

# Assignment 4: Graphical Model and Unsupervised Learning

AIGS/CS515 Machine Learning

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## Remarks

- Group study and open discussion via LMS board are encouraged, however, assignment that your hand-in must be **of your own work**, and **hand-written** unless you're asked a coding task.
- Submit a scanned copy of your answer on LMS online in **a single PDF file**, to which you also print and add your code if apply, i.e., no zip file, just a single PDF containing everything.
- Delayed submission may get some penalty in score: 5% off for delay of 0 ~ 4 hours; 20% off for delay of 4 ~ 24 hours; and delay longer than 24 hours will not be accepted.

1. [6 pt] (An application of belief propagation) Consider an integer programming (IP) of  $x_1, \dots, x_5$  with linear objective and constraints in the followings:

$$\begin{aligned} & \underset{x_1, \dots, x_5 \in \{0,1\}}{\text{maximize}} && x_1 + 2x_2 + 3x_3 + 2x_4 + 2x_5 \\ & \text{subject to} && x_1 + x_2 + x_3 \leq 1 \\ & && x_3 + x_4 \leq 1 \\ & && x_4 + x_5 \leq 1 \end{aligned}$$

In order to solve the IP, we can formulate a maximum a posterior (MAP) problem of the joint probability of  $x_1, \dots, x_5$  in the following factorized form:

$$p(x_1, \dots, x_5) = \frac{1}{Z} f_a(x_1) f_b(x_2) f_c(x_3) f_d(x_4) f_e(x_5) f_A(x_1, x_2, x_3) f_B(x_3, x_4) f_C(x_4, x_5),$$

where  $Z$  is the normalization constant,  $f_a(x_1) = \exp(x_1)$ ,  $f_b(x_2) = \exp(2x_2)$ ,  $f_c(x_3) = \exp(3x_3)$ ,  $f_d(x_4) = \exp(2x_4)$ ,  $f_e(x_5) = \exp(2x_5)$ ,

$$\begin{aligned} f_A(x_1, x_2, x_3) &= \begin{cases} 1 & \text{if } x_1 + x_2 + x_3 \leq 1 \\ 0 & \text{otherwise} \end{cases}, \\ f_B(x_3, x_4) &= \begin{cases} 1 & \text{if } x_3 + x_4 \leq 1 \\ 0 & \text{otherwise} \end{cases}, \\ f_C(x_4, x_5) &= \begin{cases} 1 & \text{if } x_4 + x_5 \leq 1 \\ 0 & \text{otherwise} \end{cases}. \end{aligned}$$

Note that only configuration of  $x_1, \dots, x_5$  verifies all the constraints in the IP has non-zero probability, which is proportional to the exponential of the objective value of the IP. Hence, the MAP configuration is a solution to the integer programming.

- (a) [2pt] Draw the factor graph corresponding to the joint probability  $p(x_1, \dots, x_5)$ .  
(b) [4pt] Solve the IP using the max-product belief propagation algorithm. What is the optimal value?

2. [11pt] (Graph learning) Consider 4 binary random variables  $X_1, X_2, X_3, X_4 \in \{0, 1\}$ . Assume we have 100 observations and the following table shows the number of counts of observations. We want to learn the structure of random variables  $X_i$ 's from our observations using the Chow-Liu tree algorithm.

$X_1$	$X_2$	$X_3$	$X_4$	Count	$X_1$	$X_2$	$X_3$	$X_4$	Count
0	0	0	0	2	1	0	0	0	7
0	0	0	1	5	1	0	0	1	5
0	0	1	0	2	1	0	1	0	7
0	0	1	1	5	1	0	1	1	12
0	1	0	0	2	1	1	0	0	10
0	1	0	1	4	1	1	0	1	10
0	1	1	0	6	1	1	1	0	10
0	1	1	1	8	1	1	1	1	5

- (a) [4pt] Compute the marginal probability  $p(X_i)$  for each  $i \in \{1, 2, 3, 4\}$  and  $p(X_i, X_j)$  for all  $i \neq j \in \{1, 2, 3, 4\}$ .

