lambda = 2, 2$$

Eigen vectors:

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$x = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow \text{only one independent Eigen vector}$$

↳ one-dim null space.

'As we can't find two independent Eigen vectors, we can't diagonalize'

n independent Eigen vectors: Algebraic multiplicity is one.

Geometric multiplicity is one.

$$(\lambda - a)(\lambda - b)$$

(Independent).

Equation:

'start with u_0 '

$$u_{k+1} = A u_k$$

$$u_2 = A u_1$$

$$u_2 = A(A u_0)$$

$$u_2 = A^2 u_0 \quad [A u_1 = A(A u_0)]$$

$$u_K = A^K u_0$$

'Solves 1 order differential equation'

'we are dealing with systems' - Matrix

To greatly solve:

write u_0 as a combination of Eigen vectors.

$$u_0 = c_1 x_1 + c_2 x_2 + \dots + c_n x_n \rightarrow \text{Any combination of Eigen vectors}$$

$$A u_0 = A c_1 x_1 + A c_2 x_2 + \dots + A c_n x_n$$

$$A x_i = \lambda_i x_i$$

$$A u_0 = c_1 \lambda_1 x_1 + c_2 \lambda_2 x_2 + \dots + c_n \lambda_n x_n$$

$$A^{100} u_0 = c_1 \lambda_1^{100} x_1 + c_2 \lambda_2^{100} x_2 + \dots + c_n \lambda_n^{100} x_n$$

∴ we have pure λ

$$A^{100} u_0 = \lambda^{\underline{100}} S C$$

$$u_{100} = A^{100} u_0 = \lambda^{\underline{100}} S C$$

Fibonacci sequence: 0, 1, 1, 2, 3, 5, 8, 13, ...

F_{100} = 100th Fibonacci number = ?

$$F_{k+2} = F_{k+1} + F_k$$

$$F_{k+1} = F_{k+1}$$

$$u_k = \begin{bmatrix} F_{k+1} \\ F_k \end{bmatrix} \rightarrow \text{made } g_k \text{ of 2nd order, despite of II order.}$$

$$u_{k+1} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} F_{k+1} \\ F_k \end{bmatrix}$$

$$\therefore F_{k+2} = F_{k+1} + F_k \rightarrow \text{II order}$$

converting g_n to I order:

$$u_{k+1} = A u_k$$

$$F_{k+2} = F_{k+1} + F_k \rightarrow ①$$

$$F_{k+1} = F_{k+1} \rightarrow ②$$

$$u_k = \begin{bmatrix} F_{k+1} \\ F_k \end{bmatrix}$$

→ 2×2 system (I order)

↳ Be a vector.