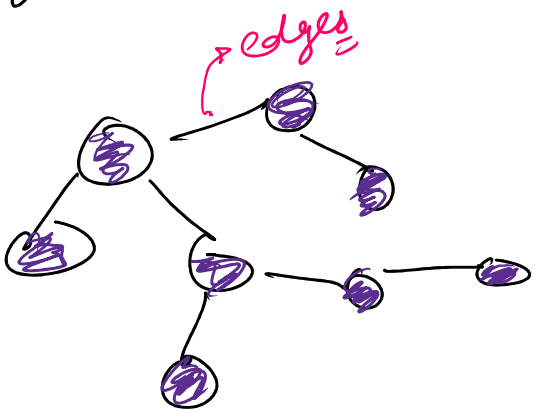
4.7 - Graphs - 1

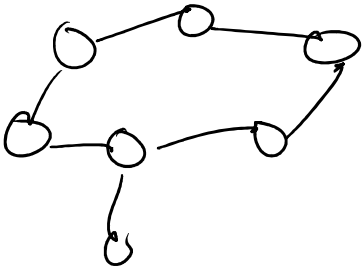
Sunday, September 7, 2025 10:50 AM

Non linear Data Structures

→ Graph is a DS made up of vertices/ nodes and edges.

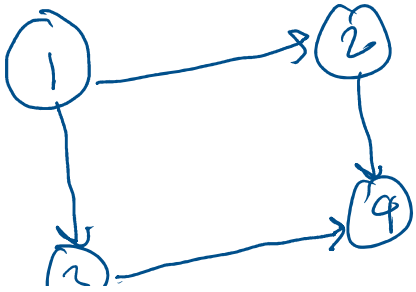


Cyclic Vs Acyclic graph

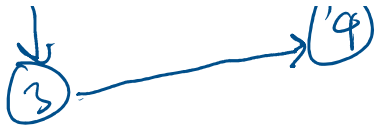


→ Cycle is a path which starts at a node and also ends at the same node

Directed Vs Undirected Graphs

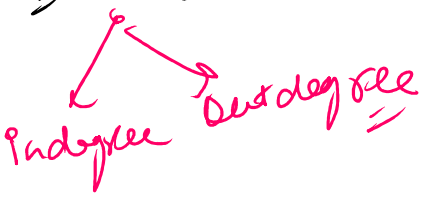


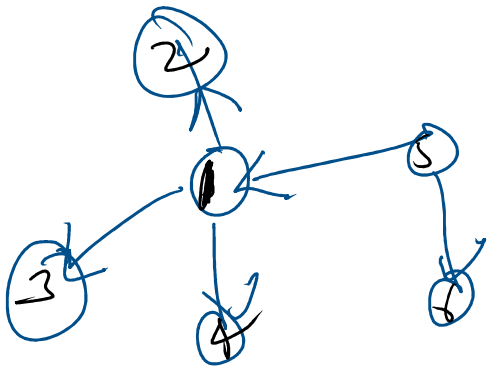
→ this doesn't have a cycle



* Direction is specified along every edge and we can only move in that direction.

Degree of a node

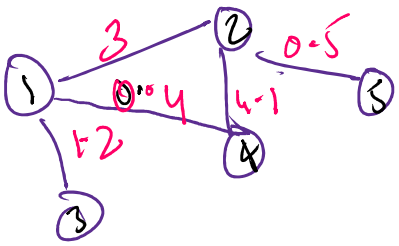




indeg(1) = 1

Outdeg(1) = 3

Weighted and unweighted graph



How to represent graphs

→) Adjacency matrix

→) List

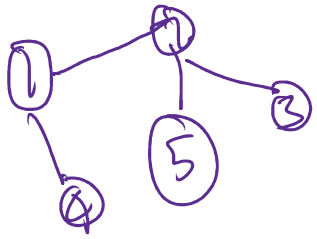
→) Adjacency matrix

→) Adjacency list.

Adjacency Matrix

→ V×V matrix

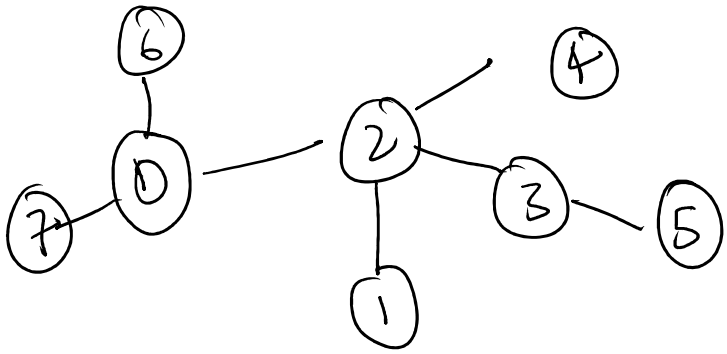
where a[i][j] represents that there is an edge from i → j