$x$	0	1
$p(X_1 = x)$		
$p(X_2 = x)$		
$p(X_3 = x)$		
$p(X_4 = x)$		

$(x, y)$	(0, 0)	(0, 1)	(1, 0)	(1, 1)
$p(X_1 = x, X_2 = y)$				
$p(X_1 = x, X_3 = y)$				
$p(X_1 = x, X_4 = y)$				
$p(X_2 = x, X_3 = y)$				
$p(X_2 = x, X_4 = y)$				
$p(X_3 = x, X_4 = y)$				

- (b) [2pt] Compute the mutual information  $I(X_i, X_j)$  for all  $i \neq j \in \{1, 2, 3, 4\}$ .

$I(X_1, X_2)$	
$I(X_1, X_3)$	
$I(X_1, X_4)$	
$I(X_2, X_3)$	
$I(X_2, X_4)$	
$I(X_3, X_4)$	

- (c) [2pt] Performing Chow-Liu algorithm, draw a Bayesian network  $T_1$  rooted from  $X_1$ .
- (d) [2pt] Performing Chow-Liu algorithm, draw a Bayesian network  $T_3$  rooted from  $X_3$ .
- (e) [1pt] Let  $p_T$  denote the probability corresponding to Bayesian network  $T$ . Compute the difference  $\text{KL}(p \| p_{T_1}) - \text{KL}(p \| p_{T_3})$  where Bayesian networks  $T_1$  and  $T_3$  are obtained in Problems 2c and 2d, resp.

3. [12pt] (K-means) Given a dataset  $\mathcal{D} = \{x^{(i)}\}_{i \in [N]}$  of  $N$  data points in  $\mathbb{R}^2$ , we want to partitioning them into  $K$  clusters using  $K$ -means algorithm. Let  $\mu_k \in \mathbb{R}^2$  denote the center of cluster  $k \in [K]$ . Then, the  $K$ -means algorithm aims at optimizing:

$$\min_{\{r_{ik}\}, \{\mu_k\}} \sum_{i \in [N]} \sum_{k \in [K]} \frac{1}{2} r_{ik} \|x^{(i)} - \mu_k\|_2^2 \quad (1a)$$

$$\text{s.t. } r_{ik} \in \{0, 1\} \quad \forall i \in [N], \forall k \in [K] \quad \text{and}; \quad (1b)$$

$$\sum_{k \in [K]} r_{ik} = 1 \quad \forall i \in [N]. \quad (1c)$$

- (a) [2pt] Given fixed cluster centers  $\{\mu_k\}_{k \in [K]}$ , obtain the optimal  $r_{ik}$  for (1). Justify your solution.
- (b) [2pt] Given fixed  $\{r_{ik}\}_{i \in [N], k \in [K]}$ , verifying (1b) and (1c), obtain the optimal cluster center  $\mu_k$  for (1). Justify your solution.
- (c) [4pt] We want to check the convergence of  $K$ -means algorithm which alternates Problems (3a) and (3b). Describe the algorithm. Let  $L_t$  be the loss (1a) after  $t$ -th iteration of  $K$ -means algorithm. Check if  $L_t$  is monotonically increasing in  $t$ . Using the following theorem (a part of monotone convergence theorem), check the convergence of  $K$ -means algorithm in terms of loss function. Can we guarantee that  $K$ -means algorithm converges to the global optimality?

**Theorem 1.** *If  $(a_t)_{t \in \mathbb{N}}$  is a monotone sequence of real numbers, i.e., if  $a_t \leq a_{t+1}$  for every  $t \geq 1$ , or  $a_t \geq a_{t+1}$  for every  $t \geq 1$ , then this sequence has a finite limit if and only if the sequence is bounded.*

- (d) [4pt] Complete `Kmeans.py` which performing  $K$ -means algorithm aforementioned. For the given dataset, after how many updates does the algorithm converge? What cost function value does it converge to? What are the obtained centers?

