

1. (a)  $L = \sqrt{w_1^2 + w_2^2} + \mu(-w_1 - 2w_2 + 5)$   
 $w_1 + 2w_2 \geq 5 \rightarrow -w_1 - 2w_2 + 5 \leq 0$

stationary condition:  $\frac{\partial L}{\partial w_1} = 0, \frac{\partial L}{\partial w_2} = 0$

$$\frac{\partial L}{\partial w_1} = \frac{1}{2} \cdot \frac{1}{\sqrt{w_1^2 + w_2^2}} \cdot 2w_1 - \mu = \frac{w_1}{\sqrt{w_1^2 + w_2^2}} - \mu = 0$$

$$\frac{\partial L}{\partial w_2} = \frac{1}{2} \cdot \frac{1}{\sqrt{w_1^2 + w_2^2}} \cdot 2w_2 - 2\mu = \frac{w_2}{\sqrt{w_1^2 + w_2^2}} - 2\mu = 0$$

$$\mu = \frac{w_1}{\sqrt{w_1^2 + w_2^2}} = \frac{w_2}{2\sqrt{w_1^2 + w_2^2}}$$

$\therefore 2w_1 = w_2$  to guarantee existence of  $\mu$

feasibility:  $-w_1 - 2w_2 + 5 \leq 0 \rightarrow -5w_1 + 5 \leq 0 \rightarrow w_1 \geq 1, w_2 \geq 2$

$$\mu = \frac{(w_1 \geq 1)}{(\sqrt{w_1^2 + w_2^2} > 0)} > 0$$

complementary:  $\underbrace{\mu}_{>0} \underbrace{(-w_1 - 2w_2 + 5)}_{=0} = 0 \therefore -w_1 - 2w_2 + 5 = 0$

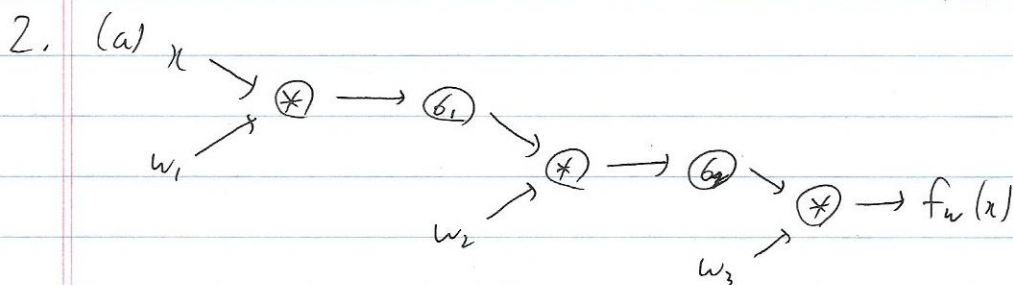
$$\downarrow$$

$$-5w_1 + 5 = 0$$

$$w_1^* = 1, w_2^* = 2 \text{ from KKT}$$

(b)  $\max \frac{1}{\sqrt{w_1^2 + w_2^2}}$  is equivalent to  $\min \sqrt{w_1^2 + w_2^2}$ ,  $\therefore (w_1^*, w_2^*) = (1, 2)$

Q.



(b)  $\frac{\partial \delta_1}{\partial u} = \left( \frac{1}{1+e^{-u}} \right)' = -\frac{1}{(1+e^{-u})^2} \cdot e^{-u} \cdot -1 = \frac{e^{-u}}{(1+e^{-u})^2}$  (i)

~~(b)~~  $\frac{\partial \delta_1}{\partial u} = \frac{e^{-u}}{(1+e^{-u})^2} = \frac{1}{1+e^{-u}} \times \left( 1 - \frac{1}{1+e^{-u}} \right) = \delta_1(u)(1-\delta_1(u))$  (ii)

(c) forward pass: calculating  $x \rightarrow f_w(x)$ , going left to right in (a)

backward pass: calculating gradients  $\frac{\partial f_w}{\partial w_3} \rightarrow \frac{\partial f_w}{\partial w_2} \rightarrow \frac{\partial f_w}{\partial w_1}$  in order going right to left

(d)  $\frac{\partial f_w}{\partial w_3} = \boxed{\delta_2(w_2 \delta_1(w, x))}$  we should retain  $\delta_2(w_2 \delta_1(w, x))$  from forward pass

(e)  $\frac{\partial f_w}{\partial w_2} = w_3 \boxed{\delta_2'(w_2 \delta_1(w, x))} \cdot \delta_1(w, x) = w_3 \boxed{\delta_2(w_2 \delta_1(w, x))} (1 - \boxed{\delta_2(w_2 \delta_1(w, x))}) \cdot \boxed{\delta_1(w, x)}$   
we should retain  $\delta_2(w_2 \delta_1(w, x))$  and  $\delta_1(w, x)$

(f)  $\frac{\partial f_w}{\partial w_1} = w_3 \boxed{\delta_2'(w_2 \delta_1(w, x))} \cdot w_2 \delta_1'(w, x) \cdot x$   
 $= w_3 \boxed{\delta_2(w_2 \delta_1(w, x))} (1 - \boxed{\delta_2(w_2 \delta_1(w, x))}) \cdot w_2 \boxed{\delta_1(w, x)} (1 - \boxed{\delta_1(w, x)}) \cdot \boxed{x}$

we should retain  $\delta_2(w_2 \delta_1(w, x))$  and  $\delta_1(w, x)$  and  $x$

order  $\frac{\partial f_w}{\partial w_3} \rightarrow \frac{\partial f_w}{\partial w_2} \rightarrow \frac{\partial f_w}{\partial w_1}$  is efficient since we can use info of  $\frac{\partial f_w}{\partial w_3}$  to compute  $\frac{\partial f_w}{\partial w_2}$   
"  $\frac{\partial f_w}{\partial w_2}$  to compute  $\frac{\partial f_w}{\partial w_1}$

this order is ~~opposite~~ right to left in (a), opposite from forward pass: left to right