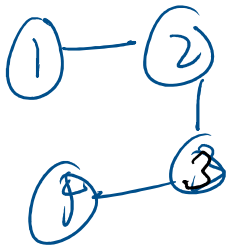


⇒

5×5

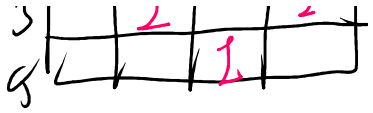
	1	2	3	4	5
1	0	1	0	1	0
2	1	0	1	0	1
3	0	1	0	0	0
4	1	0	0	0	0
5	0	1	0	0	0





→

	1	2	3	4
1		1		
2	1		1	
3		1		1
4			1	

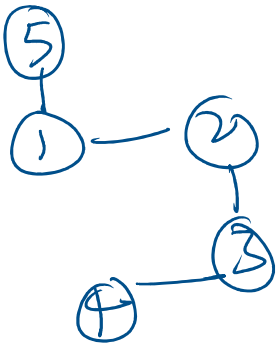


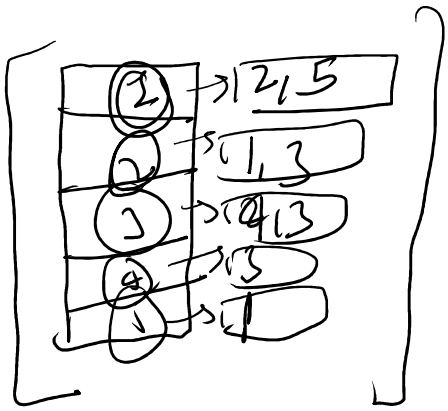
⊛ Adj Matrix wastes a lot of space for sparse graphs

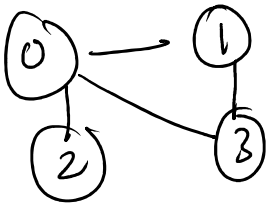
sparse ⇒ less edges wo

⇒ Adjacency Lists

Array list of array list





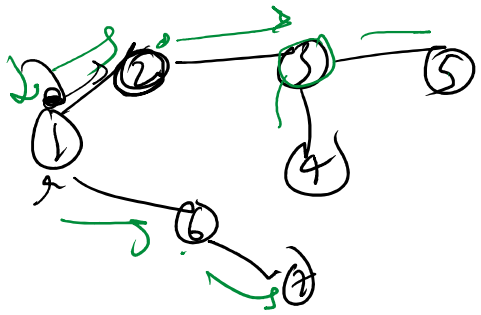


Traversal of graphs

1) Breadth first Search → A node traverses its immediate neighbors, the those neighbors traverse their imm nbr, continues.

1 → 2, 6
2 → [3, 1]
3 → [2, 4, 5]
4 → 3
5 → 3

⇒



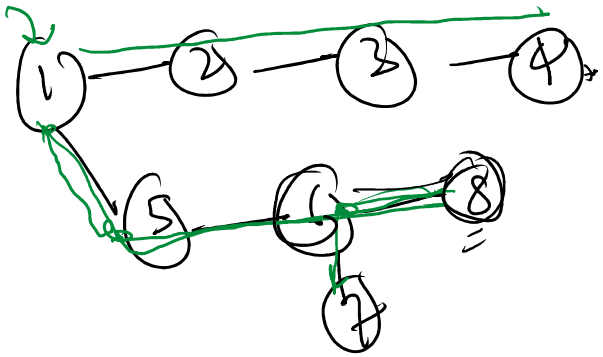
6 → 1, 7
7 → 6

T.C = O(V+E)

⊛ BFS is implemented iteratively using queue

⇒ Depth first search

⇒ We keep traversing until one path is not completely traversed.



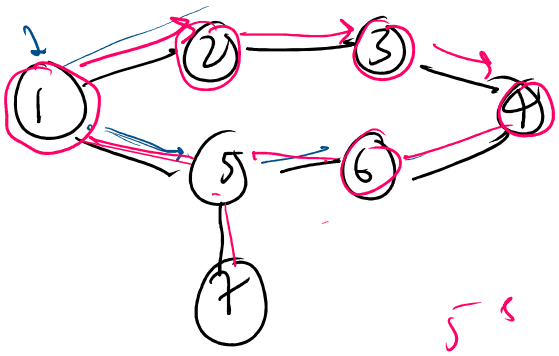
T.C = O(V+E)

⊛ DFS is implemented recursively

Connected Vs Disconnected graphs

① Disconnected graphs is where we more than one components.

Cycle in undirected graph



S = [0 to 6]

[[1,3]
[4,5]
[2,7]]

cycle in directed graph

[5]