4. [20pt] (Generative Adversarial Networks) Consider the following max-min problem for a dataset  $\mathcal{D}$  consisting of  $x$ 's:

$$\max_{\theta} \min_w - \sum_{x \in \mathcal{D}} \log p_w(y = 1 | x) - \sum_{z \in \mathcal{Z}} \log(1 - p_w(y = 1 | G_{\theta}(z))) + \frac{C}{2} \|w\|_2^2. \quad (2)$$

Here the generator  $G_{\theta}(z)$  parameterized by  $\theta$  transforms noise  $z \in \mathcal{Z}$  into artificial data. The discriminator  $p_w(y | x)$  parameterized by  $w$  checks if  $x$  is artificial or not, where  $y = 1$  indicates that  $x$  is real, and  $y = 0$  indicates that  $x$  is artificial. The hyperparameter  $C \geq 0$  controls impact of regularization. Note that solving (2) is challenging mainly due to the objective is neither convex in  $w$  nor concave in  $\theta$  in general. We will check if the cost function is convex in  $w$  for specific choice of the discriminator model. To do so, we use several facts:

**Fact1.** A function  $f(w)$  is convex in  $w$  if Hessian<sup>1</sup> of  $f(w)$  is positive semi-definite<sup>2</sup>.

**Fact2.** A sum of convex functions is also convex.

- (a) [2pt] Suppose that we model the discriminator as follows:

$$p_w(y = 1 | x) = \frac{1}{1 + \exp(w^{\top} x)}.$$

Using this, write down the resulting cost function for (2).

- (b) [2pt] Obtain Hessian of (A) =  $\frac{C}{2} \|w\|_2^2 - w^{\top} b$  in  $w$ . Check if (A) is convex, and justify your answer.
- (c) [2pt] Obtain Hessian of (B) =  $\log(1 + \exp(w^{\top} b))$  in  $w$ . Check if (B) is convex, and justify your answer.
- (d) [2pt] Check if the cost function obtained in Problem 4a is convex, and justify your answer.
- (e) [2pt] Introducing auxiliary variables  $\xi_x = w^{\top} x$  and  $\xi_z = w^{\top} G_{\theta}(z)$ , consider the following optimization (for the discriminator):

$$\min_w \quad \sum_{x \in \mathcal{D}} \log(1 + \exp \xi_x) + \sum_{z \in \mathcal{Z}} \log(1 + \exp(\xi_z)) - \sum_{z \in \mathcal{Z}} w^{\top} G_{\theta}(z) + \frac{C}{2} \|w\|_2^2 \quad (3a)$$

$$\text{s.t.} \quad \xi_x = w^{\top} x \quad \forall x \in \mathcal{D} \quad (3b)$$

$$\xi_z = w^{\top} G_{\theta}(z) \quad \forall z \in \mathcal{D} \quad (3c)$$

Write the Lagrangian for this optimization, where  $\lambda_x$  and  $\lambda_z$  are Lagrange multipliers corresponding to (3b) and (3c), resp.

<sup>1</sup>[https://en.wikipedia.org/wiki/Hessian\\_matrix](https://en.wikipedia.org/wiki/Hessian_matrix)

<sup>2</sup>[https://en.wikipedia.org/wiki/Definite\\_symmetric\\_matrix](https://en.wikipedia.org/wiki/Definite_symmetric_matrix)

- (f) [2pt] Obtain the value of

$$\min_w \frac{C}{2} \|w\|_2^2 - w^\top b$$

in terms of  $b$  and  $C \geq 0$ .

- (g) [2pt] Obtain the value of

$$\min_{\xi} \lambda \xi + \log(1 + \exp \xi)$$

in terms of  $\lambda$  assuming  $-1 \leq \lambda \leq 0$ .

- (h) [4pt] Combining Problems 4e, 4f, and 4g and using  $H(a) = a \log(-a) - (1 + a) \log(1 + a)$ , obtain dual function  $g(\lambda)$  for (3). For training the discriminator, we can replace the original minimization over  $w$  described in (2) with the dual maximization over valid values of  $\lambda$ . Using this, write down an alternative of GAN training in (2), in which we have a max-max problem instead of the max-min problem. Note that such an alternative training in max-max form can help to bypass challenges from finding a saddle-point, i.e., solving the max-min problem.
- (i) [2pt] Complete `GAN.py`, which is an implementation of the alternative training of GAN obtained in Problem 4h with the  $\log D$  trick in the lecture. (Hint: use `target1` and `target2`)